6502

6502 ASSEMBLY LANGUAGE SUBROUTINES

LANCE A. LEVENTHAL  WINTHROP SAVILLE
6502
Assembly Language Subroutines

Lance A. Leventhal
Winthrop Saville

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This book is intended to serve as a source and a reference for the assembly language programmer. It contains an overview of assembly language programming for a particular microprocessor and a collection of useful routines. In writing the routines, we have used a standard format, documentation package, and parameter passing techniques. We have followed the rules of the original manufacturer's assembler and have described the purpose, procedure, parameters, results, execution time, and memory usage of each routine.

This overview of assembly language programming provides a summary for those who do not have the time or need for a complete textbook such as is provided already in the Assembly Language Programming series. Chapter 1 contains an introduction to assembly language programming for the particular processor and a brief summary of the major features that differentiate this processor from other microprocessors and minicomputers. Chapter 2 describes how to implement instructions and addressing modes that are not explicitly available. Chapter 3 discusses common errors that the programmer is likely to encounter.

The collection of routines emphasizes common tasks that occur in many applications such as code conversion, array manipulation, arithmetic, bit manipulation, shifting functions, string manipulation, summation, sorting, and searching. We have also provided examples of I/O routines, interrupt service routines, and initialization routines for common family chips such as parallel interfaces, serial interfaces, and timers. You should be able to use these routines as subroutines in actual applications and as guidelines for more complex programs.

We have aimed this book at the person who wants to use assembly language immediately, rather than just learn about it. The reader could be

- An engineer, technician, or programmer who must write assembly language programs for use in a design project.
- A microcomputer user who wants to write an I/O driver, a diagnostic program, or a utility or systems program in assembly language.
• A programmer or engineer with experience in assembly language who needs a quick review of techniques for a particular microprocessor.
• A system designer or programmer who needs a specific routine or technique for immediate use.
• A programmer who works in high-level languages but who must debug or optimize programs at the assembly level or must link a program written in a high-level language to one written in assembly language.
• A system designer or maintenance programmer who must quickly understand how specific assembly language programs operate.
• A microcomputer owner who wants to understand how the operating system works on a particular computer, or who wants to gain complete access to the computer’s facilities.
• A student, hobbyist, or teacher who wants to see some examples of working assembly language programs.

This book can also serve as supplementary material for students of the Assembly Language Programming series.

This book should save the reader time and effort. There is no need to write, debug, test, or optimize standard routines, nor should the reader have to search through material with which he or she is thoroughly familiar. The reader should be able to obtain the specific information, routine, or technique that he or she needs with a minimum amount of effort. We have organized and indexed this book for rapid use and reference.

Obviously, a book with such an aim demands response from its readers. We have, of course, tested all the programs thoroughly and documented them carefully. If you find any errors, please inform the publisher. If you have suggestions for additional topics, routines, programming hints, index entries, and so forth, please tell us about them. We have drawn on our programming experience to develop this book, but we need your help to improve it. We would greatly appreciate your comments, criticisms, and suggestions.

NOMENCLATURE

We have used the following nomenclature in this book to describe the architecture of the 6502 processor, to specify operands, and to represent general values of numbers and addresses.

6502 Architecture

_BYTE-length registers include_

A (accumulator)
F (flags, same as P)
P (status register)
S or SP (stack pointer)
X (index register X)
Y (index register Y)

Of these, the general purpose user registers are A, X, and Y. The stack pointer always contains the address of the next available stack location on page 1 of memory (addresses 0100₁₆ through 01FF₁₆). The P (status) or F (flag) register consists of a set of bits with independent functions and meanings, organized as shown in the following diagram:

Word-length registers include

PC (program counter)

Note: Pairs of memory locations on page 0 may also be used as word-length registers to hold indirect addresses. The lower address holds the less significant byte and the higher address holds the more significant byte. Since the 6502 provides automatic wraparound, addresses 00FF₁₆ and 0000₁₆ form a rarely used pair.

Flags include

Break (B)
Carry (C)
Decimal Mode (D)
Interrupt Disable (I)
Negative or Sign (N)
Overflow (V)
Zero (Z)

These flags are arranged in the P or F register as shown previously.
6502 Assembler

Delimiters include

- space: After a label or an operation code
- ,: Between operands in the operand (address) field
- ;: Before a comment
- :: After a label (optional)
- (,): Around an indirect address

Pseudo-Operations include

- .BLOCK: Reserve bytes of memory; reserve the specified number of bytes of memory for temporary storage
- .BYTE: Form byte-length data; place the specified 8-bit data in the next available memory locations
- .DBYTE: Form double-byte (word) length data with more significant byte first; place the specified 16-bit data in the next available memory locations with more significant byte first
- .END: End of program
- .EQU: Equate; define the attached label
- .TEXT: Form string of ASCII characters; place the specified ASCII characters in the next available memory locations
- .WORD: Form double-byte (word) length data with less significant byte first; place the specified 16-bit data in the next available memory locations with less significant byte first
- *=: Set origin; assign the object code generated from the subsequent assembly language statements to memory addresses starting with the one specified
- =: Equate; define the attached label

Designations include

Number systems:

- $ (prefix) or H (suffix): Hexadecimal
- @ (prefix) or Q (suffix): Octal
- % (prefix) or B (suffix): Binary

The default mode is decimal.

Others:

- ' (in front of character): ASCII
- *: Current value of location (program) counter
' ' or " " (around a string of characters) - ASCII string

# Immediate addressing

.x Indexed addressing with index register X

.y Indexed addressing with index register Y

The default addressing mode is absolute (direct) addressing.

**General Nomenclature**

ADDR a 16-bit address in data memory

ADDRH the more significant byte of ADDR

ADDRL the less significant byte of ADDR

BASE a constant 16-bit address

BASEH the more significant byte of BASE

BASEL the less significant byte of BASE

DEST a 16-bit address in program memory, the destination for a jump or branch instruction

NTIMES an 8-bit data item

NTIMH an 8-bit data item

NTIMHC an 8-bit data item

NTIML an 8-bit data item

NTIMLC an 8-bit data item

OPER a 16-bit address in data memory

OPER1 a 16-bit address in data memory

OPER2 a 16-bit address in data memory

PGZRO an address on page 0 of data memory

PGZRO+1 the address one larger than PGZRO (with no carry to the more significant byte)

POINTER a 16-bit address in data memory

POINTH the more significant byte of POINTER

POINTL the less significant byte of POINTER

RESLT a 16-bit address in data memory
VAL16          a 16-bit data item
VAL16L         the less significant byte of VAL16
VAL16M         the more significant byte of VAL16
VALUE          an 8-bit data item
ZCOUNT         a 16-bit address in data memory
Chapter 1  General Programming Methods

This chapter describes general methods for writing assembly language programs for the 6502 and related microprocessors. It presents techniques for performing the following operations:

- Loading and saving registers
- Storing data in memory
- Arithmetic and logical functions
- Bit manipulation
- Bit testing
- Testing for specific values
- Numerical comparisons
- Looping (repeating sequences of operations)
- Array processing and manipulation
- Table lookup
- Character code manipulation
- Code conversion
- Multiple-precision arithmetic
- Multiplication and division
- List processing
- Processing of data structures.

Special sections discuss passing parameters to subroutines, writing I/O drivers and interrupt service routines, and making programs run faster or use less memory.

The operations described are required in applications such as instrumentation, test equipment, computer peripherals, communications equipment, industrial control, process control, aerospace and military systems, business equipment,
and consumer products. Microcomputer users will make use of these operations in writing I/O drivers, utility programs, diagnostics, and systems software, and in understanding, debugging, or improving programs written in high-level languages. This chapter provides a brief guide to 6502 assembly language programming for those who have an immediate application in mind.

QUICK SUMMARY FOR EXPERIENCED PROGRAMMERS

For those who are familiar with assembly language programming on other processors, we provide here a brief review of the peculiarities of the 6502. Being aware of these unusual features can save you a great deal of time and trouble.

1. The Carry flag acts as an inverted borrow in subtraction. A Subtract (SBC) or Compare (CMP, CPX, or CPY) instruction clears the Carry if the operation requires a borrow and sets it if it does not. The SBC instruction accounts for this inversion by subtracting 1—Carry from the usual difference. Thus, the Carry has the opposite meaning after subtraction (or comparison) on the 6502 than it has on most other computers.

2. The only Addition and Subtraction instructions are ADC (Add with Carry) and SBC (Subtract with Carry). If you wish to exclude the Carry flag, you must clear it before addition or set it before subtraction. That is, you can simulate a normal Add instruction with

```asm
CLC
ADC MEMORY
```

and a normal Subtract instruction with

```asm
SEC
SBC MEMORY
```

3. There are no 16-bit registers and no operations that act on 16-bit quantities. The lack of 16-bit registers is commonly overcome by using pointers stored on page 0 and the indirect indexed (postindexed) addressing mode. However, both initializing and changing those pointers require sequences of 8-bit operations.

4. There is no true indirect addressing except with JMP. For many other instructions, however, you can simulate indirect addressing by clearing index register Y and using indirect indexed addressing, or by clearing index register X and using indexed indirect addressing. Both of these modes are limited to indirect addresses stored on page 0.

5. The stack is always on page 1 of memory. The stack pointer contains the less significant byte of the next empty address. Thus, the stack is limited to 256 bytes of memory.
6. The JSR (Jump to Subroutine) instruction saves the address of its own third byte in the stack, that is, JSR saves the return address minus 1. RTS (Return from Subroutine) loads the program counter from the top of the stack and then adds 1 to it. You must remember this offset of 1 in debugging and using JSR or RTS for purposes other than ordinary calls and returns.

7. The Decimal Mode (D) flag is used to perform decimal arithmetic. When this flag is set, all additions and subtractions produce decimal results. Increments and decrements, however, produce binary results regardless of the mode. The problem with this approach is that you may not be sure of the initial or current state of the D flag (the processor does not initialize it on Reset). A simple way to avoid problems in programs that use Addition or Subtraction instructions is to save the original D flag in the stack, assign D the appropriate value, and restore the original value before exiting. Interrupt service routines, in particular, should always either set or clear D before executing any addition or subtraction instructions. The PHP (Store Status Register in Stack) and PLP (Load Status Register from Stack) instructions can be used to save and restore the D flag, if necessary. The overall system startup routine must initialize D (usually to 0, indicating binary mode, with CLD). Most 6502-based operating systems assume the binary mode as a default and always return to that mode as soon as possible.

A minor quirk of the 6502's decimal mode is that the Zero and Negative flags are no longer universally valid. These flags reflect only the binary result, not the decimal result; only the Carry flag always reflects the decimal result. Thus, for example, subtracting 80₁₀ from 50₁₀ in the decimal mode sets the Negative flag (since the binary result is D0₁₀), even though the decimal result (70₁₀) has a most significant bit of 0. Similarly, adding 50₁₀ and 50₁₀ in the decimal mode clears the Zero flag (since the binary result is A0₁₀), even though the decimal result is zero. Note that adding 50₁₀ and 50₁₀ in the decimal mode does set the Carry. Thus when working in the decimal mode, the programmer should use only branches that depend on the Carry flag or operations that do not depend on the mode at all (such as subtractions or comparisons followed by branches on the Zero flag).

8. Ordinary Load (or Pull from the Stack) and Transfer instructions (except TXS) affect the Negative (Sign) and Zero flags. This is not the case with the 8080, 8085, or Z-80 microprocessors. Storing data in memory does not affect any flags.

9. INC and DEC cannot be applied to the accumulator. To increment A, use

```
CLC
ADC #1        ;INCREMENT ACCUMULATOR BY 1
```

To decrement A, use

```
SEC
SBC #1        ;DECREMENT ACCUMULATOR BY 1
```
10. The index registers are only 8 bits long. This creates obvious problems in handling arrays or areas of memory that are longer than 256 bytes. To overcome this, use the indirect indexed (postindexed) addressing mode. This mode allows you to store the starting address of the array in two memory locations on page 0. Whenever the program completes a 256-byte section, it must add 1 to the more significant byte of the indirect address before proceeding to the next section. The processor knows that it has completed a section when index register Y returns to 0. A typical sequence is

```
INY           ; PROCEED TO NEXT BYTE
BNE LOOP     ; UNLESS A PAGE IS DONE
INC INDR+1   ; IF ONE IS, GO ON TO THE NEXT PAGE
```

Memory location INDR+1 (on page 0) contains the most significant byte of the indirect address.

11. 16-bit counters may be maintained in two memory locations. Counting up is much easier than counting down since you can use the sequence

```
INC COUNTL    ; COUNT UP LESS SIGNIFICANT BYTE
BNE LOOP
INC COUNTH    ; CARRYING TO MSB IF NECESSARY
JMP LOOP
```

COUNTL contains the less significant byte of a 16-bit counter and COUNTH the more significant byte. Note that we check the Zero flag rather than the Carry flag since, as on most computers, Increment and Decrement instructions do not affect Carry.

12. The BIT instruction (logical AND with no result saved) has several unusual features. In the first place, it allows only direct addressing (absolute and zero page). If you want to test bit 3 of memory location ADDR, you must use the sequence

```
LDA #00001000
BIT ADDR
```

BIT also loads the Negative and Overflow flags with the contents of bits 7 and 6 of the memory location, respectively, regardless of the value in the accumulator. Thus, you can perform the following operations without loading the accumulator at all. Branch to DEST if bit 7 of ADDR is 1

```
BIT ADDR
BMI DEST
```

Branch to DEST if bit 6 of ADDR is 0

```
BIT ADDR
BVC DEST
```

Of course, you should document the special use of the Overflow flag for later reference.
13. The processor lacks some common instructions that are available on the 6800, 6809, and similar processors. Most of the missing instructions are easy to simulate, although the documentation can become awkward. In particular, we should mention Clear (use load immediate with 0 instead), Complement (use logical EXCLUSIVE OR with the all 1s byte instead), and the previously mentioned Add (without carry) and Subtract (without borrow). There is also no direct way to load or store the stack pointer (this can be done through index register X), load or store the status register (this can be done through the stack), or perform operations between registers (one must be stored in memory). Other missing instructions include Unconditional Relative Branch (use jump or assign a value to a flag and branch on it having that value), Increment and Decrement Accumulator (use the Addition and Subtraction instructions), Arithmetic Shift (copy bit 7 into Carry and rotate), and Test zero or minus (use a comparison with 0 or an increment, decrement sequence). Weller\textsuperscript{1} describes the definition of macros to replace the missing instructions.

14. The 6502 uses the following common conventions:

- 16-bit addresses are stored with the less significant byte first. The order of the bytes is the same as in the 8080, Z-80, and 8085 microprocessors, but opposite the order used in 6800 and 6809.

- The stack pointer contains the address (on page 1) of the next available location. This convention is also used in the 6800, but the obvious alternative (last occupied location) is used in the 8080, 8085, Z-80, and 6809 microprocessors. Instructions store data in the stack using postdecrementing (they subtract 1 from the stack pointer after storing each byte) and load data from the stack using preincrementing (they add 1 to the stack pointer before loading each byte).

- The I (Interrupt) flag acts as a disable. Setting the flag (with SEI) disables the maskable interrupt and clearing the flag (with CLI) enables the maskable interrupt. This convention is the same as in the 6800 and 6809 but the opposite of that used in the 8080, 8085, and Z-80.

**THE REGISTER SET**

The 6502 assembly language programmer's work is complicated considerably by the processor's limited register set. In particular, there are no address-length (16-bit) user registers. Thus, variable addresses must normally be stored in pairs of memory locations on page 0 and accessed indirectly using either preindexing (indexed indirect addressing) or postindexing (indirect indexed addressing). The lack of 16-bit registers also complicates the handling of arrays or blocks that occupy more than 256 bytes of memory.
If we consider memory locations on page 0 as extensions of the register set, we may characterize the registers as follows:

- The accumulator is the center of data processing and is used as a source and destination by most arithmetic, logical, and other data processing instructions.

- Index register X is the primary index register for non-indirect uses. It is the only register that normally has a zero page indexed mode (except for the LDX STX instructions), and it is the only register that can be used for indexing with single-operand instructions such as shifts, increment, and decrement. It is also the only register that can be used for preindexing, although that mode is not common. Finally, it is the only register that can be used to load or store the stack pointer.

- Index register Y is the primary index register for indirect uses, since it is the only register that can be used for postindexing.

- Memory locations on page 0 are the only locations that can be accessed with the zero page (direct), zero page indexed, preindexed, and postindexed addressing modes.

Tables 1-1 through 1-7 contain lists of instructions having particular features. Table 1-1 lists instructions that apply only to particular registers and Table 1-2 lists instructions that can be applied directly to memory locations. Tables 1-3 through 1-7 list instructions that allow particular addressing modes: zero page (Table 1-3), absolute (Table 1-4), zero page indexed (Table 1-5), absolute indexed (Table 1-6), and preindexing and postindexing (Table 1-7).

We may describe the special features of particular registers as follows:

- **Accumulator.** Source and destination for all arithmetic and logical instructions except CPX, CPY, DEC, and INC. Only register that can be shifted with a single instruction. Only register that can be loaded or stored using preindexed or postindexed addressing.

- **Index register X.** Can be incremented using INX or decremented using DEX. Only register that can be used as an index in preindexing. Only register that can be used to load or store the stack pointer.

- **Index register Y.** Can be incremented using INY or decremented using DEY. Only register that can be used as an index in postindexing.

- **Memory locations on page 0.** Only memory locations that can hold indirect addresses for use in postindexing or preindexing. Only memory locations that can be accessed using zero page or zero page indexed addressing.

- **Status register.** Can only be stored in the stack using PHP or loaded from the stack using PLP.
### Table 1-1: Registers and Applicable Instructions

<table>
<thead>
<tr>
<th>Register</th>
<th>Instructions</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>ADC, AND, ASL, BIT, CMP, EOR, LDA, LSR, ORA, PHA, PLA, ROL, ROR, SBC, STA, TAX, TAY, TXA, TYA</td>
</tr>
<tr>
<td>P (processor status)</td>
<td>PHP, PLP (CLC, CLD, CLV, SEC, and SED affect particular flags)</td>
</tr>
<tr>
<td>S (stack pointer)</td>
<td>JSR, PHA, PHP, PLA, PLP, RTS, TSX, TXS</td>
</tr>
<tr>
<td>X</td>
<td>CPX, DEX, INX, LDX, STX, TAX, TSX, TXA, TXS</td>
</tr>
<tr>
<td>Y</td>
<td>CPY, DEY, INY, LDY, STY, TAY, TYA</td>
</tr>
</tbody>
</table>

### Table 1-2: Instructions That Can Be Applied Directly to Memory Locations

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>Arithmetic shift left</td>
</tr>
<tr>
<td>BIT</td>
<td>Bit test (test bits 6 and 7)</td>
</tr>
<tr>
<td>DEC</td>
<td>Decrement by 1</td>
</tr>
<tr>
<td>INC</td>
<td>Increment by 1</td>
</tr>
<tr>
<td>LSR</td>
<td>Logical shift right</td>
</tr>
<tr>
<td>ROL</td>
<td>Rotate left</td>
</tr>
<tr>
<td>ROR</td>
<td>Rotate right</td>
</tr>
</tbody>
</table>

### Table 1-3: Instructions That Allow Zero Page Addressing

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>Add with Carry</td>
</tr>
<tr>
<td>AND</td>
<td>Logical AND</td>
</tr>
<tr>
<td>ASL</td>
<td>Arithmetic shift left</td>
</tr>
<tr>
<td>CMP</td>
<td>Compare memory and accumulator</td>
</tr>
<tr>
<td>CPX</td>
<td>Compare memory and index register X</td>
</tr>
<tr>
<td>CPY</td>
<td>Compare memory and index register Y</td>
</tr>
<tr>
<td>DEC</td>
<td>Decrement by 1</td>
</tr>
<tr>
<td>EOR</td>
<td>Logical EXCLUSIVE OR</td>
</tr>
<tr>
<td>INC</td>
<td>Increment by 1</td>
</tr>
<tr>
<td>LDA</td>
<td>Load accumulator</td>
</tr>
<tr>
<td>LDX</td>
<td>Load index register X</td>
</tr>
<tr>
<td>LDY</td>
<td>Load index register Y</td>
</tr>
<tr>
<td>LSR</td>
<td>Logical shift right</td>
</tr>
<tr>
<td>ORA</td>
<td>Logical OR</td>
</tr>
<tr>
<td>ROL</td>
<td>Rotate left</td>
</tr>
<tr>
<td>ROR</td>
<td>Rotate right</td>
</tr>
<tr>
<td>SBC</td>
<td>Subtract with Carry</td>
</tr>
<tr>
<td>STA</td>
<td>Store accumulator</td>
</tr>
<tr>
<td>STX</td>
<td>Store index register X</td>
</tr>
<tr>
<td>STY</td>
<td>Store index register Y</td>
</tr>
</tbody>
</table>
Table 1-4: Instructions That Allow Absolute (Direct) Addressing

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>Add with Carry</td>
</tr>
<tr>
<td>AND</td>
<td>Logical AND</td>
</tr>
<tr>
<td>ASL</td>
<td>Arithmetic shift left</td>
</tr>
<tr>
<td>BIT</td>
<td>Logical bit test</td>
</tr>
<tr>
<td>CMP</td>
<td>Compare memory and accumulator</td>
</tr>
<tr>
<td>CPX</td>
<td>Compare memory and index register X</td>
</tr>
<tr>
<td>CPY</td>
<td>Compare memory and index register Y</td>
</tr>
<tr>
<td>DEC</td>
<td>Decrement by 1</td>
</tr>
<tr>
<td>EOR</td>
<td>Logical EXCLUSIVE OR</td>
</tr>
<tr>
<td>INC</td>
<td>Increment by 1</td>
</tr>
<tr>
<td>JMP</td>
<td>Jump unconditional</td>
</tr>
<tr>
<td>JSR</td>
<td>Jump to subroutine</td>
</tr>
<tr>
<td>LDA</td>
<td>Load accumulator</td>
</tr>
<tr>
<td>LDX</td>
<td>Load index register X</td>
</tr>
<tr>
<td>LDY</td>
<td>Load index register Y</td>
</tr>
<tr>
<td>LSR</td>
<td>Logical shift right</td>
</tr>
<tr>
<td>ORA</td>
<td>Logical OR</td>
</tr>
<tr>
<td>ROL</td>
<td>Rotate left</td>
</tr>
<tr>
<td>ROR</td>
<td>Rotate right</td>
</tr>
<tr>
<td>SBC</td>
<td>Subtract with Carry</td>
</tr>
<tr>
<td>STA</td>
<td>Store accumulator</td>
</tr>
<tr>
<td>STX</td>
<td>Store index register X</td>
</tr>
<tr>
<td>STY</td>
<td>Store index register Y</td>
</tr>
</tbody>
</table>

Table 1-5: Instructions That Allow Zero Page Indexed Addressing

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>Add with Carry</td>
</tr>
<tr>
<td>AND</td>
<td>Logical AND</td>
</tr>
<tr>
<td>ASL</td>
<td>Arithmetic shift left</td>
</tr>
<tr>
<td>CMP</td>
<td>Compare memory and accumulator</td>
</tr>
<tr>
<td>DEC</td>
<td>Decrement by 1</td>
</tr>
<tr>
<td>EOR</td>
<td>Logical EXCLUSIVE OR</td>
</tr>
<tr>
<td>INC</td>
<td>Increment by 1</td>
</tr>
<tr>
<td>LDA</td>
<td>Load accumulator</td>
</tr>
<tr>
<td>LDX</td>
<td>Load index register X</td>
</tr>
<tr>
<td>LDY</td>
<td>Load index register Y</td>
</tr>
<tr>
<td>LSR</td>
<td>Logical shift right</td>
</tr>
<tr>
<td>ORA</td>
<td>Logical OR</td>
</tr>
<tr>
<td>ROL</td>
<td>Rotate left</td>
</tr>
<tr>
<td>ROR</td>
<td>Rotate right</td>
</tr>
<tr>
<td>SBC</td>
<td>Subtract with Carry</td>
</tr>
<tr>
<td>STA</td>
<td>Store accumulator</td>
</tr>
<tr>
<td>STX</td>
<td>Store index register X</td>
</tr>
<tr>
<td>STY</td>
<td>Store index register Y</td>
</tr>
</tbody>
</table>

Index Register X

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>LDX</td>
<td>Load index register X</td>
</tr>
<tr>
<td>STX</td>
<td>Store index register X</td>
</tr>
</tbody>
</table>

Index Register Y
### Table 1-6: Instructions That Allow Absolute Indexed Addressing

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>Add with Carry</td>
</tr>
<tr>
<td>AND</td>
<td>Logical AND</td>
</tr>
<tr>
<td>ASL</td>
<td>Arithmetic shift left</td>
</tr>
<tr>
<td>CMP</td>
<td>Compare memory and accumulator</td>
</tr>
<tr>
<td>DEC</td>
<td>Decrement by 1</td>
</tr>
<tr>
<td>EOR</td>
<td>Logical EXCLUSIVE OR</td>
</tr>
<tr>
<td>INC</td>
<td>Increment by 1</td>
</tr>
<tr>
<td>LDA</td>
<td>Load accumulator</td>
</tr>
<tr>
<td>LDY</td>
<td>Load index register Y</td>
</tr>
<tr>
<td>LSR</td>
<td>Logical shift right</td>
</tr>
<tr>
<td>ORA</td>
<td>Logical OR</td>
</tr>
<tr>
<td>ROL</td>
<td>Rotate left</td>
</tr>
<tr>
<td>ROR</td>
<td>Rotate right</td>
</tr>
<tr>
<td>SBC</td>
<td>Subtract with Carry</td>
</tr>
<tr>
<td>STA</td>
<td>Store accumulator</td>
</tr>
</tbody>
</table>

### Table 1-7: Instructions That Allow Postindexing and Preindexing

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>Add with Carry</td>
</tr>
<tr>
<td>AND</td>
<td>Logical AND</td>
</tr>
<tr>
<td>CMP</td>
<td>Compare memory and accumulator</td>
</tr>
<tr>
<td>EOR</td>
<td>Logical EXCLUSIVE OR</td>
</tr>
<tr>
<td>LDA</td>
<td>Load accumulator</td>
</tr>
<tr>
<td>LDX</td>
<td>Load index register X</td>
</tr>
<tr>
<td>ORA</td>
<td>Logical OR</td>
</tr>
<tr>
<td>SBC</td>
<td>Subtract with Carry</td>
</tr>
<tr>
<td>STA</td>
<td>Store accumulator</td>
</tr>
</tbody>
</table>
Stack pointer. Always refers to an address on page 1. Can only be loaded from or stored in index register X using TXS and TSX, respectively.

- Almost all data processing involves the accumulator, since it provides one operand for arithmetic and logical instructions and the destination for the result.
- Only a limited number of instructions operate directly on the index registers or on memory locations. An index register can be incremented by 1, decremented by 1, or compared to a constant or to the contents of an absolute address. The data in a memory location can be incremented by 1, decremented by 1, shifted left or right, or rotated left or right.
- The available set of addressing methods varies greatly from instruction to instruction. Note in particular the limited sets available with the instructions BIT, CPX, CPY, LDX, LDY, STX, and STY.

Register Transfers

Only a limited number of direct transfers between registers are provided. A single instruction can transfer data from an index register to the accumulator, from the accumulator to an index register, from the stack pointer to index register X, or from index register X to the stack pointer. The mnemonics for the transfer instructions have the form TSD, where “S” is the source register and “D” is the destination register as in the convention proposed in IEEE Standard 694. The status (P) register may only be transferred to or from the stack using PHP or PLP.

Loading Registers from Memory

The 6502 microprocessor offers many methods for loading registers from memory. The following addressing modes are available: zero page (direct), absolute (direct), immediate zero page indexed, absolute indexed, postindexed, and preindexed. Osborne describes all these modes in Chapter 6 of An Introduction to Microcomputers: Volume 1 — Basic Concepts.

Direct Loading of Registers

The accumulator, index register X, and index register Y can be loaded from memory using direct addressing. A special zero page mode loads registers from
addresses on page 0 more rapidly than from addresses on other pages. Terminology for 6502 refers to zero page direct addressing as zero page addressing and to the more general direct addressing as absolute addressing.

Examples
1. LDA $40
   This instruction loads the accumulator from memory location 0040
   The special zero page addressing mode requires less time and memory than the more general absolute (direct) addressing.
2. LDX $C000
   This instruction loads index register X from memory location C000
   It uses absolute (direct) addressing.

Immediate Loading of Registers

This method can be used to load the accumulator, index register X, or index register Y with a specific value.

Examples
1. LDY #6
   This instruction loads index register Y with the number 6. The 6 is an 8-bit data item, not a 16-bit address; do not confuse the number 6 with the address 0006.
2. LDA #$E3
   This instruction loads the accumulator with the number E3.

Indexed Loading of Registers

The instructions LDA, LDX, and LDY can be used in the indexed mode. The limitations are that index register X cannot be loaded using X as an index; similarly, index register Y cannot be loaded using Y as an index. As with direct addressing, a special zero page mode is provided. Note, however, that the accumulator cannot be loaded in the zero page mode using Y as an index.

Examples
1. LDA $0340,X
   This instruction loads the accumulator from the address obtained by indexing with index register X from the base address 0340; that is, the effective address is 0340 + (X). This is the typical indexing described in An Introduction to Microcomputers: Volume 1 — Basic Concepts.
2. LDX $40,Y

This instruction loads index register X from the address obtained by indexing with register Y from the base address 0040_{16}. Here the special zero page indexed mode saves time and memory.

**Postindexed Loading of Registers**

The instruction LDA can be used in the postindexed mode, in which the base address is taken from two memory locations on page 0. Otherwise, this mode is the same as regular indexing.

**Example**

```assembly
LDA ($40),Y
```

This instruction loads the accumulator from the address obtained by indexing with index register Y from the base address in memory locations 0040_{16} and 0041_{16}. This mode is restricted to page 0 and index register Y. It also assumes that the indirect address is stored with its less significant byte first (at the lower address) in the usual 6502 manner.

**Preindexed Loading of Registers**

The instruction LDA can be used in the preindexed mode, in which the indexed address is itself used indirectly. This mode is restricted to page 0 and index register X. Note that it also assumes the existence of a table of 2-byte indirect addresses, so that only even values in X make sense.

**Example**

```assembly
LDA ($40,X)
```

This instruction loads the accumulator from the indirect address obtained by indexing with register X from the base address 0040_{16}. The indirect address is in the two bytes of memory starting at 0040_{16} + (X). This mode is uncommon; one of its uses is to select from a table of device addresses for input/output.

**Stack Loading of Registers**

The instruction PLA loads the accumulator from the top of the stack and subtracts 1 from the stack pointer. The instruction PLP is similar, except that it loads the status (P) register. This is the only way to load the status register with a specific value. The index registers cannot be loaded directly from the stack, but
they can be loaded via the accumulator. The required sequences are

(for index register X)

```
PLA          ;TOP OF STACK TO A
TAX          ;AND ON TO X
```

(for index register Y)

```
PLA          ;TOP OF STACK TO A
TAY          ;AND ON TO Y
```

The stack has the following special features:

- It is always located on page 1 of memory. The stack pointer contains only the less significant byte of the next available address.
- Data is stored in the stack using postdecrementing — the instructions decrement the stack pointer by 1 after storing each byte. Data is loaded from the stack using preincrementing — the instructions increment the stack pointer by 1 before loading each byte.
- As is typical with microprocessors, there are no overflow or underflow indicators.

**STORING REGISTERS IN MEMORY**

The same approaches that we used to load registers from memory can also be used to store registers in memory. The only differences between loading and storing registers are

- Store instructions do not allow immediate addressing. There is no way to directly store a number in memory. Instead, it must be transferred through a register.
- STX and STY allow only zero page indexed addressing. Neither allows absolute indexed addressing.
- As you might expect, the order of operations in storing index registers in the stack is the opposite of that used in loading them from the stack. The sequences are

(for index register X)

```
TXA          ;MOVE X TO A
PHA          ;AND THEN TO TOP OF STACK
```

(for index register Y)

```
TYA          ;MOVE Y TO A
PHA          ;AND THEN TO TOP OF STACK
```
Other storage operations operate in exactly the same manner as described in the discussion of loading registers.

Examples

1. STA $50
   This instruction stores the accumulator in memory location 0050₁₆. The special zero page mode is both shorter and faster than the absolute mode, since the more significant byte of the address is assumed to be 0.

2. STX $17E8
   This instruction stores index register X in memory location 17E8₁₆. It uses the absolute addressing mode with a full 16-bit address.

3. STA $A000,Y
   This instruction stores the accumulator in the effective address obtained by adding index register Y to the base address A000₁₆. The effective address is A000₁₆ + (Y).

4. STA ($50),Y
   This instruction stores the accumulator in the effective address obtained by adding index register Y to the base address in memory locations 0050₁₆ and 0051₁₆. The instruction obtains the base address indirectly.

5. STA ($43,X)
   This instruction stores the accumulator in the effective address obtained indirectly by adding index register X to the base 0043₁₆. The indirect address is in the two bytes of memory starting at 0043₁₆ + (X).

STORING VALUES IN RAM

The normal way to initialize RAM locations is through the accumulator, one byte at a time. The programmer can also use index registers X and Y for this purpose.

Examples

1. Store an 8-bit item (VALUE) in address ADDR.

   LDA #VALUE ;GET THE VALUE
   STA ADDR ;INITIALIZE LOCATION ADDR

   We could use either LDX, STX or LDY, STY instead of the LDA, STA sequence. Note that the 6502 treats all values the same; there is no special CLEAR instruction for generating 0s.
2. Store a 16-bit item (POINTER) in addresses ADDR and ADDR +1 (MSB in ADDR +1).

We assume that POINTER consists of POINTH (more significant byte) and POINTL (less significant byte).

\[
\begin{align*}
\text{LDA} & \ \#\text{POINTL} \quad ; \text{GET LSB} \\
\text{STA} & \ \text{ADDR} \quad ; \text{INITIALIZE LOCATION ADDR} \\
\text{LDA} & \ \#\text{POINTH} \quad ; \text{GET MSB} \\
\text{STA} & \ \text{ADDR+1} \quad ; \text{INITIALIZE LOCATION ADDR+1}
\end{align*}
\]

This method allows us to initialize indirect addresses on page 0 for later use with postindexing and preindexing.

**ARITHMETIC AND LOGICAL OPERATIONS**

Most arithmetic and logical operations (addition, subtraction, AND, OR, and EXCLUSIVE OR) can be performed only between the accumulator and an 8-bit byte in memory. The result replaces the operand in the accumulator. Arithmetic and logical operations may use immediate, zero page (direct), absolute (direct), indexed, zero page indexed, indexed indirect, or indirect indexed addressing.

**Examples**

1. Add memory location 0040\text{\textsubscript{16}} to the accumulator with carry.

\[
\text{ADC} \quad \$40
\]

This instruction adds the contents of memory location 0040\text{\textsubscript{16}} and the contents of the Carry flag to the accumulator.

2. Logically OR the accumulator with the contents of an indexed address obtained using index register X and the base 17E0\text{\textsubscript{16}}.

\[
\text{ORA} \quad \$17E0,X
\]

The effective address is 17E0\text{\textsubscript{16}} + (X).

3. Logically AND the accumulator with the contents of memory location B470\text{\textsubscript{16}}.

\[
\text{AND} \quad \$B470
\]

Note the following special features of the 6502’s arithmetic and logical instructions:

• The only addition instruction is ADC (Add with Carry). To exclude the Carry, you must clear it explicitly using the sequence

\[
\begin{align*}
\text{CLC} & \quad ; \text{MAKE CARRY ZERO} \\
\text{ADC} & \quad \$40 \quad ; \text{ADD WITHOUT CARRY}
\end{align*}
\]
The only subtraction instruction is SBC (Subtract with Borrow). This instruction subtracts a memory location and the complemented Carry flag from the accumulator. SBC produces

\[(A) = (A) - (M) - (1 - \text{CARRY})\]

where \(M\) is the contents of the effective address. To exclude the Carry, you must set it explicitly using the sequence

```
SEC        ;MAKE INVERTED BORROW ONE
SBC $40    ;SUBTRACT WITHOUT CARRY
```

Note that you must set the Carry flag before a subtraction, but clear it before an addition.

Comparison instructions perform subtractions without changing registers (except for the flags in the status register). Here we have not only CMP (Compare Memory with Accumulator), but also CPX (Compare Memory with Index Register X) and CPY (Compare Memory with Index Register Y). Note the differences between CMP and SBC; CMP does not include the Carry in the subtraction, change the accumulator, or affect the Overflow flag.

There is no explicit Complement instruction. However, you can complement the accumulator by EXCLUSIVE ORing it with a byte which contains all 1s (11111111₂ or FF₁₆). Remember, the EXCLUSIVE OR of two bits is 1 if they are different and 0 if they are the same. Thus, EXCLUSIVE ORing with a 1 will produce a result of 0 if the other bit is 1 and 1 if the other bit is 0, the same as a logical complement (NOT instruction).

Thus we have the instruction

```
EOR #$11111111 ;COMPLEMENT ACCUMULATOR
```

The BIT instruction performs a logical AND but does not return a result to the accumulator. It affects only the flags. You should note that this instruction allows only direct addressing (zero page or absolute); it does not allow immediate or indexed addressing. More complex operations require several instructions; typical examples are the following:

- Add memory locations OPER1 and OPER2, place result in RESLT

```
LDA OPER1 ;GET FIRST OPERAND
CLC        ;MAKE CARRY ZERO
ADC OPER2   ;ADD SECOND OPERAND
STA RESLT  ;SAVE SUM
```

Note that we must load the first operand into the accumulator and clear the Carry before adding the second operand.
• Add a constant (VALUE) to memory location OPER.
  LDA  OPER  ; GET CURRENT VALUE
  CLC  ; MAKE CARRY ZERO
  ADC  #VALUE  ; ADD VALUE
  STA  OPER  ; STORE SUM BACK

If VALUE is 1, we can shorten this to
  INC  OPER  ; ADD 1 TO CURRENT VALUE

Similarly, if VALUE is −1, we have
  DEC  OPER  ; SUBTRACT 1 FROM CURRENT VALUE

BIT MANIPULATION

The programmer can set, clear, complement, or test bits by means of logical operations with appropriate masks. Shift instructions can rotate or shift the accumulator or a memory location. Chapter 7 contains additional examples of bit manipulation.

You may operate on individual bits in the accumulator as follows:

• Set them by logically ORing with 1s in the appropriate positions.
• Clear them by logically ANDing with 0s in the appropriate positions.
• Invert (complement) them by logically EXCLUSIVE ORing with 1s in the appropriate positions.
• Test them by logically ANDing with 1s in the appropriate positions.

Examples

1. Set bit 6 of the accumulator.
   ORA  #01000000  ; SET BIT 6 BY ORING WITH 1

2. Clear bit 3 of the accumulator.
   AND  #11110111  ; CLEAR BIT 3 BY ANDING WITH 0

3. Invert (complement) bit 2 of the accumulator.
   EOR  #00000100  ; INVERT BIT 2 BY XORING WITH 1

4. Test bit 5 of the accumulator. Clear the Zero flag if bit 5 is a logic 1 and set the Zero flag if bit 5 is a logic 0.
   AND  #00100000  ; TEST BIT 5 BY ANDING WITH 1

You can change more than one bit at a time by changing the masks.

5. Set bits 4 and 5 of the accumulator.
   ORA  #00110000  ; SET BITS 4 AND 5 BY ORING WITH 1
6. Invert (complement) bits 0 and 7 of the accumulator.

EOR $\#10000001$ ; INVERT BITS 0 AND 7 BY XORING WITH 1

The only general way to manipulate bits in other registers or in memory is by moving the values to the accumulator.

- Set bit 4 of memory location 0040_{16}.

LDA $40$
ORA $\#00010000$ ; SET BIT 4 BY ORING WITH 1
STA $40$

- Clear bit 1 of memory location 17E0_{16}.

LDA $17E0$
AND $\#11111110$ ; CLEAR BIT 1 BY ANDING WITH 0
STA $17E0$

An occasional, handy shortcut to clearing or setting bit 0 of a register or memory location is using an increment (INC, INX, or INY) to set it (if you know that it is 0) and a decrement (DEC, DEX, or DEY) to clear it (if you know that it is 1). If you do not care about the other bit positions, you can also use DEC or INC. These shortcuts are useful when you are storing a single 1-bit flag in a byte of memory.

The instruction LSR (ASL) shifts the accumulator or a memory location right (left) one position, filling the leftmost (rightmost) bit with a 0. Figures 1-1 and 1-2 describe the effects of these two instructions. The instructions ROL and ROR provide a circular shift (rotate) of the accumulator or a memory location as shown in Figures 1-3 and 1-4. Rotates operate as if the accumulator or memory location and the Carry flag formed a 9-bit circular register. You should note the following:

- Left shifts set the Carry to the value that was in bit position 7 and the Negative flag to the value that was in bit position 6.
- Right shifts set the Carry to the value that was in bit position 0.
- Rotates preserve all the bits, whereas LSR and ASL destroy the old Carry flag.
- Rotates allow you to move serial data between memory or the accumulator and the Carry flag. This is useful in performing serial I/O and in handling single bits of information such as Boolean indicators or parity.

Multibit shifts simply require the appropriate number of single-bit instructions.

*Examples*

1. Rotate accumulator right three positions.

ROR A
ROR A
ROR A
Original contents of Carry flag and accumulator or memory location

\[
\begin{array}{c|c|c|c|c|c|c|c}
C & B_7 & B_6 & B_5 & B_4 & B_3 & B_2 & B_1 & B_0 \\
\end{array}
\]

After ASL (Arithmetic Shift Left)

\[
\begin{array}{c|c|c|c|c|c|c|c}
B_7 & B_6 & B_5 & B_4 & B_3 & B_2 & B_1 & B_0 & 0 \\
\end{array}
\]

**Figure 1-1:** The ASL (Arithmetic Shift Left) Instruction

Original contents of Carry flag and accumulator or memory location

\[
\begin{array}{c|c|c|c|c|c|c|c}
C & B_7 & B_6 & B_5 & B_4 & B_3 & B_2 & B_1 & B_0 \\
\end{array}
\]

After LSR (Logical Shift Right)

\[
\begin{array}{c|c|c|c|c|c|c|c}
B_0 & 0 & B_7 & B_6 & B_5 & B_4 & B_3 & B_2 & B_1 \\
\end{array}
\]

**Figure 1-2:** The LSR (Logical Shift Right) Instruction

Original contents of Carry flag and accumulator or memory location

<table>
<thead>
<tr>
<th>Carry</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td>B_7</td>
</tr>
</tbody>
</table>

After ROL (Rotate Left)

<table>
<thead>
<tr>
<th>Carry</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>B_7</td>
<td>B_6</td>
</tr>
</tbody>
</table>

**Figure 1-3:** The ROL (Rotate Left) Instruction

Original contents of Carry flag and accumulator or memory location

<table>
<thead>
<tr>
<th>Carry</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td>B_7</td>
</tr>
</tbody>
</table>

After ROR (Rotate Right)

<table>
<thead>
<tr>
<th>Carry</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>B_0</td>
<td>C</td>
</tr>
</tbody>
</table>

**Figure 1-4:** The ROR (Rotate Right) Instruction
2. Shift memory location $1700_{16}$ left logically four positions.

```
ASL $1700
ASL $1700
ASL $1700
ASL $1700
```

An alternative approach would be to use the accumulator; that is,

```
LDA $1700
ASL A
ASL A
ASL A
STA $1700
```

The second approach is shorter (10 bytes rather than 12) and faster (16 clock cycles rather than 24), but it destroys the previous contents of the accumulator.

You can implement arithmetic shifts by using the Carry flag to preserve the current value of bit 7. Shifting right arithmetically is called *sign extension*, since it copies the sign bit to the right. A shift that operates in this manner preserves the sign of a two's complement number and can therefore be used to divide or normalize signed numbers.

**Examples**

1. Shift the accumulator right 1 bit arithmetically, preserving the sign (most significant) bit.

```
TAX ;SAVE THE ACCUMULATOR
ASL A ;MOVE BIT 7 TO CARRY
TXA ;RESTORE THE ACCUMULATOR
ROR A ;SHIFT THE ACCUMULATOR, COPYING BIT 7
```

When the processor performs ROR A, it moves the Carry (the old bit 7) to bit 7 and bit 7 to bit 6, thus preserving the sign of the original number.

2. Shift the accumulator left 1 bit arithmetically, preserving the sign (most significant) bit.

```
ASL A ;SHIFT A, MOVING BIT 7 TO CARRY
ROL A ;SAVE BIT 7 IN POSITION 0
TAX
LSR A ;CHANGE CARRY TO OLD BIT 7
TXA
ROR A ;SHIFT THE ACCUMULATOR, PRESERVING BIT 7
```

or

```
ASL A ;SHIFT A, MOVING BIT 7 TO CARRY
BCC CLRSGN ;WAS BIT 7 1?
ORA #%10000000 ; YES, THEN KEEP IT 1
BMI EXIT
CLRSGN AND #%01111111 ; NO, THEN KEEP IT ZERO
EXIT NOP
```

BMI EXIT always forces a branch.
MAKING DECISIONS

We will now discuss procedures for making three types of decisions:

- Branching if a bit is set or cleared (a logic 1 or a logic 0).
- Branching if two values are equal or not equal.
- Branching if one value is greater than another or less than it.

The first type of decision allows the processor to sense the value of a flag, switch, status line, or other binary (ON/OFF) input. The second type of decision allows the processor to determine whether an input or a result has a specific value (e.g., an input is a specific character or terminator or a result is 0). The third type of decision allows the processor to determine whether a value is above or below a numerical threshold (e.g., a value is valid or invalid or is above or below a warning level or set point). Assuming that the primary value is in the accumulator and the secondary value (if needed) is in address ADDR, the procedures are as follows.

Branching Set or Cleared Bit

- Determine if a bit is set or cleared by logically ANDing the accumulator with a 1 in the appropriate bit position and 0s in the other bit positions. The Zero flag then reflects the bit value and can be used for branching (with BEQ or BNE).

Examples

1. Branch to DEST if bit 5 of the accumulator is 1.

   \[
   \text{AND} \quad \#\text{000100000} \quad \text{;TEST BIT 5 OF A} \\
   \text{BNE} \quad \text{DEST}
   \]

   The Zero flag is set to 1 if and only if bit 5 of the accumulator is 0. Note the inversion here.

   If we assume that the data is in address ADDR, we can use the BIT instruction to produce an equivalent effect. To branch to DEST if bit 5 of ADDR is 1, we can use either

   \[
   \begin{align*}
   \text{LDA} & \quad \text{ADDR} \\
   \text{AND} & \quad \#\text{000100000} \\
   \text{BNE} & \quad \text{DEST}
   \end{align*}
   \]

   or

   \[
   \begin{align*}
   \text{LDA} & \quad \#\text{000100000} \\
   \text{BIT} & \quad \text{ADDR} \\
   \text{BNE} & \quad \text{DEST}
   \end{align*}
   \]

   We must reverse the order of the operations, since BIT does not allow immediate addressing. It does, however, leave the accumulator unchanged for later use.
2. Branch to DEST if bit 2 of the accumulator is 0.

```assembly
AND #00000100 ;TEST BIT 2 OF A
BEQ DEST
```

There are special short procedures for examining bit positions 0, 6, or 7. Bit 7 is available readily as the Negative flag after a Load or Transfer instruction; bit 0 can be moved to the Carry with LSR A or ROR A; bit 6 can be moved to the Negative flag with ASL A or ROL A.

3. Branch to DEST if bit 7 of memory location ADDR is 1.

```assembly
LDA ADDR ;IS BIT 7 1?
BMI DEST ;YES, BRANCH
```

Note that LDA affects the Zero and Negative flags; so do transfer instructions such as TAX, TYA, TSX (but not TXS), and PLA. Store instructions (including PHA) do not affect any flags.

4. Branch to DEST if bit 6 of the accumulator is 0.

```assembly
ASL A ;MOVE BIT 6 TO BIT 7
BPL DEST
```

5. Branch to DEST if bit 0 of memory location ADDR is 1.

```assembly
ROR ADDR ;MOVE BIT 0 OF ADDR TO CARRY
BCS DEST ;AND THEN TEST THE CARRY
```

The BIT instruction has a special feature that allows one to readily test bit 6 or bit 7 of a memory location. When the processor executes BIT, it sets the Negative flag to the value of bit 7 of the addressed memory location and the Overflow flag to the value of bit 6, regardless of the contents of the accumulator.

6. Branch to DEST if bit 7 of memory location ADDR is 0.

```assembly
BIT ADDR ;TEST BIT 7 OF ADDR
BPL DEST
```

This sequence does not affect or depend on the accumulator.

7. Branch to DEST if bit 6 of memory location ADDR is 1.

```assembly
BIT ADDR ;TEST BIT 6 OF ADDR
BVS DEST
```

This sequence requires careful documentation, since the Overflow flag is being used in a special way. Here again, the contents of the accumulator do not change or affect the sequence at all.

**Branching Based on Equality**

- Determine if the value in the accumulator is equal to another value by subtraction. The Zero flag will be set to 1 if the values are equal. The Compare
instruction (CMP) is more useful than the Subtract instruction (SBC) because Compare does not change the accumulator or involve the Carry.

Examples

1. Branch to DEST if the accumulator contains the number VALUE.

```
CMP   #VALUE ; IS DATA = VALUE?
BEQ   DEST ; YES, BRANCH
```

We could also use index register X with CPX or index register Y with CPY.

2. Branch to DEST if the contents of the accumulator are not equal to the contents of memory location ADDR.

```
CMP   ADDR ; IS DATA = VALUE IN MEMORY?
BNE   DEST ; NO, BRANCH
```

3. Branch to DEST if memory location ADDR contains 0.

```
LDA   ADDR ; IS DATA ZERO?
BEQ   DEST ; YES, BRANCH
```

We can handle some special cases without using the accumulator.

4. Branch to DEST if memory location ADDR contains 0, but do not change the accumulator or either index register.

```
INC   ADDR ; TEST MEMORY FOR ZERO
DEC   ADDR
BEQ   DEST ; BRANCH IF IT IS FOUND
```

5. Branch to DEST if memory location ADDR does not contain 1.

```
DEC   ADDR ; SET ZERO FLAG IF ADDR IS 1
BNE   DEST
```

This sequence, of course, changes the memory location.

6. Branch to DEST if memory location ADDR contains $FF_{16}$.

```
INC   ADDR ; SET ZERO FLAG IF ADDR IS FF
BEQ   DEST
```

INC does not affect the Carry flag, but it does affect the Zero flag. Note that you cannot increment or decrement the accumulator with INC or DEC.

Branching Based on Magnitude Comparisons

- Determine if the contents of the accumulator are greater than or less than some other value by subtraction. If, as is typical, the numbers are unsigned, the Carry flag indicates which one is larger. Note that the 6502's Carry flag is a negative borrow after comparisons or subtractions, unlike the true borrow produced by such processors as the 8080, Z-80, and 6800. In general,
carry = 1 if the contents of the accumulator are greater than or equal to the value subtracted from it. carry = 1 if the subtraction does not require (generate) a borrow.

• Carry = 0 if the value subtracted is larger than the contents of the accumulator. That is, Carry = 0 if the subtraction does require a borrow.

Note that the Carry is the inverse of a normal borrow. If the two operands are equal, the Carry is set to 1, just as if the accumulator were larger. If, however, you want equal values to affect the Carry as if the other value were larger, all that you must do is reverse the identities of the operands, that is, you must subtract in reverse, saving the accumulator in memory and loading it with the other value instead.

Examples

1. Branch to DEST if the contents of the accumulator are greater than or equal to the number VALUE.
   
   CMP #VALUE ; IS DATA ABOVE VALUE?
   BCS DEST ; YES, BRANCH

   The Carry is set to 1 if the unsigned subtraction does not require a borrow.

2. Branch to DEST if the contents of memory address OPER1 are less than the contents of memory address OPER2.
   
   LDA OPER1 ; GET FIRST OPERAND
   CMP OPER2 ; IS IT LESS THAN SECOND OPERAND?
   BCC DEST ; YES, BRANCH

   The Carry will be set to 0 if the subtraction requires a borrow.

3. Branch to DEST if the contents of memory address OPER1 are less than or equal to the contents of memory address OPER2.
   
   LDA OPER2 ; GET SECOND OPERAND
   CMP OPER1 ; IS IT GREATER THAN OR EQUAL TO FIRST?
   BCS DEST ; YES, BRANCH

   If we loaded the accumulator with OPER1 and compared to OPER2, we could branch only on the conditions

   • OPER1 greater than or equal to OPER2 (Carry set)
   • OPER1 less than OPER2 (Carry cleared)

   Since neither of these is what we want, we must handle the operands in the opposite order.

   If the values are signed, we must allow for the possible occurrence of two's complement overflow. This is the situation in which the difference between the numbers cannot be contained in seven bits and, therefore, changes the sign of the result. For example, if one number is +7 and the other is −125, the difference is
-132, which is beyond the capacity of eight bits (it is less than -128, the most negative number that can be contained in eight bits).

Thus, in the case of signed numbers, we must allow for the following two possibilities:

- The result has the sign (positive or negative, as shown by the Negative flag) that we want, and the Overflow flag indicates that the sign is correct.

- The result does not have the sign that we want, but the Overflow flag indicates that two’s complement overflow has changed the real sign.

We have to look for both a true positive (the sign we want, unaffected by overflow) or a false negative (the opposite of the sign we want, but inverted by two’s complement overflow).

**Examples**

1. Branch to DEST if the contents of the accumulator (a signed number) are greater than or equal to the number VALUE.

```plaintext
SEC            ;CLEAR INVERTED BORROW
SBC #VALUE    ;PERFORM THE SUBTRACTION
BVS FNEG      
BPL DEST      ;TRUE POSITIVE, NO OVERFLOW
BMI DONE      
FNEG BMI DEST ;FALSE NEGATIVE, OVERFLOW
DONE NOP      
```

2. Branch to DEST if the contents of the accumulator (a signed number) are less than the contents of address ADDR.

```plaintext
SEC            ;CLEAR INVERTED BORROW
SBC ADDR      ;PERFORM THE SUBTRACTION
BVS FNEG      
BMI DEST      ;TRUE POSITIVE, NO OVERFLOW
BPL DONE      
FNEG BPL DEST ;FALSE NEGATIVE, OVERFLOW
DONE NOP      
```

Note that we must set the Carry and use SBC, because CMP does not affect the Overflow flag.

Tables 1-8 and 1-9 summarize the common instruction sequences used to make decisions with the 6502 microprocessor. Table 1-8 lists the sequences that depend only on the value in the accumulator; Table 1-9 lists the sequences that depend on numerical comparisons between the contents of the accumulator and a specific value or the contents of a memory location. Tables 1-10 and 1-11 contain the sequences that depend on an index register or on the contents of a memory location alone.
### Table 1-8: Decision Sequences Depending on the Accumulator Alone

<table>
<thead>
<tr>
<th>Condition</th>
<th>Flag-Setting Instruction</th>
<th>Conditional Branch</th>
</tr>
</thead>
<tbody>
<tr>
<td>Any bit of A = 0</td>
<td>AND #MASK (1 in bit position)</td>
<td>BEQ</td>
</tr>
<tr>
<td>Any bit of A = 1</td>
<td>AND #MASK (1 in bit position)</td>
<td>BNE</td>
</tr>
<tr>
<td>Bit 7 of A = 0</td>
<td>ASL A or ROL A</td>
<td>BCC</td>
</tr>
<tr>
<td>Bit 7 of A = 1</td>
<td>ASL A or ROL A</td>
<td>BCS</td>
</tr>
<tr>
<td>Bit 6 of A = 0</td>
<td>ASL A or ROL A</td>
<td>BMI</td>
</tr>
<tr>
<td>Bit 6 of A = 1</td>
<td>ASL A or ROL A</td>
<td>BPL</td>
</tr>
<tr>
<td>Bit 0 of A = 0</td>
<td>LSR A or ROR A</td>
<td>BCC</td>
</tr>
<tr>
<td>Bit 0 of A = 1</td>
<td>LSR A or ROR A</td>
<td>BMI</td>
</tr>
<tr>
<td>(A) = 0</td>
<td>LDA, PLA, TAX, TAY, TXA, or TYA</td>
<td>BEQ</td>
</tr>
<tr>
<td>(A) ≠ 0</td>
<td>LDA, PLA, TAX, TAY, TXA, or TYA</td>
<td>BNE</td>
</tr>
<tr>
<td>(A) positive (MSB = 0)</td>
<td>LDA, PLA, TAX, TAY, TXA, or TYA</td>
<td>BPL</td>
</tr>
<tr>
<td>(A) negative (MSB = 1)</td>
<td>LDA, PLA, TAX, TAY, TXA, or TYA</td>
<td>BMI</td>
</tr>
</tbody>
</table>

### Table 1-9: Decision Sequences Depending on Numerical Comparisons

<table>
<thead>
<tr>
<th>Condition</th>
<th>Flag-Setting Instruction</th>
<th>Conditional Branch</th>
</tr>
</thead>
<tbody>
<tr>
<td>(A) = VALUE</td>
<td>CMP #VALUE</td>
<td>BEQ</td>
</tr>
<tr>
<td>(A) ≠ VALUE</td>
<td>CMP #VALUE</td>
<td>BNE</td>
</tr>
<tr>
<td>(A) ≥ VALUE (unsigned)</td>
<td>CMP #VALUE</td>
<td>BCS</td>
</tr>
<tr>
<td>(A) &lt; VALUE (unsigned)</td>
<td>CMP #VALUE</td>
<td>BCC</td>
</tr>
<tr>
<td>(A) = (ADDR)</td>
<td>CMP ADDR</td>
<td>BEQ</td>
</tr>
<tr>
<td>(A) ≠ (ADDR)</td>
<td>CMP ADDR</td>
<td>BNE</td>
</tr>
<tr>
<td>(A) ≥ (ADDR) (unsigned)</td>
<td>CMP ADDR</td>
<td>BCS</td>
</tr>
<tr>
<td>(A) &lt; (ADDR) (unsigned)</td>
<td>CMP ADDR</td>
<td>BCC</td>
</tr>
</tbody>
</table>
### Table 1-10: Decision Sequences Depending on an Index Register

<table>
<thead>
<tr>
<th>Condition</th>
<th>Flag-Setting Instruction</th>
<th>Conditional Branch</th>
</tr>
</thead>
<tbody>
<tr>
<td>((X \text{ or } Y) = \text{ VALUE})</td>
<td>(\text{CPX or CPY } #\text{VALUE})</td>
<td>(\text{BEQ})</td>
</tr>
<tr>
<td>((X \text{ or } Y) \neq \text{ VALUE})</td>
<td>(\text{CPX or CPY } #\text{VALUE})</td>
<td>(\text{BNE})</td>
</tr>
<tr>
<td>((X \text{ or } Y) \geq \text{ VALUE}) (unsigned)</td>
<td>(\text{CPX or CPY } #\text{VALUE})</td>
<td>(\text{BCS})</td>
</tr>
<tr>
<td>((X \text{ or } Y) &lt; \text{ VALUE}) (unsigned)</td>
<td>(\text{CPX or CPY } #\text{VALUE})</td>
<td>(\text{BCC})</td>
</tr>
<tr>
<td>((X \text{ or } Y) = (\text{ADDR}))</td>
<td>(\text{CPX or CPY } \text{ADDR})</td>
<td>(\text{BEQ})</td>
</tr>
<tr>
<td>((X \text{ or } Y) \neq (\text{ADDR}))</td>
<td>(\text{CPX or CPY } \text{ADDR})</td>
<td>(\text{BNE})</td>
</tr>
<tr>
<td>((X \text{ or } Y) \geq (\text{ADDR})) (unsigned)</td>
<td>(\text{CPX or CPY } \text{ADDR})</td>
<td>(\text{BCS})</td>
</tr>
<tr>
<td>((X \text{ or } Y) &lt; (\text{ADDR})) (unsigned)</td>
<td>(\text{CPX or CPY } \text{ADDR})</td>
<td>(\text{BCC})</td>
</tr>
</tbody>
</table>

### Table 1-11: Decision Sequences Depending on a Memory Location Alone

<table>
<thead>
<tr>
<th>Condition</th>
<th>Flag-Setting Instruction(s)</th>
<th>Conditional Branch</th>
</tr>
</thead>
<tbody>
<tr>
<td>(\text{Bit 7} = 0)</td>
<td>(\text{BIT ADDR})</td>
<td>(\text{BPL})</td>
</tr>
<tr>
<td></td>
<td>(\text{ASL ADDR or ROL ADDR})</td>
<td>(\text{BCC})</td>
</tr>
<tr>
<td>(\text{Bit 7} = 1)</td>
<td>(\text{BIT ADDR})</td>
<td>(\text{BMI})</td>
</tr>
<tr>
<td></td>
<td>(\text{ASL ADDR or ROL ADDR})</td>
<td>(\text{BCS})</td>
</tr>
<tr>
<td>(\text{Bit 6} = 0)</td>
<td>(\text{BIT ADDR})</td>
<td>(\text{BVC})</td>
</tr>
<tr>
<td></td>
<td>(\text{ASL ADDR or ROL ADDR})</td>
<td>(\text{PBL})</td>
</tr>
<tr>
<td>(\text{Bit 6} = 1)</td>
<td>(\text{BIT ADDR})</td>
<td>(\text{BVS})</td>
</tr>
<tr>
<td></td>
<td>(\text{ASL ADDR or ROL ADDR})</td>
<td>(\text{BMI})</td>
</tr>
<tr>
<td>((\text{ADDR}) = 0)</td>
<td>(\text{INC ADDR, DEC ADDR})</td>
<td>(\text{BEQ})</td>
</tr>
<tr>
<td>((\text{ADDR}) \neq 0)</td>
<td>(\text{INC ADDR, DEC ADDR})</td>
<td>(\text{BNE})</td>
</tr>
<tr>
<td>(\text{Bit 0} = 0)</td>
<td>(\text{LSR ADDR or ROR ADDR})</td>
<td>(\text{BCC})</td>
</tr>
<tr>
<td>(\text{Bit 0} = 1)</td>
<td>(\text{LSR ADDR or ROR ADDR})</td>
<td>(\text{BCS})</td>
</tr>
</tbody>
</table>
LOOPING

The simplest way to implement a loop (that is, repeat a sequence of instructions) with the 6502 microprocessor is as follows:

1. Load an index register or memory location with the number of times the sequence is to be executed.
2. Execute the sequence.
3. Decrement the index register or memory location by 1.
4. Return to Step 2 if the result of Step 3 is not 0.

Typical programs look like this:

```assembly
LDX #NTIMES ; COUNT = NUMBER OF REPETITIONS
LOOP
    .
    . instructions to be repeated
    .
DEX
BNE LOOP
```

Nothing except clarity stops us from counting up (using INX, INY, or INC); of course, you must change the initialization appropriately. As we will see later, a 16-bit counter is much easier to increment than it is to decrement. In any case, the instructions to be repeated must not interfere with the counting of the repetitions. You can store the counter in either index register or any memory location. Index register X’s special features are its use in preindexing and the wide availability of zero page indexed modes. Index register Y’s special feature is its use in postindexing. As usual, memory locations on page 0 are shorter and faster to use than are memory locations on other pages.

Of course, if you use an index register or a single memory location as a counter, you are limited to 256 repetitions. You can provide larger numbers of repetitions by nesting loops that use a single register or memory location or by using a pair of memory locations as illustrated in the following examples:

- Nested loops

```assembly
LDX #NTIMM ; START OUTER COUNTER
LOOPO
LDY #NTIML ; START INNER COUNTER
LOOPI
    .
    . instructions to be repeated
    .
DEY ; DECREMENT INNER COUNTER
BNE LOOPI
DEX ; DECREMENT OUTER COUNTER
BNE LOOPO
```

The outer loop restores the inner counter (index register Y) to its starting value...
(NTIML) after each decrement of the outer counter (index register X). The nesting produces a multiplicative factor — the instructions starting at LOOPI are repeated NTIMM × NTIML times. Of course, a more general (and more reasonable) approach would use two memory locations on page 0 instead of two index registers.

- 16-bit counter in two memory locations

```
LDA #NTIMLC ; INITIALIZE LSB OF COUNTER
STA COUNTL
LDA #NTIMHC ; INITIALIZE MSB OF COUNTER
STA COUNTH
LOOP
  ; instructions to be repeated
  INC NTIMLC ; INCREMENT LSB OF COUNTER
  BNE LOOP
  INC NTIMHC ; AND CARRY TO MSB OF COUNTER IF NEEDED
  BNE LOOP
```

The idea here is to increment only the less significant byte unless there is a carry to the more significant byte. Note that we can recognize a carry only by checking the Zero flag, since INC does not affect the Carry flag. Counting up is much simpler than counting down; the comparable sequence for decrementing a 16-bit counter is

```
LDA NTIML ; IS LSB OF COUNTER ZERO?
BNE CNTLSB
DEC NTIMH ; YES, BORROW FROM MSB
CNTLSB DEC NTIML ; DECREMENT LSB OF COUNTER
BNE LOOP ; CONTINUE IF LSB HAS NOT REACHED ZERO
LDA NTIMH ; OR IF MSB HAS NOT REACHED ZERO
BNE LOOP
```

If we count up, however, we must remember to initialize the counter to the complement of the desired value (indicated by the names NTIMLC and NTIMHC in the program using INC).

**ARRAY MANIPULATION**

The simplest way to access a particular element of an array is by using indexed addressing. One can then

1. Manipulate the element by indexing from the starting address of the array.

2. Access the succeeding element (at the next higher address) by incrementing the index register using INX or INY, or access the preceding element (at the next lower address) by decrementing the index register using DEX or DEY. One
could also change the base; this is simple if the base is an absolute address, but awkward if it is an indirect address.

3. Access an arbitrary element by loading an index register with its index. Typical array manipulation procedures are easy to program if the array is one-dimensional, the elements each occupy 1 byte, and the number of elements is less than 256. Some examples are

- Add an element of an array to the accumulator. The base address of the array is a constant BASE. Update index register X so that it refers to the succeeding 8-bit element.

```assembly
ADC BASE,X
INX ;ADD CURRENT ELEMENT
```

- Check to see if an element of an array is 0 and add 1 to memory location ZCOUNT if it is. Assume that the address of the array is a constant BASE and its index is in index register X. Update index register X so that it refers to the preceding 8-bit element.

```assembly
LDA BASE,X
BNE UPDDT
INC ZCOUNT
UPDDT EXX ;GET CURRENT ELEMENT
;IS ITS VALUE ZERO?
;YES, ADD 1 TO COUNT OF ZEROS
;ADDRESS PRECEDING ELEMENT
```

- Load the accumulator with the 35th element of an array. Assume that the starting address of the array is BASE.

```assembly
LDX #35
LDA BASE,X
```

The most efficient way to process an array is to start at the highest address and work backward. This is the best approach because it allows you to count the index register down to 0 and exit when the Zero flag is set. You must adjust the initialization and the indexed operations slightly to account for the fact that the 0 index is never used. The changes are

- Load the index register with the number of elements.
- Use the base address \( \text{START} - 1 \), where \( \text{START} \) is the lowest address actually occupied by the array.

If, for example, we want to perform a summation starting at address \( \text{START} \) and continuing through \( \text{LENGTH} \) elements, we use the program

```assembly
LDX #LENGTH
LDA #0
CLC
ADC START-1,X
DEX
BNE ADBYTE
```

```
ADDBYTE
```

```assembly
;START AT THE END OF THE ARRAY
;CLEAR THE SUM INITIALLY ;ADD THE NEXT ELEMENT
;COUNT ELEMENTS
```
Manipulating array elements becomes more difficult if you need more than one element during each iteration (as in a sort that requires interchanging of elements), if the elements are more than one byte long, or if the elements are themselves addresses (as in a table of starting addresses). The basic problem is the lack of 16-bit registers or 16-bit instructions. The processor can never be instructed to handle more than 8 bits. Some examples of more general array manipulation are

- Load memory locations POINTH and POINTL with a 16-bit element of an array (stored LSB first). The base address of the array is BASE and the index of the element is in index register X. Update X so that it points to the next 16-bit element.

  ```
  LDA  BASE,X ;GET LSB OF ELEMENT
  STA  POINTL
  INX
  LDA  BASE,X ;GET MSB OF ELEMENT
  STA  POINTH
  INX ;ADDRESS NEXT ELEMENT
  ```

  The single instruction LDA BASE+1,X loads the accumulator from the same address as the sequence

  ```
  INX
  LDA  BASE,X
  ```

  assuming that X did not originally contain FF16. If, however, we are using a base address indirectly, the alternatives are

  ```
  INC  PGZRO ;INCREMENT BASE ADDRESS
  BNE  INDEX
  INC  PGZRO+1 ;WITH CARRY IF NECESSARY
  INDEX
  LDA  (PGZRO),Y
  ```

  or

  ```
  INY
  LDA  (PGZRO),Y
  ```

  The second sequence is much shorter, but the first sequence will handle arrays that are more than 256 bytes long.

- Exchange an element of an array with its successor if the two are not already in descending order. Assume that the elements are 8-bit unsigned numbers. The base address of the array is BASE and the index of the first number is in index register X.

  ```
  LDA  BASE,X ;GET ELEMENT
  CMP  BASE+1,X ;IS SUCCESSOR SMALLER?
  BCS  DONE ;NO, NO INTERCHANGE NECESSARY
  PHA ;YES, SAVE ELEMENT
  LDA  BASE+1,X ;INTERCHANGE
  STA  BASE,X
  PLA
  STA  BASE+1,X
  DONE
  INX ;ACCESS NEXT ELEMENT
  ```
- Load the accumulator from the 12th indirect address in a table. Assume that the table starts at the address BASE.

LDX #24 ;GET DOUBLE OFFSET FOR INDEX
LDA BASE,X ;GET LSB OF ADDRESS
STA PGZRO ;SAVE ON PAGE ZERO
INX
LDA BASE,X ;GET MSB OF ADDRESS
STA PGZRO+1 ;SAVE ON PAGE ZERO
LDY #0
LDA (PGZRO),Y ;LOAD INDIRECT BY INDEXING WITH ZERO

Note that you must double the index to handle tables containing addresses, since each 16-bit address occupies two bytes of memory.

If the entire table is on page 0, we can use the preindexed (indexed indirect) addressing mode.

LDX #24 ;GET DOUBLE OFFSET FOR INDEX
LDA (BASE,X) ;LOAD FROM INDEXED INDIRECT ADDRESS

You still must remember to double the index. Here we must also initialize the table of indirect addresses in the RAM on page 0.

We can generalize array processing by storing the base address in two locations on page 0 and using the postindexed (indirect indexed) addressing mode. Now the base address can be a variable. This mode assumes the use of page 0 and index register Y and is available only for a limited set of instructions.

Examples

1. Add an element of an array to the accumulator. The base address of the array is in memory locations PGZRO and PGZRO+1. The index of the element is in index register Y. Update index register Y so that it refers to the succeeding 8-bit element.

   CLC ADC (PGZRO),Y ;ADD CURRENT ELEMENT
   INY ;ADDRESS NEXT ELEMENT

2. Check to see if an element of an array is 0 and add 1 to memory location ZCOUNT if it is. Assume that the base address of the array is in memory locations PGZRO and PGZRO+1. The index of the element is in index register Y. Update index register Y so that it refers to the preceding 8-bit element.

   LDA (PGZRO),Y ;GET CURRENT ELEMENT
   BNE UPDDT ;IS ITS VALUE ZERO?
   INC ZCOUNT ;YES, ADD 1 TO COUNT OF ZEROS
   UPDDT DEY ;ADDRESS PRECEDING ELEMENT

Postindexing also lets us handle arrays that occupy more than 256 bytes. As we noted earlier, the simplest approach to long counts is to keep a 16-bit complemented count in two memory locations. If the array is described by a base address on page 0, we can update that base whenever we update the more significant byte of the complemented count. For example, if we want to clear an area of memory
described by a complemented count in memory locations COUNTH and
COUNTL and an initial base address in memory locations PGZRO and
PGZRO+1, we can use the following program:

```
LDA #0 ;DATA = ZERO
TAY ;INDEX = ZERO
CLEAR STA (PGZRO),Y ;CLEAR A BYTE
INY ;MOVE TO NEXT BYTE
BNE CHKCNT
BNE INC PGZRO+1 ;AND TO NEXT PAGE IF NEEDED
INC COUNTL ;COUNT BYTES
INC COUNTH ;WITH CARRY TO MSB
CLEAR CHKCNT
```

The idea here is to proceed to the next page by incrementing the more significant
byte of the indirect address when we finish a 256-byte section.

One can also simplify array processing by reducing the multiplications required
in indexing to additions. In particular, one can handle arrays of two-byte elements
by using ASL A to double an index in the accumulator.

**Example**

Load the accumulator from the indirect address indexed by the contents of
memory location INDEX. Assume that the table starts at address BASE.

```
LDA INDEX ;GET INDEX
ASL A ;AND DOUBLE IT FOR 2-BYTE ENTRIES
TAX
LDA BASE,X ;GET LSB OF INDIRECT ADDRESS
STA PGZRO ;SAVE ON PAGE ZERO
INX
LDA BASE,X ;GET MSB OF INDIRECT ADDRESS
STA PGZRO+1 ;SAVE ON PAGE ZERO
LDY #0 ;PREINDEX WITH ZERO
LDA (PGZRO),Y
```

As before, if the entire table of indirect addresses is on page 0, we can use the
preindexed (indexed indirect) addressing mode.

```
LDA INDEX ;GET INDEX
ASL A ;DOUBLE INDEX FOR 2-BYTE ENTRIES
TAX
LDA (BASE,X) ;LOAD FROM INDEXED INDIRECT ADDRESS
```

You can handle indexing into longer arrays by using the postindexed (indirect
indexed) mode. Here we must construct a base address with an explicit addition
before indexing, since the 6502's index registers are only 8 bits long.

**Example**

Load the accumulator from the element of an array defined by a starting
address BASE (BASEH more significant byte, BASEL less significant byte) and a
16-bit index in memory locations INDEX and INDEX+1 (MSB in INDEX+1).
TABLE LOOKUP

Table lookup can be handled by the same procedures as array manipulation. Some examples are

- Load the accumulator with an element from a table. Assume that the base address of the table is BASE (a constant) and the 8-bit index is in memory location INDEX.

  ```
  LDX INDEX ;GET INDEX
  LDA BASE,X ;GET THE ELEMENT
  ```

  The problem is more complicated if INDEX is a 16-bit number.

  - Load the accumulator with an element from a table. Assume that the base address of the table is BASE (a constant, made up of bytes BASEH and BASEL) and the 16-bit index is in memory locations INDEX and INDEX+1 (MSB in INDEX+1).

    The procedure is the same one we just showed for an array. You must add the more significant byte of the index to the more significant byte of the base with an explicit addition. You can then use postindexing to obtain the element.

    - Load memory locations POINTH and POINTL with a 16-bit element from a table. Assume that the base address of the table is BASE (a constant) and the index is in memory location INDEX.

      ```
      LDA INDEX ;GET THE INDEX
      ASL A ;DOUBLE IT FOR TWO-BYTE ENTRIES
      TAX
      LDA BASE,X ;GET LSB OF ELEMENT
      INX
      LDA BASE,X ;GET MSB OF ELEMENT
      STA POINTH
      ```

  We can also handle the case in which the base address is a variable in two memory locations on page 0 (PGZRO and PGZRO+1).
LDA INDEX ;GET THE INDEX
ASL A ;DOUBLE IT FOR TWO-BYTE ENTRIES
TAY
LDA (PGZRO),Y ;GET LSB OF ELEMENT
STA POINTL
INY
LDA (PGZRO),Y ;GET MSB OF ELEMENT
STA POINTH

We can revise the program further to handle an array with more than 128 entries.

LDA INDEX ;GET THE INDEX
ASL A ;DOUBLE IT FOR TWO-BYTE ENTRIES
BCC LDELEM ;ADD CARRY TO INDIRECT ADDRESS
INC PGZRO+1
TAY
LDA (PGZRO),Y ;GET LSB OF ELEMENT
STA POINTL
INY
LDA (PGZRO),Y ;GET MSB OF ELEMENT
STA POINTH

Still another extension handles a 16-bit index.

LDA INDEX ;GET LSB OF INDEX
ASL A ;DOUBLE IT
TAY
LDA INDEX+1 ;GET MSB OF INDEX
ROL A ;DOUBLE IT WITH CARRY
ADC PGZRO+1 ;AND ADD RESULT TO INDIRECT ADDRESS
STA PGZRO+1
LDA (PGZRO),Y ;GET LSB OF ELEMENT
STA POINTL
INY
LDA (PGZRO),Y ;GET MSB OF ELEMENT
STA POINTH

- Transfer control (jump) to a 16-bit address obtained from a table. Assume that the base address of the table is BASE (a constant) and the index is in memory location INDEX.

Here there are two options: Store the address obtained from the table in two memory locations and use an indirect jump, or store the address obtained from the table in the stack and use the RTS (Return from Subroutine) instruction.

**OPTION 1: Indirect Jump**

LDA INDEX ;GET INDEX
ASL A ;DOUBLE IT FOR TWO-BYTE ENTRIES
TAX
LDA BASE,X ;GET LSB OF DESTINATION ADDRESS
STA TEMP ;STORE LSB SOMEWHERE
### 6502 Assembly Language Subroutines

<table>
<thead>
<tr>
<th>LDA</th>
<th>BASE, X</th>
<th>;GET MSB OF DESTINATION ADDRESS</th>
</tr>
</thead>
<tbody>
<tr>
<td>STA</td>
<td>TEMP+1</td>
<td>;STORE MSB IN NEXT BYTE</td>
</tr>
<tr>
<td>JMP</td>
<td>(TEMP)</td>
<td>;INDIRECT JUMP TO DESTINATION</td>
</tr>
</tbody>
</table>

JMP is the only 6502 instruction that has true indirect addressing. Note that TEMP and TEMP+1 can be anywhere in memory; they need not be on page 0.

### OPTION 2: Jump Through the Stack

<table>
<thead>
<tr>
<th>LDA</th>
<th>INDEX</th>
<th>;GET INDEX</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>A</td>
<td>;DOUBLE IT FOR TWO-BYTE ENTRIES</td>
</tr>
<tr>
<td>TAX</td>
<td></td>
<td></td>
</tr>
<tr>
<td>INX</td>
<td></td>
<td></td>
</tr>
<tr>
<td>LDA</td>
<td>BASE, X</td>
<td>;GET MSB OF DESTINATION ADDRESS</td>
</tr>
<tr>
<td>PHA</td>
<td></td>
<td>;SAVE MSB IN STACK</td>
</tr>
<tr>
<td>DEX</td>
<td></td>
<td></td>
</tr>
<tr>
<td>LDA</td>
<td>BASE, X</td>
<td>;GET LSB OF DESTINATION ADDRESS</td>
</tr>
<tr>
<td>PHA</td>
<td></td>
<td>;SAVE LSB IN STACK</td>
</tr>
<tr>
<td>RTS</td>
<td></td>
<td>;TRANSFER CONTROL TO DESTINATION</td>
</tr>
</tbody>
</table>

This alternative is awkward for the following reasons:

- RTS adds 1 to the program counter after loading it from the stack. Thus, the addresses in the table must all be one less than the actual values to which you wish to transfer control. This offset evidently speeds the processor’s execution of the JSR (Jump to Subroutine) instruction, but it also can confuse the programmer.

- You must remember that the stack is growing down in memory, toward lower addresses. To have the destination address end up in its normal order (less significant byte at lower address), we must push the more significant byte first. This is essentially a double negative; we store the address in the wrong order but it ends up right because the stack is growing down.

- The use of RTS is confusing. How can one return from a routine that one has never called? In fact, this approach uses RTS to call a subroutine. You should remember that RTS is simply a jump instruction that obtains the new value for the program counter from the top of the stack. While the common use of RTS is to transfer control from a subroutine back to a main program (hence, the mnemonic), there is no reason to limit it to that function. The mnemonic may confuse the programmer, but the microprocessor does exactly what it is supposed to do. Careful documentation can help calm the nerves if you feel uneasy about this procedure.

The common uses of jump tables are to implement CASE statements (for example, multiway branches as used in languages such as FORTRAN, Pascal,
and PL/I) to decode commands from a keyboard, and to respond to function keys on a terminal.

**CHARACTER MANIPULATION**

The easiest way to manipulate characters is to treat them as unsigned 8-bit numbers. The letters and digits form ordered subsequences of the ASCII characters; for example, the ASCII representation of the letter A is one less than the ASCII representation of the letter B. Handling one character at a time is just like handling normal 8-bit unsigned numbers. Some examples are

- Branch to address DEST if the accumulator contains an ASCII E.
  
  ```
  CMP #'E ; IS DATA E?
  BEQ DEST ; YES, BRANCH
  ```

- Search a string starting at address STRNG until a non-blank character is found.
  
  ```
  LDX #0 ; POINT TO START OF STRING
  LDA #■ ; GET A BLANK FOR CHECKING
  EXAMC CMP STRNG,X ; IS NEXT CHARACTER A BLANK?
  BNE DONE ; NO, DONE
  INX ; YES, PROCEED TO NEXT CHARACTER
  JMP EXAMC
  DONE NOP
  ```
  
  or

  ```
  LDX #$FF ; POINT TO BYTE BEFORE START
  LDA #' ; GET A BLANK FOR COMPARISON
  EXAMC INX ; PROCEED TO NEXT CHARACTER
  CMP STRNG,X ; IS IT A BLANK?
  BEQ EXAMC ; YES, KEEP LOOKING
  ```

- Branch to address DEST if the accumulator contains a letter between C and F, inclusive.
  
  ```
  CMP #'C ; IS DATA BELOW C?
  BCC DONE ; YES, DONE
  CMP #'G ; IS DATA BELOW G?
  BCC DEST ; YES, MUST BE BETWEEN C AND F
  ```

  Chapter 8 contains further examples of string manipulation.

**CODE CONVERSION**

You can convert data from one code to another using arithmetic or logical operations (if the relationship is simple) or lookup tables (if the relationship is complex).
Examples

1. Convert an ASCII digit to its binary-coded decimal (BCD) equivalent.

\[
\text{SEC; CLEAR THE INVERTED BORROW} \\
\text{SBC #'0; CONVERT ASCII TO BCD}
\]

Since the ASCII digits form an ordered subsequence, all you must do is subtract the offset (ASCII 0).

You can also clear bit positions 4 and 5 with the single instruction

\[
\text{AND #11001111; CONVERT ASCII TO BCD}
\]

Either the arithmetic sequence or the logical instruction will, for example, convert ASCII 0 (30₁₀) to decimal 0 (00₁₀).

2. Convert a binary-coded decimal (BCD) digit to its ASCII equivalent.

\[
\text{CLC; CLEAR THE CARRY} \\
\text{ADC #'0; CONVERT BCD TO ASCII}
\]

The inverse conversion is equally simple. You can also set bit positions 4 and 5 with the single instruction

\[
\text{ORA #00110000; CONVERT BCD TO ASCII}
\]

Either the arithmetic sequence or the logical instruction will, for example, convert decimal 6 (06₁₀) to ASCII 6 (36₁₀).

3. Convert one 8-bit code to another using a lookup table. Assume that the lookup table starts at address NEWCD and is indexed by the value in the original code (for example, the 27th entry is the value in the new code corresponding to 27 in the original code). Assume that the data is in memory location CODE.

\[
\text{LDX CODE; GET THE OLD CODE} \\
\text{LDA NEWCD,X; CONVERT IT TO THE NEW CODE}
\]

Chapter 4 contains further examples of code conversion.

MULTIPLE-PRECISION ARITHMETIC

Multiple-precision arithmetic requires a series of 8-bit operations. One must

- Clear the Carry before starting addition or set the Carry before starting subtraction, since there is never a carry into or borrow from the least significant byte.

- Use the Add with Carry (ADC) or Subtract with Borrow (SBC) instruction to perform an 8-bit operation and include the carry or borrow from the previous operation.
A typical 64-bit addition program is

```
LDX #8 ;NUMBER OF BYTES = 8
CLC     ;CLEAR CARRY TO START
ADDB:
LDA NUM1-1,X ;GET A BYTE OF ONE OPERAND
ADC NUM2-1,X ;ADD A BYTE OF THE OTHER OPERAND
STA NUM1-1,X ;STORE THE 8-BIT SUM
DEX
BNE ADDB ;COUNT BYTE OPERATIONS
```

Chapter 6 contains further examples.

**MULTIPLICATION AND DIVISION**

Multiplication can be implemented in a variety of ways. One technique is to convert simple multiplications to additions or left shifts.

*Examples*

1. Multiply the contents of the accumulator by 2.

   ```
   ASL A ;DOUBLE A
   ```

2. Multiply the contents of the accumulator by 5.

   ```
   STA TEMP
   ASL A ;A TIMES 2
   ASL A ;A TIMES 4
   ADC TEMP ;A TIMES 5
   ```

This approach assumes that shifting the accumulator left never produces a carry. This approach is often handy in determining the locations of elements of two-dimensional arrays. For example, let us assume that we have a set of temperature readings taken at four different positions in each of three different tanks. We organize the readings as a two-dimensional array \(T(I,J)\), where \(I\) is the tank number (1, 2, or 3) and \(J\) is the number of the position in the tank (1, 2, 3, or 4). We store the readings in the linear memory of the computer one after another as follows, starting with tank 1:

```
BASE   T(1,1)  Reading at tank 1, location 1
BASE+1 T(1,2)  Reading at tank 1, location 2
BASE+2 T(1,3)  Reading at tank 1, location 3
BASE+3 T(1,4)  Reading at tank 1, location 4
BASE+4 T(2,1)  Reading at tank 2, location 1
BASE+5 T(2,2)  Reading at tank 2, location 2
BASE+6 T(2,3)  Reading at tank 2, location 3
BASE+7 T(2,4)  Reading at tank 2, location 4
BASE+8 T(3,1)  Reading at tank 3, location 1
BASE+9 T(3,2)  Reading at tank 3, location 2
BASE+10 T(3,3) Reading at tank 3, location 3
BASE+11 T(3,4) Reading at tank 3, location 4
```
So, generally the reading $T(I,J)$ is located at address $BASE + 4 \times (I-1) + (J-1)$. If $I$ is in memory location IND1 and $J$ is in memory location IND2, we can load the accumulator with $T(I,J)$ as follows:

```assembly
LDA IND1 ;GET I
SEC
SBC #1 ;CALCULATE I - 1
ASL A ;2 X (I - 1)
ASL A ;4 X (I - 1)
SEC
SBC #1 ;4 X (I - 1) - 1
CLC
ADC IND2 ;4 X (I - 1) + J - 1
TAX
LDA BASE,X ;GET T(I,J)
```

We can extend this approach to handle arrays with more dimensions. Obviously, the program is much simpler if we store $I-1$ in memory location IND1 and $J-1$ in memory location IND2. We can then load the accumulator with $T(I,J)$ using

```assembly
LDA IND1 ;GET I - 1
ASL A ;2 X (I - 1)
ASL A ;4 X (I - 1)
CLC
ADC IND2 ;4 X (I - 1) + (J - 1)
TAX
LDA BASE,X ;GET T(I,J)
```

- Simple divisions can also be implemented as right logical shifts.

**Example**

Divide the contents of the accumulator by 4.

```assembly
LSR A ;DIVIDE BY 2
LSR A ;AND BY 2 AGAIN
```

If you are multiplying or dividing signed numbers, you must be careful to separate the signs from the magnitudes. You must replace logical shifts with arithmetic shifts that preserve the value of the sign bit.

- Algorithms involving shifts and additions (multiplication) or shifts and subtractions (division) can be used as described in Chapter 6.

- Lookup tables can be used as discussed previously in this chapter.

Chapter 6 contains additional examples of arithmetic programs.

## LIST PROCESSING

Lists can be processed like arrays if the elements are stored in consecutive addresses. If the elements are queued or chained, however, the limitations of the instruction set are evident in that
No 16-bit registers or instructions are available.
Indirect addressing is allowed only through pointers on page 0.
No true indirect addressing is available except for JMP instructions.

Examples
1. Retrieve an address stored starting at the address in memory locations PGZRO and PGZRO+1. Place the retrieved address in memory locations POINTL and POINTh.

```
LDY #0 ;INDEX = ZERO
LDA (PGZRO),Y ;GET LSB OF ADDRESS
STA POINTL
INY
LDA (PGZRO),Y ;GET MSB OF ADDRESS
STA POINTh
```

This procedure allows you to move from one element to another in a linked list.

2. Retrieve data from the address currently in memory locations PGZRO and PGZRO+1 and increment that address by 1.

```
LDY #0 ;INDEX = ZERO
LDA (PGZRO),Y ;GET DATA USING POINTER
INC PGZRO ;UPDATE POINTER BY 1
BNE DONE
INC PGZRO+1
DONE NOP
```

This procedure allows you to use the address in memory as a pointer to the next available location in a buffer. Of course, you can also leave the pointer fixed and increment a buffer index. If that index is in memory location BUFIND, we have

```
LDY BUFIND ;GET BUFFER INDEX
LDA (PGZRO),Y ;GET DATA FROM BUFFER
INC BUFIND ;UPDATE BUFFER INDEX BY 1
```

3. Store an address starting at the address currently in memory locations PGZRO and PGZRO+1. Increment the address in memory locations PGZRO and PGZRO+1 by 2.

```
LDY #0 ;INDEX = ZERO
LDA #ADDRl ;SAVE LSB OF ADDRESS
STA (PGZRO),Y
LDA #ADDRh ;SAVE MSB OF ADDRESS
INY
STA (PGZRO),Y
CLC
LDA PGZRO
ADC #2
STA PGZRO
BCC DONE ;WITH CARRY IF NECESSARY
INC PGZRO+1
DONE NOP
```
This procedure lets you build a list of addresses. Such a list could be used, for example, to write threaded code in which each routine concludes by transferring control to its successor. The list could also contain the starting addresses of a series of test procedures or tasks or the addresses of memory locations or I/O devices assigned by the operator to particular functions. Of course, some lists may have to be placed on page 0 in order to use the 6502’s preindexed or postindexed addressing modes.

GENERAL DATA STRUCTURES

More general data structures can be processed using the procedures that we have described for array manipulation, table lookup, and list processing. The key limitations in the instruction set are the same ones that we mentioned in the discussion of list processing.

Examples

1. Queues or linked lists. Assume that we have a queue header consisting of the address of the first element in memory locations HEAD and HEAD + 1 (on page 0). If there are no elements in the queue, HEAD and HEAD + 1 both contain 0. The first two locations in each element contain the address of the next element or 0 if there is no next element.

   - Add the element in memory locations PGZRO and PGZRO + 1 to the head of the queue.

   ```
   LDX PGZRO ;REPLACE HEAD, SAVING OLD VALUE
   LDA HEAD
   STX HEAD
   PHA
   LDA PGZRO+1
   LDX HEAD+1
   STA HEAD+1
   LDY #0 ;INDEX = ZERO
   PLA ;NEW HEAD'S LINK IS OLD HEAD
   STA (HEAD),Y
   TXA
   INY
   STA (HEAD),Y
   ```

   - Remove an element from the head of the queue and set the Zero flag if no element is available.

   ```
   LDY #0 ;GET ADDRESS OF FIRST ELEMENT
   LDA (HEAD),Y ;GET LESS SIGNIFICANT BYTE
   STA PGZRO
   INY
   LDA (HEAD),Y ;GET MORE SIGNIFICANT BYTE
   ```
CHAPTER 1: GENERAL PROGRAMMING METHODS

STA PGZRO+1
ORA PGZRO ;ANY ELEMENTS IN QUEUE?
BEQ DONE ;NO, DONE (LINK = 0000)
LDA (PGZRO),Y ;YES, MAKE NEXT ELEMENT NEW HEAD
STA (HEAD),Y
DEY
LDA (PGZRO),Y
STA (HEAD),Y
INY ;CLEAR ZERO FLAG BY MAKING Y 1
DONE
NOP

Note that we can use the sequence

LDA ADDR
ORA ADDR+1

to test the 16-bit number in memory locations ADDR and ADDR + 1. The Zero flag is set only if both bytes are 0.

2. **Stacks.** Assume that we have a stack structure consisting of 8-bit elements. The address of the next empty location is in addresses SPTR and SPTR + 1 on page 0. The lowest address that the stack can occupy is LOW and the highest address is HIGH.

• If the stack overflows, clear the Carry flag and exit. Otherwise, store the accumulator in the stack and increase the stack pointer by 1. Overflow means that the stack has exceeded its area.

LDA #HIGHL :STACK POINTER GREATER THAN HIGH?
CMP SPTR
LDA #HIGHM
SBC SPTR+1
BCC EXIT ;YES, CLEAR CARRY AND EXIT (OVERFLOW)
LDY #0 ;NO STORE ACCUMULATOR IN STACK
STA (SPTR),Y
INC SPTR ;INCREMENT STACK POINTER
BNE EXIT
INC SPTR+1
EXIT
NOP

• If the stack underflows, set the Carry flag and exit. Otherwise, decrease the stack pointer by 1 and load the accumulator from the stack. Underflow means that there is nothing left in the stack.

LDA #LOWL ;STACK POINTER AT OR BELOW LOW?
CMP SPTR
LDA #LOWM
SBC SPTR+1
BCS EXIT ;YES, SET CARRY AND EXIT (UNDERFLOW)
LDA SPTR ;NO, DECREMENT STACK POINTER
BNE NOBOR
DEC SPTR+1
NOBOR DEC SPTR
LDY #0 ;LOAD ACCUMULATOR FROM STACK
LDA (SPTR),Y
EXIT
NOP
PARAMETER PASSING TECHNIQUES

The most common ways to pass parameters on the 6502 microprocessor are

1. **In registers.** Three 8-bit registers are available (A, X, and Y). This approach is adequate in simple cases but it lacks generality and can handle only a limited number of parameters. The programmer must remember the normal uses of the registers in assigning parameters. In other words,
   - The accumulator is the obvious place to put a single 8-bit parameter.
   - Index register X is the obvious place to put an index, since it is the most accessible and has the most instructions that use it for addressing. Index register X is also used in preindexing (indexed indirect addressing).
   - Index register Y is used in postindexing (indirect indexed addressing).

This approach is reentrant as long as the interrupt service routines save and restore all the registers.

2. **In an assigned area of memory.** The easiest way to implement this approach is to place the starting address of the assigned area in two memory locations on page 0. The calling routine must store the parameters in memory and load the starting address into the two locations on page 0 before transferring control to the subroutine. This approach is general and can handle any number of parameters, but it requires a large amount of management. If you assign different areas of memory for each call or each routine, you are essentially creating your own stack. If you use a common area of memory, you lose reentrancy. In this method, the programmer is responsible for assigning areas of memory, avoiding interference between routines, and saving and restoring the pointers required to resume routines after subroutine calls or interrupts. The extra memory locations on page 0 must be treated like registers.

3. **In program memory immediately following the subroutine call.** If you use this approach, you must remember the following:

   - The starting address of the memory area minus 1 is at the top of the stack. That is, the starting address is the normal return address, which is 1 larger than the address the 6502's JSR instruction saves in the stack. You can move the starting address to memory locations RETADR and RETADR + 1 on page 0 with the following sequence:

     ```asm
     PLA       ;GET LSB OF RETURN ADDRESS
     STA RETADR
     PLA       ;GET MSB OF RETURN ADDRESS
     STA RETADR+1
     INC RETADR
     BNE DONE  ;ADD 1 TO RETURN ADDRESS
     INC RETADR+1
     DONE  NOP
     ```
Now we can access the parameters through the indirect address. That is, you can load the accumulator with the first parameter by using the sequence

```
LDY #0 ;INDEX = ZERO
LDA (RETADR),Y ;LOAD FIRST PARAMETER
```

An obvious alternative is to leave the return address unchanged and start the index at 1. That is, we would have

```
PLA ;GET LSB OF RETURN ADDRESS
STA RETADR
PLA ;GET MSB OF RETURN ADDRESS
STA RETADR+1
```

Now we could load the accumulator with the first parameter by using the sequence

```
LDY #1 ;INDEX = 1
LDA (RETADR),Y ;LOAD FIRST PARAMETER
```

- All parameters must be fixed for a given call, since the program memory is typically ROM.

- The subroutine must calculate the actual return address (the address of the last byte in the parameter area) and place it on top of the stack before executing a Return from Subroutine (RTS) instruction.

**Example**

Assume that subroutine SUBR requires an 8-bit parameter and a 16-bit parameter. Show a main program that calls SUBR and contains the required parameters. Also show the initial part of the subroutine that retrieves the parameters, storing the 8-bit item in the accumulator and the 16-bit item in memory locations PGZRO and PGZRO+1, and places the correct return address at the top of the stack.

**Subroutine call**

```
JSR SUBR ;EXECUTE SUBROUTINE
.BYTE PAR8 ;8-BIT PARAMETER
.WORD PAR16 ;16-BIT PARAMETER
... next instruction ...
```

**Subroutine**

```
SUBR PLA ;GET LSB OF PARAMETER ADDRESS
STA RETADR
PLA ;GET MSB OF PARAMETER ADDRESS
STA RETADR+1
LDY #1 ;ACCESS FIRST PARAMETER
LDA (RETADR),Y ;GET FIRST PARAMETER
TAX
INY
LDA (RETADR),Y ;ACCESS LSB OF 16-BIT PARAMETER
STA PGZRO
INY
LDA (RETADR),Y ;GET MSB OF 16-BIT PARAMETER
```
The initial sequence pops the return address from the top of the stack (JSR saved it there) and stores it in memory locations RETADR and RETADR + 1. In fact, the return address does not contain an instruction; instead, it contains the first parameter. Remember that JSR actually saves the return address minus 1; that is why we must start the index at 1 rather than at 0. Finally, adding 3 to the return address and saving the sum in the stack lets a final RTS instruction transfer control back to the instruction following the parameters.

This approach allows parameters lists of any length. However, obtaining the parameters from memory and adjusting the return address is awkward at best; it becomes a longer and slower process as the number of parameters increases.

4. **In the stack.** If you use this approach, you must remember the following:

- JSR stores the return address at the top of the stack. The parameters that the calling routine placed in the stack begin at address 01ss + 3, where ss is the contents of the stack pointer. The 16-bit return address occupies the top two locations and the stack pointer itself always refers to the next empty address, not the last occupied one. Before the subroutine can obtain its parameters, it must remove the return address from the stack and save it somewhere.

- The only way for the subroutine to determine the value of the stack pointer is by using the instruction TSX. After TSX has been executed, you can access the top of the stack by indexing with register X from the base address 010116. The extra offset of 1 is necessary because the top of the stack is empty.

- The calling program must place the parameters in the stack before calling the subroutine.

- Dynamically allocating space on the stack is difficult at best. If you wish to reduce the stack pointer by NRESLT, two general approaches are

```
TSX ;MOVE STACK POINTER TO A VIA X
TXA
SEC
SBC #NRESLT
TAX
TXS
```

```
LDA RETADR ;CALCULATE ACTUAL RETURN ADDRESS
CLC
ADA
TAY
BCC INC
PHA
TYA
PHA
PGZRO+1
RETADR
#3
STRMSB
RETADR+1
STRMSB
LDA RETADR+1 ;PUT RETURN ADDRESS ON TOP OF STACK
PHA
TYA
PHA
```
Either approach leaves NRESLT empty locations at the top of the stack as shown in Figure 1-5. Of course, if NRESLT is 1 or 2, simply executing PHA the appropriate number of times will be much faster and shorter. The same approaches can be used to provide stack locations for temporary storage.

Example

Assume that subroutine SUBR requires an 8-bit parameter and a 16-bit parameter, and that it produces two 8-bit results. Show a call of SUBR, the removal of the return address from the stack, and the cleaning of the stack after the return. Figure 1-6 shows the appearance of the stack initially, after the subroutine call, and at the end. If you always use the stack for parameters and results, you will generally keep the parameters at the top of the stack in the proper order. Then you will not have to save the parameters or assign space in the stack for the results (they will replace some or all of the original parameters). You will, however, have to assign space on the stack for temporary storage to maintain generality and reentrancy.

Calling program

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TSX</td>
<td>LEAVE ROOM ON STACK FOR RESULTS</td>
</tr>
<tr>
<td>TXA</td>
<td>A GENERAL WAY TO ADJUST SP</td>
</tr>
<tr>
<td>CLC</td>
<td>$2</td>
</tr>
<tr>
<td>ADC</td>
<td>#2</td>
</tr>
<tr>
<td>TAX</td>
<td>#PAR16H</td>
</tr>
<tr>
<td>LDA</td>
<td>#PAR16L</td>
</tr>
<tr>
<td>PHA</td>
<td>#PAR8</td>
</tr>
<tr>
<td>JSR SUBR</td>
<td>EXECUTE SUBROUTINE</td>
</tr>
<tr>
<td>TSX</td>
<td>CLEAN PARAMETERS FROM STACK</td>
</tr>
<tr>
<td>TXA</td>
<td></td>
</tr>
<tr>
<td>CLC</td>
<td>#3</td>
</tr>
<tr>
<td>ADC</td>
<td></td>
</tr>
<tr>
<td>TAX</td>
<td></td>
</tr>
<tr>
<td>TXS</td>
<td>RESULT IS NOW AT TOP OF STACK</td>
</tr>
</tbody>
</table>

Subroutine

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUBR PLA</td>
<td>REMOVE RETURN ADDRESS FROM STACK</td>
</tr>
<tr>
<td>STA RETADR</td>
<td></td>
</tr>
<tr>
<td>PLA</td>
<td></td>
</tr>
<tr>
<td>STA RETADR+1</td>
<td></td>
</tr>
</tbody>
</table>
No values are placed in the locations. The initial contents of the stack pointer are ss.

**Figure 1-5:** The Stack Before and After Assigning NRESLT Empty Locations for Results

The initial contents of the stack pointer are ss.

**Figure 1-6:** The Effect of a Subroutine on the Stack
SIMPLE INPUT/OUTPUT

Simple input/output can be performed using any memory addresses and any instructions that reference memory. The most common instructions are the following:

- **LDA (load accumulator)** transfers eight bits of data from an input port to the accumulator.
- **STA (store accumulator)** transfers eight bits of data from the accumulator to an output port.

Other instructions can combine the input operation with arithmetic or logical operations. Typical examples are the following:

- **AND** logically ANDs the contents of the accumulator with the data from an input port.
- **BIT** logically ANDs the contents of the accumulator with the data from an input port but does not store the result anywhere. It does, however, load the Negative flag with bit 7 of the input port and the Overflow flag with bit 6, regardless of the contents of the accumulator.
- **CMP** subtracts the data at an input port from the contents of the accumulator, setting the flags but leaving the accumulator unchanged.

Instructions that operate on data in memory can also be used for input or output. Since these instructions both read and write memory, their effect on input and output ports may be difficult to determine. Remember, input ports cannot generally be written, nor can output ports generally be read. The commonly used instructions are the following:

- **ASL** shifts its data to the left, thus moving bit 7 to the Carry for possible serial input.
- **DEC** decrements its data. Among other effects, this inverts bit 0.
- **INC** increments its data. Among other effects, this inverts bit 0.
- **LSR** shifts its data to the right, thus moving bit 0 to the Carry for possible serial input.
- **ROR** rotates its data to the right, thus moving the old Carry to bit 7 and moving bit 0 to the Carry.
- **ROL** rotates its data to the left, thus moving the old Carry to bit 0 and moving bit 7 to the Carry.

The effects of these instructions on an input port are typically similar to their effects on a ROM location. The microprocessor can read the data, operate on it, and set the flags, but it cannot store the result back into memory. The effects on
an output port are even stranger, unless the port is latched and buffered. If it is not, the data that the processor reads is system-dependent and typically has no connection with what was last stored there.

*Examples*

1. Perform an 8-bit input operation from the input port assigned to memory address B000\textsubscript{16}.

   \begin{verbatim}
   LDA $B000 \quad ; INPUT DATA
   \end{verbatim}

2. Perform an 8-bit output operation to the output port assigned to memory address 3A5E\textsubscript{16}.

   \begin{verbatim}
   STA $3A5E \quad ; OUTPUT DATA
   \end{verbatim}

3. Set the Zero flag if bit 5 of the input port assigned to memory address 75D0\textsubscript{16} is 0.

   \begin{verbatim}
   LDA $75D0 \quad ; GET MASK
   AND $75D0 \quad ; SET FLAG IF BIT 5 IS ZERO
   \end{verbatim}

   We can also use the sequence

   \begin{verbatim}
   LDA $75D0 \quad ; GET MASK
   BIT $75D0 \quad ; SET FLAG IF BIT 5 IS ZERO
   \end{verbatim}

   If the bit position of interest is number 6, we can use the single instruction

   \begin{verbatim}
   BIT $75D0
   \end{verbatim}

   to set the Overflow flag to its value.

4. Set the Zero flag if the data at the input port assigned to memory address 1700\textsubscript{16} is 1B\textsubscript{16}.

   \begin{verbatim}
   LDA #1B
   CMP $1700
   \end{verbatim}

5. Load the Carry flag with the data from bit 7 of the input port assigned to memory address 33A5\textsubscript{16}.

   \begin{verbatim}
   ASL $33A5
   \end{verbatim}

   Note that this instruction does not change the data in memory location 33A5\textsubscript{16} unless that location is latched and buffered. If, for example, there are eight simple switches attached directly to the port, the instruction will surely have no effect on whether the switches are open or closed.

6. Place a logic 1 in bit 0 of the output port assigned to memory address B070\textsubscript{16}.

   \begin{verbatim}
   LDA $B070
   ORA #$00000001
   STA $B070
   \end{verbatim}

   If none of the other bits in address B070\textsubscript{16} are connected, we can use the sequence

   \begin{verbatim}
   SEC
   ROL $B070
   \end{verbatim}
If we know that bit 0 of address \( B070_{16} \) is currently a logic 0, we can use the single instruction:

\[
\text{INC $B070$}
\]

All of these alternatives will have strange effects if memory address \( B070_{16} \) cannot be read. The first two will surely make bit 0 a logic 1, but their effects on the other bits are uncertain. The outcome of the third alternative would be a total mystery, since we would have no idea what is being incremented. We can avoid the uncertainty by saving a copy of the data in RAM location TEMP. Now we can operate on the copy using:

\[
\begin{align*}
\text{LDA TEMP} \quad &; \text{GET COPY OF OUTPUT DATA} \\
\text{ORA #$00000001$} \quad &; \text{SET BIT 0} \\
\text{STA $B070$} \quad &; \text{OUTPUT NEW DATA} \\
\text{STA TEMP} \quad &; \text{AND SAVE A COPY OF IT}
\end{align*}
\]

**LOGICAL AND PHYSICAL DEVICES**

One way to select I/O devices by number is to use an I/O device table. An I/O device table assigns the actual I/O addresses (physical devices) to the device numbers (logical devices) to which a program refers. Using this method, a program written in a high-level language may refer to device number 2 for input and number 5 for output. For testing purposes, the operator may assign devices numbers 2 and 5 to be the input and output ports, respectively, of his or her terminal. For normal stand-alone operation, the operator may assign device number 2 to be an analog input unit and device number 5 the system printer. If the system is to be operated by remote control, the operator may assign devices numbers 2 and 5 to be communications units used for input and output.

One way to provide this distinction between logical and physical devices is to use the 6502's indexed indirect addressing or preindexing. This mode assumes that the device table is located on page 0 and is accessed via an index in register X. If we have a device number in memory location DEVNO, the following programs can be used:

- Load the accumulator from the device number given by the contents of memory location DEVNO.

\[
\begin{align*}
\text{LDA DEVNO} \quad &; \text{GET DEVICE NUMBER} \\
\text{ASL A} \quad &; \text{DOUBLE IT TO HANDLE DEVICE ADDRESSES} \\
\text{TAX} \\
\text{LDA (DEVTAB,X)} \quad &; \text{GET DATA FROM DEVICE}
\end{align*}
\]

- Store the accumulator in the device number given by the contents of memory location DEVNO.
In both cases, we assume that the I/O device table starts at address DEVTAB (on page 0) and consists of 2-byte addresses. Note that the 6502 provides an appropriate addressing method, but does not produce any error messages if the programmer uses that method improperly by accessing odd addresses or by indexing off the end of page 0 (the processor does provide automatic wraparound). In real applications (see Chapter 10), the device table will probably contain the starting addresses of I/O subroutines (drivers) rather than actual device addresses.

**STATUS AND CONTROL**

You can handle status and control signals like any other data. The only special problem is that the processor may not be able to read output ports; in that case, you must retain copies (in RAM) of the data sent to those ports.

**Examples**

1. Branch to address DEST if bit 3 of the input port assigned to memory address A100₁₀ is 1.

   LDA $A100 ;GET INPUT DATA
   AND #%00001000 ;MASK OFF BIT 3
   BNE DEST

2. Branch to address DEST if bits 4, 5, and 6 of the input port assigned to address STAT are 5 (101 binary).

   LDA STAT ;GET STATUS
   AND #%01100000 ;MASK OFF BITS 4, 5, AND 6
   CMP #%01010000 ;IS STATUS FIELD 5?
   BEQ DEST ;YES, BRANCH

3. Set bit 5 of address CNTL to 1.

   LDA CNTL ;GET CURRENT DATA FROM PORT
   ORA #%00100000 ;SET BIT 5
   STA CNTL ;RESTORE DATA TO PORT

If address CNTL cannot be read properly, we can use a copy in memory address TEMP.

   LDA TEMP ;GET CURRENT DATA FROM PORT
   ORA #%00100000 ;SET BIT 5
   STA CNTL ;RESTORE DATA TO PORT
   STA TEMP ;UPDATE COPY OF DATA
You must update the copy every time you change the data.

4. Set bits 2, 3, and 4 of address CNTL to 6 (110 binary).

   LDA CNTL ; GET CURRENT DATA FROM PORT
   AND #1110011 ; CLEAR BITS 2, 3, AND 4
   ORA #00011000 ; SET CONTROL FIELD TO 6
   STA CNTL ; RESTORE DATA TO PORT

As in example 3, if address CNTL cannot be read properly, we can use a copy in memory address TEMP.

   LDA TEMP ; GET CURRENT DATA FROM PORT
   AND #1110011 ; CLEAR BITS 2, 3, AND 4
   ORA #00011000 ; SET CONTROL FIELD TO 6
   STA CNTL ; UPDATE PORT
   STA TEMP ; UPDATE COPY OF DATA

Retaining copies of the data in memory (or using the values stored in a latched, buffered output port) allows you to change part of the data without affecting other parts that may have unrelated meanings. For example, you could change the state of one indicator light (for example, a light that indicated local or remote operation) without affecting other indicator lights attached to the same port. You could similarly change one control line (for example, a line that determined whether motion was in the positive or negative X-direction) without affecting other control lines attached to the same port.

PERIPHERAL CHIPS

The major peripheral chips in 6502-based microcomputers are the 6520 and 6522 parallel interfaces (known as the Peripheral Interface Adapter or PIA and the Versatile Interface Adapter or VIA, respectively), the 6551 and 6850 serial interfaces (known as Asynchronous Communications Interface Adapters or ACIAs), and the 6530 and 6532 multifunction devices (known as ROM-I/O-timers or RAM-I/O-timers or ROM-RAM-I/O-timers, abbreviated RIOT or RRIOT and sometimes called combo chips). All of these devices can perform a variety of functions, much like the microprocessor itself. Of course, peripheral chips perform fewer different functions than processors and the range of functions is limited. The idea behind programmable peripheral chips is that each contains many useful circuits; the designer selects the ones he or she wants to use by storing one or more selection codes in control registers, much as one selects a particular circuit from a Designer’s Casebook by turning to a particular page. The advantages of programmable chips are that a single board containing such devices can handle many applications and changes, or, corrections can be made by changing selection codes rather than by redesigning circuit boards. The disadvantages
of programmable chips are the lack of standards and the difficulty of determining how specific chips operate.

Chapter 10 contains typical initialization routines for the 6520, 6522, 6551, 6850, 6530, and 6532 devices. These devices are also discussed in detail in the *Osborne 4 and 8-Bit Microprocessor Handbook*. We will provide only a brief overview of the 6522 device here, since it is the most widely used. 6522 devices are used, for example, in the Rockwell AIM-65, Synertek SYM-1, Apple, and other popular microcomputers as well as in add-on I/O boards and other functions available from many manufacturers.

**6522 Parallel Interface**
*(Versatile Interface Adapter)*

A VIA contains two 8-bit parallel I/O ports (A and B), four status and control lines (CA1, CA2, CB1, and CB2 — two for each of the two ports), two 16-bit counter/timers (timer 1 and timer 2), an 8-bit shift register, and interrupt logic. Each VIA occupies 16 memory addresses. The RS (register select) lines choose the various internal registers as described in Table 1-12. The way that a VIA operates is determined by the values that the program stores in four registers.

- Data Direction Register A (DDRA) determines whether the pins on port A are inputs (0s) or outputs (1s). A data direction register determines only the direction in which traffic flows; you may compare it to a directional arrow that indicates which way traffic can move on a highway lane or railroad track. The data direction register does not affect what data flows or how often it changes; it only affects the direction. Each pin in the I/O port has a corresponding bit in the data direction register, and thus, each pin can be selected individually as either an input or an output. Of course, the most common choices are to make an entire 8-bit I/O port input or output by storing 0s or 1s in all eight bits of the data direction register.

- Data Direction Register B (DDRB) similarly determines whether the pins in port B are inputs or outputs.

- The Peripheral Control Register (PCR) determines how the handshaking control lines (CA1, CB1, CA2, and CB2) operate. Figure 1-7 contains the bit assignments for this register. We will discuss briefly the purposes of these bits and their uses in common applications.

- The Auxiliary Control Register (ACR) determines whether the input data ports are latched and how the timers and shift register operate. Figure 1-8 contains the bit assignments for this register. We will also discuss briefly the purposes of these bits and their uses in common applications.
Table 1-12: Addressing the Internal Registers of the 6522 VIA

<table>
<thead>
<tr>
<th>Label</th>
<th>Select Lines</th>
<th>Addressed Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEV</td>
<td>0 0 0 0</td>
<td>Output register for I/O Port B</td>
</tr>
<tr>
<td>DEV+1</td>
<td>0 0 0 1</td>
<td>Output register for I/O Port A, with handshaking</td>
</tr>
<tr>
<td>DEV+2</td>
<td>0 0 1 0</td>
<td>I/O Port B Data Direction register</td>
</tr>
<tr>
<td>DEV+3</td>
<td>0 0 1 1</td>
<td>I/O Port A Data Direction register</td>
</tr>
<tr>
<td>DEV+4</td>
<td>0 1 0 0</td>
<td>Read Timer 1 Counter low-order byte Write to Timer 1 Latch low-order byte</td>
</tr>
<tr>
<td>DEV+5</td>
<td>0 1 0 1</td>
<td>Read Timer 1 Counter high-order byte Write to Timer 1 Latch high-order byte and initiate count</td>
</tr>
<tr>
<td>DEV+6</td>
<td>0 1 1 0</td>
<td>Access Timer 1 Latch low-order byte</td>
</tr>
<tr>
<td>DEV+7</td>
<td>0 1 1 1</td>
<td>Access Timer 1 Latch high-order byte</td>
</tr>
<tr>
<td>DEV+8</td>
<td>1 0 0 0</td>
<td>Read low-order byte of Timer 2 and reset Counter interrupt Write to low-order byte of Timer 2 but do not reset interrupt</td>
</tr>
<tr>
<td>DEV+9</td>
<td>1 0 0 1</td>
<td>Access high-order byte of Timer 2, reset Counter interrupt on write</td>
</tr>
<tr>
<td>DEV+A</td>
<td>1 0 1 0</td>
<td>Serial I/O Shift register</td>
</tr>
<tr>
<td>DEV+B</td>
<td>1 0 1 1</td>
<td>Auxiliary Control register</td>
</tr>
<tr>
<td>DEV+C</td>
<td>1 1 0 0</td>
<td>Peripheral Control register</td>
</tr>
<tr>
<td>DEV+D</td>
<td>1 1 0 1</td>
<td>Interrupt Flag register</td>
</tr>
<tr>
<td>DEV+E</td>
<td>1 1 1 0</td>
<td>Interrupt Enable register</td>
</tr>
<tr>
<td>DEV+F</td>
<td>1 1 1 1</td>
<td>Output register for I/O Port A, without handshaking</td>
</tr>
</tbody>
</table>
Figure 1-7: Bit Assignments for the 6522 VIA's Peripheral Control Register

Figure 1-8: Bit Assignments for the 6522 VIA's Auxiliary Control Register
In order to initialize a VIA properly, we must know what its start-up state is. Reset clears all the VIA registers, thus making all the data and control lines inputs, disabling all latches, interrupts, and other functions, and clearing all status bits.

The data direction registers are easy to initialize. Typical routines are

- Make port A input.
  \[
  \text{LDA} \#0 \\
  \text{STA} \ DDRA
  \]

- Make port B output.
  \[
  \text{LDA} \#11111111 \\
  \text{STA} \ DDRA
  \]

- Make bits 0 through 3 of port A input, bits 4 through 7 output.
  \[
  \text{LDA} \#11110000 \\
  \text{STA} \ DDRA
  \]

- Make bit 0 of port B input, bits 1 through 7 output.
  \[
  \text{LDA} \#11111110 \\
  \text{STA} \ DDRA
  \]

Bit 0 could, for example, be a serial input line.

The Peripheral Control Register is more difficult to initialize. We will briefly discuss the purposes of the control lines before showing some examples.

Control lines CA1, CA2, CB1, and CB2 are basically intended for use as handshaking signals. In a handshake, the sender indicates the availability of data by means of a transition on a serial line; the transition tells the receiver that new data is available to it on the parallel lines. Common names for this serial line are VALID DATA, DATA READY, and DATA AVAILABLE. In response to this signal, the receiver must accept the data and indicate its acceptance by means of a transition on another serial line. This transition tells the sender that the latest parallel data has been accepted and that another transmission sequence can begin. Common names for the other serial line are DATA ACCEPTED, PERIPHERAL READY, BUFFER EMPTY, and DATA ACKNOWLEDGE.

Typical examples of complete sequences are

- **Input from a keyboard.** When the operator presses a key, the keyboard produces a parallel code corresponding to the key and a transition on the DATA READY or VALID DATA line. The computer must determine that the transition has occurred, read the data, and produce a transition on the DATA ACCEPTED line to indicate that the data has been read.

- **Output to a printer.** The printer indicates to the computer that it is ready by means of a transition on a BUFFER EMPTY or PERIPHERAL READY line. Note that PERIPHERAL READY is simply the inverse of DATA ACCEPTED, since the peripheral obviously cannot be ready as long as it has not accepted the
latest data. The computer must determine that the printer is ready, send the data, and produce a transition on the DATA READY line to indicate that new data is available. Of course, input and output are in some sense mirror images. In the input case, the peripheral is the sender and the computer is the receiver; in the output case, the computer is the sender and the peripheral is the receiver.

Thus, a chip intended for handshaking functions must provide the following functions:

• It must recognize the appropriate transitions on the DATA READY or PERIPHERAL READY lines.

• It must provide an indication that the transition has occurred in a form that is easy for the computer to handle.

• It must allow for the production of the response — that is, for the computer to indicate DATA ACCEPTED to an input peripheral or DATA READY to an output peripheral.

There are some obvious variations that the handshaking chip should allow for, including the following:

• The active transition may be either a high-to-low edge (a trailing edge) or a low-to-high edge (a leading edge). If the chip does not allow either one, we will need extra inverter gates in some situations, since both polarities are common.

• The response may require either a high-to-low edge or a low-to-high edge. In fact, it may require either a brief pulse or a long signal that lasts until the peripheral begins its next operation.

Experience has shown that the handshaking chip can provide still more convenience, at virtually no cost, in the following ways:

• It can latch the transitions on the DATA READY or PERIPHERAL READY lines, so that they are held until the computer is ready for them. The computer need not monitor the status lines continuously to avoid missing a transition.

• It can clear the status latches automatically when an input port is read or an output port is written, thus preparing them for the next operation.

• It can produce the response automatically when an input port is read or an output port is written, thus eliminating the need for additional instructions. This option is known as an automatic mode. The problem with any automatic mode, no matter how flexible the designers make it, is that it will never satisfy all applications. Thus, most chips also provide a mode in which the program retains control over the response; this mode is called a manual mode.

• In cases where the peripherals are simple switches or lights and do not need
any status or control signals, the chip should allow independent operation of the status lines. The designer can then use these lines (which would otherwise be wasted) for such purposes as threshold detection, zero-crossing detection, or clock inputs. In such cases, the designer wants the status and control signals to be entirely independent of the operations on the parallel port. We should not have any automatic clearing of latches or sending of responses. This is known as an independent mode.

The 6522 peripheral control register allows the programmer to provide any of these functions. Bits 0 through 3 govern the operation of port B and its control signals; bits 4 through 7 govern the operation of port A and its control signals. The status indicators are in the Interrupt flag register (see Figure 1-9). We may characterize the bits in the control register as follows:

- Bit 0 (for port A) and bit 4 (for port B) determine whether the active transition on control line 1 is high-to-low (0) or low-to-high (1). If control line 2 is an extra input, bit 2 (for port A) and bit 6 (for port B) has a similar function.

- If control line 2 is an extra input, bit 1 (for port A) and bit 5 (for port B) determine whether it operates independently of the parallel data port. This bit is 0 for normal handshaking and 1 for independent operation.

- Bit 3 (for port A) and bit 7 (for port B) determine whether control line 2 is an extra input line (0) or an output response (1).

- If control line 2 is an output response, bit 2 (for port A) and bit 6 (for port B) determine whether it operates in an automatic mode (0) or a manual mode (1).

- If control line 2 is being operated in the automatic mode, bit 1 (for port A) and bit 5 (for port B) determine whether the response lasts for one clock cycle (1) or until the peripheral produces another active transition on control line 1 (0).

- If control line 2 is being operated in the manual mode, bit 1 (for port A) and bit 5 (for port B) determine its level.

Some typical examples are

- The peripheral indicates DATA READY or PERIPHERAL READY with a high-to-low transition on control line 1. No response is necessary.

  In the 4 bits controlling a particular port, the only requirement is that bit 0 must be 0 to allow recognition of a high-to-low transition on control line 1. The other bits are arbitrary, although our preference is to clear unused bits as a standard convention. Thus, the bits would be 0000.

- The peripheral indicates DATA READY or PERIPHERAL READY with a low-to-high transition on control line 1. No response is necessary. Bit 0 must be set to 1; the other bits are arbitrary. Bit 0 determines which edge the VIA recognizes.
<table>
<thead>
<tr>
<th>Bit Number</th>
<th>Set by</th>
<th>Cleared by</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Active transition of the signal on the CA2 pin.</td>
<td>Reading or writing the A Port Output register (ORA) using address 0001.</td>
</tr>
<tr>
<td>1</td>
<td>Active transition of the signal on the CA1 pin.</td>
<td>Reading or writing the A Port Output register (ORA) using address 0001.</td>
</tr>
<tr>
<td>2</td>
<td>Completion of eight shifts.</td>
<td>Reading or writing the Shift register.</td>
</tr>
<tr>
<td>3</td>
<td>Active transition of the signal on the CB2 pin.</td>
<td>Reading or writing the B Port Output register.</td>
</tr>
<tr>
<td>4</td>
<td>Active transition of the signal on the CB1 pin.</td>
<td>Reading or writing the B Port Output register.</td>
</tr>
<tr>
<td>5</td>
<td>Time-out of Timer 2.</td>
<td>Reading T2 low-order counter or writing T2 high-order counter.</td>
</tr>
<tr>
<td>6</td>
<td>Time-out of Timer 1.</td>
<td>Reading T1 low-order counter or writing T1 high-order latch.</td>
</tr>
<tr>
<td>7</td>
<td>Active and enabled interrupt condition.</td>
<td>Action which clears interrupt condition.</td>
</tr>
</tbody>
</table>

Bits 0, 1, 3, and 4 are the I/O handshake signals. Bit 7 (IRQ) is 1 if any of the interrupts is both active and enabled.

**Figure 1-9:** The 6522 VIA’s Interrupt Flag Register

- The peripheral indicates DATA READY or PERIPHERAL READY with a high-to-low transition on control line 1. The port must respond by producing a pulse on control line 2 that lasts one clock cycle after the processor reads the input or writes the output.

The required 4-bit sequence is

Bit 3 = 1 to make control line 2 an output
Bit 2 = 0 to operate control line 2 in the automatic mode.

The port therefore produces the response without processor intervention.
Bit 1 = 1 to make the response last one clock cycle.
Bit 0 = 0 to recognize a high-to-low transition on control line 1.

• The peripheral indicates DATA READY or PERIPHERAL READY with a low-to-high transition on control line 1. The port must respond by bringing control line 2 low until the peripheral becomes ready again.

The required 4-bit sequence is

Bit 3 = 1 to make control line 2 an output.
Bit 2 = 0 to operate control line 2 in the automatic mode.
Bit 1 = 0 to make the response last until the peripheral becomes ready again.
Bit 0 = 1 to recognize a low-to-high transition on control line 1 as the ready signal.

• The peripheral indicates DATA READY or PERIPHERAL READY with a low-to-high transition on control line 1. The processor must respond under program control.

The required 4-bit sequence is

Bit 3 = 1 to make control line 2 an output.
Bit 2 = 1 to operate control line 2 in the manual mode.
Bit 1 is the initial state for control line.
Bit 0 = 1 to recognize a low-to-high transition on control line 1 as the ready signal.

The following sequences can be used to produce the response

Make CA2 a logic 1:
LDA VIAPCR ;READ THE PERIPHERAL REGISTER
ORA #$00000010 ;SET CONTROL LINE 2 TO 1
STA VIAPCR
Make CA2 a logic 0:
LDA VIAPCR ;READ THE PERIPHERAL REGISTER
AND #$11111101 ;SET CONTROL LINE 2 TO 0
STA VIAPCR
Make CB2 a logic 1:
LDA VIAPCR ;READ THE PERIPHERAL REGISTER
ORA #$00100000 ;SET CONTROL LINE 2 TO 1
STA VIAPCR
Make CB2 a logic 0:
LDA VIAPCR ;READ THE PERIPHERAL REGISTER
AND #$11011111 ;SET CONTROL LINE 2 TO 0
STA VIAPCR

These sequences do not depend on the contents of the peripheral control register, since they do not change any of the bits except the one that controls the response.

Tables 1-13 and 1-14 summarize the operating modes for control lines CA2 and CB2. Note that the automatic output modes differ slightly in that port A produces a response after either read or write operations, whereas port B produces a response only after write operations.
### Table 1-13: Operating Modes for Control Line CA2 of a 6522 VIA

<table>
<thead>
<tr>
<th>PCR3</th>
<th>PCR2</th>
<th>PCR1</th>
<th>Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>Input Mode — Set CA2 Interrupt flag (IFRO) on a negative transition of the input signal. Clear IFRO on a read or write of the Peripheral A Output register.</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>Independent Interrupt Input Mode — Set IFRO on a negative transition of the CA2 input signal. Reading or writing ORA does not clear the CA2 Interrupt flag.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>Input Mode — Set CA2 Interrupt flag on a positive transition of the CA2 input signal. Clear IFRO with a read or write of the Peripheral A Output register.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
<td>Independent Interrupt Input Mode — Set IFRO on a positive transition of the CA2 input signal. Reading or writing ORA does not clear the CA2 Interrupt flag.</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>Handshake Output Mode — Set CA2 output low on a read or write of the Peripheral A Output register. Reset CA2 high with an active transition on CA1.</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>Pulse Output Mode — CA2 goes low for one cycle following a read or write of the Peripheral A Output register.</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>Manual Output Mode — The CA2 output is held low in this mode.</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>Manual Output Mode — The CA2 output is held high in this mode.</td>
</tr>
</tbody>
</table>

The auxiliary control register is less important than the peripheral control register. Its bits have the following functions (see Figure 1-8):

- Bits 0 and 1, if set, cause the VIA to latch the input data on port A (bit 0) or port B (bit 1) when an active transition occurs on control line 1. This option allows for the case in which the input peripheral provides valid data only briefly, and the data must be saved until the processor has time to handle it.

- Bits 2, 3, and 4 control the operations of the seldom-used shift register. This register provides a simple serial I/O capability, but most designers prefer either to use the serial I/O chips such as the 6551 or 6850 or to provide the entire serial interface in software.

- Bit 5 determines whether timer 2 generates a single time interval (the so-called one-shot mode) or counts pulses on line PB6 (pulse-counting mode).

- Bit 6 determines whether timer 1 generates one time interval (0) or operates continuously (1), reloading its counters from the latches after each interval elapses.
### Table 1-14: Operating Modes for Control Line CB2 of a 6522 VIA

<table>
<thead>
<tr>
<th>PCR7</th>
<th>PCR6</th>
<th>PCR5</th>
<th>Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>Interrupt Input Mode — Set CB2 Interrupt flag (IFR3) on a negative transition of the CB2 input signal. Clear IFR3 on a read or write of the Peripheral B Output register.</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>Independent Interrupt Input Mode — Set IFR3 on a negative transition of the CB2 input signal. Reading or writing ORB does not clear the Interrupt flag.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>Input Mode — Set CB2 Interrupt flag on a positive transition of the CB2 input signal. Clear the CB2 Interrupt flag on a read or write of ORB.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
<td>Independent Input Mode — Set IFR3 on a positive transition of the CB2 input signal. Reading or writing ORB does not clear the CB2 Interrupt flag.</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>Handshake Output Mode — Set CB2 low on a write ORB operation. Reset CB2 high on an active transition of the CB1 input signal.</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>Pulse Output Mode — Set CB2 low for one cycle following a write ORB operation.</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>Manual Output Mode — The CB2 output is held low in this mode.</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>Manual Output Mode — The CB2 output is held high in this mode.</td>
</tr>
</tbody>
</table>

- Bit 7 determines whether timer 1 generates output pulses on PB7 (a logic 1 generates pulses).

The uses of most of these functions are straightforward. They are not as common as the handshaking functions governed by the peripheral control register.

You can also operate a 6522 VIA in an interrupt-driven mode. Interrupts are enabled or disabled by setting bits in the interrupt enable register (see Figures 1-10 and 1-11) with bit 7 (the enable/disable flag) set (for enabling) or cleared (for disabling). Interrupts can be recognized by examining the interrupt flag register (see Figure 1-9). Table 1-15 summarizes the setting and clearing (resetting) of interrupt flags on the 6522 VIA.
The Interrupt Flag register identifies those interrupts which are active. A 1 in any bit position indicates an active interrupt, whereas a 0 indicates an inactive interrupt.

**Figure 1-10:** The 6522 VIA's Interrupt Flag and Interrupt Enable Registers

You can selectively enable or disable individual interrupts via the Interrupt Enable register. You enable individual interrupts by writing to the Interrupt Enable register with a 1 in bit 7. Thus you could enable "time out for Timer 1" and "active transitions of signal CB1" by storing D016 in the Interrupt Enable register:

**Figure 1-11:** A Typical Enabling Operation on the 6522 VIA's Interrupt Enable Register
Table 1-15: A Summary of Conditions for Setting and Resetting Interrupt Flags in the 6522 VIA

<table>
<thead>
<tr>
<th></th>
<th>Set by</th>
<th>Cleared by</th>
</tr>
</thead>
<tbody>
<tr>
<td>6</td>
<td>Timeout of Timer 1</td>
<td>Reading Timer 1 Low-Order Counter or writing T1 High-Order Latch</td>
</tr>
<tr>
<td>5</td>
<td>Timeout of Timer 2</td>
<td>Reading Timer 2 Low-Order Counter or writing T2 High-Order Counter</td>
</tr>
<tr>
<td>4</td>
<td>Active transition of the signal on CB1</td>
<td>Reading from or writing to I/O Port B</td>
</tr>
<tr>
<td>3</td>
<td>Active transition of the signal on CB2 (input mode)</td>
<td>Reading from or writing to I/O Port B in input mode only</td>
</tr>
<tr>
<td>2</td>
<td>Completion of eight shifts</td>
<td>Reading or writing the Shift register</td>
</tr>
<tr>
<td>1</td>
<td>Active transition of the signal on CA1</td>
<td>Reading from or writing to I/O Port A using address 00012</td>
</tr>
<tr>
<td>0</td>
<td>Active transition of the signal on CA2 (input mode)</td>
<td>Reading from or writing to I/O Port A Output register (ORA) using address 00012 in input mode only</td>
</tr>
</tbody>
</table>

WRITING INTERRUPT-DRIVEN CODE

The 6502 microprocessor responds to an interrupt (either a nonmaskable interrupt, a maskable interrupt that is enabled, or a BRK instruction) as follows:

- By saving the program counter (more significant byte first) and the status register in the stack in the order shown in Figure 1-12. Note that the status register ends up on top of the program counter; the sequence PHP, JSR would produce the opposite order. The program counter value here is the address of the next instruction; there is no offset of 1 as there is with JSR.
  - By disabling the maskable interrupt by setting the I flag in the status register.
  - By fetching a destination address from a specified pair of memory addresses (see Table 1-16) and placing that destination in the program counter.

Thus, the programmer should consider the following guidelines when writing interrupt-driven code for the 6502:

- The accumulator and index registers must be saved and restored explicitly if the service routine changes them. Only the status register is saved automatically.
The service routine must save the accumulator before it saves the index registers, since it can only transfer an index register to the stack via the accumulator. Typical saving and restoring sequences are

- **PHA** ;SAVE ACCUMULATOR IN STACK
- **TXA** ;SAVE INDEX REGISTER X
- **PHA**
- **TYA** ;SAVE INDEX REGISTER Y
- **PHA**
- **PLA** ;RESTORE INDEX REGISTER Y
- **TAY**
- **PLA** ;RESTORE INDEX REGISTER X
- **TAX**
- **PLA** ;RESTORE ACCUMULATOR FROM STACK

The order of the index registers does not matter, as long as the saving and restoring orders are opposites.

- The interrupt need not be reenabled explicitly, since the RTI (Return from Interrupt) instruction restores the old status register as part of its execution. This restores the original state of the Interrupt Disable flag. If you wish to return with interrupts disabled, you can set the Interrupt Disable flag in the stack with the sequence

- **PLA** ;GET STATUS REGISTER
- **ORA** #$00000100 ;DISABLE INTERRUPT IN STACK
- **PHA** ;PUT STATUS REGISTER BACK IN STACK
Table 1-16: Interrupt Vectors for the 6502 Microprocessor

<table>
<thead>
<tr>
<th>Source</th>
<th>Address Used (Hexadecimal)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Interrupt Request (IRQ) and BRK Instruction</td>
<td>FFFE and FFFF</td>
</tr>
<tr>
<td>Reset (RESET)</td>
<td>FFFC and FFFD</td>
</tr>
<tr>
<td>Nonmaskable Interrupt (NMI)</td>
<td>FFFA and FFFB</td>
</tr>
</tbody>
</table>

The addresses are stored in the usual 6502 fashion with the less significant byte at the lower address.

Note the convenience here of having the status register at the top, rather than underneath the return address.

- If you have code that the processor must execute with interrupts disabled, you can use SEI (Set Interrupt Disable) to disable maskable interrupts and CLI (Clear Interrupt Disable) to enable them afterward. If the section of code could be entered with interrupts either disabled or enabled, you must be sure to restore the original state of the Interrupt Disable flag. That is, you must save and restore the status register as follows:

  ```
  PHP ;SAVE OLD INTERRUPT DISABLE
  SEI ;DISABLE INTERRUPTS
  ... CODE THAT MUST BE EXECUTED WITH INTERRUPTS DISABLED ...
  PLP ;RESTORE OLD INTERRUPT DISABLE
  ```

  The alternative (automatically reenabling the interrupts at the end) would cause a problem if the section were entered with the interrupts already disabled.

- If you want to allow the user to select the actual starting address of the service routine, place an indirect jump at the vectored address. That is, the routine starting at the vectored address is simply

  ```
  JMP (USRINT) ;GO TO USER-SPECIFIED ADDRESS
  ```

This procedure increases the interrupt response time by the execution time of an indirect jump (five clock cycles).

- You must remember to save and restore incidental information that is essential for the proper execution of the interrupted program. Such incidental information may include memory locations on page 0, priority registers (particularly if they are write-only), and other status.

- To achieve general reentrancy, you must use the stack for all temporary storage beyond that provided by the registers. As we noted in the discussion of
parameter passing, you can assign space on the stack (NPARAM bytes) with the sequence

\[
\begin{align*}
&\text{TSX} & ; \text{MOVE S OVER TO A} \\
&\text{TXA} \\
&\text{SEC} & ; \text{ASSIGN NPARAM EMPTY BYTES} \\
&\text{SBC} & \#\text{NPARAM} & ; \text{A GENERAL WAY TO ADJUST SP} \\
&\text{TAX} \\
&\text{TXS}
\end{align*}
\]

Later, you can remove the temporary storage area with the sequence

\[
\begin{align*}
&\text{TSX} & ; \text{MOVE S OVER TO A} \\
&\text{TXA} \\
&\text{CLC} \\
&\text{ADC} & \#\text{NPARAM} & ; \text{REMOVE NPARAM EMPTY BYTES} \\
&\text{TAX} \\
&\text{TXS}
\end{align*}
\]

If NPARAM is only 1 or 2, you can replace these sequences with the appropriate number of push and pull instructions in which the data is ignored.

- The service routine should initialize the Decimal Mode flag with either CLD or SED if it uses ADC or SBC instructions. The old value of that flag is saved and restored automatically as part of the status register, but the service routine should not assume a particular value on entry.

**MAKING PROGRAMS RUN FASTER**

- In general, you can make a program run substantially faster by first determining where it is spending its time. This requires that you determine which loops (other than delay routines) the processor is executing most often. Reducing the execution time of a frequently executed loop will have a major effect because of the multiplying factor. It is thus critical to determine how often instructions are being executed and to work on loops in the order of their frequency of execution.

Once you have determined which loops the processor executes most frequently, you can reduce their execution time with the following techniques:

- Eliminate redundant operations. These may include a constant that is being added during each iteration or a special case that is being tested for repeatedly. It may also include a constant value or a memory address that is being fetched each time rather than being stored in a register or used indirectly.

- Use page 0 for temporary data storage whenever possible.

- Reorganize the loop to reduce the number of jump instructions. You can often eliminate branches by changing the initial conditions, reversing the order of
operations, or combining operations. In particular, you may find it helpful to start everything back one step, thus making the first iteration the same as all the others. Reversing the order of operations can be helpful if numerical comparisons are involved, since the equality case may not have to be handled separately. Reorganization may also allow you to combine condition checking inside the loop with the overall loop control.

- Work backward through arrays rather than forward. This allows you to count the index register down to 0 and use the setting of the Zero flag as an exit condition. No explicit comparison is then necessary. Note that you will have to subtract 1 from the base addresses, since 1 is the smallest index that is actually used.

- Increment 16-bit counters and indirect addresses rather than decrementing them. 16-bit numbers are easy to increment, since you can tell if a carry has occurred by checking the less significant byte for 0 afterward. In the case of a decrement, you must check for 0 first.

- Use in-line code rather than subroutines. This will save at least a JSR instruction and an RTS instruction.

- Watch the special uses of the index registers to avoid having to move data between them. The only register that can be used in indirect indexed addressing is register Y; the only register that can be used in indexed indirect addressing or in loading and storing the stack pointer is register X.

- Use the instructions ASL, DEC, INC, LSR, ROL, and ROR to operate directly on data in memory without moving it to a register.

- Use the BIT instruction to test bits 6 or 7 of a memory location without loading the accumulator.

- Use the CPX and CPY instructions to perform comparisons without using the accumulator.

A general way to reduce execution time is to replace long sequences of instructions with tables. A single table lookup can perform the same operation as a sequence of instructions if there are no special exits or program logic involved. The cost is extra memory, but that may be justified if the memory is readily available. If enough memory is available, a lookup table may be a reasonable approach even if many of its entries are repetitive — even if many inputs produce the same output. In addition to its speed, table lookup is easy to program, easy to change, and highly flexible.
MAKING PROGRAMS USE LESS MEMORY

You can make a program use significantly less memory only by identifying common sequences of instructions and replacing those sequences with subroutine calls. The result is a single copy of each sequence. The more instructions you can place in subroutines, the more memory you save. The drawbacks of this approach are that JSR and RTS themselves require memory and take time to execute, and that the subroutines are typically not very general and may be difficult to understand or use. Some sequences of instructions may even be implemented as subroutines in a monitor or in other systems programs that are always resident. Then you can replace those sequences with calls to the systems program as long as the return is handled properly.

Some of the methods that reduce execution time also reduce memory usage. In particular, using page 0, reorganizing loops, working backward through arrays, incrementing 16-bit quantities, operating directly on memory, and using special instructions such as CPX, CPY, and BIT reduce both execution time and memory usage. Of course, using in-line code rather than loops and subroutines reduces execution time but increases memory usage.

Lookup tables generally use extra memory but save execution time. Some ways that you can reduce their memory requirements are by eliminating intermediate values and interpolating the results, eliminating redundant values with special tests, and reducing the range of input values. Often you will find that a few prior tests or restrictions will greatly reduce the size of the required table.

REFERENCES


4. Ibid.

6. Ibid.


Two hobby magazines run many articles on 6502 assembly language programming; they are Compute (P.O. Box 5406, Greensboro, NC 27403) and Micro (P.O. Box 6502, Chelmsford, MA 01824).
Chapter 2  Implementing Additional Instructions And Addressing Modes

This chapter shows how to implement instructions and addressing modes that are not included in the 6502's instruction set. Of course, no instruction set can ever include all possible combinations. Designers must make choices based on how many operation codes are available, how easily an additional combination could be implemented, and how often it would be used. A description of additional instructions and addressing modes does not imply that the basic instruction set is incomplete or poorly designed.

We concentrate our attention on additional instructions and addressing modes that are

- Obvious parallels to those included in the instruction set
- Described in the draft Microprocessor Assembly Language Standard (IEEE Task P694)
- Discussed in Volume 1 of An Introduction to Microcomputers¹
- Implemented on other microprocessors, especially ones that are closely related or partly compatible.² ³

This chapter should be of particular interest to those who are familiar with the assembly languages of other computers.

INSTRUCTION SET EXTENSIONS

In describing extensions to the instruction set, we follow the organization suggested in the draft standard for IEEE Task P694.⁴ We divide instructions into the following groups (listed in the order in which they are discussed): arithmetic, logical, data transfer, branch, skip, subroutine call, subroutine return, and miscellaneous. Within each type of instruction, we discuss operand types in the
following order: byte (8-bit), word (16-bit), decimal, bit, nibble or digit, and multiple. In describing addressing modes, we use the following order: direct, indirect, immediate, indexed, register, autopreincrement, autopostincrement, autopredecrement, autopostdecrement, indirect preindexed (also called preindexed or indexed indirect), and indirect postindexed (also called postindexed or indirect indexed).

ARITHMETIC INSTRUCTIONS

In this group, we consider addition, addition with carry, subtraction, subtraction in reverse, subtraction with carry (borrow), increment, decrement, multiplication, division, comparison, two's complement (negate), and extension. Instructions that do not obviously fall into a particular category are repeated for convenience.

Addition Instructions
(Without Carry)

1. Add memory location ADDR to accumulator.
   
   \[ \text{CLC} \quad ; \text{CLEAR CARRY} \]
   \[ \text{ADC} \quad \text{ADDR} \quad ; (A) = (A) + (ADDR) \]
   
   The same approach works for all addressing modes.

2. Add VALUE to accumulator.
   
   \[ \text{CLC} \quad ; \text{CLEAR CARRY} \]
   \[ \text{ADC} \quad \#\text{VALUE} \quad ; (A) = (A) + \text{VALUE} \]

3. Add Carry to accumulator.
   
   \[ \text{ADC} \quad \#0 \quad ; (A) = (A) + 0 + \text{CARRY} \]

4. Decimal add memory location ADDR to accumulator.
   
   \[ \text{SED} \quad ; \text{ENTER DECIMAL MODE} \]
   \[ \text{CLC} \quad ; \text{CLEAR CARRY} \]
   \[ \text{ADC} \quad \text{ADDR} \quad ; (A) = (A) + (ADDR) \text{ IN DECIMAL} \]
   \[ \text{CLD} \quad ; \text{LEAVE DECIMAL MODE} \]

   A more general approach restores the original value of the D flag; that is,

   \[ \text{PHP} \quad ; \text{SAVE OLD D FLAG} \]
   \[ \text{SED} \quad ; \text{ENTER DECIMAL MODE} \]
   \[ \text{CLC} \quad ; \text{CLEAR CARRY} \]
   \[ \text{ADC} \quad \text{ADDR} \quad ; (A) = (A) + (ADDR) \text{ IN DECIMAL} \]
   \[ \text{PLP} \quad ; \text{RESTORE OLD D FLAG} \]
Note that restoring the status register destroys the carry from the addition.

5. Decimal add VALUE to accumulator.

```
SED ; ENTER DECIMAL MODE
CLC ; CLEAR CARRY
ADC #VALUE ; (A) = (A) + VALUE IN DECIMAL
CLD ; LEAVE DECIMAL MODE
```

6. Decimal add Carry to accumulator.

```
SED ; ENTER DECIMAL MODE
ADC #0 ; (A) = (A) + CARRY IN DECIMAL
CLD ; LEAVE DECIMAL MODE
```

7. Add index register to accumulator (using memory location ZPAGE).

```
STX ZPAGE ; SAVE INDEX REGISTER ON PAGE ZERO
CLC ; CLEAR CARRY
ADC ZPAGE ; (A) = (A) + (X)
```

This approach works for index register Y also.

8. Add the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) to memory locations SUM and SUM+1 (MSB in SUM+1).

```
CLC ; CLEAR CARRY
LDA SUM
ADC ADDR ; ADD LSB'S
STA SUM
LDA SUM+1 ; ADD MSB'S WITH CARRY
ADC ADDR+1
STA SUM+1
```

9. Add 16-bit number VAL16 (VAL16M more significant byte, VAL16L less significant byte) to memory locations SUM and SUM+1 (MSB in SUM+1).

```
CLC ; CLEAR CARRY
LDA SUM ; ADD LSB'S WITHOUT CARRY
ADC #VAL16L
STA SUM
LDA SUM+1 ; ADD MSB'S WITH CARRY
ADC #VAL16
STA SUM+1
```

**Addition Instructions (With Carry)**

1. Add Carry to accumulator

```
ADC #0 ; (A) = (A) + CARRY
```
2. Decimal add VALUE to accumulator with Carry.

```
SED           ;ENTER DECIMAL MODE
ADC #VALUE   ;(A) = (A) + VALUE + CARRY IN DECIMAL
CLD           ;LEAVE DECIMAL MODE
```

3. Decimal add memory location ADDR to accumulator with Carry.

```
SED           ;ENTER DECIMAL MODE
ADC ADDR      ;(A) = (A) + (ADDR) + CARRY IN DECIMAL
CLD           ;LEAVE DECIMAL MODE
```

4. Add the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) to memory locations SUM and SUM+1 (MSB in SUM+1) with Carry.

```
LDA SUM       ;ADD LSB'S WITH CARRY
ADC ADDR      
STA SUM       
LDA SUM+1     ;ADD MSB'S WITH CARRY
ADC ADDR+1    
STA SUM+1     
```

5. Add 16-bit number VAL16 (VAL16M more significant byte, VAL16L less significant byte) to memory locations SUM and SUM+1 (MSB in SUM+1) with Carry.

```
LDA SUM       ;ADD LSB'S WITH CARRY
ADC VAL16L    
STA SUM       
LDA SUM+1     ;ADD MSB'S WITH CARRY
ADC ADDR+1    
STA SUM+1     
```

**Subtraction Instructions**

(Without Borrow)

1. Subtract memory location ADDR from accumulator.

```
SEC           ;SET INVERTED BORROW
SBC ADDR      ;(A) = (A) - (ADDR)
```

The Carry flag acts as an inverted borrow, so it must be set to 1 if its value is to have no effect on the subtraction.

2. Subtract VALUE from accumulator.

```
SEC           ;SET INVERTED BORROW
SBC #VALUE    ;(A) = (A) - VALUE
```

3. Subtract inverse of borrow from accumulator.

```
SBC #0         ;(A) = (A) - (1-CARRY)
```
The result is \((A) - 1\) if Carry is 0 and \((A)\) if Carry is 1.

4. Decimal subtract memory location ADDR from accumulator.

\[
\begin{align*}
\text{SED} & ; \text{ENTER DECIMAL MODE} \\
\text{SEC} & ; \text{SET INVERTED BORROW} \\
\text{SBC} & \text{ ADDR} \quad ; (A) = (A) - (ADDR) \text{ IN DECIMAL} \\
\text{CLD} & ; \text{LEAVE DECIMAL MODE}
\end{align*}
\]

The Carry flag has the same meaning in the decimal mode as in the binary mode.

5. Decimal subtract VALUE from accumulator.

\[
\begin{align*}
\text{SED} & ; \text{ENTER DECIMAL MODE} \\
\text{SEC} & ; \text{SET INVERTED BORROW} \\
\text{SBC} & \#\text{VALUE} \quad ; (A) = (A) - \text{VALUE} \text{ IN DECIMAL} \\
\text{CLD} & ; \text{LEAVE DECIMAL MODE}
\end{align*}
\]

6. Subtract the contents of memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) from memory locations DIFF and DIFF + 1 (MSB in DIFF + 1).

\[
\begin{align*}
\text{LDA} & \text{ DIFF} \quad ; \text{SUBTRACT LSB'S WITH NO BORROW} \\
\text{SEC} & \text{ SBC} \text{ ADDR} \\
\text{STA} & \text{ DIFF} \\
\text{LDA} & \text{ DIFF} + 1 \\
\text{SBC} & \text{ ADDR} + 1 \\
\text{STA} & \text{ DIFF} + 1
\end{align*}
\]

7. Subtract 16-bit number VAL16 (VAL16M more significant byte, VAL16L less significant byte) from memory locations DIFF and DIFF + 1 (MSB in DIFF + 1).

\[
\begin{align*}
\text{LDA} & \text{ DIFF} \quad ; \text{SUBTRACT LSB'S WITH NO BORROW} \\
\text{SEC} & \text{ SBC} \#\text{VAL16L} \\
\text{STA} & \text{ DIFF} \\
\text{LDA} & \text{ DIFF} + 1 \\
\text{SBC} & \#\text{VAL16M} \\
\text{STA} & \text{ DIFF} + 1
\end{align*}
\]

8. Decimal subtract inverse of borrow from accumulator.

\[
\begin{align*}
\text{SED} & ; \text{ENTER DECIMAL MODE} \\
\text{SBC} & \#0 \quad ; (A) = (A) - (1\text{-CARRY}) \text{ IN DECIMAL} \\
\text{CLD} & ; \text{LEAVE DECIMAL MODE}
\end{align*}
\]
Subtraction in Reverse Instructions

1. Subtract accumulator from VALUE and place difference in accumulator.

   \begin{align*}
   \text{EOR} & \quad \#$FF \quad ; \text{ONE'S COMPLEMENT A} \\
   \text{CLC} & \quad \text{ADC} \quad \#1 \quad ; \text{TWO'S COMPLEMENT A} \\
   \text{CLC} & \quad \text{ADC} \quad \#\text{VALUE} \quad ; \text{FORM } -A + \text{VALUE} \\
   \text{or} & \\
   \text{STA} & \quad \text{TEMP} \quad ; \text{SAVE A TEMPORARILY} \\
   \text{LDA} & \quad \#\text{VALUE} \quad ; \text{FORM VALUE } - A \\
   \text{SEC} & \quad \text{SBC} \quad \text{TEMP} \\
   \end{align*}

The Carry acts as an inverted borrow in either method; that is, the Carry is set to 1 if no borrow is necessary.

2. Subtract accumulator from the contents of memory location ADDR and place difference in accumulator.

   \begin{align*}
   \text{EOR} & \quad \#$FF \quad ; \text{ONE'S COMPLEMENT A} \\
   \text{CLC} & \quad \text{ADC} \quad \#1 \quad ; \text{TWO'S COMPLEMENT A} \\
   \text{CLC} & \quad \text{ADC} \quad \text{ADDR} \quad ; \text{FORM } -A + (\text{ADDR}) \\
   \text{STA} & \quad \text{TEMP} \quad ; \text{SAVE A TEMPORARILY} \\
   \text{LDA} & \quad \text{ADDR} \quad ; \text{FORM (ADDR) } - A \\
   \text{SEC} & \quad \text{SBC} \quad \text{TEMP} \\
   \end{align*}

3. Decimal subtract accumulator from VALUE and place difference in accumulator.

   \begin{align*}
   \text{SED} & \quad ; \text{ENTER DECIMAL MODE} \\
   \text{STA} & \quad \text{TEMP} \quad ; \text{FORM VALUE } - A \\
   \text{LDA} & \quad \#\text{VALUE} \\
   \text{SEC} & \quad \text{SBC} \quad \text{TEMP} \quad ; \text{LEAVE DECIMAL MODE} \\
   \text{CLD} & \\
   \end{align*}

4. Decimal subtract accumulator from the contents of memory location ADDR and place difference in accumulator.

   \begin{align*}
   \text{SED} & \quad ; \text{ENTER DECIMAL MODE} \\
   \text{STA} & \quad \text{TEMP} \quad ; \text{FORM (ADDR) } - A \\
   \text{LDA} & \quad \text{ADDR} \\
   \text{SEC} & \quad \text{SBC} \quad \text{TEMP} \quad ; \text{LEAVE DECIMAL MODE} \\
   \text{CLD} & \\
   \end{align*}
Subtraction with Borrow (Carry) Instructions

1. Subtract inverse of borrow from accumulator.
   
   \[
   \text{SBC } \#0 \quad ;(A) = (A) - (1-CARRY) \]

2. Decimal subtract VALUE from accumulator with borrow.
   
   \[
   \text{SED} \quad \text{ENTER DECIMAL MODE} \\
   \text{SBC } \#\text{VALUE} \quad ;(A) = (A) - \text{VALUE} - \text{BORROW IN DECIMAL} \\
   \text{CLD} \quad \text{LEAVE DECIMAL MODE} 
   \]

3. Decimal subtract memory location ADDR from accumulator with borrow.
   
   \[
   \text{SED} \quad \text{ENTER DECIMAL MODE} \\
   \text{SBC } \text{ADDR} \quad ;(A) = (A) - \text{VALUE} - \text{BORROW IN DECIMAL} \\
   \text{CLD} \quad \text{LEAVE DECIMAL MODE} 
   \]

4. Subtract the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) from memory locations DIFF and DIFF+1 (MSB in DIFF+1) with borrow.
   
   \[
   \text{LDA DIFF} \quad ;\text{SUBTRACT LSB'S WITH BORROW} \\
   \text{SBC ADDR} \\
   \text{STA DIFF} \\
   \text{LDA DIFF+1} \quad ;\text{SUBTRACT MSB'S WITH BORROW} \\
   \text{SBC ADDR+1} \\
   \text{STA DIFF+1} 
   \]

5. Subtract 16-bit number VAL16 (VAL16M more significant byte, VAL16L less significant byte) from memory locations DIFF and DIFF+1 (MSB in DIFF+1) with borrow.
   
   \[
   \text{LDA DIFF} \quad ;\text{SUBTRACT LSB'S WITH BORROW} \\
   \text{SBC VAL16L} \\
   \text{STA DIFF} \\
   \text{LDA DIFF+1} \quad ;\text{SUBTRACT MSB'S WITH BORROW} \\
   \text{SBC VAL16M} \\
   \text{STA DIFF+1} 
   \]

Increment Instructions

1. Increment accumulator, setting the Carry flag if the result is zero.
   
   \[
   \text{CLC} \quad ;\text{CLEAR CARRY} \\
   \text{ADC } \#1 \quad ;\text{INCREMENT BY ADDING 1} \\
   \]

   or

   \[
   \text{SEC} \quad ;\text{SET CARRY} \\
   \text{ADC } \#0 \quad ;\text{INCREMENT BY ADDING 1} 
   \]
2. Increment accumulator without affecting the Carry flag.

```
TAX       ;MOVE A TO X
INX       ;INCREMENT X
TXA
```

INX does not affect the Carry flag; it does, however, affect the Zero flag.

3. Increment stack pointer.

```
TSX       ;MOVE S TO X
INX       ;THEN INCREMENT X AND RETURN VALUE
TXS
```
or
```
TAX       ;SAVE A
PLA       ;INCREMENT STACK POINTER
TXA       ;RESTORE A
```

Remember that PLA affects the Zero and Negative flags.

4. Decimal increment accumulator (add 1 to A in decimal).

```
SED       ;ENTER DECIMAL MODE
CLC
ADC      #1 ;(A) = (A) + 1 DECIMAL
CLD
```

Remember that INC and DEC produce binary results even when the D flag is set.

5. Increment contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1).

```
INC       ADDR       ;INCREMENT LSB
BNE DONE
INC ADDR+1 ;CARRY TO MSB IF LSB GOES TO ZERO
DONE NOP
```
or
```
LDA ADDR       ;INCREMENT LSB
CLC
ADC #1
STA ADDR
LDA ADDR+1     ;WITH CARRY TO MSB
ADC #0
STA ADDR+1
```

The first alternative is clearly much shorter.

6. Decimal increment contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1).

```
SED       ;ENTER DECIMAL MODE
LDA ADDR       ;ADD 1 TO LSB
CLC
ADC #1
```
INC produces a binary result even when the Decimal Mode flag is set. Note that we could eliminate the BCC instruction from the program without affecting the result, but the change would increase the average execution time.

**Decrement Instructions**

1. Decrement accumulator, clearing the Carry flag if the result is \( \text{FF}_{16} \).
   - SEC
   - SBC \#1
   - SBC \#0
   - CLC
   - SBC \#0
   - ADC \#FF

2. Decrement accumulator without affecting the Carry flag.
   - TAX
   - DEX
   - TXA

   DEX does not affect the Carry flag; it does, however, affect the Zero flag.

3. Decrement stack pointer.
   - TSX
   - DEX
   - TXS

   You can also decrement the stack pointer with PHA or PHP, neither of which affects any flags.

4. Decimal decrement accumulator (subtract 1 from \( A \) in decimal).
   - SED
   - SEC
   - SBC \#1
   - CLD

5. Decrement contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1).
Decrementing a 16-bit number is significantly more difficult than incrementing one. In fact, incrementing is not only faster but also leaves the accumulator unchanged; of course, one could replace LDA with LDX, LDY, or the sequence INC, DEC. An alternative that uses no registers is

```
INC ADDR ; IS LSB ZERO?
DEC ADDR
BNE DECLSB ; YES, BORROW FROM MSB
DECLSB DEC ADDR ; BEFORE DECREMENTING LSB
```

6. Decimal decrement contents of memory locations ADDR and ADDR + 1 (MSB in ADDR + 1).

```
SED
LDA ADDR
SEC
SBC #1
STA ADDR
BCS DONE
LDA ADDR+1
SBC #0
STA ADDR+1
DONE CLD ; LEAVE DECIMAL MODE
```

DEC produces a binary result even when the Decimal Mode flag is set. Note that we could eliminate the BCS instruction from the program without affecting the result, but the change would increase the average execution time.

**Multiplication Instructions**

1. Multiply accumulator by 2.

```
ASL A ; MULTIPLY BY SHIFTING LEFT
```

The following version places the Carry (if any) in Y.

```
LDY #0 ;_ASSUME MSB = 0
ASL A ; MULTIPLY BY SHIFTING LEFT
BCC DONE
INY
DONE NOP ; AND MOVING CARRY TO Y
```

2. Multiply accumulator by 3 (using ADDR for temporary storage).
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STA ADDR ;SAVE A
ASL A ;2 X A
ADC ADDR ;3 X A

ASL A ;2 X A
ASL A ;4 X A

We can easily extend cases 1, 2, and 3 to multiplication by other small integers.

4. Multiply an index register by 2.
TAX ;MOVE TO A
ASL A ;MULTIPLY BY SHIFTING LEFT
TXA ;RETURN RESULT

5. Multiply the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) by 2.
ASL ADDR ;MULTIPLY BY SHIFTING LEFT
ROL ADDR+1 ;AND MOVING CARRY OVER TO MSB

6. Multiply the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) by 4.
ASL ADDR ;MULTIPLY BY SHIFTING LEFT
ROL ADDR+1 ;AND MOVING CARRY OVER TO MSB
ASL ADDR ;THEN MULTIPLY AGAIN
ROL ADDR+1

Eventually, of course, moving one byte to the accumulator, shifting the accumulator, and storing the result back in memory becomes faster than leaving both bytes in memory.

Division Instructions

1. Divide accumulator by 2 unsigned.
LSR A ;DIVIDE BY SHIFTING RIGHT

2. Divide accumulator by 4 unsigned.
LSR A ;DIVIDE BY SHIFTING RIGHT
LSR A

3. Divide accumulator by 2 signed.
TAX ;SAVE ACCUMULATOR
ASL A ;MOVE SIGN TO CARRY
TXA ;RESTORE ACCUMULATOR
ROR A ;SHIFT RIGHT BUT PRESERVE SIGN
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The second instruction moves the original sign bit (bit 7) to the Carry flag, so the final rotate can preserve it. This is known as an arithmetic shift, since it preserves the sign of the number while reducing its magnitude. The fact that the sign bit is copied to the right is known as sign extension.

4. Divide the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) by 2 unsigned.

```
LSR ADDR+1 ;DIVIDE BY SHIFTING RIGHT
ROR ADDR ;AND MOVING CARRY OVER TO LSB
```

5. Divide the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) by 2 signed.

```
LDA ADDR+1 ;MOVE SIGN TO CARRY
ASL A
ROR ADDR+1 ;DIVIDE BY SHIFTING RIGHT WITH SIGN
ROR ADDR ;AND MOVING CARRY OVER TO LSB
```

**Comparison Instructions**

1. Compare VALUE with accumulator bit by bit, setting each bit position that is different.

```
EOR #VALUE
```

Remember, the EXCLUSIVE OR of two bits is 1, if and only if the two bits are different.

2. Compare memory locations ADR1 and ADR1+1 (MSB in ADR1+1) with memory locations ADR2 and ADR2+1 (MSB in ADR2+1). Set Carry if the first operand is greater than or equal to the second one (that is, if ADR1 and ADR1+1 contain a 16-bit unsigned number greater than or equal to the contents of ADR2 and ADR2+1). Clear Carry otherwise. Set the Zero flag if the two operands are equal and clear it otherwise.

```
LDA ADR1+1 ;COMPARE MSB'S
CMP ADR2+1
BCC DONE ;CLEAR CARRY, ZERO IF 2ND IS LARGER
BNE DONE ;SET CARRY, CLEAR ZERO IF 1ST LARGER
LDA ADR1 ;IF MSB'S EQUAL, COMPARE LSB'S
CMP ADR2 ;CLEAR CARRY IF 2ND IS LARGER
DONE NOP
```

3. Compare memory locations ADR1 and ADR1+1 (MSB in ADR1+1) with the 16-bit number VAL16 (VAL16M more significant byte, VAL16L less significant byte). Set Carry if the contents of ADR1 and ADR1+1 are greater than or
equal to VAL16 in the unsigned sense. Clear Carry otherwise. Set the Zero flag if
the contents of ADR1 and ADR1+1 are equal to VAL16, and clear it otherwise.

LDA ADR1+1 ;COMPARE MSB'S
CMP #VAL16M
BCC DONE ;CLEAR CARRY, ZERO IF VAL16 LARGER
BNE DONE ;SET CARRY, CLEAR ZERO IF DATA LARGER
LDA ADR1 ;IF MSB'S EQUAL, COMPARE LSB'S
CMP #VAL16L ;CLEAR CARRY IF VAL16 LARGER
DONE NOP

4. Compare memory locations ADR1 and ADR1+1 (MSB in ADR1+1) with
memory locations ADR2 and ADR2+1 (MSB in ADR2+1). Set Carry if the
first operand is greater than or equal to the second one in the unsigned sense.

LDA ADR1 ;COMPARE LSB'S
CMP ADR2
LDA ADR1+1 ;SUBTRACT MSB'S WITH BORROW
SBC ADR2+1

We use SBC on the more significant bytes in order to include the borrow from the
less significant bytes. This sequence destroys the value in A and sets the Zero flag
only from the final subtraction.

5. Compare memory locations ADR1 and ADR1+1 (MSB in ADR1+1) with
the 16-bit number VAL16 (VAL16M more significant byte, VAL16L less signifi-
cant byte). Set Carry if the contents of ADR1 and ADR1+1 are greater than or
equal to VAL16 in the unsigned sense.

LDA ADR1 ;COMPARE LSB'S
CMP VAL16L
LDA ADR1+1 ;SUBTRACT MSB'S WITH BORROW
SBC VAL16M

If you want to set the Carry if the contents of ADR1 and ADR1+1 are greater
than VAL16, perform the comparison with VAL16+1.

6. Compare stack pointer with the contents of memory location ADDR. Set
Carry if the stack pointer is greater than or equal to the contents of the memory
location in the unsigned sense. Clear Carry otherwise. Set the Zero flag if the two
values are equal and clear it otherwise.

TSX ;MOVE STACK POINTER TO X
CPX ADDR ;AND THEN COMPARE

7. Compare stack pointer with the 8-bit number VALUE. Set Carry if the
stack pointer is greater than or equal to VALUE in the unsigned sense. Clear
Carry otherwise. Set the Zero flag if the two values are equal and clear it other-
wise.

TSX ;MOVE STACK POINTER TO X
CPX #VALUE ;AND THEN COMPARE
8. Block comparison. Compare accumulator with memory bytes starting at address BASE and continuing until either a match is found (indicated by Carry = 1) or until a byte counter in memory location COUNT reaches zero (indicated by Carry = 0).

```
LDY COUNT ; GET COUNT
BEQ NOTFND ; EXIT IF COUNT IS ZERO
LDX #0 ; START INDEX AT ZERO
CMPBYT CMP BASE,X ; CHECK CURRENT BYTE
BEQ DONE ; DONE IF MATCH FOUND (CARRY = 1)
INX ; OTHERWISE, PROCEED TO NEXT BYTE
DEY
BNE CMPBYT ; IF ANY ARE LEFT
NOTFND CLC ; OTHERWISE, EXIT CLEARING CARRY
DONE NOP
```

Remember, comparing two equal numbers sets the Carry flag.

### Two’s Complement (Negate) Instructions

1. Negate accumulator.

```
EOR #$FF ; ONE’S COMPLEMENT
CLC
ADC #1 ; TWO’S COMPLEMENT
```

The two’s complement is the one’s complement plus 1.

```
STA TEMP ; ALTERNATIVE IS 0 - (A)
LDA #0
SEC
SBC TEMP
```

2. Negate memory location ADDR.

```
LDA #0 ; FORM 0 - (ADDR)
SEC
SBC ADDR
STA ADDR
```

3. Negate memory locations ADDR and ADDR + 1 (MSB in ADDR + 1).

```
LDA ADDR ; ONE’S COMPLEMENT LSB
EOR #$FF
CLC
ADC #1
STA ADDR
LDA ADDR+1 ; ONE’S COMPLEMENT MSB
EOR #$FF
ADC #0 ; ADD CARRY FOR TWO’S COMPLEMENT
STA ADDR+1
```
or

```
LDA  #0 ; FORM 0 - (ADDR+1) (ADDR)
SEC  
SBC  ADDR  ; SUBTRACT LSB'S WITHOUT BORROW
STA  ADDR
LDA  #0  ; SUBTRACT MSB'S WITH BORROW
SBC  ADDR+1
STA  ADDR+1
```

4. Nine's complement accumulator (that is, replace A with $99-A$).

```
STA  TEMP  ; FORM 99-A
LDA  #$99
SEC  
SBC  TEMP
```

There is no need to bother with the decimal mode, since $99-A$ is always a valid BCD number if A originally contained a valid BCD number.

5. Ten's complement accumulator (that is, replace A with $100-A$).

```
SED  ; ENTER DECIMAL MODE
STA  TEMP  ; FORM 100-A
LDA  #0
SEC  
SBC  TEMP
CLD  ; LEAVE DECIMAL MODE
```

**Extend Instructions**

1. Extend accumulator to a 16-bit unsigned number in memory locations ADDR and ADDR + 1 (MSB in ADDR + 1).

```
STA  ADDR  ; 8-BIT MOVE
LDA  #0  ; EXTEND TO 16 BITS WITH 0'S
STA  ADDR+1
```

2. Extend accumulator to a 16-bit signed number in memory locations ADDR and ADDR + 1 (MSB in ADDR + 1).

```
STA  ADDR  ; 8-BIT MOVE
ASL  A  ; MOVE SIGN BIT TO CARRY
LDA  #$FF  ; (A) = -1 + SIGN BIT
ADC  #0
EOR  #$FF  ; (A) = -SIGN BIT
STA  ADDR+1  ; SET MSB TO -SIGN BIT
```

The result of the calculation is $-(-1+\text{SIGN BIT})-1=-\text{SIGN BIT}$. That is, $(\text{ADDR}+1) = 00$ if $A$ was positive and $\text{FF}_{16}$ if $A$ was negative. An alternative is
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STA ADDR ; 8-BIT MOVE
LDX #$FF ; (X) = -1
ASL A
BCS STRSGN
INX ; (X) = -1 + (1 - SIGN BIT) = -SIGN BIT
STRSGN STX ADDR+1 ; SET MSB TO -SIGN BIT

3. Extend bit 0 of accumulator across entire accumulator; that is, (A) = 00 if bit 0 = 0 and FF₁₆ if bit 0 = 1.

LSR A ; CARRY = BIT 0
LDA #$FF ; (A) = -1 + BIT 0
ADC #0
EOR #$FF ; (A) = -BIT 0

As in case 2, the result we want is −1 if the specified bit is 1 and 0 if the specified bit is 0. That is, we want the negative of the original bit value. The sequence LDA #$FF, ADC #0 obviously produces the result −1+Carry. The one’s complement then gives us the negative of what we had minus 1 (or 1−Carry−1 = −Carry).

4. Sign function. Replace the value in the accumulator by 00 if it is positive and by FF₁₆ if it is negative.

ASL A ; MOVE SIGN BIT TO CARRY
LDA #$FF ; (A) = -1 + SIGN BIT
ADC #0
EOR #$FF ; (A) = -SIGN BIT

5. Sign function of a memory location. Set accumulator to 00 if memory location ADDR is positive and to FF₁₆ if it is negative.

LDX #$FF ; ASSUME NEGATIVE
LDA ADDR ; IS (ADDR) POSITIVE?
BMI DONE
INX ; YES, SET SIGN TO ZERO
DONE TXA

The approach shown in case 4 can also be used.

LOGICAL INSTRUCTIONS

In this group, we consider logical AND, logical OR, logical EXCLUSIVE OR, logical NOT (complement), shift, rotate, and test instructions.

Logical AND Instructions

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AND #MASK ; CLEAR BIT BY MASKING

MASK has 0 bits in the positions to be cleared and 1 bits in the positions that are to be left unchanged. For example,

AND #111011011 ; CLEAR BITS 2 AND 5

Remember, logically ANDing a bit with 1 leaves it unchanged.

2. Bit test-set the flags according to the value of a bit of memory location ADDR.

   Bits 0 through 5
   
   LDA #MASK
   BIT ADDR ; TEST BIT OF ADDR

   MASK should have a 1 in the position to be tested and 0s everywhere else. The Zero flag will be set to 1 if the bit tested is 0 and to 0 if the bit tested is 1.

   Bits 6 or 7
   
   BIT ADDR ; TEST BITS 6 AND 7 OF ADDR

   This single instruction sets the Negative flag to bit 7 of ADDR and the Overflow flag to bit 6 of ADDR, regardless of the value in the accumulator. Note that the flags are not inverted as the Zero flag is in normal masking.

3. Logical AND immediate with condition codes (flags). Logically AND a byte of immediate data with the contents of the status register, clearing those flags that are logically ANDed with 0s. This instruction is implemented on the 6809 microprocessor.

   PHP ; MOVE STATUS TO A
   PLA
   AND #MASK ; CLEAR FLAGS
   PHA ; RETURN RESULT TO STATUS
   PLP

Logical OR Instructions

1. Set bit of accumulator.

   ORA #MASK ; SET BIT BY MASKING

MASK has 1 bits in the positions to be set and 0 bits in the positions that are to be left unchanged. For example,

   ORA #00010010 ; SET BITS 1 AND 4
Remember, logically ORing a bit with 0 leaves it unchanged.

2. Test memory locations ADDR and ADDR+1 for 0. Set the Zero flag if both bytes are 0.

\[ \text{LDA ADDR, TEST 16-BIT NUMBER FOR ZERO} \]
\[ \text{ORA ADDR+1} \]

The Zero flag is set if and only if both bytes of the 16-bit number are 0. The other flags are also changed.

3. Logical OR immediate with condition codes (flags). Logically OR a byte of immediate data (MASK) with the contents of the status register, setting those flags that are logically ORed with 1s. This instruction is implemented on the 6809 microprocessor.

\[ \text{PHP, MOVE STATUS TO A} \]
\[ \text{PLA} \]
\[ \text{ORA #MASK, SET FLAGS} \]
\[ \text{PHA, RETURN RESULT TO STATUS} \]

### Logical EXCLUSIVE OR Instructions

1. Complement bit of accumulator.

\[ \text{EOR #MASK, COMPLEMENT BIT BY MASKING} \]

MASK has 1 bits in the positions to be complemented and 0 bits in the positions that are to be left unchanged. For example,

\[ \text{EOR #11000000, COMPLEMENT BITS 6 AND 7} \]

Remember, logically EXCLUSIVE ORing a bit with 0 leaves it unchanged.

2. Complement accumulator, setting flags.

\[ \text{EOR #11111111, COMPLEMENT ACCUMULATOR} \]

Logically EXCLUSIVE ORing the accumulator with all 1s inverts all the bits.

3. Compare memory location ADDR with accumulator bit by bit, setting each bit position that is different.

\[ \text{EOR ADDR, BIT-BY-BIT COMPARISON} \]

The EXCLUSIVE OR function is the same as a "not equal" function. Note that the Negative (Sign) flag is 1 if the two operands have different values in bit position 7.
4. Add memory location ADDR to accumulator logically (i.e., without any carries between bit positions).

\[
\text{EOR ADDR ; LOGICAL ADDITION}
\]

The EXCLUSIVE OR function is also the same as a bit by bit sum with no carries. Logical sums are often used to form checksums and error-detecting or error-correcting codes.

**Logical NOT instructions**

1. Complement accumulator, setting flags.

\[
\text{EOR #$FF ; COMPLEMENT ACCUMULATOR}
\]

Logically EXCLUSIVE ORing with all 1s inverts all the bits.

2. Complement bit of accumulator.

\[
\text{EOR #MASK ; COMPLEMENT BIT BY MASKING}
\]

MASK has 1 bits in the positions to be complemented and 0 bits in the positions that are to be left unchanged. For example,

\[
\text{EOR %#01010001 ; COMPLEMENT BITS 0, 4, AND 6}
\]

Remember, logically EXCLUSIVE ORing a bit with 0 leaves it unchanged.

3. Complement a memory location.

\[
\text{LDA ADDR}
\text{EOR #$FF ; COMPLEMENT}
\text{STA ADDR}
\]

4. Complement bit 0 of a memory location.

\[
\text{INC ADDR ; COMPLEMENT BY INCREMENTING}
\]

or

\[
\text{DEC ADDR ; COMPLEMENT BY DECREMENTING}
\]

Either of these instructions may, of course, affect the other bits in the memory location. The final value of bit 0, however, will surely be 0 if it was originally 1 and 1 if it was originally 0.

5. Complement digit of accumulator.

- Less significant digit

\[
\text{EOR %#00001111 ; COMPLEMENT LESS SIGNIFICANT 4 BITS}
\]

- More significant digit

\[
\text{EOR %#11110000 ; COMPLEMENT MORE SIGNIFICANT 4 BITS}
\]
These procedures are useful if the accumulator contains a decimal digit in negative logic (e.g., the input from a typical ten-position rotary or thumbwheel switch).

6. Complement Carry flag.

\[
\begin{align*}
\text{ROR} & \quad A & \text{; MOVE CARRY TO BIT 7 OF A} \\
\text{EOR} & \quad \#\text{FF} & \text{; COMPLEMENT ALL OF A} \\
\text{ROL} & \quad A & \text{; MOVE COMPLEMENTED CARRY BACK}
\end{align*}
\]

Other combinations such as ROL, EOR, ROR, or ROR, EOR, ASL will work just as well. We could leave the accumulator intact by saving it in the stack originally and restoring it afterward.

An alternative that does not affect the accumulator is

\[
\begin{align*}
\text{BCC} & \quad \text{SETCAR} & \text{; CLEAR CARRY IF IT WAS SET} \\
\text{CLC} & \quad \text{DONE} & \text{; SET CARRY IF IT WAS CLEARED}
\end{align*}
\]

**Shift Instructions**

1. Shift accumulator right arithmetically, preserving the sign bit.

\[
\begin{align*}
\text{TAX} & \quad \text{; SAVE ACCUMULATOR} \\
\text{ASL} & \quad A & \text{; MOVE SIGN BIT TO CARRY} \\
\text{TXA} & \quad \text{; SHIFT RIGHT, PRESERVING SIGN}
\end{align*}
\]

We need a copy of the sign bit for an arithmetic shift. Of course, we could use a memory location for temporary storage instead of the index register.

2. Shift memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) left logically.

\[
\begin{align*}
\text{ASL} & \quad \text{ADDR} & \text{; SHIFT LSB LEFT LOGICALLY} \\
\text{ROL} & \quad \text{ADDR+1} & \text{; AND MOVE CARRY OVER TO MSB}
\end{align*}
\]

The key point here is that we must shift the more significant byte circularly (i.e., rotate it). The first 8-bit shift moves one bit (the least significant bit for a right shift and the most significant bit for a left shift) to the Carry. The 8-bit rotate then moves that bit from the Carry into the other half of the word.

3. Shift memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) right logically.

\[
\begin{align*}
\text{LSR} & \quad \text{ADDR+1} & \text{; SHIFT MSB RIGHT LOGICALLY} \\
\text{ROR} & \quad \text{ADDR} & \text{; AND MOVE CARRY OVER TO LSB}
\end{align*}
\]
4. Shift memory locations ADDR and ADDR+1 (MSB in ADDR+1) right arithmetically.

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LDA ADDR+1</td>
<td>MOVE SIGN BIT TO CARRY</td>
</tr>
<tr>
<td>ASL A</td>
<td>SHIFT MSB RIGHT ARITHMETICALLY</td>
</tr>
<tr>
<td>ROR ADDR+1</td>
<td>AND MOVE CARRY OVER TO LSB</td>
</tr>
<tr>
<td>ROR ADDR</td>
<td></td>
</tr>
</tbody>
</table>

5. Digit shift memory locations ADDR and ADDR+1 (MSB in ADDR+1) left; that is, shift the 16-bit number left 4 bits logically.

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LDX #4</td>
<td>NUMBER OF SHIFTS = 4</td>
</tr>
<tr>
<td>LDA ADDR</td>
<td>MOVE LSB TO A</td>
</tr>
<tr>
<td>SHFT1 ASL A</td>
<td>SHIFT LSB LEFT LOGICALLY</td>
</tr>
<tr>
<td>ROL ADDR+1</td>
<td>AND MOVE CARRY OVER TO MSB</td>
</tr>
<tr>
<td>DEX</td>
<td></td>
</tr>
<tr>
<td>BNE SHFT1</td>
<td>COUNT BITS</td>
</tr>
<tr>
<td>STA ADDR</td>
<td>RETURN LSB TO ADDR</td>
</tr>
</tbody>
</table>

A shorter but slower version that does not use the accumulator is

<table>
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</tr>
</thead>
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<tr>
<td>LDX #4</td>
<td>NUMBER OF SHIFTS = 4</td>
</tr>
<tr>
<td>SHFT1 ASL ADDR</td>
<td>SHIFT LSB LEFT LOGICALLY</td>
</tr>
<tr>
<td>ROL ADDR+1</td>
<td>AND MOVE CARRY OVER TO MSB</td>
</tr>
<tr>
<td>DEX</td>
<td></td>
</tr>
<tr>
<td>BNE SHFT1</td>
<td>COUNT SHIFTS</td>
</tr>
<tr>
<td>STA ADDR</td>
<td>RETURN LSB TO ADDR</td>
</tr>
</tbody>
</table>

6. Digit shift memory locations ADDR and ADDR+1 (MSB in ADDR+1) right; that is, shift the 16-bit number right 4 bits logically.

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<tbody>
<tr>
<td>LDX #4</td>
<td>NUMBER OF SHIFTS = 4</td>
</tr>
<tr>
<td>LDA ADDR</td>
<td>MOVE LSB TO A</td>
</tr>
<tr>
<td>SHFT1 LSR ADDR+1</td>
<td>SHIFT MSB RIGHT LOGICALLY</td>
</tr>
<tr>
<td>ROR A</td>
<td>AND MOVE CARRY OVER TO LSB</td>
</tr>
<tr>
<td>DEX</td>
<td></td>
</tr>
<tr>
<td>BNE SHFT1</td>
<td>COUNT SHIFTS</td>
</tr>
<tr>
<td>STA ADDR</td>
<td>RETURN LSB TO ADDR</td>
</tr>
</tbody>
</table>

A shorter but slower version that does not use the accumulator is

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LDX #4</td>
<td>NUMBER OF SHIFTS = 4</td>
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<td>SHFT1 LSR ADDR+1</td>
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</tr>
<tr>
<td>DEX</td>
<td></td>
</tr>
<tr>
<td>BNE SHFT1</td>
<td>COUNT SHIFTS</td>
</tr>
</tbody>
</table>

7. Normalize memory locations ADDR and ADDR+1 (MSB in ADDR+1); that is, shift the 16-bit number left until the most significant bit is 1. Do not shift at all if the entire number is 0.

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LDA ADDR+1</td>
<td>EXIT IF NUMBER ALREADY NORMALIZED</td>
</tr>
<tr>
<td>BMI DONE</td>
<td></td>
</tr>
<tr>
<td>ORA ADDR</td>
<td>OR IF ENTIRE NUMBER IS ZERO</td>
</tr>
<tr>
<td>BEQ DONE</td>
<td></td>
</tr>
<tr>
<td>LDA ADDR</td>
<td>MOVE LSB TO A</td>
</tr>
</tbody>
</table>
**Rotate Instructions**

A rotate through or with Carry acts as if the data were arranged in a circle with its least significant bit connected to its most significant bit through the Carry flag. A rotate without Carry differs in that it acts as if the least significant bit of the data were connected directly to the most significant bit.

1. Rotate memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) right 1 bit position through Carry.

   - `ROR ADDR+1` ; ROTATE BIT 8 TO CARRY
   - `ROR ADDR` ; AND ON IN TO BIT 7

2. Rotate memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) right 1 bit position without Carry.

   - `LDA ADDR` ; CAPTURE BIT 0 IN CARRY
   - `ROR A` ; ROTATE MSB WITH BIT 0 ENTERING AT LEFT
   - `ROR ADDR+1` ; ROTATE LSB
   - `ROR ADDR` ; AND ON IN TO BIT 7

3. Rotate memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) left 1 bit position through Carry.

   - `ROL ADDR` ; ROTATE BIT 7 TO CARRY
   - `ROL ADDR+1` ; AND ON IN TO BIT 8

4. Rotate memory locations ADDR and ADDR + 1 (MSB in ADDR + 1) left 1 bit position without Carry.

   - `LDA ADDR+1` ; CAPTURE BIT 15 IN CARRY
   - `ROL A` ; ROTATE LSB WITH BIT 15 ENTERING AT RIGHT
   - `ROL ADDR` ; MOVE AND SET FLAGS
   - `ROL ADDR+1` ; MOVE AND SET FLAGS

**Test Instructions**

1. Test accumulator. Set flags according to the value in the accumulator without changing that value.

   - `TAX` ; MOVE AND SET FLAGS
   - `TAY` ; MOVE AND SET FLAGS
The following alternative does not affect either index register.

```
CMP #0 ;TEST ACCUMULATOR
```

The instructions AND #$FF or ORA #0 would also do the job without affecting the Carry (CMP #0 sets the Carry flag).

2. **Test index register.** Set flags according to the value in an index register without changing that value.

```
CPX #0 ;CHECK VALUE IN INDEX REGISTER
```

3. **Test memory location.** Set flags according to the value in memory location ADDR without changing that value.

```
INC ADDR ;CHECK VALUE IN MEMORY LOCATION
DEC ADDR
```

4. **Test a pair of memory locations.** Set the Zero flag according to the value in memory locations ADDR and ADDR+1.

```
LDA ADDR ;TEST 16-BIT NUMBER FOR ZERO
ORA ADDR+1
```

This sequence sets the Zero flag to 1 if and only if both bytes of the 16-bit number are 0. This procedure can readily be extended to handle numbers of any length.

5. **Test bit of accumulator.**

```
AND #MASK ;TEST BIT BY MASKING
```

MASK has a 1 bit in the position to be tested and 0 bits elsewhere. The instruction sets the Zero flag to 1 if the tested bit position contains 0 and to 0 if the tested bit position contains 1. For example,

```
AND #%00001000 ;TEST BIT 3 BY MASKING
```

The result is 0 if bit 3 of A is 0 and 00001000 (binary) if bit 3 of A is 1. So the Zero flag ends up containing the logical complement of bit 3.

6. **Compare memory location ADDR with accumulator bit by bit.** Set each each bit position that is different.

```
EOR ADDR ;BIT-BY-BIT COMPARISON
```

The EXCLUSIVE OR function is the same as a “not equal” function.

## DATA TRANSFER INSTRUCTIONS

In this group, we consider load, store, move, exchange, clear, and set instructions.
Load Instructions

1. Load accumulator indirect from address in memory locations PGZRO and PGZRO+1.

   LDY #0 ;AVOID INDEXING
   LDA (PGZRO),Y ;LOAD INDIRECT INDEXED

   The only instruction that has true indirect addressing is JMP. However, you can produce ordinary indirect addressing by using the postindexed (indirect indexed) addressing mode with index register Y set to 0.

   An alternative approach is to clear index register X and use preindexing.

   LDX #0 ;AVOID INDEXING
   LDA (PGZRO),X ;LOAD INDEXED INDIRECT

   The advantage of the first approach is that one can index from the indirect address with Y. For example, we could load addresses POINTL and POINTH indirectly from the address in memory locations PGZRO and PGZRO+1 as follows:

   LDY #0 ;AVOID INDEXING
   LDA (PGZRO),Y ;GET LSB OF ADDRESS INDIRECTLY
   STA POINTL
   INY ;GET MSB OF ADDRESS INDIRECTLY
   LDA (PGZRO),Y
   STA POINTH

2. Load index register X indirect from address in memory locations PGZRO and PGZRO+1.

   LDY #0 ;AVOID INDEXING
   LDA (PGZRO),Y ;LOAD ACCUMULATOR INDIRECT INDEXED
   TAX

   Only the accumulator can be loaded using the indirect modes, but its contents can be transferred easily to an index register.

3. Load index register Y indirect from address in memory locations PGZRO and PGZRO+1.

   LDX #0 ;AVOID INDEXING
   LDA (PGZRO),X ;LOAD ACCUMULATOR INDEXED INDIRECT
   TAY

4. Load stack pointer immediate with the 8-bit number VALUE.

   LDX #VALUE ;INITIALIZE STACK POINTER
   TXS

   Only index register X can be transferred to or from the stack pointer.

5. Load stack pointer direct from memory location ADDR.

   LDX ADDR ;INITIALIZE STACK POINTER
   TXS
6. Load status register immediate with the 8-bit number VALUE.

```
LDA  #$VALUE ;GET THE VALUE
PHA    ;TRANSFER IT THROUGH STACK
PLP
```

This procedure allows the user of a computer system to initialize the status register for debugging or testing purposes.

7. Load status register direct from memory location ADDR.

```
LDA ADDR       ;GET THE INITIAL VALUE
PHA    ;TRANSFER IT THROUGH STACK
PLP
```

8. Load index register from stack.

```
PLA    ;TRANSFER STACK TO X THROUGH A
TAX
```

If you are restoring values from the stack, you must restore X and Y before A, since there is no direct path from the stack to X or Y.

9. Load memory locations PGZRO and PGZRO+1 (a pointer on page 0) with ADDR (ADDRH more significant byte, ADDRL less significant byte).

```
LDA  #$ADDRL ;INITIALIZE LSB
STA  PGZRO
LDA  #$ADDRH ;INITIALIZE MSB
STA  PGZRO+1
```

There is no simple way to initialize the indirect addresses that must be saved on page 0.

**Store Instructions**

1. Store accumulator indirect at address in memory locations PGZRO and PGZRO+1.

```
LDY  #0 ;AVOID INDEXING
STA  (PGZRO),Y ;STORE INDIRECT INDEXED
```

or

```
LDX  #0 ;AVOID INDEXING
STA  (PGZRO,X) ;STORE INDEXED INDIRECT
```

2. Store index register X indirect at address in memory locations PGZRO and PGZRO+1.

```
LDY  #0 ;AVOID INDEXING
TXA ;STORE X INDIRECT INDEXED THROUGH A
STA  (PGZRO),Y
```

3. Store index register Y indirect at address in memory locations PGZRO and PGZRO+1.
LDX #0 ;AVOID INDEXING
TYA ;STORE Y INDEXED INDIRECT THROUGH A
STA (PGZRO, X)

4. Store stack pointer in memory location ADDR.
TSX ;STORE S THROUGH X
STX ADDR

5. Store status register in memory location ADDR.
PHP ;STORE P THROUGH STACK AND A
PLA
STA ADDR

TXA ;STORE X (OR Y) IN STACK VIA A
PHA

If you are saving values in the stack, you must save A before X or Y, since there is no direct path from X or Y to the stack.

Move Instructions

1. Transfer accumulator to status register.
PHA ;TRANSFER THROUGH STACK
PLP

2. Transfer status register to accumulator.
PHP ;TRANSFER THROUGH STACK
PLA

3. Transfer index register X to index register Y.
TXA
TAY

or without changing the accumulator
STX TEMP ;TRANSFER THROUGH MEMORY
LDY TEMP

4. Transfer accumulator to stack pointer.
TAX ;TRANSFER THROUGH X REGISTER
TXS

5. Transfer stack pointer to accumulator.
TSX ;TRANSFER THROUGH X REGISTER
TXA
6. Move the contents of memory locations ADDR and ADDR+1 (MSB in ADDR+1) to the program counter.

\[
\text{JMP (ADDR)} \quad ; \text{JUMP INDIRECT}
\]

Note that JMP with indirect addressing loads the program counter with the contents of memory locations ADDR and ADDR+1; it acts more like LDA with direct addressing than like LDA with indirect (indexed) addressing.

7. Block move. Transfer data from addresses starting at the one in memory locations SORCE and SORCE+1 (on page 0) to addresses starting at the one in memory locations DEST and DEST+1 (on page 0). Register Y contains the number of bytes to be transferred.

\[
\text{MOVBYT DEY} \quad ; \text{TEST NUMBER OF BYTES}
\]
\[
\text{LDA (SORCE), Y} \quad ; \text{GET A BYTE FROM SOURCE}
\]
\[
\text{STA (DEST), Y} \quad ; \text{MOVE TO DESTINATION}
\]
\[
\text{TYA BNE MOVBYT} \quad ; \text{COUNT BYTES}
\]

We assume here that the addresses do not overlap and that the initial value of Y is 1 or greater. Chapter 5 contains a more general block move.

The program becomes simpler if we reduce the base addresses by 1. That is, let memory locations SORCE and SORCE+1 contain an address one less than the lowest address in the source area, and let memory locations DEST and DEST+1 contain an address one less than the lowest address in the destination area. Now we can exit when Y is decremented to 0.

\[
\text{MOVBYT LDA (SORCE), Y} \quad ; \text{GET A BYTE FROM SOURCE}
\]
\[
\text{STA (DEST), Y} \quad ; \text{MOVE BYTE TO DESTINATION}
\]
\[
\text{DEY BNE MOVBYT} \quad ; \text{COUNT BYTES}
\]

The 0 index value is never used.

8. Move multiple (fill). Place the contents of the accumulator in memory locations starting at the one in memory locations PGZRO and PGZRO+1.

\[
\text{FILBYT DEY} \quad ; \text{FILL}
\]
\[
\text{STA (PGZRO), Y} \quad ; \text{FILL A BYTE}
\]
\[
\text{INY} \quad \text{DEY} \quad \text{FILBYT} \quad ; \text{COUNT BYTES}
\]

Chapter 5 contains a more general version.

Here again we can simplify the program by letting memory locations PGZRO and PGZRO+1 contain an address one less than the lowest address in the area to be filled. The revised program is

\[
\text{FILBYT STA (PGZRO), Y} \quad ; \text{FILL A BYTE}
\]
\[
\text{DEY BNE FILBYT} \quad ; \text{COUNT BYTES}
\]
Exchange Instructions

1. Exchange index registers X and Y.

   STX    TEMP       ;SAVE X
   TYA          ;Y TO X
   TAX
   LDY    TEMP       ;X TO Y
   or

   TXA          ;SAVE X
   PHA
   TYA          ;Y TO X
   TAX
   PLA
   TXA          ;SAVE X
   TYA
   TAX
   PLA
   TAY

Both versions take the same number of bytes (assuming TEMP is on page 0). The second version is slower but reentrant.

2. Exchange memory locations ADDR1 and ADDR2.

   LDA    ADDR1
   LDX    ADDR2
   STX    ADDR1
   STA    ADDR2

3. Exchange accumulator and top of stack.

   TAY          ;SAVE A
   PLA          ;GET TOP OF STACK
   TAX          ;SAVE TOP OF STACK
   TYA          ;A TO TOP OF STACK
   PHA
   TXA          ;TOP OF STACK TO A

Clear Instructions

1. Clear the accumulator.

   LDA    #0

The 6502 treats 0 like any other number. There are no special clear instructions.

2. Clear an index register.

   LDX    #0
   or

   LDY    #0

3. Clear memory location ADDR.

   LDA    #0
   STA    ADDR
Obviously, we could use X or Y as easily as A.


```asm
LDA #0
STA ADDR
STA ADDR+1
```

5. Clear bit of accumulator.

```asm
AND #MASK ;CLEAR BIT BY MASKING
```

MASK has 0 bits in the positions to be cleared and 1 bits in the positions that are to be left unchanged. For example,

```asm
AND #10111110 ;CLEAR BITS 0 AND 6 OF A
```

Logically ANDing a bit with 1 leaves it unchanged.

### Set Instructions

1. Set the accumulator to FF\(_{16}\) (all ones in binary).

```asm
LDA #$FF
```

2. Set an index register to FF\(_{16}\).

```asm
LDX #$FF
```

or

```asm
LDY #$FF
```

3. Set the stack pointer to FF\(_{16}\).

```asm
LDX #$FF
TXS
```

The next available location in the stack is at address 01FF\(_{16}\).

4. Set a memory location to FF\(_{16}\).

```asm
LDA #$FF
STA ADDR
```

5. Set bit of accumulator.

```asm
ORA #MASK ;SET BIT BY MASKING
```

MASK has 1 bits in the positions to be set and 0 bits elsewhere. For example,

```asm
ORA #$10000000 ;SET BIT 7 (SIGN BIT)
```

Logically ORing a bit with 0 leaves it unchanged.
BRANCH (JUMP) INSTRUCTIONS

Unconditional Branch Instructions

1. Unconditional branch relative to DEST.
   
   \[
   \begin{align*}
   &\text{CLC} \\
   &\text{BCC }\text{DEST ;DELIBERATELY CLEAR CARRY} \\
   &\text{BCC }\text{DEST ;FORCE AN UNCONDITIONAL BRANCH}
   \end{align*}
   \]

   You can always force an unconditional branch by branching conditionally on a condition that is known to be true. Some obvious alternatives are

   \[
   \begin{align*}
   &\text{SEC} \\
   &\text{BCS }\text{DEST}
   \end{align*}
   \]

   or

   \[
   \begin{align*}
   &\text{LDA }\#0 \\
   &\text{BEQ }\text{DEST}
   \end{align*}
   \]

   or

   \[
   \begin{align*}
   &\text{LDA }\#1 \\
   &\text{BNE }\text{DEST}
   \end{align*}
   \]

2. Jump indirect to address at the top of the stack.
   
   \[
   \text{RTS}
   \]

   RTS is just an ordinary indirect jump in which the processor obtains the destination from the top of the stack. Be careful, however, of the fact that the processor adds 1 to the address before proceeding.

3. Jump indexed, assuming that the base of the address table is BASE and the index is in memory location INDEX. The addresses are arranged in the usual 6502 manner with the less significant byte first.\(^5\)

   - Using indirect addressing:

   \[
   \begin{align*}
   &\text{LDA INDEX} \\
   &\text{ASL A} ;\text{DOUBLE INDEX FOR 2-BYTE ENTRIES} \\
   &\text{TAX} \\
   &\text{LDA BASE,X} ;\text{GET LSB OF DESTINATION} \\
   &\text{STA INDIR} \\
   &\text{INX} \\
   &\text{LDA BASE,X} ;\text{GET MSB OF DESTINATION} \\
   &\text{STA INDIR+1} \\
   &\text{JMP (INDIR) ;JUMP INDIRECT TO DESTINATION}
   \end{align*}
   \]

   - Using the stack:

   \[
   \begin{align*}
   &\text{LDA INDEX} \\
   &\text{ASL A} ;\text{DOUBLE INDEX FOR 2-BYTE ENTRIES} \\
   &\text{TAX} \\
   &\text{LDA BASE+1,X} ;\text{GET MSB OF DESTINATION} \\
   &\text{PHA}
   \end{align*}
   \]
LDABASE,X ;GET LSB OF DESTINATION
PHA
RTS ;JUMP INDIRECT TO DESTINATION OFFSET 1

The second approach is faster but less straightforward. Note the following:

1. You must store the more significant byte first since the stack is growing toward lower addresses. Thus the bytes end up in their usual order.

2. Since RTS adds 1 to the program counter after loading it from the stack, the table entries must all be 1 less than the actual destination addresses for this method to work correctly.

3. Documentation is essential, since this method uses RTS for the rather surprising purpose of transferring control to a subroutine, rather than from it. The mnemonic may confuse the reader, but it obviously does not bother the microprocessor.

Conditional Branch Instructions

1. Branch if zero.
   · Branch if accumulator contains zero.

   TAX DEST ;TEST ACCUMULATOR
   BEQ DEST

   or

   CMP #0 ;TEST ACCUMULATOR
   BEQ DEST

   Either AND #$FF or ORA #0 will set the Zero flag if (A) = 0 without affecting the Carry flag (CMP #0 sets Carry).

   · Branch if an index register contains 0.

   CPX #0 ;TEST INDEX REGISTER
   BEQ DEST

   The instruction TXA or the sequence INX, DEX can be used to test the contents of index register X without affecting the Carry flag (CPX #0 sets the Carry). TXA, of course, changes the accumulator.

   · Branch if a memory location contains 0.

   INC ADDR ;TEST MEMORY LOCATION
   DEC ADDR
   BEQ DEST

   or

   LDA ADDR ;TEST MEMORY LOCATION
   BEQ DEST
• Branch if a pair of memory locations (ADDR and ADDR+1) both contain 0.

\[
\text{LDA} \quad \text{ADDR} \quad \text{;TEST 16-BIT NUMBER FOR ZERO} \\
\text{ORA} \quad \text{ADDR+1} \\
\text{BEQ} \quad \text{DEST}
\]

• Branch if a bit of the accumulator is zero.

\[
\text{AND} \quad \#\text{MASK} \quad \text{;TEST BIT OF ACCUMULATOR} \\
\text{BEQ} \quad \text{DEST}
\]

MASK has a 1 bit in the position to be tested and 0s elsewhere. Note the inversion here; if the bit of the accumulator is a 0, the result is 0 and the Zero flag is set to 1. Special cases are

- Bit position 7
  \[
  \text{ASL} \quad \text{A} \quad \text{;MOVE BIT 7 TO CARRY} \\
  \text{BCC} \quad \text{DEST}
  \]

- Bit position 6
  \[
  \text{ASL} \quad \text{A} \quad \text{;MOVE BIT 6 TO NEGATIVE FLAG} \\
  \text{BPL} \quad \text{DEST}
  \]

- Bit position 0
  \[
  \text{LSR} \quad \text{A} \quad \text{;MOVE BIT 0 TO CARRY} \\
  \text{BCC} \quad \text{DEST}
  \]

• Branch if a bit of a memory location is 0.

\[
\text{LDA} \quad \#\text{MASK} \\
\text{BIT} \quad \text{ADDR} \quad \text{;TEST BIT OF MEMORY} \\
\text{BEQ} \quad \text{DEST}
\]

MASK has a 1 bit in the position to be tested and 0s elsewhere. Special cases are

- Bit position 7
  \[
  \text{BIT} \quad \text{ADDR} \quad \text{;TEST MEMORY} \\
  \text{BPL} \quad \text{DEST} \quad \text{;BRANCH ON BIT 7}
  \]

- Bit position 6
  \[
  \text{BIT} \quad \text{ADDR} \quad \text{;TEST MEMORY} \\
  \text{BVC} \quad \text{DEST} \quad \text{;BRANCH ON BIT 6}
  \]

The BIT instruction sets the Negative flag from bit 7 of the memory location and the Overflow flag from bit 6, regardless of the contents of the accumulator.

We can also use the shift instructions to test the bits at the ends, as long as we can tolerate changes in the memory locations.

- Bit position 7
  \[
  \text{ASL} \quad \text{ADDR} \quad \text{;TEST BIT 7} \\
  \text{BCC} \quad \text{DEST}
  \]

- Bit position 6
  \[
  \text{ASL} \quad \text{ADDR} \quad \text{;TEST BIT 6} \\
  \text{BPL} \quad \text{DEST}
  \]
Bit position 0

LSR ADDR ; TEST BIT 0
BCC DEST

- Branch if the Interrupt Disable flag (bit 2 of the status register) is 0.

PHP ; MOVE STATUS TO A
PLA
AND #$00000100 ; TEST INTERRUPT DISABLE
BEQ DEST ; BRANCH IF INTERRUPTS ARE ON

- Branch if the Decimal Mode flag (bit 3 of the status register) is 0.

PHP ; MOVE STATUS TO A
PLA
AND #$00001000 ; TEST DEcimal MODE FLAG
BEQ DEST ; BRANCH IF MODE IS BINARY

2. Branch if not 0.

- Branch if accumulator does not contain 0.

TAX ; TEST ACCUMULATOR
BNE DEST

or

CMP #0 ; TEST ACCUMULATOR
BNE DEST

- Branch if an index register does not contain 0.

CPX #0 ; TEST INDEX REGISTER
BNE DEST

- Branch if a memory location does not contain 0.

INC ADDR ; TEST MEMORY LOCATION
DEC ADDR
BNE DEST

or

LDA ADDR ; TEST MEMORY LOCATION
BNE DEST

- Branch if a pair of memory locations (ADDR and ADDR+1) do not both contain 0.

LDA ADDR ; TEST 16-BIT NUMBER FOR ZERO
ORA ADDR+1
BNE DEST

- Branch if a bit of the accumulator is 1.

AND #$MASK ; TEST BIT OF ACCUMULATOR
BNE DEST
MASK has a 1 bit in the position to be tested and 0s elsewhere. Note the inversion here; if the bit of the accumulator is a 1, the result is not 0 and the Zero flag is set to 0. Special cases are

**Bit position 7**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>A</td>
<td>DEST</td>
<td>;MOVE BIT 7 TO CARRY</td>
</tr>
<tr>
<td>BCS</td>
<td>DEST</td>
<td></td>
<td>;AND TEST CARRY</td>
</tr>
</tbody>
</table>

**Bit position 6**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>A</td>
<td>DEST</td>
<td>;MOVE BIT 6 TO SIGN</td>
</tr>
<tr>
<td>BMI</td>
<td>DEST</td>
<td></td>
<td>;AND TEST SIGN</td>
</tr>
</tbody>
</table>

**Bit position 0**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>LSR</td>
<td>A</td>
<td>DEST</td>
<td>;MOVE BIT 0 TO CARRY</td>
</tr>
<tr>
<td>BCS</td>
<td>DEST</td>
<td></td>
<td>;AND TEST CARRY</td>
</tr>
</tbody>
</table>

- Branch if a bit of a memory location is 1.

```
LDA  #MASK
BIT  ADDR
BNE  DEST
;jTEST BIT OF MEMORY
```

MASK has a 1 bit in the position to be tested and 0s elsewhere. Special cases are

**Bit position 7**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>BIT</td>
<td>ADDR</td>
<td></td>
<td>;TEST BIT 7 OF MEMORY</td>
</tr>
<tr>
<td>BMI</td>
<td>DEST</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Bit position 6**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>BIT</td>
<td>ADDR</td>
<td></td>
<td>;TEST BIT 6 OF MEMORY</td>
</tr>
<tr>
<td>BVS</td>
<td>DEST</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The BIT instruction sets the Negative flag from bit 7 of the memory location and the Overflow flag from bit 6, regardless of the contents of the accumulator.

We can also use the shift instructions to test the bits at the ends, as long as we can tolerate changes in the memory locations.

**Bit position 7**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>ADDR</td>
<td>DEST</td>
<td>;TEST BIT 7 OF MEMORY</td>
</tr>
</tbody>
</table>

This alternative is slower than BIT by 2 clock cycles, since it must write the result back into memory.

**Bit position 6**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASL</td>
<td>ADDR</td>
<td>DEST</td>
<td>;TEST BIT 6 OF MEMORY</td>
</tr>
<tr>
<td>BMI</td>
<td>DEST</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Bit position 0**

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Register</th>
<th>Destination</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>LSR</td>
<td>ADDR</td>
<td>DEST</td>
<td>;TEST BIT 0 OF MEMORY</td>
</tr>
<tr>
<td>BCS</td>
<td>DEST</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
• Branch if the Interrupt Disable flag (bit 2 of the status register) is 1.
  PHP
  PLA
  AND #$00000100
  BNE DEST
  ; TEST INTERRUPT DISABLE
  ; BRANCH IF INTERRUPTS ARE DISABLED

• Branch if the Decimal Mode flag (bit 3 of the status register) is 1.
  PHP
  PLA
  AND #$0001000
  BNE DEST
  ; TEST DECIMAL MODE FLAG
  ; BRANCH IF MODE IS DECIMAL

3. Branch if Equal.
   • Branch if \( A = VALUE \).
     CMP #VALUE
     BEQ DEST
     ; COMPARE BY SUBTRACTING
   • Branch if \( X = VALUE \).
     CPX #VALUE
     BEQ DEST
     ; COMPARE BY SUBTRACTING

   Two special cases are
   Branch if \( X = 1 \)
     DEX
     BEQ DEST

   Branch if \( X = FF_{16} \).
     INX
     BEQ DEST

   • Branch if \( A = (ADDR) \).
     CMP ADDR
     BEQ DEST
     ; COMPARE BY SUBTRACTING
   • Branch if \( X = (ADDR) \).
     CPX ADDR
     BEQ DEST
     ; COMPARE BY SUBTRACTING

   Branch if the contents of memory locations PGZRO and PGZRO + 1 equal
   VAL16 (VAL16L less significant byte, VAL16M more significant byte).
   LDA PGZRO+1
   CMP #VAL16M
   BNE DONE
   LDA PGZRO
   CMP #VAL16L
   BNE DEST
   DONE NOP
   ; COMPARE MSB'S
   ; AND LSB'S ONLY IF NECESSARY

   Branch if the contents of memory locations PGZRO and PGZRO + 1 equal
   those of memory locations LIML and LIMH.
LDA PGZRO+1 ;COMPARE MSB'S
CMP LIMH
BNE DONE
LDA PGZRO ;AND LSB'S ONLY IF NECESSARY
CMP LIML
BEQ DEST
DONE NOP

Note: Neither of the next two sequences should be used to test for stack overflow or underflow, since intervening instructions (for example, a single JSR or RTS) could change the stack pointer by more than 1.

- Branch if (S) = VALUE.
  TSX #VALUE ;CHECK IF STACK IS AT LIMIT
  CPX DEST
  BEQ DEST

- Branch if (S) = (ADDR).
  TSX #VALUE ;CHECK IF STACK IS AT LIMIT
  CPX ADDR
  BEQ DEST

4. Branch if Not Equal.
- Branch if (A) ≠ VALUE.
  CMP #VALUE ;COMPARE BY SUBTRACTING
  BNE DEST

- Branch if (X) ≠ VALUE.
  CPX #VALUE ;COMPARE BY SUBTRACTING
  BNE DEST

Two special cases are
- Branch if (X) ≠ 1.
  DEX BNE DEST

- Branch if (X) ≠ FF16.
  INX BNE DEST

- Branch if (A) ≠ (ADDR).
  CMP ADDR ;COMPARE BY SUBTRACTING
  BNE DEST

- Branch if (X) ≠ (ADDR).
  CPX ADDR ;COMPARE BY SUBTRACTING
  BNE DEST

- Branch if the contents of memory locations PGZRO and PGZRO+1 are not equal to VAL16 (VAL16L less significant byte, VAL16M more significant byte).
• Branch if the contents of memory locations PGZRO and PGZRO + 1 are not equal to those of memory locations LIML and LIMH.

Note: Neither of the next two sequences should be used to test for stack overflow or underflow, since intervening instructions (for example, a single JSR or RTS) could change the stack pointer by more than 1.

• Branch if (S) ≠ VALUE.

  TSX ; CHECK IF STACK IS AT LIMIT
  CPX #VALUE
  BNE DEST

• Branch if (S) ≠ (ADDR).

  TSX ; CHECK IF STACK IS AT LIMIT
  CPX ADDR
  BNE DEST

5. Branch if Positive.

• Branch if contents of accumulator are positive.

  TAX ; TEST ACCUMULATOR
  BPL DEST

or

  CMP #0 ; TEST ACCUMULATOR
  BPL DEST

• Branch if contents of index register X are positive.

  TXA ; TEST REGISTER X
  BPL DEST

or

  CPX #0 ; TEST INDEX REGISTER X
  BPL DEST

• Branch if contents of a memory location are positive.

  LDA ADDR ; TEST A MEMORY LOCATION
  BPL DEST

or

  BIT ADDR
  BPL DEST
• Branch if 16-bit number in memory locations ADDR and ADDR+1 (MSB in ADDR+1) is positive.

```
BIT ADDR+1 ;TEST MSB
BPL DEST
```

Remember that BIT sets the Negative flag from bit 7 of the memory location, regardless of the contents of the accumulator.

6. Branch if Negative.

• Branch if contents of accumulator are negative.

```
TAX ;TEST ACCUMULATOR
BMI DEST
```

or

```
CMP #0 ;TEST ACCUMULATOR
BMI DEST
```

• Branch if contents of index register X are negative.

```
TXA ;TEST REGISTER X
BMI DEST
```

or

```
CPX #0 ;TEST INDEX REGISTER X
BMI DEST
```

• Branch if contents of a memory location are negative.

```
BIT ADDR ;TEST A MEMORY LOCATION
BMI DEST
```

or

```
LDA ADDR ;TEST A MEMORY LOCATION
BMI DEST
```

• Branch if 16-bit number in memory locations ADDR and ADDR+1 (MSB in ADDR+1) is negative.

```
BIT ADDR+1 ;TEST MSB
BMI DEST
```

Remember that BIT sets the Negative flag from bit 7 of the memory location, regardless of the contents of the accumulator.

7. Branch if Greater Than (Signed).

• Branch if \((A) > VALUE\).

```
CMP #VALUE ;COMPARE BY SUBTRACTING
BEQ DONE ;NO BRANCH IF EQUAL
BVS CHKOPP ;DID OVERFLOW OCCUR?
BPL DEST ;NO, THEN BRANCH ON POSITIVE
BMI DONE

CHKOPP BMI DEST ;YES, THEN BRANCH ON NEGATIVE
DONE NOP
```
The idea here is to branch if the result is greater than zero and overflow did not occur, or if the result is less than zero and overflow did occur. Overflow makes the apparent sign the opposite of the real sign.

- Branch if \((A) > (ADDR)\).

```
CMP ADDR ;COMPARE BY SUBTRACTING
BEQ DONE ;NO BRANCH IF EQUAL
BVS CHKOPP ;DID OVERFLOW OCCUR?
BPL DEST ;NO, THEN BRANCH ON POSITIVE
BMI DONE
CHKOPP BMI DEST ;YES, THEN BRANCH ON NEGATIVE
DONE NOP
```

8. Branch if Greater Than or Equal To (Signed)

- Branch if \((A) \geq VALUE\).

```
CMP #VALUE ;COMPARE BY SUBTRACTING
BVS CHKOPP ;DID OVERFLOW OCCUR?
BPL DEST ;NO, THEN BRANCH ON POSITIVE
BMI DONE
CHKOPP BMI DEST ;YES, THEN BRANCH ON NEGATIVE
DONE NOP
```

The idea here is to branch if the result is greater than or equal to 0 and overflow did not occur, or if the result is less than 0 and overflow did occur.

- Branch if \((A) \geq (ADDR)\).

```
CMP ADDR ;COMPARE BY SUBTRACTING
BVS CHKOPP ;DID OVERFLOW OCCUR?
BPL DEST ;NO, THEN BRANCH ON POSITIVE
BMI DONE
CHKOPP BMI DEST ;YES, THEN BRANCH ON NEGATIVE
DONE NOP
```

9. Branch if Less Than (Signed)

- Branch if \((A) < VALUE\) (signed).

```
CMP #VALUE ;COMPARE BY SUBTRACTING
BVS CHKOPP ;DID OVERFLOW OCCUR?
BMI DEST ;NO, THEN BRANCH ON NEGATIVE
BPL DONE
CHKOPP BPL DEST ;YES, THEN BRANCH ON POSITIVE
DONE NOP
```

The idea here is to branch if the result is negative and overflow did not occur, or if the result is positive but overflow did occur.

- Branch if \((A) < (ADDR)\) (signed).

```
CMP ADDR ;COMPARE BY SUBTRACTING
BVS CHKOPP ;DID OVERFLOW OCCUR?
BMI DEST ;NO, THEN BRANCH ON NEGATIVE
BPL DONE
CHKOPP BPL DEST ;YES, THEN BRANCH ON POSITIVE
DONE NOP
```
10. Branch if Less Than or Equal (Signed).
   • Branch if \( A \leq \text{VALUE} \) (signed).
     \[
     \begin{align*}
     \text{CMP} & \quad \#\text{VALUE} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING} \\
     \text{BEQ} & \quad \text{DEST} \hspace{1cm} ;\text{BRANCH IF EQUAL} \\
     \text{BVS} & \quad \text{CHKOPP} \hspace{1cm} ;\text{DID OVERFLOW OCCUR?} \\
     \text{BMI} & \quad \text{DEST} \hspace{1cm} ;\text{NO, THEN BRANCH ON NEGATIVE} \\
     \text{BPL} & \quad \text{DONE} \\
     \text{CHKOPP} & \quad \text{BPL} \quad \text{DEST} \hspace{1cm} ;\text{YES, THEN BRANCH ON POSITIVE} \\
     \text{DONE} & \quad \text{NOP}
     \end{align*}
     \]

   The idea here is to branch if the result is 0, negative without overflow, or positive with overflow.

   • Branch if \( A \leq (\text{ADDR}) \) (signed).
     \[
     \begin{align*}
     \text{CMP} & \quad \text{ADDR} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING} \\
     \text{BEQ} & \quad \text{DEST} \hspace{1cm} ;\text{BRANCH IF EQUAL} \\
     \text{BVS} & \quad \text{CHKOPP} \hspace{1cm} ;\text{DID OVERFLOW OCCUR?} \\
     \text{BMI} & \quad \text{DEST} \hspace{1cm} ;\text{NO, THEN BRANCH ON NEGATIVE} \\
     \text{BPL} & \quad \text{DONE} \\
     \text{CHKOPP} & \quad \text{BPL} \quad \text{DEST} \hspace{1cm} ;\text{YES, THEN BRANCH ON POSITIVE} \\
     \text{DONE} & \quad \text{NOP}
     \end{align*}
     \]

11. Branch if Higher (Unsigned). That is, branch if the unsigned comparison is nonzero and does not require a borrow.
   • Branch if \( A > \text{VALUE} \) (unsigned).
     \[
     \begin{align*}
     \text{CMP} & \#\text{VALUE} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING} \\
     \text{BEQ} & \quad \text{DONE} \hspace{1cm} ;\text{NO BRANCH IF EQUAL} \\
     \text{BCS} & \quad \text{DEST} \hspace{1cm} ;\text{BRANCH IF NO BORROW NEEDED} \\
     \text{DONE} & \quad \text{NOP}
     \end{align*}
     \]

     or
     \[
     \begin{align*}
     \text{CMP} & \#\text{VALUE+1} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING VALUE + 1} \\
     \text{BCS} & \quad \text{DEST} \hspace{1cm} ;\text{BRANCH IF NO BORROW NEEDED}
     \end{align*}
     \]

   It is shorter and somewhat more efficient to simply compare to a number one higher than the actual threshold. Then we can use BCS, which causes a branch if the contents of the accumulator are greater than or equal to \( \text{VALUE+1} \) (unsigned).

   • Branch if \( A > (\text{ADDR}) \) (unsigned).
     \[
     \begin{align*}
     \text{CMP} & \quad \text{ADDR} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING} \\
     \text{BEQ} & \quad \text{DONE} \hspace{1cm} ;\text{NO BRANCH IF EQUAL} \\
     \text{BCS} & \quad \text{DEST} \hspace{1cm} ;\text{BRANCH IF NO BORROW NEEDED} \\
     \text{DONE} & \quad \text{NOP}
     \end{align*}
     \]

   • Branch if \( X > \text{VALUE} \) (unsigned).
     \[
     \begin{align*}
     \text{CPX} & \#\text{VALUE+1} \hspace{1cm} ;\text{COMPARE BY SUBTRACTING VALUE+1} \\
     \text{BCS} & \quad \text{DEST}
     \end{align*}
     \]
• Branch if \( (X) > (ADDR) \) (unsigned).

\[
\begin{align*}
\text{CPX} & \quad \text{ADDR} \quad \text{;COMPAR} \text{E BY SUBTRACTING} \\
\text{BEQ} & \quad \text{DONE} \quad \text{;NO BRANCH IF EQUAL} \\
\text{BCS} & \quad \text{DEST} \quad \text{;BRANCH IF NO BORROW NEEDED} \\
\text{DONE} & \quad \text{NOP}
\end{align*}
\]

• Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are larger (unsigned) than VAL16 (VAL16L less significant byte, VAL16M more significant byte).

\[
\begin{align*}
\text{LDA} & \quad \#\text{VAL16L} \quad \text{;GENERATE BORROW BY COMPARING LSB'S} \\
\text{CMP} & \quad \text{PGZRO} \\
\text{LDA} & \quad \#\text{VAL16M} \quad \text{;COMPARE MSB'S WITH BORROW} \\
\text{SBC} & \quad \text{PGZRO} + 1 \\
\text{BCC} & \quad \text{DEST} \quad \text{;BRANCH IF BORROW GENERATED}
\end{align*}
\]

• Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are larger (unsigned) than the contents of memory locations LIML and LIMH (MSB in LIMH).

\[
\begin{align*}
\text{LDA} & \quad \text{LIML} \quad \text{;GENERATE BORROW BY COMPARING LSB'S} \\
\text{CMP} & \quad \text{PGZRO} \\
\text{LDA} & \quad \text{LIMH} \quad \text{;COMPARE MSB'S WITH BORROW} \\
\text{SBC} & \quad \text{PGZRO} + 1 \\
\text{BCC} & \quad \text{DEST} \quad \text{;BRANCH IF BORROW GENERATED}
\end{align*}
\]

• Branch if \( (S) > \text{VALUE} \) (unsigned).

\[
\begin{align*}
\text{TSX} & \quad \text{;CHECK IF STACK BEYOND LIMIT} \\
\text{CPX} & \quad \#\text{VALUE} \\
\text{BEQ} & \quad \text{DONE} \quad \text{;NO BRANCH IF EQUAL} \\
\text{BCS} & \quad \text{DEST} \quad \text{;BRANCH IF NO BORROW NEEDED} \\
\text{DONE} & \quad \text{NOP}
\end{align*}
\]

or

\[
\begin{align*}
\text{TSX} & \quad \text{;CHECK IF STACK BEYOND LIMIT} \\
\text{CPX} & \quad \#\text{VALUE} + 1 \quad \text{;COMPARE BY SUBTRACTING VALUE + 1} \\
\text{BCS} & \quad \text{DEST} \quad \text{;BRANCH IF NO BORROW NEEDED}
\end{align*}
\]

• Branch if \( (S) > (ADDR) \) (unsigned).

\[
\begin{align*}
\text{TSX} & \quad \text{;CHECK IF STACK BEYOND LIMIT} \\
\text{BEQ} & \quad \text{DONE} \quad \text{;NO BRANCH IF EQUAL} \\
\text{BCS} & \quad \text{DEST} \quad \text{;BRANCH IF NO BORROW NEEDED} \\
\text{DONE} & \quad \text{NOP}
\end{align*}
\]

12. Branch if Not Higher (Unsigned). Branch if the unsigned comparison is 0 or requires a borrow.

Branch if \( (A) \leq \text{VALUE} \) (unsigned).

\[
\begin{align*}
\text{CMP} & \quad \#\text{VALUE} \quad \text{;COMPARE BY SUBTRACTING} \\
\text{BCC} & \quad \text{DEST} \quad \text{;BRANCH IF BORROW NEEDED} \\
\text{BEQ} & \quad \text{DEST} \quad \text{;BRANCH IF EQUAL}
\end{align*}
\]
If the two values are the same, CMP sets the Carry to indicate that no borrow was necessary.

or

\[
\text{CMP } \#\text{VALUE+1} \quad ; \text{COMPARE BY SUBTRACTING VALUE + 1}
\]

\[
\text{BCC } \text{DEST} \quad ; \text{BRANCH IF BORROW NEEDED}
\]

- Branch if (A) ≤ (ADDR) (unsigned).

\[
\text{CMP } \text{ADDR} \quad ; \text{COMPARE BY SUBTRACTING}
\]

\[
\text{BCC } \text{DEST} \quad ; \text{BRANCH IF BORROW NEEDED}
\]

\[
\text{BEQ } \text{DEST} \quad ; \text{BRANCH IF EQUAL}
\]

or

\[
\text{CPX } \#\text{VALUE+1} \quad ; \text{COMPARE BY SUBTRACTING VALUE + 1}
\]

\[
\text{BCC } \text{DEST} \quad ; \text{BRANCH IF BORROW NEEDED}
\]

- Branch if (X) ≤ VALUE (unsigned).

\[
\text{CPX } \#\text{VALUE} \quad ; \text{COMPARE BY SUBTRACTING}
\]

\[
\text{BCC } \text{DEST} \quad ; \text{BRANCH IF BORROW NEEDED}
\]

\[
\text{BEQ } \text{DEST} \quad ; \text{BRANCH IF EQUAL}
\]

- Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are less than or equal to (unsigned) VAL16 (VAL16M more significant byte, VAL16L less significant byte).

\[
\text{LDA } \#\text{VAL16L} \quad ; \text{GENERATE BORROW BY COMPARING LSB'S}
\]

\[
\text{CMP } \text{PGZRO}
\]

\[
\text{LDA } \#\text{VAL16M} \quad ; \text{COMPARE MSB'S WITH BORROW}
\]

\[
\text{SBC } \text{PGZRO+1}
\]

\[
\text{BCS } \text{DEST} \quad ; \text{BRANCH IF NO BORROW GENERATED}
\]

- Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are less than or equal to (unsigned) the contents of memory locations LIML and LIMH (MSB in LIMH).

\[
\text{LDA } \text{LIML} \quad ; \text{GENERATE BORROW BY COMPARING LSB'S}
\]

\[
\text{CMP } \text{PGZRO}
\]

\[
\text{LDA } \text{LIMH} \quad ; \text{COMPARE MSB'S WITH BORROW}
\]

\[
\text{SBC } \text{PGZRO+1}
\]

\[
\text{BCS } \text{DEST} \quad ; \text{BRANCH IF NO BORROW GENERATED}
\]

- Branch if (S) ≤ VALUE (unsigned).

\[
\text{TSX} \quad ; \text{CHECK IF STACK AT OR BELOW LIMIT}
\]

\[
\text{CPX } \#\text{VALUE} \quad ; \text{BRANCH IF BORROW NEEDED}
\]

\[
\text{BEQ } \text{DEST} \quad ; \text{BRANCH IF EQUAL}
\]
or

```
TSX          ;CHECK IF STACK AT OR BELOW LIMIT
CPX          ;COMPARE BY SUBTRACTING VALUE + 1
BCC DEST

• Branch if (S) ≤ (ADDR) (unsigned).
   TSX
   CPX ADDR
   BCC DEST ;BRANCH IF BORROW NEEDED
   BEQ DEST ;BRANCH IF EQUAL

13. Branch if Lower (Unsigned). That is, branch if the unsigned comparison requires a borrow.
   • Branch if (A) < (unsigned).
   CMP #VALUE ;COMPARE BY SUBTRACTING
   BCC DEST ;BRANCH IF BORROW GENERATED

The Carry flag is set to 0 if the subtraction generates a borrow.
   • Branch if (A) < (ADDR) (unsigned).
   CMP ADDR ;COMPARE BY SUBTRACTING
   BCC DEST ;BRANCH IF BORROW GENERATED

• Branch if (X) < VALUE (unsigned).
   CPX #VALUE ;COMPARE BY SUBTRACTING
   BCC DEST ;BRANCH IF BORROW GENERATED

• Branch if (X) < (ADDR) (unsigned).
   CPX ADDR ;COMPARE BY SUBTRACTING
   BCC DEST ;BRANCH IF BORROW GENERATED

• Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are less than (unsigned) VAL16 (VAL16L less significant byte, VAL16M more significant byte).
   LDA PGZRO ;GENERATE BORROW BY COMPARING LSB'S
   CMP #VAL16L
   LDA PGZRO+1 ;COMPARE MSB'S WITH BORROW
   SBC #VAL16M
   BCC DEST ;BRANCH IF BORROW GENERATED

• Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are less than (unsigned) the contents of memory locations LIML and LIMH (MSB in LIMH).
   LDA PGZRO ;GENERATE BORROW BY COMPARING LSB'S
   CMP LIML
   LDA PGZRO+1 ;COMPARE MSB'S WITH BORROW
   SBC LIMH
   BCC DEST ;BRANCH IF BORROW GENERATED
```
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- Branch if \( S < \text{VALUE} \) (unsigned).
  
  ```asm
  TSX ; CHECK IF STACK BELOW LIMIT
  CPX #VALUE
  BCC DEST ; BRANCH IF BORROW NEEDED
  ```

- Branch if \( S < \text{(ADDR)} \) (unsigned).
  
  ```asm
  TSX ; CHECK IF STACK BELOW LIMIT
  CPX ADDR
  BCC DEST ; BRANCH IF BORROW NEEDED
  ```

14. Branch if Not Lower (Unsigned). That is, branch if the unsigned comparison does not require a borrow.

- Branch if \( A \geq \text{VALUE} \) (unsigned).
  
  ```asm
  CMP #VALUE ; COMPARE BY SUBTRACTING
  BCS DEST ; BRANCH IF NO BORROW GENERATED
  ```

- Branch if \( A \geq \text{(ADDR)} \) (unsigned).
  
  ```asm
  CMP ADDR ; COMPARE BY SUBTRACTING
  BCS DEST
  ```

- Branch if \( X \geq \text{VALUE} \) (unsigned).
  
  ```asm
  CPX #VALUE ; COMPARE BY SUBTRACTING
  BCS DEST ; BRANCH IF NO BORROW GENERATED
  ```

- Branch if \( X \geq \text{(ADDR)} \) (unsigned).
  
  ```asm
  CPX ADDR ; COMPARE BY SUBTRACTING
  BCS DEST
  ```

- Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are greater than or equal to (unsigned) VAL16 (VAL16L less significant byte, VAL16M more significant byte).
  
  ```asm
  LDA PGZRO ; GENERATE BORROW BY COMPARING LSB'S
  CMP #VAL16L
  LDA PGZRO+1 ; COMPARE MSB'S WITH BORROW
  SBC #VAL16M
  BCS DEST ; BRANCH IF NO BORROW GENERATED
  ```

- Branch if the contents of memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1) are greater than or equal to (unsigned) the contents of memory locations LIML and LIMH (MSB in LIMH).
  
  ```asm
  LDA PGZRO ; GENERATE BORROW BY COMPARING LSB'S
  CMP LIML
  LDA PGZRO+1 ; COMPARE MSB'S WITH BORROW
  SBC LIMH
  BCS DEST ; BRANCH IF NO BORROW GENERATED
  ```
• Branch if \((S) \geq \text{VALUE}\) (unsigned).

\[
\text{TSX} \quad \text{;CHECK IF STACK AT OR ABOVE LIMIT}
\]
\[
\text{CPX \#VALUE}
\]
\[
\text{BCS \text{DEST}} \quad \text{;BRANCH IF NO BORROW NEEDED}
\]

• Branch if \((S) \geq \text{ADDR}\) (unsigned).

\[
\text{TSX} \quad \text{;CHECK IF STACK AT OR ABOVE LIMIT}
\]
\[
\text{CPX \text{ADDR}}
\]
\[
\text{BCS \text{DEST}} \quad \text{;BRANCH IF NO BORROW NEEDED}
\]

**SKIP INSTRUCTIONS**

You can implement skip instructions on the 6502 microprocessor by using branch or jump instructions with the proper destination. That destination should be one instruction beyond the one that the processor would execute sequentially after the branch. Note that skip instructions are awkward to implement on most microprocessors, because their instructions vary in length and it is difficult to determine how long a jump is required to skip an instruction.

**SUBROUTINE CALL INSTRUCTIONS**

**Unconditional Call Instructions**

You can implement an indirect call on the 6502 microprocessor by calling a routine that performs an ordinary indirect jump. A RETURN FROM SUBROUTINE (RTS) instruction at the end of the subroutine will then transfer control back to the original calling point. The main program performs

\[
\text{JSR \ TRANS}
\]

where TRANS is the subroutine that actually transfers control using a jump instruction. Note that TRANS ends with a jump, not with a return. Typical TRANS routines are:

• To address in memory locations INDIR and INDIR + 1 (MSB in INDIR + 1).

\[
\text{JMP \ (INDIR)}
\]

• To address in table starting at memory location BASE and using index in memory location INDEX.
LDA INDEX ;DOUBLE INDEX FOR 2-BYTE ENTRIES
ASL A
TAX
LDA BASE,X ;GET LSB OF DESTINATION
STA INDIR
INX
LDA BASE,X ;GET MSB OF DESTINATION
STA INDIR+1
JMP (INDIR) ;JUMP INDIRECT TO DESTINATION

or
LDA INDEX ;DOUBLE INDEX FOR 2-BYTE ENTRIES
ASL A
TAX
LDA BASE+1,X ;GET MSB OF DESTINATION
PHA
LDA BASE,X ;GET LSB OF DESTINATION
PHA
RTS ;JUMP TO DESTINATION PLUS 1

In the second approach, the table must contain the actual destination addresses minus 1, since RTS adds 1 to the program counter after loading it from the stack.

**Conditional Call Instructions**

You can implement a conditional call on the 6502 microprocessor by branching on the opposite condition around the call. For example, you could provide CALL ON CARRY CLEAR with the sequence

```
BCS NEXT ;BRANCH AROUND IF CARRY SET
JSR SUBR ;CALL IF CARRY CLEAR
NEXT NOP
```

**RETURN INSTRUCTIONS**

**Unconditional Return Instructions**

The RTS instruction returns control automatically to the address saved at the top of the stack (plus 1). If the return address is saved elsewhere (i.e., in two memory locations), you can return control to it by performing an indirect jump. Note that you must add 1 to the return address to simulate RTS.

The following sequence pops the return address from the top of the stack, adds 1 to it, and stores the adjusted value in memory locations RETADR and RETADR +1.
PLA ; POP LSB OF RETURN ADDRESS
CLC ; ADD 1 TO LSB
ADC #1
STA RETADR
PLA
ADC #0 ; POP MSB OF RETURN ADDRESS
STA RETADR+1

A final JMP (RETADR) will now transfer control to the proper place.

Conditional Return Instructions

You can implement conditional returns on the 6502 microprocessor by using the conditional branches (on the opposite condition) to branch around an RTS instruction. That is, for example, you could provide RETURN ON NOT ZERO with the sequence

BEQ NEXT ; BRANCH AROUND IF ZERO
RTS ; RETURN ON NOT ZERO

Return with Skip Instructions

• Return control to the address at the top of the stack after it has been incremented by an offset NUM. This sequence allows you to transfer control past parameters, data, or other nonexecutable items.

PLA ; POP RETURN ADDRESS
CLC
ADC #NUM+1 ; INCREMENT BY NUM
STA RETADR
PLA
ADC #0 ; WITH CARRY IF NECESSARY
STA RETADR+1
JMP (RETADR)
or

TSX ; MOVE STACK POINTER TO INDEX REGISTER
LDA $0101,X ; INCREMENT RETURN ADDRESS BY NUM
CLC
ADC #NUM
STA $0101,X
BCC DONE
INC $0102,X ; WITH CARRY IF NECESSARY
DONE RTS

• Change the return address to RETPT. Assume that the return address is stored currently at the top of the stack. RETPT consists of RETPTH (MSB) and RETPTL (LSB).
The actual return point is RETPT + 1.

Return from Interrupt Instructions

If the initial portion of the interrupt service routine saves all the registers with the sequence.

```
PHA ;SAVE ACCUMULATOR
TXA ;SAVE INDEX REGISTER X
PHA
TYA ;SAVE INDEX REGISTER Y
PHA
```

A standard return sequence is

```
PLA ;RESTORE INDEX REGISTER Y
TAY
PLA ;RESTORE INDEX REGISTER X
TAX
PLA ;RESTORE ACCUMULATOR
```

MISCELLANEOUS INSTRUCTIONS

In this category, we include push and pop instructions, halt, wait, break, decimal adjust, enabling and disabling of interrupts, translation (table lookup), and other instructions that do not fall into any of the earlier categories.

1. Push Instructions.
   - Push index register X.
     
     ```
     TXA ;SAVE X IN STACK VIA A
     PHA
     ```
   - Push index register Y.
     
     ```
     TYA ;SAVE Y IN STACK VIA A
     PHA
     ```
   - Push memory location ADDR.
     
     ```
     LDA ADDR ;SAVE MEMORY LOCATION IN STACK
     PHA
     ```
ADDR could actually be an external priority register or a copy of it.
- Push memory locations ADDR and ADDR+1 (ADDR+1 most significant).

```assembly
LDA ADDR+1 ;SAVE 16-BIT NUMBER IN STACK
PHA
LDA ADDR
PHA
```

Since the stack is growing toward lower addresses, the 16-bit number ends up stored in its usual 6502 form.

2. Pop (pull) instructions.
- Pop index register X.

```assembly
PLA ;RESTORE X FROM STACK VIA A
TAX
```

- Pop index register Y.

```assembly
PLA ;RESTORE Y FROM STACK VIA A
TAY
```

- Pop memory location ADDR.

```assembly
PLA ;RESTORE MEMORY LOCATION FROM STACK
STA ADDR
```

ADDR could actually be an external priority register or a copy of it.
- Pop memory locations ADDR and ADDR+1 (ADDR+1 most significant byte).

```assembly
PLA ;RESTORE 16-BIT NUMBER FROM STACK
STA ADDR
PLA
STA ADDR+1
```

We assume that the 16-bit number is stored in the usual 6502 form with the less significant byte at the lower address.

**Wait Instructions**

The simplest way to implement a wait on the 6502 microprocessor is to use an endless loop such as:

```assembly
HERE JMP HERE
```

The processor will continue executing the instruction until it is interrupted and will resume executing it after the interrupt service routine returns control. Of course, maskable interrupts must have been enabled or the processor will
execute the loop endlessly. The nonmaskable interrupt can interrupt the processor at any time.

Another alternative is a sequence that waits for a high-to-low transition on the Set Overflow input. Such a transition sets the Overflow (V) flag. So the required sequence is

```
CLV ;CLEAR THE OVERFLOW FLAG
WAIT BVC WAIT ;AND WAIT FOR A TRANSITION TO SET IT
```

This sequence is essentially a "Wait for Input Transition" instruction.

### Adjust Instructions

1. Branch if accumulator does not contain a valid decimal (BCD) number.

   ```
   STA TEMP ;SAVE ACCUMULATOR
   SED ;ENTER DECIMAL MODE
   CLC ;ADD 0 IN DECIMAL MODE
   ADC #0
   CLD ;LEAVE DECIMAL MODE
   ```

2. Decimal increment accumulator (add 1 to A in decimal).

   ```
   SED ;ENTER DECIMAL MODE
   CLC
   ADC #1 ;ADD 1 DECIMAL
   CLD ;LEAVE DECIMAL MODE
   ```

3. Decimal decrement accumulator (subtract 1 from A in decimal).

   ```
   SED ;ENTER DECIMAL MODE
   SEC
   SBC #1 ;SUBTRACT 1 DECIMAL
   CLD ;LEAVE DECIMAL MODE
   ```

4. Enter decimal mode but save the old Decimal Mode flag.

   ```
   PHP ;SAVE OLD DECIMAL MODE FLAG
   SED ;ENTER DECIMAL MODE
   ```

   A final PLP instruction will restore the old value of the Decimal Mode flag (and the rest of the status register as well).

5. Enter binary mode but save the old Decimal Mode flag.

   ```
   PHP ;SAVE OLD DECIMAL MODE FLAG
   CLD ;ENTER BINARY MODE
   ```

   A final PLP instruction will restore the old value of the Decimal Mode flag (and the rest of the status register as well).
Enable and Disable Interrupt Instructions

1. Enable interrupts but save previous value of I flag.

```plaintext
PHP  ;SAVE OLD I FLAG
CLI  ;ENABLE INTERRUPTS
```

After a sequence that must run with interrupts enabled, a PLP instruction will restore the previous state of the interrupt system (and the rest of the status register as well).

2. Disable interrupts but save previous value of I flag.

```plaintext
PHP  ;SAVE OLD I FLAG
SEI  ;DISABLE INTERRUPTS
```

After a sequence that must run with interrupts disabled, a PLP instruction will restore the previous state of the interrupt system (and the rest of the status register as well).

Translate Instructions

1. Translate the operand in A to a value obtained from the corresponding entry in a table starting at the address in memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1).

```plaintext
TAY
LDA (PGZRO),Y  ;REPLACE OPERAND WITH TABLE ENTRY
```

This procedure can be used to convert data from one code to another.

2. Translate the operand in A to a 16-bit value obtained from the corresponding entry in a table starting at the address in memory locations PGZRO and PGZRO+1 (MSB in PGZRO+1). Store the entry in memory locations TEMPL and TEMPH (MSB in TEMPH).

```plaintext
ASL A  ;DOUBLE INDEX FOR 2-BYTE ENTRIES
TAY
LDA (PGZRO),Y  ;GET LSB OF ENTRY
STA TEMPL
INY
LDA (PGZRO),Y  ;GET MSB OF ENTRY
STA TEMPH
```

ADDITIONAL ADDRESSING MODES

- **Indirect Addressing.** You can provide indirect addressing on the 6502 processor (for addresses on page 0) by using the postindexed (indirect indexed)
addressing mode with register Y set to 0. A somewhat less powerful alternative (because you cannot index from the indirect address) is to use preindexing (indexed indirect addressing) with register X set to 0. Otherwise, indirect addressing is available only for the JMP instruction. Note that with JMP, the indirect address may be located anywhere in memory; it is not restricted to page 0.

*Examples*

1. Load the accumulator indirectly from the address in memory locations PGZRO and PGZRO + 1.
   
   ```
   LDY #0 ; SET INDEX TO ZERO
   LDA (PGZRO),Y ; LOAD INDIRECT INDEXED
   ```
   
   b. Store the accumulator indirectly at the address in memory locations PGZRO and PGZRO + 1.
   
   ```
   LDY #0 ; SET INDEX TO ZERO
   STA (PGZRO),Y ; STORE INDIRECT INDEXED
   ```
   
   In the case of instructions that lack the indirect indexed mode (such as ASL, DEC, INC, LSR, ROL, ROR), you must move the data to the accumulator, operate on it there, and then store it back in memory.

3. Increment the data at the address in memory locations PGZRO and PGZRO + 1.
   
   ```
   LDY #0 ; SET INDEX TO ZERO
   LDA (PGZRO),Y ; GET THE DATA
   CLC
   ADC #1 ; INCREMENT THE DATA
   STA (PGZRO),Y ; STORE THE RESULT BACK
   ```
   
4. Logically shift right the data at the address in memory locations PGZRO and PGZRO+1.
   
   ```
   LDY #0 ; SET INDEX TO ZERO
   LDA (PGZRO),Y ; GET THE DATA
   LSR A ; SHIFT IT RIGHT
   STA (PGZRO),Y ; STORE THE RESULT BACK
   ```
   
5. Clear the address in memory locations PGZRO and PGZRO+1.
   
   ```
   LDY #0 ; SET INDEX TO ZERO
   TYA ; DATA = ZERO
   STA (PGZRO),Y ; CLEAR THE INDIRECT ADDRESS
   ```
   
   The only way to provide indirect addressing for other pages is to move the indirect address to page 0 first.

6. Clear the address in memory locations INDIR and INDIR+1 (not on page 0).
• **Indexed Addressing.** Indexed addressing is available for most instructions in the 6502 set. We will discuss briefly the handling of the few for which it is not available and will then discuss the handling of indexes that are larger than 256.

No indexing is available for BIT, CPX, CPY, JMP, and JSR. Only page 0 indexing is available for STX and STY. We can overcome these limitations as follows:

1. **BIT**

BIT indexed can be simulated by saving the accumulator, using AND, and restoring the accumulator. You should note that restoring the accumulator with LDA, PHA, TXA, or TYA will affect the Zero and Negative flags. A typical sequence without restoring the accumulator is:

```
PHA                     ;SAVE A
AND BASE,X             ;LOGICAL AND INDEXED
```

The Zero flag is set as if an indexed BIT had been executed and the contents of A are available at the top of the stack.

2. **CPX or CPY**

CPX or CPY indexed can be simulated by moving the index register to A and using CMP. That is, CPX indexed with Y can be simulated by the sequence:

```
TXA                     ;MOVE X TO A
CMP BASE,Y             ;THEN COMPARE INDEXED
```

3. **JMP**

JMP indexed can be simulated by calculating the required indexed address, storing it in memory, and using either JMP indirect or RTS to transfer control. The sequences are:

```
LDA INDEX              ;DOUBLE INDEX FOR 2-BYTE ENTRIES
ASL A
TAX
LDA BASE,X            ;GET LSB OF DESTINATION
STA INDIR
INX
LDA BASE,X            ;GET MSB OF DESTINATION
STA INDIR+1
JMP (INDIR)           ;JUMP INDIRECT TO DESTINATION
```
or

LDA INDEX
ASL A ;DOUBLE INDEX FOR 2-BYTE ENTRIES
TAX
LDA BASE+1,X ;GET MSB OF DESTINATION
PHA
LDA BASE,X ;GET LSB OF DESTINATION
PHA
RTS ;JUMP INDIRECT TO DESTINATION OFFSET 1

The second approach requires that the table contain entries that are all 1 less than the actual destinations, since RTS adds 1 to the program counter after restoring it from the stack.

4. JSR

JSR indexed can be simulated by calling a transfer program that executes JMP indexed as shown above. The ultimate return address remains at the top of the stack and a final RTS instruction will transfer control back to the original calling program. That is, the main program contains:

JSR TRANS

TRANS performs an indexed jump and thus transfers control to the actual subroutine.

5. STX or STY

STX or STY indexed can be simulated by moving the index register to A and using STA. That is, we can simulate STX indexed with Y by using the sequence:

TXA ;MOVE X TO A
STA BASE,Y ;THEN STORE INDEXED

BASE can be anywhere in memory, not just on page 0.

We can handle indexes that are larger than 256 by performing an explicit addition on the more significant bytes and using the indirect indexed addressing mode. That is, if the base address is in memory locations PGZRO and PGZRO+1 and the index is in memory locations INDEX and INDEX+1, the following sequence will place the corrected base address in memory locations TEMP and TEMP+1 (on page 0).

LDA PGZRO ;SIMPLY MOVE LSB
STA TEMP
LDA PGZRO+1 ;ADD MSB'S
CLC
ADC INDEX+1
STA TEMP+1

TEMP and TEMP+1 now contain a base address that can be used (in conjunction with INDEX) in the indirect indexed mode.
Examples

1. Load accumulator indexed.

   LDY INDEX ; GET LSB OF INDEX
   LDA (TEMP),Y ; LOAD A INDIRECT INDEXED

2. Store accumulator indexed, assuming that we have saved A at the top of the stack.

   LDY INDEX ; GET LSB OF INDEX
   PLA ; RESTORE A
   STA (TEMP),Y ; STORE A INDIRECT INDEXED

• Autopreincrementing. Autopreincrementing means that the contents of the index register are incremented automatically before they are used. You can provide autopreincrementing on the 6502 processor either by using INX or INY on an index register or by using the 16-bit methods to increment a base address in memory.

Examples

• Load the accumulator from address BASE using autopreincrementing on index register X.

   INX ; AUTOPREINCREMENT X
   LDA BASE,X

We assume that the array contains fewer than 256 elements.

• Load the accumulator from the address in memory locations PGZRO and PGZRO + 1 using autopreincrementing on the contents of memory locations INDEX and INDEX + 1.

   INC INDEX ; AUTOPREINCREMENT INDEX
   BNE DONE
   INC INDEX+1 ; WITH CARRY IF NECESSARY
   LDA PGZRO ; MOVE LSB
   STA TEMP
   LDA PGZRO+1 ; ADD MSB'S
   CLC
   ADC INDEX+1
   STA TEMP+1
   LDY INDEX ; GET LSB OF INDEX
   LDA (TEMP),Y ; LOAD ACCUMULATOR

If you must autoincrement by 2 (as in handling arrays of addresses) use the sequence

   LDA INDEX ; AUTOINCREMENT INDEX BY 2
   CLC
   ADC #2
   STA INDEX
   BCC DONE
   INC INDEX+1 ; CARRY TO MSB IF NECESSARY
   DONE NOP
• **Autopostincrementing.** Autopostincrementing means that the contents of the index register are incremented automatically after they are used. You can provide autopreincrementing on the 6502 processor either by using INX or INY on an index register or by using the 16-bit methods to increment an index in memory.

*Examples*

- Load the accumulator from address BASE using autopostincrementing on index register Y.

  ```assembly
  LDA BASE, Y ;AUTOPOSTINCREMEN Y
  INY
  ```

- Load the accumulator from the address in memory locations PGZRO and PGZRO + 1 using autopostincrementing on the contents of memory locations INDEX and INDEX + 1.

  ```assembly
  LDA PGZRO ;MOVE LSB OF BASE
  STA TEMP
  LDA PGZRO+1 ;ADD MSB'S OF BASE AND INDEX
  CLC
  ADC INDEX+1
  STA TEMP+1
  LDY INDEX ;GET LSB OF INDEX
  LDA (TEMP), Y ;LOAD ACCUMULATOR
  INC INDEX ;AUTOPOSTINCREMENT INDEX
  BNE DONE
  INC INDEX+1 ;WITH CARRY IF NECESSARY
  DONE NOP
  ```

• **Autopredecrementing.** Autopredecrementing means that the contents of the index register are decremented automatically before they are used. You can provide autopredecrementing on the 6502 processor either by using DEX or DEY on an index register or by using the 16-bit methods to decrement a base address or index in memory.

*Examples*

- Load the accumulator from address BASE using autopredecrementing on index register X.

  ```assembly
  DEX ;AUTOPREDECREMENT X
  LDA BASE, X
  ```

We assume that the array contains fewer than 256 elements.

- Load the accumulator from the address in memory locations PGZRO and PGZRO + 1 using autopredecrementing on the contents of memory locations INDEX and INDEX + 1.
LDA INDEX ;AUTODECREMENT INDEX
BNE DECLSBD
DEC INDEX+1 ;BORROWING FROM MSB IF NECESSARY
DECLSBD
DEC INDEX
LDA PGZRO ;MOVE LSB OF BASE
STA TEMP
LDA PGZRO+1 ;ADD MSB'S OF BASE AND INDEX
CLC
ADC INDEX+1
STA TEMP+1
LDY INDEX ;GET LSB OF INDEX
LDA (TEMP),Y ;LOAD ACCUMULATOR

If you must autodecrement by 2 (as in handling arrays of addresses), use the sequence:

LDA INDEX ;AUTODECREMENT INDEX BY 2
SEC
SBC #2
STA INDEX
BCS DONE
DEC INDEX+1 ;BORROWING FROM MSB IF NECESSARY
DONE NOP

- **Autopostdecrementing.** Autopostdecrementing means that the contents of the index register are decremented automatically after they are used. You can provide autopostdecrementing on the 6502 processor by using either DEX or DEY on an index register or by using the 16-bit methods to decrement an index in memory.

**Examples**

- Load the accumulator from address BASE using autopostdecrementing on index register Y.

LDA BASE,Y ;AUTOPOSTDECREMENT Y
DEY

- Load the accumulator from the address in memory locations PGZRO and PGZRO + 1 using autopostdecrementing on the contents of memory locations INDEX and INDEX + 1.

LDA PGZRO ;MOVE LSB OF BASE
STA TEMP
LDA PGZRO+1 ;ADD MSB'S OF BASE AND INDEX
CLC
ADC INDEX+1
STA TEMP+1
LDY INDEX ;GET LSB OF INDEX
LDA (TEMP),Y ;LOAD ACCUMULATOR
CPY #0 ;AUTOPOSTDECREMENT INDEX
BNE DECLSBD
DEC INDEX+1 ;BORROWING FROM MSB IF NECESSARY
DECLSBD DEC INDEX
| Indexed indirect addressing (preindexing). The 6502 processor provides preindexing for many instructions. We can simulate preindexing for the instructions that lack it by moving the data to the accumulator using preindexing, operating on it, and (if necessary) storing the result back into memory using preindexing.

**Examples**

1. Rotate right the data at the preindexed address obtained by indexing with X from base address PGZRO.

   ```
   LDA (PGZRO,X) ;GET THE DATA
   ROR A ;ROTATE DATA RIGHT
   STA (PGZRO,X) ;STORE RESULT BACK IN MEMORY
   ```

2. Clear the preindexed address obtained by indexing with X from base address PGZRO.

   ```
   LDA #0 ;DATA = ZERO
   STA (PGZRO,X) ;CLEAR PREINDEXED ADDRESS
   ```

Note that if the calculation of an effective address in preindexing produces a result too large for eight bits, the excess is truncated and no error warning occurs. That is, the processor provides an automatic wraparound on page 0.

| Indirect indexed addressing (postindexing). The 6502 processor provides postindexing for many instructions. We can simulate postindexing for the instructions that lack it by moving the data to the accumulator using postindexing, operating on it, and (if necessary) storing the result back into memory using postindexing.

**Examples**

1. Decrement the data at the address in memory locations PGZRO and PGZRO+1 using Y as an index.

   ```
   LDA (PGZRO),Y ;GET THE DATA
   SEC
   SBC #1 ;DECREMENT DATA BY 1
   STA (PGZRO),Y ;STORE RESULT BACK IN MEMORY
   ```

2. Rotate left the data at the address in memory locations PGZRO and PGZRO+1 using Y as an index.

   ```
   LDA (PGZRO),Y ;GET THE DATA
   ROL A ;ROTATE DATA LEFT
   STA (PGZRO),Y ;STORE RESULT BACK IN MEMORY
   ```
REFERENCES


This chapter describes common errors in 6502 assembly language programs. The final section describes common errors in input/output drivers and interrupt service routines. Our aims here are the following:

- To warn programmers of potential trouble spots and sources of confusion.
- To indicate likely causes of programming errors.
- To emphasize some of the techniques and warnings presented in Chapters 1 and 2.
- To inform maintenance programmers where to look for errors and misinterpretations.
- To provide the beginner with a starting point in the difficult process of locating and correcting errors.

Of course, no list of errors can be complete. We have emphasized the most common ones in our work, but we have not attempted to describe the rare, subtle, or occasional errors that frustrate even the experienced programmer. However, most errors are remarkably simple once you uncover them and this list should help you debug most programs.

CATEGORIZATION OF PROGRAMMING ERRORS

We may generally divide common 6502 programming errors into the following categories:

- Using the Carry improperly. Typical errors include forgetting to clear the Carry before addition or set it before subtraction, and interpreting it incorrectly after comparisons (it acts as an inverted borrow).
Using the other flags improperly. Typical errors include using the wrong flag (such as Negative instead of Carry), branching after instructions that do not affect a particular flag, inverting the branch conditions (particularly when the Zero flag is involved), and changing a flag accidentally before branching.

Confusing addresses and data. Typical errors include using immediate instead of direct addressing, or vice versa, and confusing memory locations on page 0 with the addresses accessed indirectly through those locations.

Using the wrong formats. Typical errors include using BCD (decimal) instead of binary, or vice versa, and using binary or hexadecimal instead of ASCII.

Handling arrays incorrectly. Typical problems include accidentally overrunning the array at one end or the other (often by 1) and ignoring page boundaries when the array exceeds 256 bytes in length.

Ignoring implicit effects. Typical errors include using the contents of the accumulator, index register, stack pointer, flags, or page 0 locations without considering the effects of intermediate instructions on these contents. Most errors arise from instructions that have unexpected, implicit, or indirect effects.

Failing to provide proper initial conditions for routines or for the microcomputer as a whole. Most routines require the initialization of counters, indirect addresses, indexes, registers, flags, and temporary storage locations. The microcomputer as a whole requires the initialization of the Interrupt Disable and Decimal Mode flags and all global RAM addresses (note particularly indirect addresses and other temporary storage on page 0).

Organizing the program incorrectly. Typical errors include skipping or repeating initialization routines, failing to update indexes, counters, or indirect addresses, and forgetting to save intermediate or final results.

A common source of errors, one that is beyond the scope of our discussion, is conflict between user programs and systems programs. A simple example is a user program that saves results in temporary storage locations that operating systems or utility programs need for their own purposes. The results thus disappear mysteriously even though a detailed trace of the user program does not reveal any errors.

More complex sources of conflict may include the interrupt system, input/output ports, the stack, or the flags. After all, the systems programs must employ the same resources as the user programs. (Systems programs generally attempt to save and restore the user’s environment, but they often have subtle or unexpected effects.) Making an operating system transparent to the user is a problem comparable to devising a set of regulations, laws, or tax codes that have no loopholes or side effects.
USING THE CARRY IMPROPERLY

The following instructions and conventions are the most common sources of errors:

- CMP, CPX, and CPY affect the Carry as if it were an inverted borrow, that is, they set the Carry if the subtraction of the memory location from the register did not require a borrow, and they clear the Carry if it did. Thus, Carry = 1 if no borrow was necessary and Carry = 0 if a borrow was required. This is contrary to the sense of the Carry in most other microprocessors (the 6800, 6809, 8080, 8085, or Z-80).

- SBC subtracts the inverted Carry flag from the normal subtraction of the memory location from the accumulator. That is, it produces the result \( (A) - (M) - (1 - \text{Carry}) \). If you do not want the Carry flag to affect the result, you must set it with SEC. Like comparisons, SBC affects the Carry as if it were an inverted borrow; Carry = 0 if the subtraction requires a borrow and 1 if it does not.

- ADC always includes the Carry in the addition. This produces the result \( (A) = (A) + (M) + \text{Carry} \). If you do not want the Carry flag to affect the result, you must clear it with CLC. Note that the Carry has its normal meaning after ADC.

Examples

1. CMP ADDR

   This instruction sets the flags as if the contents of memory location ADDR had been subtracted from the accumulator. The Carry flag is set if the subtraction does not require a borrow and cleared if it does. Thus

   \[
   \begin{align*}
   \text{Carry} = 1 & \text{ if } (A) \geq (ADDR) \\
   \text{Carry} = 0 & \text{ if } (A) < (ADDR)
   \end{align*}
   \]

   We are assuming that both numbers are unsigned. Note that the Carry is set (to 1) if the numbers are equal.

2. SBC #VALUE

   This instruction subtracts VALUE and \(1 - \text{Carry}\) from the accumulator. It sets the flags just like a comparison. To subtract VALUE alone from the accumulator, you must use the sequence

   \[
   \text{SEC} ; \text{SET INVERTED BORROW} \\
   \text{SBC} \ #\text{VALUE} ; \text{SUBTRACT VALUE}
   \]

   This sequence produces the result \( (A) = (A) - \text{VALUE} \). If \( \text{VALUE} = 1 \), the sequence is equivalent to a Decrement Accumulator instruction (remember, DEC cannot be applied to A).
3. ADC #VALUE

This instruction adds VALUE and Carry to the accumulator. To add VALUE alone to the accumulator, you must use the sequence

```
CLC ; CLEAR CARRY
ADC  #VALUE ; ADD VALUE
```

This sequence produces the result \((A) = (A) + VALUE\). If VALUE = 1, the sequence is equivalent to an Increment Accumulator instruction (remember, INC cannot be applied to A).

**USING THE OTHER FLAGS INCORRECTLY**

Instructions for the 6502 generally have expected effects on the flags. The only special case is BIT. Situations that require some care include the following:

- Store instructions (STA, STX, and STY) do not affect the flags, so the flags do not necessarily reflect the value that was just stored. You may need to test the register by transferring it to another register or comparing it with 0. Note that load instructions (including PHA) and transfer instructions (excluding TXS) affect the Zero and Negative flags.

- After a comparison (CMP, CPX, or CPY), the Zero flag indicates whether the operands are equal. The Zero flag is set if the operands are equal and cleared if they are not. There is some potential confusion here — BEQ means *branch if the result is equal to 0*; that is, *branch if the Zero flag is 1*. Be careful of the difference between the result being 0 and the Zero flag being 0. These two conditions are opposites; the Zero flag is 0 if the result is not 0.

- In comparing unsigned numbers, the Carry flag indicates which number is larger. CMP, CPX, or CPY clears the Carry if the register’s contents are greater than or equal to the other operand and sets the Carry if the register’s contents are less. Note that comparing equal operands sets the Carry. If these alternatives (greater than or equal and less than) are not what you need (you want the alternatives to be greater than and less than or equal), you can reverse the subtraction, subtract 1 from the accumulator, or add 1 to the other operand.

- In comparing signed numbers, the Negative flag indicates which operand is larger unless two’s complement overflow has occurred. We must first look at the Overflow flag. If that flag is 0, the Negative flag indicates which operand is larger; if that flag is 1, the sense of the Negative flag is inverted.

After a comparison (if no overflow occurs), the Negative flag is set if the register’s contents are less than the other operand, and cleared if the register’s
contents are greater than or equal to the other operand. Note that comparing equal operands clears the Negative flag. As with the Carry, you can handle the equality case in the opposite way by adjusting either operand or by reversing the subtraction.

- If a condition holds and you wish the computer to do something, a common procedure is to branch around a section of the program on the opposite condition. For example, to increment memory location OVFLW if the Carry is 1, use the sequence

```
BCC NEXT
INC OVFLW
NEXT NOP
```

The branch condition is the opposite of the condition under which the section should be executed.

- Increment and decrement instructions do not affect the Carry flag. This allows the instructions to be used for counting in loops that perform multiple-byte arithmetic (the Carry is needed to transfer carries or borrows between bytes). Increment and decrement instructions do, however, affect the Zero and Negative flags; you can use the effect on the Zero flag to determine whether an increment has produced a carry. Note the following typical sequences:

1. 16-bit increment of memory locations INDEX and INDEX+1 (MSB in INDEX+1)

```
INC INDEX ;INCREMENT LSB
BNE DONE
INC INDEX+1 ;AND CARRY TO MSB IF NECESSARY
DONE NOP
```

We determine if a carry has been generated by examining the Zero flag after incrementing the less significant byte.

2. 16-bit decrement of memory locations INDEX and INDEX+1 (MSB in INDEX+1)

```
LDA INDEX ;CHECK LSB
BNE DECLSB
DEC INDEX+1 ;BORROW FROM MSB IF NECESSARY
DECLSB DEC INDEX ;DECREMENT MSB
```

We determine if a borrow will be generated by examining the less significant byte before decrementing it.

- The BIT instruction has rather unusual effects on the flags. It places bit 6 of the memory location in the Overflow flag and bit 7 in the Negative flag, regardless of the value in the accumulator. Thus, only the Zero flag actually reflects the logical ANDing of the accumulator and the memory location.
· Only a few instructions affect the Carry or Overflow flags. The instructions that affect Carry are arithmetic (ADC, SBC), comparisons (CMP, CPX, and CPY), and shifts (ASL, LSR, ROL, and ROR), besides the obvious CLC and SEC. The only instructions that affect Overflow are ADC, BIT, CLV, and SBC; comparison and shift instructions do not affect the Overflow flag, unlike the situation in the closely related 6800 and 6809 microprocessors.

Examples
1. The sequence

```
STA $1700
BEQ DONE
```

will have unpredictable results, since STA does not affect any flags. Sequences that will produce a jump if the value stored is 0 are

```
STA $1700 ;TEST ACCUMULATOR
CMP #0
BEQ DONE
```
or

```
STA $1700 ;TEST ACCUMULATOR
TAX
BEQ DONE
```

2. The instruction CMP #$25 sets the Zero flag as follows:

Zero = 1 if the contents of A are $25_{16}$

Zero = 0 if the contents of A are not $25_{16}$

Thus, if you want to increment memory location COUNT, if (A) = $25_{16}$, use the sequence

```
CMP #$25 ;IS A 25?
BNE DONE
INC COUNT ;YES, INCREMENT COUNT
DONE
```

Note that we use BNE to branch around the increment if the condition (A = $25_{16}$) does not hold. It is obviously easy to err by inverting the branch condition.

3. The instruction CPX #$25 sets the Carry flag as follows:

Carry = 0 if the contents of X are between 00 and $24_{16}$

Carry = 1 if the contents of X are between $25_{16}$ and $FF_{16}$

Thus, the Carry flag is cleared if X contains an unsigned number less than the other operand and set if X contains an unsigned number greater than or equal to the other operand.
If you want to clear the Carry if the X register contains $25_{16}$, use CPX #$26 instead of CPX #$25. That is, we have

\[
\begin{align*}
\text{CPX} & \quad \#25 \\
\text{BCC} & \quad \text{LESS} \quad ; \text{BRANCH IF (X) LESS THAN 25}
\end{align*}
\]

or

\[
\begin{align*}
\text{CPX} & \quad \#26 \\
\text{BCC} & \quad \text{LESSEQ} \quad ; \text{BRANCH IF (X) 25 OR LESS}
\end{align*}
\]

4. The sequence SEC, SBC #$40$ sets the Negative (Sign) flag as follows:

- Negative = 0 if A is between $40_{16}$ and $7F_{16}$ (normal signed arithmetic) or if A is between $80_{16}$ and $C0_{16}$ (because of two’s complement overflow)
- Negative = 1 if A is between $00_{16}$ and $3F_{16}$ or between $C1_{16}$ and $FF_{16}$ (normal signed arithmetic)

Two’s complement overflow occurs if A contains a number between $80_{16}$ (−$128_{10}$ in two's complement) and $C0_{16}$ (−$64_{10}$ in two’s complement). Then subtracting $40_{16}$ (64_{10}) produces a result less than $-128_{10}$, which is beyond the range of an 8-bit signed number. The setting of the Overflow flag indicates this out-of-range condition.

The following sequence will thus produce a branch if A contains a signed number less than $40_{16}$.

\[
\begin{align*}
\text{SEC} & \quad ; \text{SET INVERTED BORROW} \\
\text{SBC} & \quad \#40 \quad ; \text{SUBTRACT 40 HEX} \\
\text{BVS} & \quad \text{DEST} \quad ; \text{BRANCH IF OVERFLOW IS SET} \\
\text{BMI} & \quad \text{DEST} \quad ; \text{OR IF DIFFERENCE IS NEGATIVE}
\end{align*}
\]

Note that we cannot use CMP here, since it does not affect the Overflow flag. We could, however, use the sequence

\[
\begin{align*}
\text{CMP} & \quad \#0 \quad ; \text{BRANCH IF A IS NEGATIVE} \\
\text{BMI} & \quad \text{DEST} \\
\text{CMP} & \quad \#40 \quad ; \text{OR IF A IS POSITIVE BUT BELOW 40 HEX} \\
\text{BCC} & \quad \text{DEST}
\end{align*}
\]

We eliminate the possibility of overflow by handling negative numbers separately.

5. The sequence

\[
\begin{align*}
\text{INC} & \quad \text{ADDR} \\
\text{BCS} & \quad \text{NXTPG}
\end{align*}
\]

will have unpredictable results, since INC does not affect the Carry flag. A sequence that will produce a jump, if the result of the increment is 00 (thus implying the production of a carry), is illustrated below.
INC ADDR
BEQ NXTPG

We can tell when an increment has produced a carry, but we cannot tell when a decrement has required a borrow since the result then is FF₁₆, not 0. Thus, it is much simpler to increment a multibyte number than to decrement it.

6. The sequence

BIT ADDR
BVS DEST

produces a branch if bit 6 of ADDR is 1. The contents of the accumulator do not affect it. Similarly, the sequence

BIT ADDR
BPL DEST

produces a branch if bit 7 of ADDR is 0. The contents of the accumulator do not affect it. The only common sequence with BIT in which the accumulator matters is

LDA #MASK
BIT ADDR

This sequence sets the Zero flag if logically ANDing MASK and the contents of ADDR produces a result of 0. A typical example using the Zero flag is

LDA #00010000
BIT ADDR
BNE DEST ;BRANCH IF BIT 4 OF ADDR IS 1

This sequence forces a branch if the result of the logical AND is nonzero, that is, if bit 4 of ADDR is 1.

The effects of BIT on the Overflow and Negative flags do not generally cause programming errors since there are no standard, widely used effects that might cause confusion. These effects do, however, create documentation problems since the approach is unique and those unfamiliar with the 6502 cannot be expected to guess what is happening.

7. The sequence

CMP #VALUE
BVS DEST

produces unpredictable results, since CMP does not affect the Overflow flag. Instead, to produce a branch if the subtraction results in two’s complement overflow, use the sequence

SEC ;SET INVERTED BORROW
SBC #VALUE ;SUBTRACT VALUE
BVS DEST ;BRANCH IF OVERFLOW OCCURS
CONFUSING ADDRESSES AND DATA

The rules to remember are

- The immediate addressing mode requires the actual data as an operand. That is, LDA #$40 loads the accumulator with the number $40_{16}$.

- The absolute and zero page (direct) addressing modes require the address of the data as an operand. That is, LDA $40$ loads the accumulator with the contents of memory location $0040_{16}$.

- The indirect indexed and indexed indirect addressing modes obtain the indirect address from two memory locations on page 0. The indirect address is in two memory locations starting at the specified address; it is stored upside-down, with its less significant byte at the lower address. Fortunately, the indexed indirect (preindexed) mode is rarely used and is seldom a cause of errors. The meaning of addressing modes with JMP and JSR can be confusing, since these instructions use addresses as if they were data. The assumption is that one could not transfer control to a number, so a jump with immediate addressing would be meaningless. However, the instruction JMP $1C80$ loads $1C80_{16}$ into the program counter, just like a load with immediate addressing, even though we conventionally say that the instruction uses absolute addressing. Similarly, the instruction JMP (ADDR) loads the program counter with the address from memory locations ADDR and ADDR + 1; it thus acts like a load instruction with absolute (direct) addressing.

Examples

1. LDX #$20 loads the number $20_{16}$ into index register X. LDX $20$ loads the contents of memory location $0020_{16}$ into index register X.

2. LDA ($40),Y loads the accumulator from the address obtained by indexing with Y from the base address in memory locations $0040_{16}$ and $0041_{16}$ (MSB in $0041_{16}$). Note that if LDA ($40),Y makes sense, then LDA ($41),Y generally does not, since it uses the base address in memory locations $0041_{16}$ and $0042_{16}$. Thus, the indirect addressing modes generally make sense only if the indirect addresses are aligned properly on word boundaries; however, the 6502 does not check this alignment in the way that many computers (particularly IBM machines) do. The programmer must make sure that all memory locations used indirectly contain addresses with the bytes arranged properly.

Confusing addresses and their contents is a frequent problem in handling data structures. For example, the queue of tasks to be executed by a piece of test equipment might consist of a block of information for each task. That block might contain

- The starting address of the test routine.
• The number of seconds for which the test is to run.
• The address in which the result is to be saved.
• The upper and lower thresholds against which the result is to be compared.
• The address of the next block in the queue.

Thus, the block contains data, direct addresses, and indirect addresses. Typical errors that a programmer could make are

• Transferring control to the memory locations containing the starting address of the test routine, rather than to the actual starting address.
• Storing the result in the block rather than in the address specified in the block.
• Using a threshold as an address rather than as data.
• Assuming that the next block starts within the current block, rather than at the address given in the current block.

Jump tables are another common source of errors. The following are alternative implementations:

• Form a table of jump instructions and transfer control to the correct element (for example, to the third jump instruction).
• Form a table of destination addresses and transfer control to the contents of the correct element (for example, to the address in the third element).

You will surely have problems if you try to use the jump instructions as indirect addresses or if you try to execute the indirect addresses.

**FORMAT ERRORS**

The rules you should remember are

• A $ in front of a number (or an H at the end) indicates hexadecimal to the assembler and a % in front or a B at the end indicates binary. Be careful — some assemblers use different symbols.

• The default mode of most assemblers is decimal; that is, most assemblers assume all numbers to be decimal unless they are specifically designated as something else. A few assemblers (such as Apple’s minisembler and the mnemonic entry mode in Rockwell’s AIM-65) assume hexadecimal as a default.

• ADC and SBC instructions produce decimal results if the Decimal Mode flag is 1 and binary results if the Decimal Mode flag is 0. All other instructions, including DEC, DEX, DEY, INC, INX, and INY, always produce binary results.
You should make special efforts to avoid the following common errors:

- Omitting the hexadecimal designation ($ or H) from a hexadecimal data item or address. The assembler will assume the item to be a decimal number if it contains no letter digits. It will treat the item as a name if it is valid (it must start with a letter in most assemblers). The assembler will indicate an error only if the item cannot be interpreted as a decimal number or a name.

- Omitting the binary designation (%) or B) from a binary data item. The assembler will assume it to be a decimal number.

- Confusing decimal (BCD) representations with binary representations. Remember, ten is not an integral power of two, so the binary and BCD representations are not the same beyond nine. Standard BCD constants must be designated as hexadecimal numbers, not as decimal numbers.

- Confusing binary or decimal representations with ASCII representations. An ASCII input device produces ASCII characters and an ASCII output device responds to ASCII characters.

Examples

1. **LDA 2000**
   This instruction loads the accumulator from memory address 2000₁₀ (07D₀₁₆), not address 2000₁₆. The assembler will not produce an error message, since 2000 is a valid decimal number.

2. **AND #00000011**
   This instruction logically ANDs the accumulator with the decimal number 11 (1011₂), not with the binary number 11 (3₁₀). The assembler will not produce an error message, since 00000011 is a valid decimal number despite its unusual form.

3. **ADC #40**
   This instruction adds 40₁₀ (not 40₁₆ = 6₄₁₀) and the Carry to the accumulator. Note that 40₁₀ is not the same as 40 BCD, which is 40₁₆; 40₁₀ = 2₈₁₆. The assembler will not produce an error message, since 40 is a valid decimal number.

4. **LDA #3**
   This instruction loads the accumulator with the number 3. If this value is now sent to an ASCII output device, it will respond as if it had received the character ETX (03₁₆), not the character 3 (3₃₁₆). The correct version is

   ```
   LDA    # '3    ;GET AN ASCII 3
   ```

5. If memory location 0040₁₆ contains a single digit, the sequence

   ```
   LDA    $40
   STA    FORT
   ```
will not print that digit on an ASCII output device. The correct sequence is

\[
\begin{align*}
\text{LDA} & \quad 0x40 \quad ; \text{GET DECIMAL DIGIT} \\
\text{CLC} & \\
\text{ADC} & \quad #0 \quad ; \text{ADJUST TO ASCII} \\
\text{STA} & \quad \text{PORT}
\end{align*}
\]

or

\[
\begin{align*}
\text{LDA} & \quad 0x40 \quad ; \text{GET DECIMAL DIGIT} \\
\text{ORA} & \quad #0x010000 \quad ; \text{ADJUST TO ASCII} \\
\text{STA} & \quad \text{PORT}
\end{align*}
\]

6. If input port IPORT contains a single ASCII decimal digit, the sequence

\[
\begin{align*}
\text{LDA} & \quad \text{IPORT} \\
\text{STA} & \quad 0x40
\end{align*}
\]

will not store the actual digit in memory location 0040\textsubscript{16}. Instead, it will store the ASCII version, which is the actual digit plus 30\textsubscript{16}. The correct sequence is

\[
\begin{align*}
\text{LDA} & \quad \text{IPORT} \quad ; \text{GET ASCII DIGIT} \\
\text{SEC} & \\
\text{SBC} & \quad #0 \quad ; \text{ADJUST TO DECIMAL} \\
\text{STA} & \quad 0x40
\end{align*}
\]

or

\[
\begin{align*}
\text{LDA} & \quad \text{IPORT} \quad ; \text{GET ASCII DIGIT} \\
\text{AND} & \quad #0x11001111 \quad ; \text{ADJUST TO DECIMAL} \\
\text{STA} & \quad 0x40
\end{align*}
\]

Handling decimal arithmetic on the 6502 microprocessor is simple, since the processor has a Decimal Mode (D) flag. When that flag is set (by SED), all additions and subtractions produce decimal results. So, the following sequences implement decimal addition and subtraction:

- Decimal addition of memory location ADDR to the accumulator

\[
\begin{align*}
\text{SED} & \quad ; \text{ENTER DECIMAL MODE} \\
\text{CLC} & \\
\text{ADC} & \quad \text{ADDR} \quad ; \text{ADD DECIMAL} \\
\text{CLD} & \quad ; \text{LEAVE DECIMAL MODE}
\end{align*}
\]

- Decimal subtraction of memory location ADDR from the accumulator

\[
\begin{align*}
\text{SED} & \quad ; \text{ENTER DECIMAL MODE} \\
\text{SEC} & \\
\text{SBC} & \quad \text{ADDR} \quad ; \text{SUBTRACT DECIMAL} \\
\text{CLD} & \quad ; \text{LEAVE DECIMAL MODE}
\end{align*}
\]

Since increment and decrement instructions always produce binary results, we must use the following sequences (assuming the D flag is set).
Increment memory location 0040\textsubscript{16} in the decimal mode

\begin{verbatim}
LDA $40
CLC
ADC #1
STA $40
\end{verbatim}

Decrement memory location 0040\textsubscript{16} in the decimal mode

\begin{verbatim}
LDA $40
SEC
SBC #1
STA $40
\end{verbatim}

The problem with the decimal mode is that it has implicit effects. That is, the same ADC and SBC instructions with the same data will produce different results, depending on the state of the Decimal Mode flag. The following procedures will reduce the likelihood of the implicit effects causing unforeseen errors:

- Initialize the Decimal Mode flag (with CLD) as part of the regular system initialization. Note that RESET has no effect on the Decimal Mode flag.
- Clear the Decimal Mode flag as soon as you are through performing decimal arithmetic.
- Initialize the Decimal Mode flag in interrupt service routines that include ADC or SBC instructions. That is, such service routines should execute CLD before performing any binary addition or subtraction.

**HANDLING ARRAYS INCORRECTLY**

The following situations are the most common sources of errors:

- If you are counting an index register down to 0, the zero index value may never be used. The solution is to reduce the base address or addresses by 1. For example, if the terminating sequence in a loop is

\begin{verbatim}
DEX
BNE LOOP
\end{verbatim}

the processor will fall through as soon as \( X \) is decremented to 0. A typical adjusted loop (clearing NTIMES bytes of memory) is

\begin{verbatim}
LDX #NTIMES
LDA #0
CLEAR STA BASE-1,X
DEX
BNE CLEAR
\end{verbatim}
Note the use of BASE−1 in the indexed store instruction. The program clears addresses BASE through BASE + NTIMES−1.

- Although working backward through an array is often more efficient than working forward, programmers generally find it confusing. Remember that the address BASE+(X) contains the previous entry in a loop like the example shown above. Although the processor can work backward just as easily as it can work forward, programmers usually find themselves conditioned to thinking ahead.

- Be careful not to execute one extra iteration or stop one short. Remember, memory locations BASE through BASE+N contain N+1 entries, not N entries. It is easy to forget the last entry or, as shown above, drop the first one. On the other hand, if you have N entries, they will occupy memory locations BASE through BASE+N-1; now it is easy to find yourself working off the end of the array.

- You cannot extend absolute indexed addressing or zero-page indexed addressing beyond 256 bytes. If an index register contains FF16, incrementing it will produce a result of 00. Similarly, if an index register contains 00, decrementing it will produce a result of FF16. Thus, you must be careful about incrementing or decrementing index registers when you might accidentally exceed the capacity of eight bits. To extend loops beyond 256 bytes, use the indirect indexed (postindexed) addressing mode. Then the following sequence will add 1 to the more significant byte of the indirect address when index register Y is incremented to 0.

```
INY ;INCREMENT INDEX REGISTER
BNE DONE
INC INDIR+1
DONE NOP
```

Here INDIR and INDIR+1 are the locations on page 0 that contain the indirect address.

**Example**

1. Let us assume (INDIR) = 8016 and (INDIR+1) = 4C16, so that the initial base address is 4C8016. If the loop refers to the address (INDIR), Y, the effective address is (INDIR+1) (INDIR) + Y or 4C8016 + (Y). When Y = FF16, the effective address is

```
4C8016 + (Y) = 4C8016 + FF16 = 4D7F16
```

The sequence shown above for incrementing the index and the indirect address produces the results

```
(Y) = (Y) + 1 = 00
(INDIR+1) = (INDIR+1) = 1 = 4D16
```
The effective address for the next iteration will be

\[ 4D80_{16} + (Y) = 4D80_{16} = 00_{16} = 4D80_{16} \]

which is the next higher address in the normal consecutive sequence.

**IMPLICIT EFFECTS**

Some of the implicit effects you should remember are

- The changing of the Negative and Zero flags by load and transfer instructions, such as LDA, LDX, LDY, PLA, TAX, TAY, TSX, TXA, and TYA.
  - The dependence of the results of ADC and SBC instructions on the values of the Carry and Decimal Mode flags.
  - The special use of the Negative and Overflow flags by the BIT instruction.
  - The use of the memory address one larger than the specified one in the indirect, indirect indexed, and indexed indirect addressing modes.
  - The changing of the stack pointer by PHA, PHP, PLA, PLP, JSR, RTS, RTI, and BRK. Note that JSR and RTS change the stack pointer by 2, and BRK and RTI change it by 3.
  - The saving of the return address minus 1 by JSR and the addition of 1 to the restored address by RTS.
  - The inclusion of the Carry in the rotate instructions ROL and ROR. The rotation involves nine bits, not eight bits.

*Examples*

1. **LDX $40**
   - This instruction affects the Negative and Zero flags, so those flags will no longer reflect the value in the accumulator or the result of the most recent operation.

2. **ADC #$20**
   - This instruction adds in the Carry flag as well as the immediate data \( (20_{16}) \). The result will be binary if the Decimal Mode flag is cleared, but BCD if the Decimal Mode flag is set.

3. **BIT $1700**
   - This instruction sets the Overflow flag from the value of bit 6 of memory location \( 1700_{16} \). This is the only instruction that has a completely unexpected effect on that flag.
4. **JMP ($1C00)**

This instruction transfers control to the address in memory locations $1C00_{16}$ and $1C01_{16}$ (MSB in $1C01_{16}$). Note that $1C01_{16}$ is involved even though it is not specified, since indirect addresses always occupy two bytes of memory.

5. **PHA**

This instruction not only saves the accumulator in memory, but it also decrements the stack pointer by 1.

6. **RTS**

This instruction not only loads the program counter from the top two locations in the stack, but it also increments the stack pointer by 2 and the program counter by 1.

7. **ROR A**

This instruction rotates the accumulator right 1 bit, moving the former contents of bit position 0 into the Carry and the former contents of the Carry into bit position 7.

**INITIALIZATION ERRORS**

The initialization routines must perform the following tasks, either for the microcomputer system as a whole or for particular routines:

- Load all RAM locations with initial values. This includes indirect addresses and other temporary storage on page 0. You cannot assume that a memory location contains 0 just because you have not used it.

- Load all registers and flags with initial values. Reset initializes only the Interrupt Disable flag (to 1). Note, in particular, the need to initialize the Decimal Mode flag (usually with CLD) and the stack pointer (using the LDX, TXS sequence).

- Load all counters and indirect addresses with initial values. Be particularly careful of addresses on page 0 that are used in either the indirect indexed (postindexed) addressing mode or the indexed indirect (preindexed) mode.

**ORGANIZING THE PROGRAM INCORRECTLY**

The following problems are the most common:

- Failing to initialize a register, flag, or memory location. You cannot assume
that a register, flag, or memory location contains zero just because you have not
used it.

- Accidentally reinitializing a register, flag, memory location, index, counter,
or indirect address. Be sure that your branches do not cause some or all of the
initialization instructions to be repeated.

- Failing to update indexes, counters, or indirect addresses. A problem here
may be one path that branches around the updating instructions or changes some
of the conditions before executing those instructions.

- Forgetting to save intermediate or final results. It is remarkably easy to
calculate a result and then load something else into the accumulator. Errors like
this are particularly difficult to locate, since all the instructions that calculate the
result work properly and yet the result itself is being lost. A common problem
here is for a branch to transfer control to an instruction that writes over the result
that was just calculated.

- Forgetting to branch around instructions that should not be executed in a
particular path. Remember, the computer will execute instructions consecutively
unless told specifically to do otherwise. Thus, it is easy for a program to acciden-
tally fall through to a section that the programmer expects it to reach only via a
branch. An awkward feature of the 6502 is its lack of an unconditional relative
branch; you must either use JMP with absolute addressing or set a condition and
branch on it holding (SEC, BCS, DEST and CLV, BVC DEST).

ERROR RECOGNITION BY ASSEMBLERS

Most assemblers will immediately recognize the following common errors:

- Undefined operation code (usually a misspelling or an omission)
- Undefined name (often a misspelling or an omitted definition)
- Illegal character (for example, a 2 in a binary number or a B in a decimal
  number)
- Illegal format (for example, an incorrect delimiter or the wrong register or
  operand)
- Illegal value (usually a number too large for 8 or 16 bits)
- Missing operand
- Double definition (two different values assigned to one name)
- Illegal label (for example, a label attached to a pseudo-operation that does
  not allow a label)
- Missing label (for example, on an = pseudo-operation that requires one).
These errors are generally easy to correct. Often the only problem is an error, such as omitting the semicolon or other delimiter in front of a comment, that confuses the assembler and results in a series of meaningless error messages.

There are, however, many common errors that assemblers will not recognize. The programmer should be aware that his or her program may contain such errors even if the assembler does not report them. Typical examples are

- Omitted lines. Obviously, the assembler cannot identify a completely omitted line unless that line contains a label or definition that is used later in the program. The easiest lines to omit are repetitions (that is, one or more lines that are the same or sequences that start the same) or instructions that seem to be unnecessary. Typical repetitions are series of shifts, branches, increments, or decrements. Instructions that may appear unnecessary include CLC, SEC, and so forth.

- Omitted designations. The assembler cannot tell if you omitted a designation such as #, H, $, B, or % unless the omission results in an illegal character (such as C in a decimal number). Otherwise, the assembler will assume all addresses to be direct and all numbers to be decimal. Problems occur with numbers that are valid as either decimal or hexadecimal values (such as 44 or 2050) and with binary numbers (such as 00000110).

- Misspellings that are still valid. Typical examples are typing BCC instead of BCS, LDX instead of LDY, and SEC instead of SED. Unless the misspelling is invalid, the assembler has no way of knowing what you meant. Valid misspellings are often a problem if you use similar names or labels such as XXX and XXXX, L121 and L112, or VAR11 and VARII.

- Designating instructions as comments. If you place a semicolon at the start of an instruction line, the assembler will treat the line as a comment. This can be a perplexing error, since the line appears in the listing but is not assembled into object code.

Sometimes you can confuse the assembler by entering invalid instructions. An assembler may accept a totally illogical entry simply because its developer never considered such possibilities. The result can be unpredictable, much like the results of giving someone a completely wrong number (for example, a telephone number instead of a street address or a driver license number instead of a credit card number). Some cases in which a 6502 assembler can go wrong are

- If you designate an impossible register or addressing mode. Some assemblers will accept instructions like INC A, LDA ($40), X, or LDY BASE, Y. They will produce erroneous object code without any warning.

- If you enter an invalid digit, such as Q in a decimal or hexadecimal number or 7 in a binary number. Some assemblers will assign values to such erroneous digits in an arbitrary manner.
• If you enter an invalid operand such as LDA #$HX. Some assemblers will accept this and generate incorrect code.

The assembler will recognize only errors that its developer anticipated. Programmers are often able to make mistakes that the developer never imagined, much as automobile drivers are often capable of performing maneuvers that never occurred in the wildest dreams of a highway designer or traffic planner. Note that only a line-by-line hand checking of the program will find errors that the assembler does not recognize.

IMPLEMENTATION ERRORS

Occasionally, a microprocessor’s instructions simply do not work the way the designers or anyone else would expect. The 6502 has one implementation error that is, fortunately, quite rare. The instruction JMP ($XXFF) where the Xs represent any page number, does not work correctly. One would expect this instruction to obtain the destination address from memory locations XXFF and (XX + 1)00. Instead, it apparently does not increment the more significant byte of the indirect address; it therefore obtains the destination address from memory locations XXFF and XX00. For example, JMP ($1CFF) will jump to the address stored in memory locations 1CFF₁₆ (LSB) and 1C00₁₆ (MSB), surely a curious outcome. Most assemblers expect the programmer to ensure that no indirect jumps ever obtain their destination addresses across page boundaries.

COMMON ERRORS IN I/O DRIVERS

Most errors in I/O drivers involve both hardware and software, so they are often difficult to categorize. Some mistakes you should watch for are

• Confusing input ports and output ports. Many I/O interfaces use the READ/ WRITE line for addressing, so that reading and writing the same memory address results in operations on different physical registers. Even when this is not done, it may still be impossible to read back output data unless it is latched and buffered.

• Attempting to perform operations that are physically impossible. Reading data from an output device (such as a display) or sending data to an input device (such as a keyboard) makes no physical sense. However, accidentally using the wrong address will cause no assembly errors; the address, after all, is valid and the assembler has no way of knowing that certain operations cannot be performed on it. Similarly, a program may attempt to save data in a nonexistent address or in a ROM.
- Forgetting implicit hardware effects. Sometimes transferring data to or from a port will change the status lines automatically, particularly if you are using a 6520 or 6522 parallel interface. Even reading or writing a port while debugging a program will change the status lines. Be particularly careful of instructions like comparisons and BIT which read a memory address even though they do not change any registers, and instructions like decrement, increment, and shift which both read and write a memory address (the actual operation, of course, takes place inside the processor).

- Reading or writing without checking status. Many devices can accept or provide data only when a status line indicates they are ready. Transferring data to or from them at other times will have unpredictable effects.

- Ignoring the differences between input and output. Remember that an input device normally starts out in the not ready state — it has no data available although the computer is ready to accept data. On the other hand, an output device normally starts out in the ready state, that is, it could accept data but the computer usually has none to send it. In many situations, particularly when using 6520, 6522, 6551, or 6850 devices, you may have to disable the outputs initially or send a null character (something that has no effect) to each output port just to change its state from ready to not ready initially.

- Failing to keep copies of output data. Remember that you may not be able to read the data back from the output port. If you need to repeat it later as part of repeating a transmission that was incorrectly received, change part of it (turn on or off one of several indicator lights attached to the same port), or save it as part of the interrupted status (the data is the current priority level). You must: save a copy in memory. The copy must be updated every time the actual data is changed.

- Reading data before it is stable or while it is changing. Be sure that you understand exactly when the input device is guaranteed to produce stable data. In the case of switches that may bounce, you may want to sample them twice (more than a debouncing time apart) before taking any action. In the case of keys that may bounce, you may want to take action only when they are released rather than when they are pressed. The action on release also forces the operator to release the key rather than holding it down. In the case of persistent data (such as in serial I/O), you should center the reception, that is, read the data near the centers of the pulses rather than at the edges where the values may be changing.

- Forgetting to reverse the polarity of data being transferred to or from devices that operate in negative logic. Many simple I/O devices, such as switches and displays, use negative logic. A logic 0 means that a switch is closed or a display is lit. Common ten-position switches or dials also often produce data in negative logic, as do many encoders. The solution is simple — complement the data (using EOR ≠$FF) after reading it or before sending it.
- Confusing actual I/O ports with registers that are inside I/O devices. Programmable I/O devices, such as the 6520, 6522, 6551, and 6850, have control or command registers which determine how the device operates, and status registers that reflect the current state of the device or the transfer. These registers are inside the I/O devices; they are not connected to peripherals. Transferring data to or from status or control registers is not the same as transferring data to or from actual I/O ports.

- Using bidirectional ports improperly. Many devices, such as the 6520, 6522, 6530, and 6532, have bidirectional I/O ports. The ports (and perhaps even individual lines) can be used either as inputs or outputs. Normally, resetting the computer to avoid initial transients makes these ports inputs, so you must explicitly change them to outputs if necessary. Be cautious when reading bits or ports that are designated as outputs or writing into bits or ports that are designated as inputs. The only way to determine what will happen is to read the documentation for the specific device.

- Forgetting to clear status after performing an I/O operation. Once the processor has read data from an input port, that port should revert to the not ready state. Similarly, once the processor has written data into an output port, that port should revert to the not ready state. Some I/O devices change the status of their ports automatically after input or output operations, but others either do not or (as in the 6520) change status automatically only after input operations. Leaving the status set can result in an endless loop or highly erratic operation.

**COMMON ERRORS IN INTERRUPT SERVICE ROUTINES**

Many interrupt-related errors involve both hardware and software, but some of the common mistakes include the following:

- Failing to reenable interrupts during the service routine. The 6502 processor automatically disables interrupts after accepting one. It does reenable interrupts when RTI is executed, since RTI restores the status register from the stack.

- Failing to save and restore registers. The 6502 does not automatically save any registers except the program counter and the status register. So the accumulator, index registers, and scratchpad locations must be saved explicitly in the stack.

- Saving or restoring registers in the wrong order. Registers must be restored in the opposite order from that in which they were saved.
Enabling interrupts before establishing priorities and other parameters of the interrupt system.

Forgetting that the response to an interrupt includes saving the status register and the program counter at the top of the stack. The status register is on top and the program counter value is the actual return address, so the situation differs from subroutines in which the return address minus 1 is normally at the top of the stack.

Not disabling the interrupt during multibyte transfers or instruction sequences that cannot be interrupted. In particular, you must avoid partial updating of data (such as time) that an interrupt service routine may use. In general, interrupts should be disabled when the main program is changing memory locations that it shares with interrupt service routines.

Failing to reenable the interrupt after a sequence that must run with interrupts disabled. A corollary problem here is that you do not want to enable interrupts if they were not enabled when the sequence was entered. The solution is to save the previous state of the Interrupt Disable flag (using PHP) before executing the sequence and restore the previous state (using PLP) afterward. Note, however, that PLP restores the entire status register.

Failing to initialize or establish the value of the Decimal Mode flag. An interrupt service routine should not assume a particular value (0) for the D flag. Instead, it should initialize that flag with CLD or SED if it executes ADC or SBC instructions. There is no need to save or restore the old D flag since that is done automatically as part of the saving and restoring of the status register. Initializing the D flag avoids problems if the service routine is entered from a program that runs with the D flag set.

Failing to clear the signal that caused the interrupt. The service routine must clear the interrupt even if it does not require an immediate response or any input or output operations. Even when the processor has, for example, no data to send to an interrupting output device, it must still either clear the interrupt or disable it. Otherwise, the processor will get caught in an endless loop. Similarly, a real-time clock interrupt will typically require no servicing other than an updating of time, but the service routine still must clear the clock interrupt. This clearing may involve reading a 6520 or 6522 I/O port or timer.

Failing to communicate with the main program. The main program will not realize that the interrupt has been serviced unless it is informed explicitly. The usual way to inform the main program is to have the interrupt service routine change a flag that the main program can examine. The main program will then know that the service routine has been executed. The procedure is comparable to the practice of a postal patron raising a flag to indicate that he or she has mail to be picked up. The postman lowers the flag after picking up the mail. Note that this
simple procedure means that the main program must examine the flag often enough to avoid missing data or messages. Of course, the programmer can always provide an intermediate storage area (or buffer) that can hold many data items.

- Failing to save and restore priority. The priority of an interrupt is often held in a write-only register or in a memory location. That priority must be saved just like the registers and restored properly at the end of the service routine. If the priority register is write-only, a copy of its contents must be saved in memory.
Introduction to the Program Section

The program section contains sets of assembly language subroutines for the 6502 microprocessor. Each subroutine is documented with an introductory section and comments; each is followed by at least one example of its use. The introductory material contains the following information:

1. Purpose of the routine
2. Procedure followed
3. Registers used
4. Execution time
5. Program size
6. Data memory required
7. Special cases
8. Entry conditions
9. Exit conditions
10. Examples

We have made each routine as general as possible. This is most difficult in the case of the input/output (I/O) and interrupt service routines described in Chapters 10 and 11, since in practice these routines are always computer-dependent. In such cases, we have limited the computer dependence to generalized input and output handlers and interrupt managers. We have drawn specific examples there from the popular Apple II computer, but the general principles are applicable to other 6502-based computers as well.

In all routines, we have used the following parameter passing techniques:

1. A single 8-bit parameter is passed in the accumulator. A second 8-bit parameter is passed in index register Y.
2. A single 16-bit parameter is passed in the accumulator and index register Y with the more significant byte in the accumulator. An accompanying 8-bit parameter is passed in index register X.

3. Larger numbers of parameters are passed in the stack, either directly or indirectly. We assume that subroutines are entered via a JSR instruction that places the return address at the top of the stack, and hence on top of the parameters.

Where there has been a choice between execution time and memory usage, we have chosen the approach that minimizes execution time. For example, in the case of arrays that are more than 256 bytes long, it is faster to handle the full pages, then handle the remaining partial page separately, than to handle the entire array in a single loop. The reason is that the first approach can use an 8-bit counter in an index register, whereas the second approach requires a 16-bit counter in memory.

We have also chosen the approach that minimizes the number of repetitive calculations. For example, in the case of array indexing, the number of bytes between the starting addresses of elements differing only by one in a particular subscript (known as the size of that subscript) depends only on the number of bytes per element and the bounds of the array. Thus, the sizes of the various subscripts can be calculated as soon as the bounds of the array are known; the sizes are therefore used as parameters for the indexing routines, so that they need not be calculated each time a particular array is indexed.

As for execution time, we have specified it for most short routines. For longer routines, we have given an approximate execution time. The execution time of programs involving many branches will obviously depend on which path is followed in a particular case. This is further complicated for the 6502 by the fact that branch instructions themselves require different numbers of clock cycles depending on whether the branch is not taken, taken within the current page, or taken across a page boundary. Thus, a precise execution time is often impossible to define. The documentation always contains at least one typical example showing an approximate or maximum execution time.

Our philosophy on error indications and special cases has been the following:

1. Routines should provide an easily tested indicator (such as the Carry flag) of whether any errors or exceptions have occurred.

2. Trivial cases, such as no elements in an array or strings of zero length, should result in immediate exits with minimal effect on the underlying data.

3. Misspecified data (such as a maximum string length of zero or an index beyond the end of an array) should result in immediate exits with minimal effect on the underlying data.
4. The documentation should include a summary of errors and exceptions (under the heading of “Special Cases”).

5. Exceptions that may actually be convenient for the user (such as deleting more characters than could possibly be left in a string rather than counting the precise number) should be handled in a reasonable way, but should still be indicated as errors.

Obviously, no method of handling errors or exceptions can ever be completely consistent or well suited to all applications. We have taken the approach that a reasonable set of subroutines must deal with this issue, rather than ignoring it or assuming that the user will always provide data in the proper form.

The subroutines are listed as follows:

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11C  Buffered Interrupt-Driven Input/Output Using a 6850 ACIA  480
11D  Real-Time Clock and Calendar  490
Binary to BCD Conversion (BN2BCD)

Converts one byte of binary data to two bytes of BCD data.

Procedure: The program subtracts 100 repeatedly from the original data to determine the hundreds digit, then subtracts ten repeatedly from the remainder to determine the tens digit, and finally shifts the tens digit left four positions and combines it with the ones digit.

Registers Used: All
Execution Time: 133 cycles maximum, depends on the number of subtractions required to determine the tens and hundreds digits.
Program Size: 38 bytes
Data Memory Required: One byte anywhere in RAM (address TEMP).

Entry Conditions
Binary data in the accumulator.

Exit Conditions
Hundreds digit in the accumulator
Tens and ones digits in index register Y.

Examples
1. Data: (A) = 6E16 (110 decimal)
   Result: (A) = 0116 (hundreds digit)
   (Y) = 1016 (tens and ones digits)

2. Data: (A) = B716 (183 decimal)
   Result: (A) = 0116 (hundreds digit)
   (Y) = 8316 (tens and ones digits)
Registers used: All

Time: 133 cycles maximum

Size: Program 38 bytes
Data 1 byte

BN2BCD:

; CALCULATE 100'S DIGIT
; DIVIDE BY 100
; Y = QUOTIENT
; A = REMAINDER
LDY #0FFH ;START QUOTIENT AT -1
SEC ;SET CARRY FOR INITIAL SUBTRACTION

D100LP:

INY ;ADD 1 TO QUOTIENT
SBC #100 ;SUBTRACT 100
Bcs D100LP ;BRANCH IF A IS STILL LARGER THAN 100
ADC #100 ;ADD THE LAST 100 BACK
TAX ;SAVE REMAINDER
TYA
PHA ;SAVE 100'S DIGIT ON THE STACK
TXA ;GET REMAINDER

; CALCULATE 10'S AND 1'S DIGITS
; DIVIDE REMAINDER OF THE 100'S DIGIT BY 10
; Y = 10'S DIGIT
; A = 1'S DIGIT
LDY #0FFH ;START QUOTIENT AT -1
SEC ;SET CARRY FOR INITIAL SUBTRACTION

D10LP:

INY ;ADD 1 TO QUOTIENT
SBC #10 ;SUBTRACT 10
Bcs D10LP ;BRANCH IF A IS STILL LARGER THAN 10
ADC #10 ;ADD THE LAST 10 BACK

;COMBINE 1'S AND 10'S DIGITS
STA TEMP ;SAVE 1'S DIGIT
TYA ;GET 10'S DIGIT
ASL A
ASl A
ASL A
ASL A
ORA TEMP ;OR IN THE 1'S DIGIT

;RETURN WITH Y = LOW BYTE A = HIGH BYTE
TAX ;PLACE IN REG Y
PLA ;GET 100'S DIGIT
RTS

;DATA
TEMP: .BLOCK 1 ;TEMPORARY USED TO COMBINE 1'S AND 10'S DIGITS
SAMPLE EXECUTION:

SC0401:

; CONVERT 0A HEXADECIMAL TO 10 BCD
LDA #0AH
JSR BN2BCD
BRK ; A=0, Y=10H

; CONVERT FF HEXADECIMAL TO 255 BCD
LDA #0FFH
JSR BN2BCD
BRK ; A=02H, Y=55H

; CONVERT 0 HEXADECIMAL TO 0 BCD
LDA #0
JSR BN2BCD
BRK ; A=0, Y=0

.END
BCD to Binary Conversion (BCD2BN)

Converts one byte of BCD data to one byte of binary data.

Procedure: The program masks off the more significant digit, multiplies it by ten using shifts (10 = 8 + 2, and multiplying by eight or by two is equivalent to three or one left shifts, respectively), and adds the product to the less significant digit.

Registers Used: A, P, Y
Execution Time: 38 cycles
Program Size: 24 bytes
Data Memory Required: One byte anywhere in RAM (Address TEMP).

Entry Conditions
BCD data in the accumulator.

Exit Conditions
Binary data in the accumulator.

Examples
1. Data: \( (A) = 99_{16} \)
   Result: \( (A) = 63_{16} = 99_{10} \)

2. Data: \( (A) = 23_{16} \)
   Result: \( (A) = 17_{16} = 23_{10} \)
BCD2BN:
;MULTIPLY UPPER NIBBLE BY 10 AND SAVE IT
; TEMP := UPPER NIBBLE * 10 WHICH EQUALS UPPER NIBBLE * (8 + 2)
TAY ;SAVE ORIGINAL VALUE
AND #0F0H ;GET UPPER NIBBLE
LSR A ;DIVIDE BY 2 WHICH = UPPER NIBBLE * 8
STA TEMP ;SAVE * 8
LSR A ;DIVIDE BY 4
LSR A ;DIVIDE BY 8: A = UPPER NIBBLE * 2
CLC
ADC TEMP
STA TEMP ;REG A = UPPER NIBBLE * 10
TYA ;GET ORIGINAL VALUE
AND #0FH ;GET LOWER NIBBLE
CLC
ADC TEMP ;ADD TO UPPER NIBBLE
RTS

;DATA
TEMP: .BLOCK 1

;SAMPLE EXECUTION:

;SC0402:
;CONVERT 0 BCD TO 0 HEXADECIMAL
LDA #0
JSR BCD2BN
BRK ;A=0

;CONVERT 99 BCD TO 63 HEXADECIMAL
LDA #099H
JSR BCD2BN
BRK ;A=63H

;CONVERT 23 BCD TO 17 HEXADECIMAL
LDA #23H
JSR BCD2BN
BRK ;A=17H

.END
Binary to Hexadecimal ASCII Conversion
(BN2HEX)

Converts one byte of binary data to two ASCII characters corresponding to the two hexadecimal digits.

Procedure: The program masks off each hexadecimal digit separately and converts it to its ASCII equivalent. This involves a simple addition of 3016 if the digit is decimal. If the digit is non-decimal, an additional factor of seven must be added to handle the break between ASCII 9 (3916) and ASCII A (4116).

Registers Used: All
Execution Time: 77 cycles plus three extra cycles for each non-decimal digit.
Program Size: 31 bytes
Data Memory Required: None

Entry Conditions
Binary data in the accumulator.

Exit Conditions
ASCII equivalent of more significant hexadecimal digit in the accumulator
ASCII equivalent of less significant hexadecimal digit in index register Y.

Examples
1. Data: \((A) = \text{FB}_{16}\)
   Result: \((A) = 46_{16} \text{ (ASCII F)}\)
           \((Y) = 42_{16} \text{ (ASCII B)}\)

2. Data: \((A) = \text{59}_{16}\)
   Result: \((A) = 35_{16} \text{ (ASCII 5)}\)
           \((Y) = 39_{16} \text{ (ASCII 9)}\)
BN2HEX:

;CONVERT HIGH NIBBLE
TAX
AND #0F0H
LSR A
LSR A
LSR A
LSR A
JSR NASCII
PHA

;CONVERT LOW NIBBLE
TXA
AND #0FH
JSR NASCII
TAY
PLA
RTS

;SUBROUTINE NASCII
;PURPOSE: CONVERT A HEXADECIMAL DIGIT TO ASCII
;ENTRY: A = BINARY DATA IN LOWER NIBBLE
;EXIT: A = ASCII CHARACTER
;REGISTERS USED: A,P

NASCII:
CMP #10
BCC NAS1
CLC
ADC #7

NAS1:
ADC #'0'
RTS

SAMPLE EXECUTION:
SC0403:

; CONVERT 0 TO '00'
LDA   #0
JSR   BN2HEX
BRK
; A='0'=30H, Y='0'=30H

; CONVERT FF HEX TO 'FF'
LDA   #0FFH
JSR   BN2HEX
BRK
; A='F'=46H, Y='F'=46H

; CONVERT 23 HEX TO '23'
LDA   #23H
JSR   BN2HEX
BRK
; A='2'=32H, Y='3'=33H

.END
Converts two ASCII characters (representing two hexadecimal digits) to one byte of binary data.

**Procedure:** The program converts each ASCII character separately to a hexadecimal digit. This involves a simple subtraction of 30₁₀ (ASCII zero) if the digit is decimal. If the digit is non-decimal, an additional factor of seven must be subtracted to handle the break between ASCII 9 (39₁₀) and ASCII A (41₁₀). The program then shifts the more significant digit left four bits and combines it with the less significant digit. The program does not check the validity of the ASCII characters (i.e., whether they are, in fact, the ASCII representations of hexadecimal digits).

### Entry Conditions

More significant ASCII digit in the accumulator, less significant ASCII digit in index register Y.

### Exit Conditions

Binary data in the accumulator.

### Examples:

1. Data:  
   
   (A) = 44₁₆ (ASCII D)  
   
   (Y) = 37₁₆ (ASCII 7)  
   
   Result:  
   
   (A) = D7₁₆

2. Data:  
   
   (A) = 31₁₆ (ASCII 1)  
   
   (Y) = 42₁₆ (ASCII B)  
   
   Result:  
   
   (A) = 1B₁₆
172  CODE CONVERSION

; Entry:  Register A = First ASCII digit, high order value;
;         Register Y = Second ASCII digit, low order value;
; Exit:   Register A = Binary data
; Registers used: A,P,Y
; Time:   Approximately 74 cycles
; Size:   Program 30 bytes
;         Data   1 byte

HEX2BN:
PHA         ;SAVE HIGH CHARACTER
TYA         ;GET LOW CHARACTER
JSR A2HEX   ;CONVERT IT
STA TEMP    ;SAVE LOW NIBBLE
PLA         ;GET THE HIGH CHARACTER
JSR A2HEX   ;CONVERT IT
ASL A       ;SHIFT HIGH NIBBLE TO THE UPPER 4 BITS
ASL A       ;OR IN THE LOW NIBBLE
ASL A
ORA TEMP    ;SUBROUTINE: A2HEX
RTS

;SUBROUTINE: A2HEX
;PURPOSE: CONVERT ASCII TO A HEX NIBBLE
;ENTRY: A = ASCII CHARACTER
;EXIT:  A = BINARY VALUE OF THE ASCII CHARACTER
;REGISTERS USED: A,P

A2HEX:
SEC         ;SUBTRACT ASCII OFFSET
SBC #0'      
CMP #10      ;BRANCH IF A IS A DECIMAL DIGIT
BCC A2HEX1   ;ELSE SUBTRACT OFFSET FOR LETTERS
SBC #7

A2HEX1:
RTS

;DATA
TEMP:      .BLOCK 1

; SAMPLE EXECUTION:
SC0404:

;CONVERT 'C7' TO C7 HEXADECIMAL
LDA '#C'
LDY '#7'
JSR HEX2BN
BRK ;A=C7H

;CONVERT '2F' TO 2F HEXADECIMAL
LDA '#2'
LDY '#F'
JSR HEX2BN ;A=2FH
BRK

;CONVERT '23' TO 23 HEXADECIMAL
LDA '#2'
LDY '#3'
JSR HEX2BN
BRK ;A=23H

.END
Conversion of a Binary Number to Decimal ASCII (BN2DEC)

Converts a 16-bit signed binary number to an ASCII string, consisting of the length of the number (in bytes), an ASCII minus sign (if necessary), and the ASCII digits.

Procedure: The program takes the absolute value of the number if it is negative and then keeps dividing by ten until it produces a quotient of zero. It converts each digit of the quotient to ASCII (by adding ASCII 0) and concatenates the digits along with an ASCII minus sign (in front) if the original number was negative.

Registers Used: All
Execution Time: Approximately 7,000 cycles
Program Size: 174 bytes
Data Memory Required: Seven bytes anywhere in RAM for the return address (two bytes starting at address RETADR), the sign of the original value (address NGFLAG), temporary storage for the original value (two bytes starting at address VALUE), and temporary storage for the value mod 10 (two bytes starting at address MOD10). Also, two bytes on page 0 for the buffer pointer (address BUFPTR, taken as 00D016 and 00D116 in the listing). This data memory does not include the output buffer which should be seven bytes long.

Entry Conditions

Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of output buffer address
More significant byte of output buffer address
Less significant byte of value to convert
More significant byte of value to convert

Exit Conditions

Order in buffer
Length of the string in bytes
ASCII − (if original number was negative)
ASCII digits (most significant digit first)

Examples

1. Data: Value to convert = 3EB716

   Result (in output buffer):
   05 (number of bytes in buffer)
   31 (ASCII 1)
   36 (ASCII 6)
   30 (ASCII 0)
   35 (ASCII 5)
   35 (ASCII 5)

   That is, $3EB7_{16} = 16055_{10}$.

2. Data: Value to convert = FFC816

   Result (in output buffer):
   03 (number of bytes in buffer)
   2D (ASCII −)
   35 (ASCII 5)
   36 (ASCII 6)

   That is, $FFC8_{16} = -5610$, when considered as a signed two's complement number.
Title: Binary to decimal ASCII

Name: BN2DEC

Purpose: Convert a 16-bit signed binary number to ASCII data

Entry:
- TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Low byte of the output buffer address,
- High byte of the output buffer address,
- Low byte of the value to convert,
- High byte of the value to convert

Exit: The first byte of the buffer is the length, followed by the characters.

Registers used: All

Time: Approximately 7,000 cycles

Size:
- Program 170 bytes
- Data 7 bytes plus
- 2 bytes in page zero

; PAGE ZERO POINTER
BUFPTR: .EQU 0D0H

; PAGE ZERO BUFFER POINTER

; PROGRAM
BN2DEC:

; SAVE PARAMETERS
PLA
STA RETADR ; SAVE LOW BYTE OF RETURN ADDRESS
PLA
STA RETADR+1 ; SAVE HIGH BYTE
PLA
STA VALUE ; SAVE LOW BYTE OF VALUE
PLA
STA VALUE+1 ; SAVE HIGH BYTE OF THE VALUE TO CONVERT
STA NGFLAG ; SAVE MSB OF VALUE AS SIGN OF VALUE
BPL GETBP ; BRANCH IF VALUE IS POSITIVE
LDA #0 ; ELSE TAKE ABSOLUTE VALUE (0 - VALUE)
SEC
SBC VALUE
STA VALUE
LDA  #0
SBC  VALUE+1
STA  VALUE+1

GETBP:

PLA
STA  BUFPTR
PLA
STA  BUFPTR+1

;SAVE STARTING ADDRESS OF OUTPUT BUFFER

;SET BUFFER TO EMPTY
LDA  #0
LDY  #0
STA  (BUFPTR),Y

;BUFFER[0] := 0

;CONVERT VALUE TO A STRING

;VALUE := VALUE DIV 10
;MOD10 := VALUE MOD 10
LDA  #0
STA  MOD10
STA  MOD10+1

LDX  #16
CLC

;CLEAR CARRY

DVLOOP:

ROL  VALUE
ROL  VALUE+1
ROL  MOD10
ROL  MOD10+1

;SHIFT THE CARRY INTO DIVIDEND BIT 0
;WHICH WILL BE THE QUOTIENT
;AND SHIFT DIVIDEND AT THE SAME TIME

;A,Y = DIVIDEND - DIVISOR
SEC
LDA  MOD10
SBC  #0
TAY
LDA  MOD10+1
SBC  #0
BCC  DECCNT
;BRANCH IF DIVIDEND < DIVISOR
STY  MOD10
;ELSE
STA  MOD10+1

; NEXT BIT OF QUOTIENT IS A ONE AND SET
; DIVIDEND := DIVIDEND - DIVISOR

DECCNT:

DEX
BNE  DVLOOP

ROL  VALUE
ROL  VALUE+1

;SHIFT IN THE LAST CARRY FOR THE QUOTIENT

;CONCATENATE THE NEXT CHARACTER
CONCH:
LDA MOD10
CLC
ADC #'0' ;CONVERT 0..9 TO ASCII '0'..'9'
JSR CONCAT

;IF VALUE <> 0 THEN CONTINUE
LDA VALUE
ORA VALUE+1
BNE

EXIT:
LDA NGFLAG
BPL POS ;BRANCH IF ORIGINAL VALUE WAS POSITIVE
LDA '#-';ELSE
JSR CONCAT ;PUT A MINUS SIGN IN FRONT

POS:
LDA RETADR+1
PHA
LDA RETADR
PHA
RTS ;RETURN

;SUBROUTINE: CONCAT
;PURPOSE: CONCATENATE THE CHARACTER IN REGISTER A TO THE
;FRONT OF THE STRING ACCESSED THROUGH BUFPTR
;ENTRY: BUFPTR[0] = LENGTH
;EXIT: REGISTER A CONCATENATED (PLACED IMMEDIATELY AFTER THE LENGTH BYTE)
;REGISTERS USED: A,P,Y

CONCAT:
PHA ;SAVE THE CHARACTER ON THE STACK

;MOVE THE BUFFER RIGHT ONE CHARACTER
LDY #0
LDA (BUFPTR),Y ;GET CURRENT LENGTH
TAY
BEQ EXITMR ;BRANCH IF LENGTH = 0

MVELP:
LDA (BUFPTR),Y ;GET NEXT CHARACTER
INY
STA (BUFPTR),Y ;STORE IT
DEY
DEY
BNE MVELP ;CONTINUE UNTIL DONE

EXITMR:
PLA ;GET THE CHARACTER BACK FROM THE STACK
LDY #1
STA (BUFPTR),Y ;STORE THE CHARACTER
LDY #0
LDA (BUFPTR),Y ;GET LENGTH BYTE
CLC
ADC       #1                  ;INCREMENT LENGTH BY 1
STA       (BUF PTR), Y      ;UPDATE LENGTH

;DATA
RTS
RETA DR: .BLOCK 2          ;SAVE RETURN ADDRESS
NGFLAG: .BLOCK 1           ;SIGN OF ORIGINAL VALUE
VALUE:  .BLOCK 2           ;VALUE TO CONVERT
MOD10:  .BLOCK 2           ;MODULO 10 TEMPORARY

;SAMPLE EXECUTION:

;SC0405:
;CONVERT 0 TO '0'
LDA      BUFADR+1           ;HIGH BYTE OF BUFFER ADDRESS
PHA
LDA      BUFADR             ;LOW BYTE BUFFER ADDRESS
PHA
LDA      VALUEADR+1         ;HIGH BYTE OF VALUE
PHA
LDA      VALUE1             ;LOW BYTE OF VALUE
PHA
JSR      BN2DEC             ;CONVERT
BRK
;BUFFER SHOULD = '0'

;CONVERT 32767 TO '32767'
LDA      BUFADR+1           ;HIGH BYTE OF BUFFER ADDRESS
PHA
LDA      BUFADR             ;LOW BYTE BUFFER ADDRESS
PHA
LDA      VALUE2+1           ;HIGH BYTE OF VALUE
PHA
LDA      VALUE2             ;LOW BYTE OF VALUE
PHA
JSR      BN2DEC             ;CONVERT
BRK
;BUFFER SHOULD = '32767'

;CONVERT -32768 TO '-32768'
LDA      BUFADR+1           ;HIGH BYTE OF BUFFER ADDRESS
PHA
LDA      BUFADR             ;LOW BYTE BUFFER ADDRESS
PHA
LDA      VALUE3+1           ;HIGH BYTE OF VALUE
PHA
LDA      VALUE3             ;LOW BYTE OF VALUE
JSR       BN2DEC  ; CONVERT
BRK       SC0405  ; BUFFER SHOULD = '-32768'
JMP  

VALUE1:  .WORD  0       ; TEST VALUE 1
VALUE2:  .WORD  32767  ; TEST VALUE 2
VALUE3:  .WORD  -32768 ; TEST VALUE 3
BUFADR:  .WORD BUFFER   ; BUFFER ADDRESS
BUFFER:  .BLOCK 7       ; 7 BYTE BUFFER

.END
Conversion of ASCII Decimal to Binary
(DEC2BN)

Converts an ASCII string consisting of the length of the number (in bytes), a possible ASCII – or + sign, and a series of ASCII digits to two bytes of binary data. Note that the length is an ordinary binary number, not an ASCII number.

Procedure: The program sets a flag if the first ASCII character is a minus sign and skips over a leading plus sign. It then converts each subsequent digit to decimal (by subtracting ASCII zero), multiplies the previous digits by ten (using the fact that 10 = 8 + 2, so a multiplication by ten can be reduced to left shifts and additions), and adds the new digit to the product. Finally, the program subtracts the result from zero if the original number was negative. The program exits immediately, setting the Carry flag, if it finds something other than a leading sign or a decimal digit in the string.

Registers Used: All
Execution Time: 670 cycles (approximately)
Program Size: 171 bytes
Data Memory Required: Four bytes anywhere in RAM for an index, a two-byte accumulator (starting address ACCUM), and a flag indicating the sign of the number (address NGLAG), two-bytes on page zero for a pointer to the string (address BUFPTR, taken as 00F0\textsubscript{16} and 00F1\textsubscript{16} in the listing).

Special Cases:
1. If the string contains something other than a leading sign or a decimal digit, the program returns with the Carry flag set to 1. The result in registers A and Y is invalid.
2. If the string contains only a leading sign (ASCII + or ASCII –), the program returns with the Carry flag set to 1 and a result of zero.

Entry Conditions
(A) = More significant byte of string address
(Y) = Less significant byte of string address

Exit Conditions
(A) = More significant byte of binary value
(Y) = Less significant byte of binary value

Carry flag is 0 if the string was valid; Carry flag is 1 if the string contained an invalid character. Note that the result is a signed two's complement 16-bit number.

Examples
1. Data: String consists of
04 (number of bytes in string)
31 (ASCII 1)
32 (ASCII 2)
33 (ASCII 3)
34 (ASCII 4)
That is, the number is +1,234\textsubscript{10}.

Result: (A) = 04\textsubscript{16} (more significant byte of binary data)
(Y) = C2\textsubscript{16} (less significant byte of binary data)
That is, the number +1234\textsubscript{10} = 04C2\textsubscript{16}.
2. Data: String consists of

- 06 (number of bytes in string)
- 2D (ASCII -)
- 33 (ASCII 3)
- 32 (ASCII 2)
- 37 (ASCII 7)
- 35 (ASCII 5)
- 30 (ASCII 0)

That is, the number is $-32,750_{10}$.

Result: (A) = $80_{16}$ (more significant byte of binary data)
(Y) = $12_{16}$ (less significant byte of binary data)

That is, the number $-32,750_{10} = 8012_{16}$.

Title: Decimal ASCII to binary
Name: DEC2BN

Purpose: Convert ASCII characters to two bytes of binary data.

Entry: Register A = high byte of string address
Register Y = low byte of string address
The first byte of the string is the length of the string.

Exit: Register A = high byte of the value
Register Y = low byte of the value
IF NO ERRORS THEN
CARRY FLAG = 0
ELSE
CARRY FLAG = 1

Registers used: All

Time: Approximately 670 cycles

Size: Program 171 bytes
Data 4 bytes plus
2 bytes in page zero

; PAGE ZERO LOCATION
BUF PTR: .EQU 0F0H ; PAGE ZERO POINTER TO STRING

; PROGRAM
DEC2BN:
STA BUF PTR +1
STY BUF PTR ; SAVE THE STRING ADDRESS
;INITIALIZE
LDY #0
LDA (BUFPTR), Y ;GET LENGTH
TAX ; TO REGISTER X
LDA #1
STA INDEX ;INDEX := 1
LDA #0
STA ACCUM ;ACCUM := 0
STA ACCUM+1
STA NGFLAG ;SIGN OF NUMBER IS POSITIVE

;CHECK THAT THE BUFFER IS NOT ZERO
TXA
BNE INIT1 ;EXIT WITH ACCUM = 0 IF BUFFER IS EMPTY
JMP EREXIT ;ERROR EXIT IF NOTHING IN BUFFER

INIT1:
LDY INDEX
LDA (BUFPTR), Y ;GET FIRST CHARACTER
CMP #'-' ;IS IT A MINUS ?
BNE PLUS ;BRANCH IF NOT '-'
LDA #$FFH
STA NGFLAG ;ELSE SIGN OF NUMBER IS NEGATIVE
INC INDEX ;SKIP PAST MINUS SIGN
DEX ;DECREMENT COUNT
BEQ EREXIT ;ERROR EXIT IF ONLY '-' IN BUFFER
JMP CNVERT ;START CONVERSION

PLUS:
CMP #'+' ;START CONVERSION IF FIRST CHARACTER IS NOT '+'
BNE CHKDIG ;DECREMENT COUNT, IGNORE PLUS SIGN
INC INDEX
DEX
BEQ EREXIT ;ERROR EXIT IF ONLY '+' IN BUFFER

CNVERT:
LDY INDEX
LDA (BUFPTR), Y ;GET NEXT CHARACTER

CHKDIG:
CMP #'0'
BMI EREXIT ;ERROR IF < '0' (NOT A DIGIT)
CMP #'9'+1
BPL EREXIT ;ERROR IF > '9' (NOT A DIGIT)
PHA ;SAVE THE DIGIT ON THE STACK

;VALID DECIMAL DIGIT SO
; ACCUM := ACCUM * 10
; = ACCUM * (8 + 2)
; = (ACCUM * 8) + (ACCUM * 2)
ASL ACCUM
ROL ACCUM+1 ;TIMES 2
LDA ACCUM
LDY ACCUM+1 ;SAVE ACCUM * 2
ASL ACCUM
ROL ACCUM+1
ASL ACCUM
ROL ACCUM+1 ;TIMES 8
CLC
ADCAccum;SUMWITH*2
STAACCUM
TYA
ADCAccum+1
STAACCUM+1;ACCUM:=ACCUM*10

;ADDINTHENEXTDIGIT
;ACCUM:=ACCUM+DIGIT
PLA
SEC
SBC'#0';CONVERT'0'..'9'TOBINARY0..9
CLC
ADCACCUM
STAACCUM
BCCD2B1;BRANCHIFNOCARRYTOHIGHBYTE
INCACCUM+1;ELSEINCREMENTHIGHBYTE

D2B1:
INCINDEX;INCREMENTTONEXTCARACTER
DEXBNECNVERT;CONTINUECONVERSION
LDA NGFLAG
BPL OKEXIT;BRANCHIFTHEVALUEWASPOSITIVE
LDA #0;ELSEREPLACERESULTWITH-RESULT
SEC
SBCACCUM
STAACCUM
LDA #0
SBCACCUM+1
STAACCUM+1

;GETTHEBINARYVALUEANDRETURN
OKEXIT:
CLC
BCCEXIT

EREXIT:
SEC

EXIT:
LDA ACCUM+1;GETHIGHBYTEOVALUE
LDY ACCUM
RTS

;DATA
INDEX:.BLOCK1
ACCUM:.BLOCK2
NGFLAG:.BLOCK1

;INDEXINTOSTRING
;ACCUMULATEDVALUE(2BYTES)
;SIGNOFNUMBER

;SAMPLEEXECUTION:
SC0406:

; CONVERT '1234' TO 04D2 HEX
LDA ADRS1+1
LDY ADRS1
JSR DEC2BN
BRK ; A = 04, Y = D2 HEX

; CONVERT '-32767' TO 7FFF HEX
LDA ADRS2+1
LDY ADRS2
JSR DEC2BN
BRK ; A = 7F, Y = FF HEX

; CONVERT '-32768' TO 8000 HEX
LDA ADRS3+1
LDY ADRS3
JSR DEC2BN
BRK ; A = 80 HEX, Y = 00 HEX

S1: .BYTE 4,'1234'
S2: .BYTE 6,'+32767'
S3: .BYTE 6,'-32768'

ADRS1: .WORD S1 ; ADDRESS OF S1
ADRS2: .WORD S2 ; ADDRESS OF S2
ADRS3: .WORD S3 ; ADDRESS OF S3

.END
Converts an ASCII lower-case letter to its upper-case equivalent.

Procedure: The program determines from comparisons whether the data is an ASCII lower-case letter. If it is, the program subtracts 20₁₀ from it, thus converting it to its upper-case equivalent. If it is not, the program leaves it unchanged.

<table>
<thead>
<tr>
<th>Registers Used: A, P</th>
</tr>
</thead>
<tbody>
<tr>
<td>Execution Time: 18 cycles if the original character is valid, fewer cycles otherwise.</td>
</tr>
<tr>
<td>Program Size: 12 bytes</td>
</tr>
<tr>
<td>Data Memory Required: None</td>
</tr>
</tbody>
</table>

Register A = Lowercase ASCII character

Exit Conditions
If the character is an ASCII lower-case letter, the upper-case equivalent is in the accumulator. If the character is not an ASCII lower-case letter, the accumulator is unchanged.

Examples
1. Data: (A) = 62₁₀ (ASCII b)
Result: (A) = 42₁₀ (ASCII B)

2. Data: (A) = 74₁₀ (ASCII t)
Result: (A) = 54₁₀ (ASCII T)

Title
Lower case to upper case translation
LC2UC

Purpose: Convert one ASCII character to upper case from lower case if necessary.

Entry: Register A = Lower case ASCII character
; Exit: Register A = Upper case ASCII character if A is lower case, else A is unchanged.;
; Registers used: A, P
; Time: 18 cycles if A is lower case, less otherwise
; Size: Program 12 bytes
; Data none

LC2UC:
CMP #'a'
BCC $1 ; BRANCH IF < 'a'
CMP #'z'+1 ; BRANCH IF > 'z'
BCS EXIT
SEC
SBC #20H ; CHANGE 'a'..'z' into 'A'..'Z'

EXIT:
RTS

; SAMPLE EXECUTION:

SC0407:
; CONVERT LOWER CASE E TO UPPER CASE
LDA #'e'
JSR LC2UC
BRK ; A='E'=45H

; CONVERT LOWER CASE Z TO UPPER CASE
LDA #'z'
JSR LC2UC
BRK ; A='Z'=5AH

; CONVERT UPPER CASE A TO UPPER CASE A
LDA #'A'
JSR LC2UC
BRK ; A='A'=41H

.END ; OF PROGRAM
ASCII to EBCDIC Conversion (ASC2EB) 4H

Converts an ASCII character to its EBCDIC equivalent.

Procedure: The program uses a simple table lookup with the data as the index and address EBCDIC as the base. Printable ASCII characters for which there are no EBCDIC equivalents are translated to an EBCDIC space (4016); nonprintable ASCII characters without EBCDIC equivalents are translated to an EBCDIC NUL (0016).

Registers Used: A, P, Y
Execution Time: 14 cycles
Program Size: Seven bytes, plus 128 bytes for the conversion table.
Data Memory Required: None

Entry Conditions
ASCII character in the accumulator.

Exit Conditions
EBCDIC equivalent in the accumulator.

Examples
1. Data: \( (A) = 35_{16} \) (ASCII 5)
   Result: \( (A) = F5_{16} \) (EBCDIC 5)
2. Data: \( (A) = 77_{16} \) (ASCII w)
   Result: \( (A) = A6_{16} \) (EBCDIC w)
3. Data: \( (A) = 2A_{16} \) (ASCII *)
   Result: \( (A) = 5C_{16} \) (EBCDIC *)
Registers used: A, P, Y
Time: 14 cycles
Size: Program 7 bytes, Data 128 bytes for the table

ASC2EB:
AND #7FH
TAY
LDA EBCDIC,Y
RTS

; ASCII TO EBCDIC TABLE
; PRINTABLE ASCII CHARACTERS FOR WHICH THERE ARE NO EBCDIC EQUIVALENTS
; ARE TRANSLATED TO AN EBCDIC SPACE (040H), NON PRINTABLE ASCII CHARACTERS
; WITH NO EQUIVALENTS ARE TRANSLATED TO A EBCDIC NULL (000H)

EBCDIC:

; ASCII
NUL SOH STX ETX EOT ENQ ACK BEL 

; EBCDIC
.CODE 000H,000H,000H,022H,037H,000H,000H,000H

; ASCII
BS HT LF VT FF CR SO SI 

; EBCDIC
.CODE 000H,02BH,025H,000H,02DH,000H,000H,000H

; ASCII
DLE DC1 DC2 DC3 DC4 NAK SYN ETB 

; EBCDIC
.CODE 000H,000H,000H,037H,000H,000H,000H,000H

; ASCII
CAN EM SUB ESC FS GS RS VS 

; EBCDIC
.CODE 000H,000H,000H,000H,000H,000H,000H,000H

; ASCII
SPACE ! " # $ % & ' ( ) * + , - . / 0 1 2 3 4 5 6 7 8 9 : ; < = > ? @ [ \ ] ^ _ ` a b c d e f g h i j k l m n o p q r s t u v w x y z 

; EBCDIC
.CODE 0A7H,0A8H,0A9H,040H,04OH,040H,06AH,040H

; ASCII
abcdefg

; EBCDIC
.CODE 07CH,081H,082H,083H,084H,085H,086H,087H

; ASCII
h i j k l m n o p q r s t u v w

; EBCDIC

; ASCII

; EBCDIC
.CODE 097H,098H,099H,0A2H,0A3H,0A4H,0A5H,0A6H

; ASCII

; EBCDIC

; ASCII

; EBCDIC
SAMPLE EXECUTION:

;ASCII 'A'  
LDA #$'A'   ;ASCII 'A'
JSR ASC2EB  ;EBCDIC 'A' = 0C1H
BRK         

;ASCII '1'
LDA #$'1'
JSR ASC2EB  ;ASCII '1'
BRK         ;EBCDIC '1' = 0F1H

;ASCII 'a'
LDA #$'a'
JSR ASC2EB  ;ASCII 'a'
BRK         ;EBCDIC 'a' = 081H

.END       ;END PROGRAM
**EBCDIC to ASCII Conversion (EB2ASC)**

Converts an EBCDIC character to its ASCII equivalent.

**Procedure:** The program uses a simple table lookup with the data as the index and address ASCII as the base. Printable EBCDIC characters for which there are no ASCII equivalents are translated to an ASCII space (20<sub>16</sub>); nonprintable EBCDIC characters without ASCII equivalents are translated to an ASCII NUL (00<sub>16</sub>).

<table>
<thead>
<tr>
<th>Registers Used: A, P, Y</th>
</tr>
</thead>
<tbody>
<tr>
<td>Execution Time: 12 cycles</td>
</tr>
<tr>
<td>Program Size: Five bytes, plus 256 bytes for the conversion table.</td>
</tr>
<tr>
<td>Data Memory Required: None</td>
</tr>
</tbody>
</table>

**Entry Conditions**

EBCDIC character in the accumulator.

**Exit Conditions**

ASCII equivalent in the accumulator.

**Examples**

1. Data: (A) = 85<sub>16</sub> (EBCDIC e)  
   Result: (A) = 65<sub>16</sub> (ASCII e)

2. Data: (A) = 4E<sub>16</sub> (EBCDIC +)  
   Result: (A) = 2B<sub>16</sub> (ASCII +)
EB2ASC:

TAY
LDA ASCII,Y ;TRANSLATE
RTS

; EBCDIC TO ASCII TABLE
; PRINTABLE EBCDIC CHARACTERS FOR WHICH THERE ARE NO ASCII EQUIVALENTS
; ARE TRANSLATED TO AN ASCII SPACE (020H), NON PRINTABLE EBCDIC CHARACTERS
; WITH NO EQUIVALENTS ARE TRANSLATED TO A ASCII NULL (000H)

ASCII:

; NUL        TAB       DEL
; ASCII
.BYTE 000H,000H,000H,000H,000H,009H,000H,07FH ;ASCII
.BYTE 000H,000H,000H,000H,000H,000H,000H,000H  ;ASCII
; NEW LINE
.BYTE 000H,000H,000H,000H,000H,000H,000H,000H  ;ASCII
.BYTE 000H,000H,000H,000H,000H,000H,000H,000H  ;ASCII
; LF
.BYTE 000H,003H,000H,000H,00AH,000H,000H       ;ASCII
; CR
.BYTE 000H,000H,000H,009H,000H,00DH,000H,000H   ;ASCII
; EOT
.BYTE 000H,000H,000H,000H,000H,000H,000H,004H   ;ASCII
; SPACE
.BYTE ' ',000H,000H,000H,000H,000H,000H,000H    ;ASCII
; BRITISH $, <, (,+ |'-',$,',','}',',',');','-',
.BYTE 000H,000H,' ',' ',' ',' '</','','','','','','','');','-',
; &
.BYTE '&',000H,000H,000H,000H,000H,000H,000H    ;ASCII
; ~
.BYTE '!',000H,000H,000H,000H,000H,000H,000H     ;ASCII
; 040H
.BYTE 000H,000H,<' ',',',' ',',',',',> ',?,? ' ;ASCII
; @
.BYTE 000H,000H,':','@','','=' ',',','",000H    ;ASCII
; a b c d e f g h i j k l m n o p q r s t u v w x y z
.BYTE 000H,'a','b','c','d','e','f','g' ;ASCII
; , i
.BYTE 'h','i',000H,000H,000H,000H,000H,000H    ;ASCII
; j
.BYTE 000H,'j',',','k','','l','','m','n','c','p' ;ASCII
; EBCDIC
SAMPLE EXECUTION:

SC0409:

;CONVERT EBCDIC 'A'
LDA #0C1H ;EBCDIC 'A'
JSR EB2ASC ;ASCII 'A' = 041H
BRK

;CONVERT EBCDIC '1'
LDA #0F1H ;EBCDIC '1'
JSR EB2ASC ;ASCII '1' = 031H
BRK

;CONVERT EBCDIC 'a'
LDA #081H ;EBCDIC 'a'
JSR EB2ASC ;ASCII 'a' = 061H
BRK

.END ;END PROGRAM
Memory Fill (MFILL)

Places a specified value in each byte of a memory area of known size, starting at a given address.

Procedure: The program fills all the whole pages with the specified value first and then fills the remaining partial page. This approach is faster than dealing with the entire area in one loop, since 8-bit counters can be used instead of a 16-bit counter. The approach does, however, require somewhat more memory than a single loop with a 16-bit counter. A size of \(0000_{16}\) causes an exit with no memory changed.

Registers Used: All

Execution Time: Approximately 11 cycles per byte plus 93 cycles overhead.

Program Size: 68 bytes

Data Memory Required: Five bytes anywhere in RAM for the array size (two bytes starting at address ARYSZ), the value (one byte at address VALUE), and the return address (two bytes starting at address RETADR). Also two bytes on page 0 for an array pointer (taken as addresses \(00D0_{16}\) and \(00D1_{16}\) in the listing).

Special Cases:
1. A size of zero causes an immediate exit with no memory changed.
2. Filling areas occupied or used by the program itself will cause unpredictable results. Obviously, filling any part of page 0 requires caution, since both this routine and most systems programs use that page.

Entry Conditions
Order in stack (starting from the top)
- Less significant byte of return address
- More significant byte of return address
- Value to be placed in memory
- Less significant byte of area size (in bytes)
- More significant byte of area size (in bytes)
- Less significant byte of starting address
- More significant byte of starting address

Exit Conditions
The area from the starting address through the number of bytes given by the area size is filled with the specified value. The area filled thus starts at BASE and continues through BASE + SIZE - 1 (BASE is the starting address and SIZE is the area size).
Examples

1. Data: \( \text{Value} = \text{FF}_{16} \)
   Area size (in bytes) = \( 0380_{16} \)
   Starting address = \( 1AE0_{16} \)

   Result: \( \text{FF}_{16} \) is placed in memory addresses \( 1AE0_{16} \) through \( 1E5F_{16} \).

2. Data: \( \text{Value} = \text{EA}_{16} \) (6502 operation code for NOP)
   Area size (in bytes) = \( 1C65_{16} \)
   Starting address = \( E34C_{16} \)

   Result: \( \text{EA}_{16} \) is placed in memory addresses \( E34C_{16} \) through \( FFB0_{16} \).

Title
Name: Memory fill
MFILL

Purpose: Fill an area of memory with a value

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Value to be placed in memory,
Low byte of area size in bytes,
High byte of area size in bytes,
Low byte of starting address,
High byte of starting address

Exit: Area filled with value

Registers used: All

Time: Approximately 11 cycles per byte plus 93 cycles overhead.

Size: Program 68 bytes
      Data 5 bytes plus
      2 bytes in page zero

;PAGE ZERO POINTER
ARYPTR: .EQU OD0H ;PAGE ZERO POINTER TO THE ARRAY

MFILL:
;POP THE PARAMETERS FROM THE STACK
PLA
STA RETADR
PLA STA RETADR+1 ;GET THE RETURN ADDRESS
PLA STA VALUE ;GET FILL VALUE
PLA STA ARYSZ
PLA STA ARYSZ+1 ;GET SIZE OF AREA
PLA STA ARYPTR
PLA STA ARYPTR+1 ;GET STARTING ADDRESS OF AREA
LDA RETADR+1
PHA LDA RETADR ;RESTORE RETURN ADDRESS
PHA
;
;DO THE FULL PAGES FIRST
LDA VALUE ;GET VALUE FOR FILL
LDX ARYSZ+1 ;X = NUMBER OF PAGES TO DO
BEQ PARTPG ;BRANCH IF THE HIGH BYTE OF SIZE = 0
LDY #0 FULLPG:
STA (ARYPTR),Y ;STORE VALUE
INY ;INCREMENT TO NEXT BYTE
BNE FULLPG ;BRANCH IF NOT DONE WITH THIS PAGE
INC ARYPTR+1 ;ADVANCE TO THE NEXT PAGE
DEX
BNE FULLPG ;BRANCH IF NOT DONE WITH THE FULL PAGES
;
;DO THE REMAINING PARTIAL PAGE
; REGISTER A STILL CONTAINS VALUE
PARTPG:
LDX ARYSZ ;GET THE NUMBER OF BYTES IN THIS FINAL PAGE
BEQ EXIT ;BRANCH IF LOW BYTE OF SIZE = 0
LDY #0 PARTLP:
STA (ARYPTR),Y ;STORE VALUE
INY ;INCREMENT INDEX
DEX ;DECREMENT COUNTER
BNE PARTLP ;BRANCH IF PARTIAL PAGE IS NOT DONE
EXIT:
RTS

;DATA
ARYSZ: .BLOCK 2 ;NUMBER OF BYTES TO INITIALIZE
VALUE: .BLOCK 1 ;VALUE TO INITIALIZE ARRAY WITH
RETADR: .BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS

;  ;
;  ; SAMPLE EXECUTION
;  ;
;

SC0501:
;FILL A SMALL BUFFER WITH 00
LDA BF1ADR+1
PHA
LDA BF1ADR ;PUSH STARTING ADDRESS
PHA
LDA BF1SZ+1
PHA
LDA BF1SZ ;PUSH NUMBER OF BYTES
LDA #0
PHA ;PUSH VALUE
JSR MFILL ;FILL BUFFER
BRK

;FILL A BIG BUFFER WITH EA HEX (NOP)
LDA BF2ADR+1
PHA
LDA BF2ADR ;PUSH STARTING ADDRESS
PHA
LDA BF2SZ+1
PHA
LDA BF2SZ ;PUSH NUMBER OF BYTES
LDA #0EAH
PHA ;PUSH VALUE
JSR MFILL ;FILL BUFFER
BRK
JMP SC0501

SIZE1: .EQU 47H
SIZE2: .EQU 6000H
BF1ADR: .WORD BF1
BF2ADR: .WORD BF2
BF1SZ: .WORD SIZE1
BF2SZ: .WORD SIZE2
BF1: .BLOCK SIZE1
BF2: .BLOCK SIZE2

.END
Block Move (BLKMOV)

Moves a block of data from a source area to a destination area.

Procedure: The program determines if the starting address of the destination area is within the source area. If it is, then working up from the starting address would overwrite some of the source data. To avoid that problem, the program works down from the highest address (this is sometimes called move right). If the starting address of the destination area is not within the source area, the program simply moves the data starting from the lowest address (this is sometimes called a move left). In either case, the program moves the data by handling complete pages separately from the remaining partial page. This approach allows the program to use 8-bit counters rather than a 16-bit counter, thus reducing execution time (although increasing memory usage). An area size (number of bytes to move) of 0000\text{16} causes an exit with no memory changed.

Important Note: The user should be careful if either the source or the destination area includes the temporary storage used by the program itself. The program provides automatic address wraparound (mod 64K), but the results of any move involving the program’s own temporary storage are unpredictable.

<table>
<thead>
<tr>
<th>Registers Used: All</th>
</tr>
</thead>
<tbody>
<tr>
<td>Execution Time: 128 cycles overhead plus the following:</td>
</tr>
<tr>
<td>1. If data can be moved starting from the lowest address (i.e., left):</td>
</tr>
<tr>
<td>( 20 + 4110 \times (\text{more significant byte of number of bytes to move}) + 18 \times (\text{less significant byte of number of bytes to move}) ).</td>
</tr>
<tr>
<td>2. If data must be moved starting from the highest address (i.e., right) because of overlap:</td>
</tr>
<tr>
<td>( 42 + 4622 \times (\text{more significant byte of number of bytes to move}) + 18 \times (\text{less significant byte of number of bytes to move}) ).</td>
</tr>
</tbody>
</table>

Program Size: 157 bytes

Data Memory Required: Two bytes anywhere in RAM for the length of the move (starting at address MVELEN), four bytes on page 0 for source and destination pointers (starting at addresses MVSRC and MVDEST taken as addresses 00\text{D0}\text{16} and 00\text{D1}\text{16} — source pointer — and addresses 00\text{D2}\text{16 and 00D3}\text{16} — destination pointer — in the listing).

Special Cases:
1. A size (number of bytes to move) of zero causes an immediate exit with no memory changed.
2. Moving data to or from areas occupied or used by the program itself will produce unpredictable results. Obviously, moving data to or from page 0 requires caution, since both this routine and most systems programs use that page. This routine does provide automatic address wraparound (mod 64K) for consistency, but the user must still approach moves involving page 0 carefully.
Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of number of bytes to move
More significant byte of number of bytes to move
Less significant byte of lowest address of destination area
More significant byte of lowest address of destination area
Less significant byte of lowest address of source area
More significant byte of lowest address of source area

Exit Conditions

The block of memory is moved from the source area to the destination area. If the number of bytes to be moved is NBYTES, the lowest address in the destination area is DEST, and the lowest address in the source area is SOURCE, then the area from addresses SOURCE through SOURCE + NBYTES - 1 is moved to addresses DEST through DEST + NBYTES - 1.

Examples

1. Data: Number of bytes to move = 020016
   Lowest address in destination area = 05D116
   Lowest address in source area = 035E16

   Result: The contents of memory locations 035E16 through 055D16 are moved to 05D116 through 07D016.

2. Data: Number of bytes to move = 1B7A16
   Lowest address in destination area = C94616
   Lowest address in source area = C30016

   Result: The contents of memory locations C30016 through DE7916 are moved to C94616 through E4BF16

Note that Example 2 presents a more complex problem than Example 1 because the source and destination areas overlap. If, for instance, the program were simply to move data to the destination area starting from the lowest address, it would initially move the contents of C30016 to C94616. This would destroy the old contents of C94616, which are needed later in the move. The solution to this problem is to move the data starting from the highest address if the destination area is above the source area but overlaps it.
Title:  Block Move
Name:  BLKMOV

Purpose:  Move data from source to destination

Entry:  TOP OF STACK
        Low byte of return address,
        High byte of return address,
        Low byte of number of bytes to move,
        High byte of number of bytes to move,
        Low byte of lowest address in destination
        area,
        High byte of lowest address in destination
        area,
        Low byte of lowest address in source area,
        High byte of lowest address in source area

Exit:  Data moved from source to destination

Registers used:  All

Time:  102 cycles overhead plus move
       move left cycles equals
          20 +
          (high byte of length * 4110) +
          (low byte of length * 18)

       move right cycles equals
          42 +
          (high byte of length * 4622) +
          (low byte of length * 18)

Size:  Program 146 bytes
       Data  2 bytes plus
              4 bytes in page zero

;PAGE ZERO POINTERS
MVSRCE  .EQU  0D0H ;SOURCE ADDRESS
MVDEST  .EQU  0D2H ;DESTINATION ADDRESS

BLKMOV:
;GET RETURN ADDRESS
PLA
TAY
PLA
TAX

;SAVE LOW BYTE
;SAVE HIGH BYTE

;GET NUMBER OF BYTES
PLA
STA MVELEN ;STORE LOW BYTE
PLA
STA MVELEN+1 ;STORE HIGH BYTE

;GET STARTING DESTINATION ADDRESS
PLA
STA MVDEST ;STORE LOW BYTE
PLA
STA MVDEST+1 ;STORE HIGH BYTE

;GET STARTING SOURCE ADDRESS
PLA
STA MVSrCE ;STORE LOW BYTE
PLA
STA MVSrCE+1 ;STORE HIGH BYTE

;RESTORE RETURN ADDRESS
TXA
PHA ;RESTORE HIGH BYTE
TYA
PHA ;RESTORE LOW BYTE

;
;DETERMINE IF DESTINATION AREA IS ABOVE SOURCE AREA BUT OVERLAPS IT. REMEMBER, OVERLAP CAN BE MOD 64K. OVERLAP OCCURS IF;
; STARTING DESTINATION ADDRESS MINUS STARTING SOURCE ADDRESS (MOD 64K)
; IS LESS THAN NUMBER OF BYTES TO MOVE
LDA MVDEST ;CALCULATE DESTINATION - SOURCE
SEC
SBC MVSrCE
TAX
LDA MVDEST+1
SBC MVSrCE+1 ;MOD 64K IS AUTOMATIC - DISCARD CARRY
TAY
TXA
CMP MVELEN
TYA
SBC MVELEN+1
BCS DOLEFT ;BRANCH IF NO PROBLEM WITH OVERLAP

;DESTINATION AREA IS ABOVE SOURCE AREA BUT OVERLAPS IT
;MOVE FROM HIGHEST ADDRESS TO AVOID DESTROYING DATA
JSR MVERHT
JMP EXIT

;NO PROBLEM DOING ORDINARY MOVE STARTING AT LOWEST ADDRESS
DOLEFT:
JSR MVELFT

EXIT:
RTS
SUBROUTINE: MVELFT
PURPOSE: MOVE SOURCE TO DESTINATION STARTING FROM THE LOWEST ADDRESS
ENTRY: MVSRCE = 2 BYTE LOWEST ADDRESS OF SOURCE AREA
        MVDEST = 2 BYTE LOWEST ADDRESS OF DESTINATION AREA
        MVELEN = 2 BYTE NUMBER OF BYTES TO MOVE
EXIT: SOURCE MOVED TO DESTINATION

MVELFT:

LDY #0  ; ZERO INDEX
LDX MVELEN+1  ; X = NUMBER OF FULL PAGES TO MOVE
BEQ MLPAGE  ; IF X = 0 THEN DO PARTIAL PAGE

MLPAGE:

LDA (MVSRCE),Y  ; MOVE ONE BYTE
STA (MVDEST),Y
INY
BNE MLPAGE  ; CONTINUE UNTIL 256 BYTES ARE MOVED
INC MVSRCE+1  ; ADVANCE TO NEXT PAGE OF SOURCE
INC MVDEST+1  ; AND DESTINATION
DEX
BNE MLPAGE  ; DECREMENT PAGE COUNT

MLPART:

LDX MVELEN  ; GET LENGTH OF LAST PAGE
BEQ MLEXIT  ; BRANCH IF LENGTH OF LAST PAGE = 0

MLAST:

LDA (MVSRCE),Y  ; MOVE BYTE
STA (MVDEST),Y
INY
DEX
BNE MLAST  ; CONTINUE UNTIL LAST PAGE IS DONE

MLEXIT:

RTS

SUBROUTINE: MVERHT
PURPOSE: MOVE SOURCE TO DESTINATION STARTING FROM THE HIGHEST ADDRESS
ENTRY: MVSRCE = 2 BYTE LOWEST ADDRESS OF SOURCE AREA
        MVDEST = 2 BYTE LOWEST ADDRESS OF DESTINATION AREA
        MVELEN = 2 BYTE NUMBER OF BYTES TO MOVE
EXIT: SOURCE MOVED TO DESTINATION

MVERHT:

MOVE THE PARTIAL PAGE FIRST

LDA MVELEN+1
CLC
ADC MVSRCE+1
STA MVSRCE+1  ; POINT TO LAST PAGE OF SOURCE
LDA MVELEN+1
CLC
ADC MVDEST+1
STA MVDEST+1 ;POINT TO LAST PAGE OF DESTINATION

;MOVE THE LAST PARTIAL PAGE FIRST
LDY MVELEN ;GET LENGTH OF LAST PAGE
BEQ MRPAGE ;IF Y = 0 THEN DO THE FULL PAGES

MR0:
DEY ;BACK UP Y TO THE NEXT BYTE
LDA (MVSRCER),Y
STA (MVDEST),Y ;MOVE BYTE
CPY #0
BNE MR0 ;BRANCH IF NOT DONE WITH THE LAST PAGE

MRPAGE:
LDX MVELEN+1 ;GET HIGH BYTE OF COUNT AS PAGE COUNTER
BEQ MREXIT ;BRANCH IF HIGH BYTE = 0 (NO FULL PAGES)

MR1:
DEC MVSRCER+1 ;BACK UP TO PREVIOUS PAGE OF SOURCE
DEC MVDEST+1 ; AND DESTINATION

MR2:
DEY ;BACK UP Y TO THE NEXT BYTE
LDA (MVSRCER),Y
STA (MVDEST),Y ;MOVE BYTE
CPY #0
BNE MR2 ;BRANCH IF NOT DONE WITH THIS PAGE
DEX ;DECREMENT PAGE COUNTER
BNE MR1 ;BRANCH IF NOT ALL PAGES ARE MOVED

MREXIT:
RTS

;DATA SECTION
MVELEN .BLOCK 2 ;LENGTH OF MOVE

;SAMPLE EXECUTION: MOVE 0800 THROUGH 097F TO 0900 THROUGH 0A7F

;SC0502:
LDA SRCE+1 ;PUSH HIGH BYTE OF SOURCE
PHA
LDA SRCE ;PUSH LOW BYTE OF SOURCE
PHA
LDA DEST+1 ;PUSH HIGH BYTE OF DESTINATION
LDA DEST
PHA ;PUSH LOW BYTE OF DESTINATION
LDA LEN+1 ;PUSH HIGH BYTE OF LENGTH
PHA LEN
LDA LEN ;PUSH LOW BYTE OF LENGTH
PHA
JSR BLKMOV ;MOVE DATA FROM SOURCE TO DESTINATION
BRK ;FOR THE DEFAULT VALUES MEMORY FROM 800 HEX
LEN+1 THROUGH 97F HEX IS MOVED TO 900 HEX THROUGH
LEN A7F HEX.
JMP SC0502

;TEST DATA, CHANGE TO TEST OTHER VALUES
SRCE .WORD 0800H ;STARTING ADDRESS OF SOURCE AREA
DEST .WORD 0900H ;STARTING ADDRESS OF DESTINATION AREA
LEN .WORD 0180H ;NUMBER OF BYTES TO MOVE

.END ;PROGRAM
One-Dimensional Byte Array Index (D1BYTE)

Calculates the address of an element of a byte-length array, given the base address and the subscript (index) of the element.

Procedure: The program simply adds the base address to the subscript. The sum is the address of the element.

Registers Used: All
Execution Time: 74 cycles
Program Size: 37 bytes
Data Memory Required: Four bytes anywhere in RAM to hold the return address (two bytes starting at address RETADR) and the subscript (two bytes starting at address SUBSCR).

---

Entry Conditions
Order in stack (starting at the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of subscript
More significant byte of subscript
Less significant byte of base address of array
More significant byte of base address of array

Exit Conditions

(A) = More significant byte of address of element
(Y) = Less significant byte of address of element

---

Examples

1. Data: Base address = 0E00₁₆  
Subscript = 012C₁₆
Result: Address of element = 0E00₁₆  
+ 012C₁₆ = 0F2C₁₆.

2. Data: Base address = C4E₁₆  
Subscript = 02E4₁₆
Result: Address of element = C4E₁₆  
+ 02E4₁₅ = C7C5₁₆.
Title: One dimensional byte array indexing
Name: D1BYTE

Purpose: Given the base address of a byte array and a subscript 'I', calculate the address of A[I].

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Low byte of subscript,
High byte of subscript,
Low byte of base address of array,
High byte of base address of array

Exit: Register A = High byte of address
Register Y = Low byte of address

Registers used: All

Time: 74 cycles

Size: Program 37 bytes
Data 4 bytes

D1BYTE:
; SAVE RETURN ADDRESS
PLA
STA  RETADR
PLA
STA  RETADR+1

; GET SUBSCRIPT
PLA
STA  SS
PLA
STA  SS+1

; ADD BASE ADDRESS TO SUBSCRIPT
PLA
CLC
ADC  SS
TAY ; REGISTER Y = LOW BYTE
PLA
ADC  SS+1
TAX ; SAVE HIGH BYTE IN REGISTER X

; RESTORE RETURN ADDRESS TO STACK
LDA  RETADR+1
PHA
LDA      RETADR
PHA
TXA
RTS

; RESTORE RETURN ADDRESS
; GET HIGH BYTE BACK TO REGISTER A
; EXIT

; DATA
RETADR:  .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS
SS:     .BLOCK 2 ; SUBSCRIPT INTO THE ARRAY

; SAMPLE EXECUTION:

SC0503:  ; PUSH ARRAY ADDRESS
LDA  ARYADR+1 ; HIGH BYTE
PHA
LDA  ARYADR ; LOW BYTE
PHA

; PUSH A SUBSCRIPT
LDA  SUBSCR+1 ; HIGH BYTE
PHA
LDA  SUBSCR ; LOW BYTE
PHA
JSR  D1BYTE ; CALCULATE ADDRESS
BRK

JMP   SC0503

; TEST DATA, CHANGE SUBSCR FOR OTHER VALUES
SUBSCR:  .WORD 2 ; TEST SUBSCRIPT INTO THE ARRAY
ARYADR:  .WORD ARY ; BASE ADDRESS OF ARRAY

; THE ARRAY (8 ENTRIES)
ARY:    .BYTE  1,2,3,4,5,6,7,8

.END   ; PROGRAM
One-Dimensional Word Array Index (D1WORD)

Calculates the starting address of an element of a word-length (16-bit) array, given the base address of the array and the subscript (index) of the element. The element occupies the starting address and the address one larger; elements may be organized with either the less significant byte or the more significant byte in the starting address.

Procedure: The program multiplies the subscript by two (using a logical left shift) before adding it to the base address. The sum (BASE + 2*SUBSCRIPT) is then the starting address of the element.

Registers Used: All
Execution Time: 78 cycles
Program Size: 39 bytes
Data Memory Required: Four bytes anywhere in RAM to hold the return address (two bytes starting at address RETADR) and the subscript (two bytes starting at address SUBSCR).

Entry Conditions
Order in stack (starting at the top)
Less significant byte of return address
More significant byte of return address
Less significant byte of subscript
More significant byte of subscript
Less significant byte of base address of array
More significant byte of base address of array

Exit Conditions
(A) = More significant byte of starting address of element
(Y) = Less significant byte of starting address of element

Examples
1. Data: Base address = A148₁₆
   Subscript = 01A9₁₆
   Result: Address of first byte of element
   = A148₁₆ + 2 × 01A9₁₆
   = A148₁₆ + 0342₁₆ = A49A₁₆.
   That is, the word-length element occupies addresses A49A₁₆ and A49B₁₆.

2. Data: Base address = C4E0₁₆
   Subscript = 015B₁₆
   Result: Address of first byte of element
   = C4E0₁₆ + 2 × 015B₁₆
   = C4E0₁₆ + 02B6₁₆ = C796₁₆.
   That is, the word-length element occupies addresses C796₁₆ and C797₁₆.
Title: One dimensional word array indexing
Name: DLWORD

Purpose: Given the base address of a word array and a subscript 'I', calculate the address of A[I]

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Low byte of subscript,
High byte of subscript,
Low byte of base address of array,
High byte of base address of array

Exit: Register A = High byte of address
Register Y = Low byte of address

Registers used: All
Time: 78 cycles
Size:
Program 39 bytes
Data 4 bytes

DLWORD:
;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET SUBSCRIPT AND MULTIPLY IT BY 2
PLA
ASL A
STA SS
PLA
ROL A
STA SS+1

;ADD BASE ADDRESS TO DOUBLED SUBSCRIPT
PLA
CLC
ADC SS
TAY ;REGISTER Y = LOW BYTE
PLA
ADC SS+1
TAX ;SAVE HIGH BYTE IN REGISTER X

;RESTORE RETURN ADDRESS TO STACK
LDA RETADR+1
PHA
LDA RETADR
PHA

;RESTORE RETURN ADDRESS

TXA
RTS

;GET HIGH BYTE BACK TO REGISTER A
;EXIT

;DATA
RETAADR: .BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS
SS: .BLOCK 2 ;SUBSCRIPT INTO THE ARRAY

;SAMPLE EXECUTION:
SC0504:
;PUSH ARRAY ADDRESS
LDA ARYADR+1
PHA
LDA ARYADR
PHA

;PUSH A SUBSCRIPT OF 3
LDA SUBSCR+1
PHA
LDA SUBSCR
PHA
JSR D1WORD
BRK

;CALCULATE ADDRESS
;FOR THE INITIAL TEST DATA
;AY = STARTING ADDRESS OF ARY(3)
; = ARY + (3*2)
; = ARY + 6
; = ARY(3) CONTAINS 240 HEX

JMP SC0504

;TEST DATA
SUBSCR: .WORD 3 ;TEST SUBSCRIPT INTO ARY
ARYADR: .WORD ARY ;BASE ADDRESS OF ARRAY

;THE ARRAY (8 ENTRIES)
ARY: .WORD 0180H,01C0H,0200H,0240H,0280H,02C0H,03E7H,0A34H
.END ;PROGRAM
**Two-Dimensional Byte Array Index (D2BYTE)**

Calculates the address of an element of a two-dimensional byte-length array, given the base address of the array, the two subscripts of the element, and the size of a row (that is, the number of columns). The array is assumed to be stored in row major order (that is, by rows) and both subscripts are assumed to begin at zero.

**Procedure:** The program multiplies the row size (number of columns in a row) times the row subscript (since the elements are stored by rows) and adds the product to the column subscript. It then adds the sum to the base address. The program performs the multiplication using a standard shift-and-add algorithm (see Subroutine 6H).

**Registers Used:** All

**Execution Time:** Approximately 1500 cycles, depending mainly on the amount of time required to perform the multiplication.

**Program Size:** 119 bytes

**Data Memory Required:** Ten bytes anywhere in memory to hold the return address (two bytes starting at address RETADR), the row subscript (two bytes starting at address SS1), the size (length) of the rows (two bytes starting at address SS1SZ), the column subscript (two bytes starting at address SS2), and the product of row size times row subscript (two bytes starting at address PROD).

**Entry Conditions**

Order in stack (starting at the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of column subscript
More significant byte of column subscript
Less significant byte of the size of a row
More significant byte of the size of a row
Less significant byte of row subscript
More significant byte of row subscript
Less significant byte of base address of array
More significant byte of base address of array

**Exit Conditions**

(A) = More significant byte of address of element
(Y) = Less significant byte of address of element
Examples

1. Data: Base address = 3C00<sub>16</sub>
   Column subscript = 004<sub>16</sub>
   Size of row (number of columns) = 0018<sub>16</sub>
   Row subscript = 003<sub>16</sub>

   Result: Address of element = 3C00<sub>16</sub>
   + 003<sub>16</sub> \times 0018<sub>16</sub> + 004<sub>16</sub>
   = 3C00<sub>16</sub> + 0048<sub>16</sub> + 0004<sub>16</sub>
   = 3C4C<sub>16</sub>.

   Thus the address of ARRAY (3,4) is 3C4C<sub>16</sub>.

2. Data: Base address = 6A4A<sub>16</sub>
   Column subscript = 0035<sub>16</sub>
   Size of row (number of columns) = 0050<sub>16</sub>
   Row subscript = 0002<sub>16</sub>

   Result: Address of element = 6A4A<sub>16</sub>
   + 0002<sub>16</sub> \times 0050<sub>16</sub>
   = 6A4A<sub>16</sub>
   + 00A0<sub>16</sub> + 0035<sub>16</sub> = 6B1F<sub>16</sub>.

   Thus the address of ARRAY (2,35) is 6B1F<sub>16</sub>.

The general formula is

\[
\text{ADDRESS OF ELEMENT} = \text{BASE ADDRESS OF ARRAY} + \text{ROW SUBSCRIPT} \times \text{SIZE OF ROW} + \text{COLUMN SUBSCRIPT}
\]

Note that we refer to the size of the row subscript; the size is the number of consecutive memory addresses for which the subscript has the same value. This is also the number of bytes from the starting address of an element to the starting address of the element with the same column subscript but a row subscript one larger.

---

Title: Two dimensional byte array indexing

Name: D2BYTE

Purpose: Given the base address of a byte array, two subscripts 'I', 'J', and the size of the first subscript in bytes, calculate the address of A[I,J]. The array is assumed to be stored in row major order (A[0,0], A[0,1],..., A[K,L]), and both dimensions are assumed to begin at zero as in the following Pascal declaration:

\[
\text{A:ARRAY[0..2,0..7] OF BYTE;}
\]

Entry:

- TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Low byte of second subscript,
- High byte of second subscript,
- Low byte of size of first subscript in bytes,
; High byte of size of first subscript in bytes,
; Low byte of first subscript,
; High byte of first subscript,
; Low byte of base address of array,
; High byte of base address of array

NOTE:
The size of the first subscript is the length
of a row

Exit: Register A = High byte of address
Register Y = Low byte of address

Registers used: All

Time: Approximately 1500 cycles

Size: Program 119 bytes
Data 10 bytes

D2BYTE:
;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET SECOND SUBSCRIPT
PLA
STA SS2
PLA
STA SS2+1

;GET SIZE OF FIRST SUBSCRIPT (LENGTH OF A ROW)
PLA
STA SS1SZ
PLA
STA SS1SZ+1

;GET FIRST SUBSCRIPT
PLA
STA SS1
PLA
STA SS1+1

;MULTIPLY FIRST SUBSCRIPT * ROW LENGTH USING THE SHIFT AND ADD
; ALGORITHM. THE RESULT WILL BE IN SS1
LDA #0 ;PARTIAL PRODUCT = ZERO INITIALLY
STA PROD
STA PROD+1
LDX #17 ;NUMBER OF SHIFTS = 17
CLC
MULLP:

ROR       PROD+1 ; SHIFT PARTIAL PRODUCT
ROR       PROD   
ROR       SS1+1 ; SHIFT MULTIPLIER
ROR       SS1
BCC       DECCNT
CLC
LDA       SS1SZ
ADC       PROD
STA       PROD
LDA       SS1SZ+1
ADC       PROD+1
STA       PROD+1

DECCNT:

DEX
BNE       MULLP

; ADD IN THE SECOND SUBSCRIPT
LDA       SS1
CLC
ADC       SS2
STA       SS1
LDA       SS1+1
ADC       SS2+1
STA       SS1+1

; ADD BASE ADDRESS TO FORM THE FINAL ADDRESS
PLA
CLC
ADC       SS1 ; REGISTER Y = LOW BYTE
TAY
PLA
ADC       SS1+1 ; SAVE HIGH BYTE IN REGISTER X
TAX

; RESTORE RETURN ADDRESS TO STACK
LDA       RETADR+1
PHA
LDA       RETADR
PHA ; RESTORE RETURN ADDRESS

TXA ; GET HIGH BYTE BACK TO REGISTER A
RTS ; EXIT

; DATA
RETADR: .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS
SS1:   .BLOCK 2 ; SUBSCRIPT 1
SS1SZ: .BLOCK 2 ; SIZE OF SUBSCRIPT 1 IN BYTES
SS2:   .BLOCK 2 ; SUBSCRIPT 2
PROD:  .BLOCK 2 ; TEMPORARY FOR THE MULTIPLY
SAMPLE EXECUTION:

SC0505:

;PUSH ARRAY ADDRESS
LDA ARYADR+1
PHA
LDA ARYADR
PHA

;PUSH FIRST SUBSCRIPT
LDA SUBS1+1
PHA
LDA SUBS1
PHA

;PUSH SIZE OF FIRST SUBSCRIPT
LDA SSUBS1+1
PHA
LDA SSUBS1
PHA

;PUSH SECOND SUBSCRIPT
LDA SUBS2+1
PHA
LDA SUBS2
PHA

JSR D2BYTE ;CALCULATE ADDRESS
BRK ;FOR THE INITIAL TEST DATA
;AY = ADDRESS OF ARY(2,4)
; = ARY + (2*8) + 4
; = ARY + 20 (CONTENTS ARE 21)

JMP SC0505

;DATA
SUBS1: .WORD 2 ;SUBSCRIPT 1
SSUBS1: .WORD 8 ;SIZE OF SUBSCRIPT 1
SUBS2: .WORD 4 ;SUBSCRIPT 2
ARYADR: .WORD ARY ;ADDRESS OF ARRAY

;THE ARRAY (3 ROWS OF 8 COLUMNS)
ARY: .BYTE 1,2,3,4,5,6,7,8
 BYTE 9,10,11,12,13,14,15,16
 BYTE 17,18,19,20,21,22,23,24

.END ;PROGRAM
Two-Dimensional Word Array Index (D2WORD)

Calculates the starting address of an element of a two-dimensional word-length (16-bit) array, given the base address of the array, the two subscripts of the element, and the size of a row in bytes. The array is assumed to be stored in row major order (that is, by rows) and both subscripts are assumed to begin at zero.

Procedure: The program multiplies the row size (in bytes) times the row subscript (since the elements are stored by row), adds the product to the doubled column subscript (doubled because each element occupies two bytes), and adds the sum to the base address. The program uses a standard shift-and-add algorithm (see Subroutine 6H) to multiply.

Registers Used: All
Execution Time: Approximately 1500 cycles, depending mainly on the amount of time required to perform the multiplication of row size in bytes times row subscript.
Program Size: 121 bytes
Data Memory Required: Ten bytes anywhere in memory to hold the return address (two bytes starting at address RETADR), the row subscript (two bytes starting at address SS1), the row size in bytes (two bytes starting at address SS1SZ), the column subscript (two bytes starting at address SS2), and the product of row size times row subscript (two bytes starting at address PROD).

Entry Conditions
Order in stack (starting at the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of column subscript
More significant byte of column subscript
Less significant byte of size of rows (in bytes)
More significant byte of size of rows (in bytes)
Less significant byte of row subscript
More significant byte of row subscript
Less significant byte of base address of array
More significant byte of base address of array

Exit Conditions

(A) = More significant byte of starting address of element
(Y) = Less significant byte of starting address of element
The element occupies the address in AY and the next higher address.
Examples

1. Data:  
   Base address = 5E14\text{16}  
   Column subscript = 0008\text{16}  
   Size of a row (in bytes) = 001C\text{16}  
   (i.e., each row has 0014\text{10} or 000E\text{16} word-length elements)  
   Row subscript = 0005\text{16}  

   Result:  
   Starting address of element  
   \[= 5E14\text{16} + 0005\text{16} \times \]
   \[001C_{16} + 0008_{16} \times 2 = 5E14_{16} + 008C_{16} + 0010_{16} = 5EB0_{16}.\]
   Thus, the starting address of ARRAY(5,8) is 5EB0_{16} and the element occupies addresses 5EB0_{16} and 5EB1_{16}.

2. Data:  
   Base address = B100\text{16}  
   Column subscript = 0002\text{16}  
   Size of a row (in bytes) = 0008\text{16}  
   (i.e., each row has 4 word-length elements)  
   Row subscript = 0006\text{16}  

   Result:  
   Starting address of element  
   \[= B100\text{16} + 0006\text{16} \times \]
   \[0008_{16} + 0002_{16} \times 2 = B100_{16} + 0004_{16} + B134_{16} = B134_{16}.\]
   Thus, the starting address of ARRAY(6,2) is B134_{16} and the element occupies addresses B134_{16} and B135_{16}.

The general formula is

\[
\text{STARTING ADDRESS OF ELEMENT} = \text{BASE ADDRESS OF ARRAY} + \text{ROW SUBSCRIPT} \times \text{SIZE OF ROW} + \text{COLUMN SUBSCRIPT} \times 2
\]

Note that one parameter of this routine is the size of a row in bytes. The size in the case of word-length elements is the number of columns (per row) times two (the size of an element). The reason why we chose this parameter rather than the number of columns or the maximum column index is that this parameter can be calculated once (when the array bounds are determined) and used whenever the array is accessed. The alternative parameters (number of columns or maximum column index) would require extra calculations as part of each indexing operation.

---

Title: Two dimensional word array indexing
Name: D2WORD
Purpose: Given the base address of a word array, two subscripts 'I', 'J', and the size of the first subscript in bytes, calculate the address of A[I,J]. The array is assumed to be stored in row major order (A[0,0], A[0,1],..., A[K,L]).
and both dimensions are assumed to begin at zero as in the following Pascal declaration:

A:ARRAY[0..2,0..7] OF WORD;

Entry:

TOP OF STACK

Low byte of return address,
High byte of return address,
Low byte of second subscript,
High byte of second subscript,
Low byte of size of first subscript in bytes,
High byte of size of first subscript in bytes,
Low byte of first subscript,
High byte of first subscript,
Low byte of base address of array,
High byte of base address of array

Exit:

Register A = High byte of address
Register Y = Low byte of address

Registers used: ALL

Time: Approximately 1500 cycles

Size: Program 121 bytes
Data 10 bytes

D2WORD:

;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET SECOND SUBSCRIPT AND MULTIPLY BY 2 FOR WORD-LENGTH ELEMENTS
PLA
ASL A
STA SS2
PLA
ROL A
STA SS2+1

;GET SIZE OF FIRST SUBSCRIPT
PLA
STA SS1SZ
PLA
STA SS1SZ+1

;GET FIRST SUBSCRIPT
PLA
STA SS1
PLA
STA SS1+1
;MULTIPLY FIRST SUBSCRIPT * ROW SIZE (IN BYTES) USING THE SHIFT AND ADD
;ALGORITHM. THE RESULT WILL BE IN SS1
LDA   #0 ;PARTIAL PRODUCT = ZERO INITIALLY
STA   PROD
STA   PROD+1
LDX   #17 ;NUMBER OF SHIFTS = 17
CLC

MULLP:
ROR   PROD+1 ;SHIFT PARTIAL PRODUCT
ROR   PROD
ROR   SS1+1 ;SHIFT MULTIPLIER
ROR   SS1
BCC   DECCNT ;ADD MULTIPLICAND TO PARTIAL PRODUCT
CLC
LDA   SS1SZ ; IF NEXT BIT OF MULTIPLIER IS 1
ADC   PROD
STA   PROD
LDA   SS1SZ+1
ADC   PROD+1
STA   PROD+1

DECCNT:
DEX
BNE   MULLP

;ADD IN THE SECOND SUBSCRIPT DOUBLED
LDA   SS1
CLC
ADC   SS2
STA   SS1
LDA   SS1+1
ADC   SS2+1
STA   SS1+1

;ADD BASE ADDRESS TO FORM THE FINAL ADDRESS
PLA
CLC
ADC   SS1 ;REGISTER Y = LOW BYTE
TAY
PLA
ADC   SS1+1 ;SAVE HIGH BYTE IN REGISTER X
TAX

;RESTORE RETURN ADDRESS TO STACK
LDA   RETADR+1
PHA
LDA   RETADR
PHA ;RESTORE RETURN ADDRESS
TXA ;GET HIGH BYTE BACK TO REGISTER A
RTS ;EXIT

;DATA
RETADR: .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS
SS1: .BLOCK 2 ; SUBSCRIPT 1
SS1SZ: .BLOCK 2 ; SIZE OF SUBSCRIPT 1 IN BYTES
SS2: .BLOCK 2 ; SUBSCRIPT 2
PROD: .BLOCK 2 ; TEMPORARY FOR THE MULTIPLY

; ; ; SAMPLE EXECUTION:
; ; ;
; ; ;

SC0506:
; PUSH ARRAY ADDRESS
LDA ARYADR+1
PHA
LDA ARYADR
PHA

; PUSH FIRST SUBSCRIPT
LDA SUBS1+1
PHA
LDA SUBS1
PHA

; PUSH SIZE OF FIRST SUBSCRIPT
LDA SSUBS1+1
PHA
LDA SSUBS1
PHA

; PUSH SECOND SUBSCRIPT
LDA SUBS2+1
PHA
LDA SUBS2
PHA

JSR D2WORD ; CALCULATE ADDRESS
BRK ; FOR THE INITIAL TEST DATA
; AY = STARTING ADDRESS OF ARY(2,4)  
; = ARY + (2*16) + (4*2)  
; = ARY + 40  
; = ARY(2,4) CONTAINS 2100 HEX
JMP SC0506

; ; DATA
SUBS1: .WORD 2 ; SUBSCRIPT 1
SSUBS1: .WORD 16 ; SIZE OF SUBSCRIPT 1
SUBS2: .WORD 4 ; SUBSCRIPT 2
ARYADR: .WORD ARY ; ADDRESS OF ARRAY

; THE ARRAY (3 ROWS OF 8 COLUMNS)
ARY:

.WORD 0100H, 0200H, 0300H, 0400H, 0500H, 0600H, 0700H, 0800H
.WORD 0900H, 0A00H, 0B00H, 0C00H, 0D00H, 0E00H, 0F00H, 1000H
.WORD 1100H, 1200H, 1300H, 1400H, 1500H, 1600H, 1700H, 1800H
.WORD 1900H, 1A00H, 1B00H, 1C00H, 1D00H, 1E00H, 1F00H, 2000H
.WORD 2100H, 2200H, 2300H, 2400H

.END ;PROGRAM
N-Dimensional Array Index (NDIM)

Calculates the starting address of an element of an N-dimensional array given the base address and N pairs of sizes and subscripts. The size of a dimension is the number of bytes from the starting address of an element to the starting address of the element with an index one larger in the dimension but the same in all other dimensions. The array is assumed to be stored in row major order (that is, organized so that subscripts to the right change before subscripts to the left).

Note that the size of the rightmost subscript is simply the size of the elements (in bytes); the size of the next subscript is the size of the elements times the maximum value of the rightmost subscript plus 1, etc. All subscripts are assumed to begin at zero; otherwise, the user must normalize the subscripts (see the second example at the end of the listing).

Procedure: The program loops on each dimension, calculating the offset in that dimension as the subscript times the size. If the size is an easy case (an integral power of 2), the program reduces the multiplication to left shifts. Otherwise, it performs each multiplication using the shift-and-add algorithm of Subroutine 6H. Once the program has calculated the overall offset, it adds that offset to the base address to obtain the starting address of the element.

Registers Used: All
Execution Time: Approximately 1100 cycles per dimension plus 90 cycles overhead. Depends mainly on the time required to perform the multiplications.
Program Size: 192 bytes
Data Memory Required: Eleven bytes anywhere in memory to hold the return address (two bytes starting at address RETADR), the current subscript (two bytes starting at address SS), the current size (two bytes starting at address SIZE), the accumulated offset (two bytes starting at address OFFSET), the number of dimensions (one byte at address NUMDIM), and the product of size times subscript (two bytes starting at address PROD).
Special Case: If the number of dimensions is zero, the program returns with the base address in registers A (more significant byte) and Y (less significant byte).
**Entry Conditions**  
*Order in stack (starting at the top)*

- Less significant byte of return address
- More significant byte of return address
- Number of dimensions
- Less significant byte of size of rightmost dimension
- More significant byte of size of rightmost dimension
- Less significant byte of rightmost subscript
- More significant byte of rightmost subscript

...  

- Less significant byte of size of leftmost dimension
- More significant byte of size of leftmost dimension
- Less significant byte of leftmost subscript
- More significant byte of leftmost subscript
- Less significant byte of base address of array
- More significant byte of base address of array

**Exit Conditions**

(A) = More significant byte of address of element
(Y) = Less significant byte of address of element

The element occupies memory addresses from the calculated starting address through that address plus the rightmost subscript minus 1. That is, the element occupies memory addresses \( \text{START} \) through \( \text{START} + \text{SIZE} - 1 \), where \( \text{START} \) is the calculated address and \( \text{SIZE} \) is the size of an element in bytes.
Example

Data:
- Base address = 3C0016
- Number of dimensions = 0316
- Rightmost subscript = 000516
- Rightmost size = 000316 (3-byte entries)
- Middle subscript = 000316
- Middle size = 001216 (six 3-byte entries)
- Leftmost subscript = 000416
- Leftmost size = 007E16 (seven sets of six 3-byte entries)

Result:
- Address of entry = 3C0016 + 000516 × 000316 + 000316 × 001216 + 000416 × 007E16 = 3C0016 + 00F016 + 003616 + 01F816 = 3E3D16.

That is, the element is ARRAY (4,3,5); it occupies addresses 3E3D16 through 3E3F16. The maximum values of the various subscripts are 6 (leftmost) and 5 (middle). Each element consists of three bytes.

The general formula is

\[ \text{STARTING ADDRESS} = \text{BASE ADDRESS} + \sum_{i=0}^{N-1} \text{SUBSCRIPT}_i \times \text{SIZE}_i \]

where:
- \( N \) is the number of dimensions
- \( \text{SUBSCRIPT}_i \) is the \( i \)th subscript
- \( \text{SIZE}_i \) is the size of the \( i \)th dimension

Note that we use the sizes of each dimension as parameters to reduce the number of repetitive multiplications and to generalize the procedure. The sizes can be calculated (and saved) as soon as the bounds of the array are known. Those sizes can then be used whenever indexing is performed on that array. Obviously, the sizes do not change if the bounds are fixed and they should not be recalculated as part of each indexing operation. The sizes are also general, since the elements can themselves consist of any number of bytes.

Title: N-dimensional array indexing
Name: NDIM

Purpose: Calculate the address of an element in a
N-dimensional array given the base address,
N pairs of size in bytes and subscript, and the
number of dimensions of the array. The array is
assumed to be stored in row major order
(A[0,0,0], A[0,0,1],..., A[0,1,0], A[0,1,1],...)
Also it is assumed that all dimensions begin
at 0 as in the following Pascal declaration:
A: ARRAY [0..10,0..3,0..5] OF SOMETHING

Entry: TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Number of dimensions,
- Low byte of size (dim N-1) in bytes,
- High byte of size (dim N-1) in bytes,
- Low byte of subscript (dim N-1),
- High byte of subscript (dim N-1),
224 ARRAY MANIPULATION

`; Low byte of size (dim 0) in bytes,`
`; High byte of size (dim 0) in bytes,`
`; Low byte of subscript (dim 0),`
`; High byte of subscript (dim 0),`
`; Low byte of base address of array,`
`; High byte of base address of array`

Exit: Register A = High byte of address
    Register Y = Low byte of address

Registers used: All

Time: Approximately 1100 cycles per dimension
    plus 90 cycles overhead.

Size: Program 192 bytes
    Data   11 bytes

NDIM:

;POP PARAMETERS
PLA
STA   RETADR
PLA
STA   RETADR+1  ;SAVE RETURN ADDRESS

PLA
STA   NUMDIM   ;GET NUMBER OF DIMENSIONS

;OFFSET := 0
LDA   #0
STA   OFFSET
STA   OFFSET+1

;CHECK FOR ZERO DIMENSIONS JUST IN CASE
LDA   NUMDIM
BEQ   ADBASE    ;ASSUME THERE IS A BASE ADDRESS EVEN
              ; IF THERE ARE NO DIMENSIONS

;LOOP ON EACH DIMENSION
; DOING OFFSET := OFFSET + (SUBSCRIPT * SIZE)

LOOP:

PLA   ;POP SIZE
STA   SIZE
PLA
STA   SIZE+1

PLA
STA   SS   ;POP SUBSCRIPT
PLA
STA SS+1
JSR NXTOFF  ;OFFSET := OFFSET + (SUBSCRIPT * SIZE)
DEC NUMDIM  ;DECREMENT NUMBER OF DIMENSIONS
BNE LOOP    ;CONTINUE THROUGH ALL DIMENSIONS

ADBASE:
;CALCULATE THE STARTING ADDRESS OF THE ELEMENT
;OFFSET = BASE + OFFSET
PLA           ;GET LOW BYTE OF BASE
CLC
ADC OFFSET    ;ADD LOW BYTE OF OFFSET
STA OFFSET    ;GET HIGH BYTE OF BASE
PLA
ADC OFFSET+1  ;A = HIGH BYTE OF BASE + OFFSET
STA OFFSET+1

;RESTORE RETURN ADDRESS AND EXIT
LDA RETADR+1
PHA
LDA RETADR
PHA
LDA OFFSET+1  ;RETURN THE ADDRESS WHICH IS IN OFFSET
LDY OFFSET
RTS

;SUBROUTINE NXTOFF
;PURPOSE: OFFSET := OFFSET + (SUBSCRIPT * SIZE);
;ENTRY: OFFSET = CURRENT OFFSET
;        SUBSCRIPT = CURRENT SUBSCRIPT
;        SIZE = CURRENT SIZE OF THIS DIMENSION
;EXIT: OFFSET = OFFSET + (SUBSCRIPT * SIZE);
;REGISTERS USED: ALL

NXTOFF:
;CHECK IF SIZE IS POWER OF 2 OR 8 (EASY MULTIPLICATIONS - SHIFT ONLY)
LDA SIZE+1  ;HIGH BYTE = 0 ?
BNE BIGSZ    ;BRANCH IF SIZE IS LARGE

LDA SIZE
LDY $0       ;Y=INDEX INTO EASY ARRAY
LDX #SZEASY  ;X=SIZE OF EASY ARRAY

EASYLP:
CMP EASYAY,Y ;BRANCH IF SIZE IS AN EASY ELEMENT
BEQ ISEASY   ;INCREMENT INDEX
INY
DEX           ;DECREMENT COUNT
BNE EASYLP   ;BRANCH IF NOT THROUGH ALL EASY ELEMENTS
BEQ BIGSZ    ;BRANCH IF SIZE IS NOT EASY
ISEASY:

CPY  #0
BEQ  ADDOFF ;BRANCH IF SHIFT FACTOR = 0

;ELEMENT SIZE * SUBSCRIPT CAN BE PERFORMED WITH A SHIFT LEFT

SHL:

ASL  SS ;SHIFT LEFT LOW BYTE
ROL  SS+1 ;SHIFT LEFT HIGH BYTE
DEY
BNE  SHL  ;CONTINUE UNTIL DONE
BEQ  ADDOFF ;DONE SO ADD OFFSET + SUBSCRIPT

BIGSZ:

;SIZE IS NOT AN EASY MULTIPLICATION SO PERFORM MULTIPLICATION OF
;ELEMENT SIZE AND SUBSCRIPT THE HARD WAY
LDA  #0 ;PARTIAL PRODUCT = ZERO INITIALLY
STA  PROD
STA  PROD+1
LDX  #17 ;NUMBER OF SHIFTS = 17
CLC

MULLP:

ROR  PROD+1 ;SHIFT PARTIAL PRODUCT
ROR  PROD
ROR  SS+1 ;SHIFT MULTIPLIER
ROR  SS
BCC  DECCNT
CLC
LDA  SIZE ;ADD MULTIPICAND TO PARTIAL PRODUCT
ADC  PROD
STA  PROD
LDA  SIZE+1
ADC  PROD+1
STA  PROD+1

DECCNT:

DEX
BNE  MULLP

ADDOFF:

LDA  SS
CLC
ADC  OFFSET ;ADD LOW BYTES
STA  OFFSET
LDA  SS+1
ADC  OFFSET+1 ;ADD HIGH BYTES
STA  OFFSET+1

RTS

EASYAY: ;SHIFT FACTOR

.BYTE 1  ;0
.BYTE 2  ;1
.BYTE 4  ;2
.BYTE 8 ; 3
 BYTE 16.; 4
 BYTE 32.; 5
 BYTE 64.; 6
 BYTE 128.; 7
SZEASY .EQU $-EASY
;
;DATA
RETAIR: .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS
SS: .BLOCK 2 ; SUBSCRIPT INTO THE ARRAY
SIZE: .BLOCK 2 ; SIZE OF AN ARRAY ELEMENT
OFFSET: .BLOCK 2 ; TEMPORARY FOR CALCULATING
NUMDIM: .BLOCK 1 ; NUMBER OF DIMENSIONS
PROD: .BLOCK 2 ; TEMPORARY FOR MULTIPLICATION IN NGXTOFF
;
;
; SAMPLE EXECUTION:
;
;
;PROGRAM SECTION
SC0507:
;
; FIND ADDRESS OF AY1[1,3,0]
; SINCE LOWER BOUNDS OF ARRAY 1 ARE ALL ZERO IT IS NOT
; NECESSARY TO NORMALIZE THEM
;
; PUSH BASE ADDRESS OF ARRAY 1
LDA AYLADR+1
PHA
LDA AYLADR
PHA
;
; PUSH SUBSCRIPT AND SIZE FOR DIMENSION 1
LDA #0
PHA
LDA #1
PHA
LDA #0
PHA
LDA #A1SZ1
PHA
;
; PUSH SUBSCRIPT AND SIZE FOR DIMENSION 2
LDA #0
PHA
LDA #3
PHA
LDA #0
PHA
LDA #A1SZ2
PHA
ARRAY MANIPULATION

; PUSH SUBSCRIPT AND SIZE FOR DIMENSION 3
LDA   #0
PHA
LDA   #0
PHA
LDA   #0
PHA
LDA   #A1SZ3
PHA

; PUSH NUMBER OF DIMENSIONS
LDA   #A1DIM
PHA

JSR   NDIM               ; CALCULATE ADDRESS
BRK   ; AY = STARTING ADDRESS OF ARY1(1, 3, 0)
       ; = ARY + (1*126) + (3*21) + (0*3)
       ; = ARY + 189

; CALCULATE ADDRESS OF AY[−1, 6]
; SINCE LOWER BOUNDS OF AY 2 DO NOT START AT ZERO THE SUBSCRIPTS
; MUST BE NORMALIZED
; PUSH BASE ADDRESS OF ARRAY 2
LDA   AY2ADR+1
PHA
LDA   AY2ADR
PHA

; PUSH (SUBSCRIPT - LOWER BOUND) AND SIZE FOR DIMENSION 1
LDA   #−1
SEC
SBC   #A2D1L              ; SAVE LOW BYTE
TAX
LDA   #0FFH              ; HIGH BYTE OF −1 SUBSCRIPT
SBC   #0FFH              ; HIGH BYTE OF A2D1L
PHA
TXA
PHA
PHA
LDA   #0
PHA
LDA   #A2SZ1
PHA

; PUSH (SUBSCRIPT - LOWER BOUND) AND SIZE FOR DIMENSION 2
LDA   #6
SEC
SBC   #A2D2L              ; SAVE LOW BYTE
TAX
LDA   #0
SBC   #0
PHA
TXA
PHA
PHA
LDA   #0
PHA
LDA  #A2SZ2
PHA

;PUSH NUMBER OF DIMENSIONS
LDA  #A2DIM
PHA

JSR  NDIM    ;CALCULATE ADDRESS
BRK    ;AY = STARTING ADDRESS OF ARY1(-1,6)
;   = ARY + (((-1) - (-5))*18) + ((6 - 2)*2)
;   = ARY + 80

JMP  SC0507

;DATA
AY1ADR: .WORD  AY1   ;ADDRESS OF ARRAY 1
AY2ADR: .WORD  AY2   ;ADDRESS OF ARRAY 2

;     [ 0 .. 3 , 0 .. 5 , 0 .. 6 ]
A1DIM: .EQU  3   ;NUMBER OF DIMENSIONS OF ARRAY 1
A1D1L: .EQU  0   ;LOW BOUND OF ARRAY 1 DIMENSION 1
A1D1H: .EQU  3   ;HIGH BOUND OF ARRAY 1 DIMENSION 1
A1D2L: .EQU  0   ;LOW BOUND OF ARRAY 1 DIMENSION 2
A1D2H: .EQU  5   ;HIGH BOUND OF ARRAY 1 DIMENSION 2
A1D3L: .EQU  0   ;LOW BOUND OF ARRAY 1 DIMENSION 3
A1D3H: .EQU  6   ;HIGH BOUND OF ARRAY 1 DIMENSION 3
A1SZ3: .EQU 10   ;SIZE OF AN ELEMENT IN DIMENSION 3
A1SZ2: .EQU  ((A1D3H-A1D3L)+1)*A1SZ3 ;SIZE OF AN ELEMENT IN DIMENSION 2
A1SZ1: .EQU  ((A1D2H-A1D2L)+1)*A1SZ2 ;SIZE OF AN ELEMENT IN DIMENSION 1
AY1:  .BLOCK  ((A1D1H-A1D1L)+1)*A1SZ1 ;THE ARRAY

;AY2 : ARRAY[A2D1L..A2D1H,A2D2L..A2D2H] OF WORD
;     [ -5 .. -1 , 2 .. 10 ]
A2DIM: .EQU  2   ;NUMBER OF DIMENSIONS OF ARRAY 2
A2D1L: .EQU  0   ;LOW BOUND OF ARRAY 2 DIMENSION 1
A2D1H: .EQU  -1  ;HIGH BOUND OF ARRAY 2 DIMENSION 1
A2D2L: .EQU  2   ;LOW BOUND OF ARRAY 2 DIMENSION 2
A2D2H: .EQU  10  ;HIGH BOUND OF ARRAY 2 DIMENSION 2
A2SZ2: .EQU  2   ;SIZE OF AN ELEMENT IN DIMENSION 2
A2SZ1: .EQU  ((A2D2H-A2D2L)+1)*A2SZ2 ;SIZE OF AN ELEMENT IN DIMENSION 1
AY2:  .BLOCK  ((A2D1H-A2D1L)+1)*A2SZ1 ;THE ARRAY

.END   ;PROGRAM
Add two 16-bit operands obtained from the stack and places the sum at the top of the stack. All 16-bit numbers are stored in the usual 6502 style with the less significant byte on top of the more significant byte.

Procedure: The program clears the Carry flag initially and adds the operands one byte at a time, starting with the less significant bytes. It sets the Carry flag from the addition of the more significant bytes.

**Entry Conditions**

Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Less significant byte of first operand
- More significant byte of first operand
- Less significant byte of second operand
- More significant byte of second operand

**Exit Conditions**

Order in stack (starting from the top)

- Less significant byte of sum
- More significant byte of sum

**Examples**

1. **Data:**  
   - First operand = 03E1\textsubscript{16}  
   - Second operand = 07E4\textsubscript{16}  
   
   **Result:**  
   - Sum = 0BC5\textsubscript{16}  
   - Carry = 0

2. **Data:**  
   - First operand = A45D\textsubscript{16}  
   - Second operand = 97E1\textsubscript{16}  
   
   **Result:**  
   - Sum = 3C3E\textsubscript{16}  
   - Carry = 1

**Registers Used:** A, P, Y  
**Execution Time:** 80 cycles  
**Program Size:** 38 bytes  
**Data Memory Required:** Four bytes anywhere in memory for the second operand (two bytes starting at address ADEND2) and the return address (two bytes starting at address RETADR).
Title: 16 bit addition
Name: ADD16

Purpose: Add 2 16 bit signed or unsigned words and return a 16 bit signed or unsigned sum.

Entry: TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Low byte of operand 2,
- High byte of operand 2,
- Low byte of operand 1,
- High byte of operand 1

Exit: Sum = operand 1 + operand 2
- TOP OF STACK
- Low byte of sum,
- High byte of sum

Registers used: A,P,Y

Time: 80 cycles
Size: Program 38 bytes
Data 4 bytes

ADD16:
;SAVE THE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET ADDEND 2
PLA
STA ADEND2
PLA
STA ADEND2+1

;SUM ADDEND 2 WITH ADDEND 1
PLA
CLC
ADC ADEND2
TAY ;SAVE LOW BYTE OF SUM
PLA
ADC ADEND2+1

;PUSH THE SUM
PHA
TYA ;PUSH HIGH BYTE
PHA ;PUSH LOW BYTE

;PUSH RETURN ADDRESS AND EXIT
LDA RETADR+1
PHA
LDA RETADR
PHA
RTS

;DATA
ADEND2: .BLOCK 2 ;TEMPORARY FOR ADDEND 2
RETAQR :. BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS

; SAMPLE EXECUTION

; TEST DATA, CHANGE FOR DIFFERENT VALUES
OPRND1 .WORD 1023 ;1023 + 123 = 1146 = 047AH
OPRND2 .WORD 123

.END ;PROGRAM
16-Bit Subtraction (SUB16)

Subtracts two 16-bit operands obtained from the stack and places the difference at the top of the stack. All 16-bit numbers are stored in the usual 6502 style with the less significant byte on top of the more significant byte. The subtrahend (number to be subtracted) is stored on top of the minuend (number from which the subtrahend is subtracted). The Carry flag acts as an inverted borrow, its usual role in the 6502.

Procedure: The program sets the Carry flag (the inverted borrow) initially and subtracts the subtrahend from the minuend one byte at a time, starting with the less significant bytes. It sets the Carry flag from the subtraction of the more significant bytes.

Registers Used: A, P, Y
Execution Time: 80 cycles
Program Size: 38 bytes
Data Memory Required: Four bytes anywhere in memory for the subtrahend (two bytes starting at address SUBTRA) and the return address (two bytes starting at address RETADR).

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of subtrahend
More significant byte of subtrahend
Less significant byte of minuend
More significant byte of minuend

Exit Conditions
Order in stack (starting from the top)

Less significant byte of difference (minuend — subtrahend)
More significant byte of difference (minuend — subtrahend)

Examples

1. Data: Minuend = A45D₁₆
       Subtrahend = 97E₁₆
       Result: Difference = Minuend — Subtrahend
               = 0C7C₁₆
               Carry = 1 (no borrow)

2. Data: Minuend = 03E₁₁₆
       Subtrahend = 07E₁₁₆
       Result: Difference = Minuend — Subtrahend
               = FBFD₁₁₆
               Carry = 0 (borrow generated)
Title: 16 bit subtraction
Name: SUB16

Purpose: Subtract 2 16 bit signed or unsigned words and return a 16 bit signed or unsigned difference.

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Low byte of subtrahend,
High byte of subtrahend,
Low byte of minuend,
High byte of minuend

Exit: Difference = minuend - subtrahend
TOP OF STACK
Low byte of difference,
High byte of difference

Registers used: A,P,Y

Time: 80 cycles

Size: Program 38 bytes
Data 4 bytes

SUB16:
;SAVE THE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET SUBTRAHEND
PLA
STA SUBTRA
PLA
STA SUBTRA+1

;SUBTRACT SUBTRAHEND FROM MINUEND
PLA
SEC
SBC SUBTRA
TAY
PLA
SBC SUBTRA+1

;SAVE LOW BYTE OF THE DIFFERENCE
;PUSH THE DIFFERENCE
PHA
TYA
PHA
;PUSH HIGH BYTE
PHA
;PUSH LOW BYTE
;PUSH RETURN ADDRESS AND EXIT
LDA    RETADR+1
PHA
LDA    RETADR
PHA
RTS

;DATA
SUBTRA: .BLOCK 2 ;TEMPORARY FOR SUBTRAHEND
RETADR: .BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS

; SAMPLE EXECUTION

SC0602:
;SUBTRACT OPRND2 FROM OPRND1
LDA    OPRND1+1
PHA
LDA    OPRND1
PHA
LDA    OPRND2+1
PHA
LDA    OPRND2
PHA
JSR    SUB16
PLA
TAY
PLA
BRK    ;A = HIGH BYTE, Y = LOW BYTE
JMP    SC0602

;TEST DATA - CHANGE TO TEST OTHER VALUES
OPRND1 .WORD 123 ;123 - 1023 = -900 = 0FC7CH
OPRND2 .WORD 1023

.END ;PROGRAM
Multiplies two 16-bit operands obtained from the stack and places the less significant word of the product at the top of the stack. All 16-bit numbers are stored in the usual 6502 style with the less significant byte on top of the more significant byte.

Procedure: The program uses an ordinary add-and-shift algorithm, adding the multiplicand to the partial product each time it finds a 1 bit in the multiplier. The partial product and the multiplier are shifted 17 times (the number of bits in the multiplier plus 1) with the extra loop being necessary to move the final Carry into the product. The program maintains a full 32-bit unsigned partial product in memory locations (starting with the most significant byte) HIPROD + 1, HIPROD, MLIER + 1, and MLIER. The less significant word of the product replaces the multiplier as the multiplier is shifted and examined for 1 bits.

## Entry Conditions
Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Less significant byte of multiplier
- More significant byte of multiplier
- Less significant byte of multiplicand
- More significant byte of multiplicand

## Exit Conditions
Order in stack (starting from the top)

- Less significant byte of less significant word of product
- More significant byte of less significant word of product

## Examples
1. Data: Multiplier = 0012₁₆ (18₁₀)
   Multiplicand = 03D₁₁ (977₁₀)

   Result: Product = 44B₂₁₆ (17,586₁₀)

2. Data: Multiplier = 37D₁₁ (14,289₁₀)
   Multiplicand = A045₁₁ (41,029₁₀)

   Result: Product = AB5₅₁₁ (43,861₁₀). This is actually the less significant 16-bit word of the 32-bit product 22F1AB5₅₁₁ (586,264,381₁₀).
Note that MUL16 returns only the less significant word of the product to maintain compatibility with other 16-bit arithmetic operations. The more significant word of the product is available in memory locations HIPROD (less significant byte) and HIPROD+1 (more significant byte), but the user should note that it is correct only if the operands are unsigned. If the operands are signed numbers and either one is negative, the user must determine the sign of the product and replace negative operands with their absolute values (two’s complements) before calling MUL16.

; Title: 16 bit Multiplication ;
; Name: MUL16 ;
;
;
; Purpose: Multiply 2 signed or unsigned 16 bit words and return a 16 bit signed or unsigned product. ;
;
; Entry: TOP OF STACK ;
; Low byte of return address, ;
; High byte of return address, ;
; Low byte of multiplier, ;
; High byte of multiplier, ;
; Low byte of multiplicand, ;
; High byte of multiplicand ;
;
; Exit: Product = multiplicand * multiplier ;
; TOP OF STACK ;
; Low byte of product, ;
; High byte of product, ;
;
; Registers used: All ;
;
; Time: Approximately 650 to 1100 cycles ;
;
; Size: Program 238 bytes ;
; Data 8 bytes ;
;
;
MUL16: ;SAVE RETURN ADDRESS PLA PLA STA RETADR PLA STA RETADR+1

;GET MULTIPLIER PLA STA MLIER PLA
STA MLIER+1

; GET MULTIPLICAND
PLA
STA MCAND
PLA
STA MCAND+1

; PERFORM MULTIPLICATION USING THE SHIFT AND ADD ALGORITHM
; THIS ALGORITHM PRODUCES A UNSIGNED 32 BIT PRODUCT IN
; HIPROD AND MLIER WITH HIPROD BEING THE HIGH WORD.
LDA #0
STA HIPROD ; ZERO HIGH WORD OF PRODUCT
STA HIPROD+1
LDX #17

; NUMBER OF BITS IN MULTIPLIER PLUS 1, THE
; EXTRA LOOP IS TO MOVE THE LAST CARRY INTO
; THE PRODUCT
; CLEAR CARRY FOR FIRST TIME THROUGH LOOP

MULLP:

; IF NEXT BIT = 1 THEN
; HIPROD := HIPROD + MULTIPLICAND
ROR HIPROD+1
ROR HIPROD
ROR MLIER+1
ROR MLIER
BCC DECCNT

; BRANCH IF NEXT BIT OF MULTIPLIER IS 0

CLC

LDA MCAND
ADC HIPROD
STA HIPROD
LDA MCAND+1
ADC HIPROD+1
STA HIPROD+1

; CARRY = OVERFLOW FROM ADD

DECCNT:

DEX
BNE MULLP ; CONTINUE UNTIL DONE

; PUSH LOW WORD OF PRODUCT ON TO STACK
LDA MLIER+1
PHA
LDA MLIER
PHA

; RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA
RTS

; DATA

MCAND: .BLOCK 2 ; MULTIPLICAND
MLIER: .BLOCK 2 ;MULTIPLIER AND LOW WORD OF PRODUCT
HIPROD: .BLOCK 2 ;HIGH WORD OF PRODUCT
RETA DR: .BLOCK 2 ;RETURN ADDRESS

; SAMPLE EXECUTION:

SC0603:
;MULTIPLY OPRND1 * OPRND2 AND STORE THE PRODUCT AT RESULT
LDA OPRND1+1
PHA
LDA OPRND1
PHA
LDA OPRND2+1
PHA
LDA OPRND2
PHA
JSR MUL16 ;MULTIPLY
PLA
STA RESULT
PLA
STA RESULT+1
BRK ;RESULT OF 1023 * -2 = -2046 = 0F802H
; IN MEMORY RESULT = 02H
; RESULT+1 = F8H
JMP SC0603

OPRND1 .WORD -2
OPRND2 .WORD 1023
RESULT: .BLOCK 2 ;2 BYTE RESULT

.END ;PROGRAM
Divides two 16-bit operands obtained from the stack and places either the quotient or the remainder at the top of the stack. There are four entry points: SDIV16 returns a 16-bit signed quotient from dividing two 16-bit signed operands, UDIV16 returns a 16-bit unsigned quotient from dividing two 16-bit unsigned operands, SREM16 returns a 16-bit remainder (a signed number) from dividing two 16-bit signed operands, and UREM16 returns a 16-bit unsigned remainder from dividing two 16-bit unsigned operands. All 16-bit numbers are stored in the usual 6502 style with the less significant byte on top of the more significant byte. The divisor is stored on top of the dividend. If the divisor is zero, the Carry flag is set and a zero result is returned; otherwise, the Carry flag is cleared.

**Procedure:** If the operands are signed, the program determines the sign of the quotient and takes the absolute values of any negative operands. It also must retain the sign of the dividend, since that determines the sign of the remainder. The program then performs the actual unsigned division by the usual shift-and-subtract algorithm, shifting quotient and dividend and placing a 1 bit in the quotient each time a trial subtraction is successful. If the operands are signed, the program must negate (that is, subtract from zero) any result (quotient or remainder) that is negative. The Carry flag is cleared if the division is proper and set if the divisor is found to be zero. A zero divisor also results in a return with the result (quotient or remainder) set to zero.

**Entry Conditions**
Order in stack (starting from the top)
- Less significant byte of return address
- More significant byte of return address
- Less significant byte of divisor
- More significant byte of divisor
- Less significant byte of dividend
- More significant byte of dividend

**Exit Conditions**
Order in stack (starting from the top)
- Less significant byte of result
- More significant byte of result
- If the divisor is non-zero, Carry = 0 and the result is normal. If the divisor is zero, Carry = 1 and the result is 0000₁₆.
Examples

1. Data: Dividend = 03E0₁₆ = 992₁₀
   Divisor = 00B6₁₆ = 182₁₀

   Result: Quotient (from UDIV16) = 0005₁₆
            Remainder (from UREM16) = 0052₁₆
            = 0082₁₀
            Carry = 0 (no divide-by-zero error)

2. Data: Dividend = D73A₁₆ = -10,438₁₀
   Divisor = 02F₁₁₆ = 753₁₀

   Result: Quotient (from SDIV16) = FFF3₁₆
            = -13₁₀
            Remainder (from SREM16) = FD77₁₆
            = -649₁₀
            Carry = 0 (no divide-by-zero error)

Note that we have taken the view that the remainder of a signed division may be either positive or negative. In our procedure, the remainder always takes the sign of the dividend. The user can easily examine the quotient and change the form to obtain a remainder that is always positive. In that case, the final result of Example 2 would be

   Quotient = FFF₁₆ = -14₁₀
   Remainder (always positive) = 0068₁₆
   = 104₁₀

Regardless of the entry point used, the program always calculates both the quotient and the remainder. Upon return, the quotient is available in addresses DVEND and DVEND +1 (more significant byte in DVEND +1) and the remainder in addresses DVEND +2 and DVEND +3 (more significant byte in DVEND +3). Thus, the user can always obtain the result that is not returned in the stack.

Title
Name: 16 bit division
      SDIV16, UDIV16, SREM16, UREM16

Purpose:
      SDIV16
      Divide 2 signed 16 bit words and return a 16 bit signed quotient.

      UDIV16
      Divide 2 unsigned 16 bit words and return a 16 bit unsigned quotient.

      SREM16
      Divide 2 signed 16 bit words and return a 16 bit signed remainder.

      UREM16
      Divide 2 unsigned 16 bit words and return a 16 bit unsigned remainder.

Entry: TOP OF STACK
ARITHMETIC

Low byte of return address,  ;
High byte of return address,  ;
Low byte of divisor,  ;
High byte of divisor,  ;
Low byte of dividend,  ;
High byte of dividend  ;

Exit: TOP OF STACK  ;
Low byte of result,  ;
High byte of result,  ;

If no errors then  ;
carry := 0  ;
else  ;
divide by zero error  ;
carry := 1  ;
quotient := 0  ;
remainder := 0  ;

Registers used: All  ;

Time: Approximately 1000 to 1160 cycles  ;

Size: Program 293 bytes  ;
Data 13 bytes  ;

;UNSIGNED DIVISION
UDIV16:
LDA #0  ;RESULT IS QUOTIENT (INDEX=0)
BEQ UDIVMD

;UNSIGNED REMAINDER
UREM16:
LDA #2  ;RESULT IS REMAINDER (INDEX=2)

UDIVMD:
STA RSLTIX  ;RESULT INDEX (0 FOR QUOTIENT,
             ;2 FOR REMAINDER)

;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET DIVISOR
PLA
STA DVSOR
PLA
STA DVSOR+1

;GET DIVIDEND
PLA
STA DVEND
PLA
STA DVEND+1

;PERFORM DIVISION
JSR UDIV
BCC DIVOK ;BRANCH IF NO ERRORS
DIVER: JMP EREXIT
DIVOK: JMP OKEEXIT

;SIGNED DIVISION
SDIV16:
LDA #0 ;RESULT IS QUOTIENT (INDEX=0)
BNE SDIVMD

;SIGNED REMAINDER
SREM16:
LDA #2 ;RESULT IS REMAINDER (INDEX=2)
BNE SDIVMD

SDIVMD:
STA RSLTIX ;RESULT INDEX (0 FOR QUOTIENT,
; 2 FOR REMAINDER)

;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET DIVISOR
PLA
STA DVSOR
PLA
STA DVSOR+1

;GET DIVIDEND
PLA
STA DVEND
PLA
STA DVEND+1

;DETERMINE SIGN OF QUOTIENT BY PERFORMING AN EXCLUSIVE OR OF THE
; HIGH BYTES. IF THE SIGNS ARE THE SAME THEN BIT 7 WILL BE 0 AND THE
; QUOTIENT IS POSITIVE. IF THE SIGNS ARE DIFFERENT THEN THE QUOTIENT
; IS NEGATIVE.
LDA DVEND+1
EOR DVSOR+1
STA SQUOT

;SIGN OF REMAINDER IS THE SIGN OF THE DIVIDEND
LDA DVEND+1
STA SREM

;TAKE THE ABSOLUTE VALUE OF THE DIVISOR
LDA DVSOR+1
BPL CHKDE ;BRANCH IF ALREADY POSITIVE
244  ARITHMETIC

LDA  #0                      ;SUBTRACT DIVISOR FROM ZERO
SEC
SBC  DVSOR
STA  DVSOR
LDA  #0
SBC  DVSOR+1
STA  DVSOR+1

;TAKE THE ABSOLUTE VALUE OF THE DIVIDEND

CHKDE:
LDA  DVEND+1
BPL  DODIV                    ;BRANCH IF DIVIDEND IS POSITIVE
LDA  #0                       ;SUBTRACT DIVIDEND FROM ZERO
SEC
SBC  DVEND
STA  DVEND
LDA  #0
SBC  DVEND+1
STA  DVEND+1

;DIVIDE ABSOLUTE VALUES

DODIV:
JSR  UDIV
BCS  EREXIT                  ;EXIT IF DIVIDE BY ZERO

;NEGATE QUOTIENT IF IT IS NEGATIVE

LDA  SQOUT
BPL  DOREM                    ;BRANCH IF QUOTIENT IS POSITIVE
LDA  #0                       ;SUBTRACT QUOTIENT FROM ZERO
SEC
SBC  DVEND
STA  DVEND
LDA  #0
SBC  DVEND+1
STA  DVEND+1

DOREM:
;NEGATE REMAINDER IF IT IS NEGATIVE

LDA  SREM
BPL  OKEXIT                   ;BRANCH IF REMAINDER IS POSITIVE
LDA  #0
SEC
SBC  DVEND+2
STA  DVEND+2
LDA  #0
SBC  DVEND+3
STA  DVEND+3
JMP  OKEXIT

;ERROR EXIT (CARRY = 1, RESULTS ARE ZERO)

EREXIT:
LDA  #0
STA  DVEND
STA  DVEND+1               ;QUOTIENT := 0
STA  DVEND+2
STA  DVEND+3               ;REMAINDER := 0
SEC                ;CARRY = 1 IF ERROR
BCS DVEXIT

;GOOD EXIT (CARRY = 0)

OKEXIT:
CLC ;CARRY = 0, NO ERRORS

DVEXIT:

;PUSH RESULT
LDX RSLITIX ;GET INDEX TO RESULT (0=QUOTIENT, 2=REMAINDER)
LDA DVEND+1,X
PHA
LDA DVEND,X
PHA

;RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA
RTS

;ROUTINE: UDIV
;PURPOSE: DIVIDE A 16 BIT DIVIDEND BY A 16 BIT DIVISOR
;ENTRY: DVEND = DIVIDEND
; DVSOR = DIVISOR
;EXIT: DVEND = QUOTIENT
; DVEND+2 = REMAINDER
;REGISTERS USED: ALL
;******************************

UDIV:

;ZERO UPPER WORD OF DIVIDEND THIS WILL BE CALLED DIVIDEND[1] BELOW
LDA $0
STA DVEND+2
STA DVEND+3

;FIRST CHECK FOR DIVISION BY ZERO
LDA DVSOR
ORA DVSOR+1
BNE OKUDIV ;BRANCH IF DIVISOR IS NOT ZERO
SEC ;ELSE ERROR EXIT
RTS

;PERFORM THE DIVISION BY TRIAL SUBTRACTIONS

OKUDIV:

LDX $16 ;LOOP THROUGH 16 BITS

DIVLP:
ROL DVEND ;SHIFT THE CARRY INTO BIT 0 OF DIVIDEND
ROL DVEND+1 ;WHICH WILL BE THE QUOTIENT
ROL DVEND+2 ;AND SHIFT DIVIDEND AT THE SAME TIME
ROL DVEND+3

;CHECK IF DIVIDEND[1] IS LESS THAN DIVISOR
CHKLT:

SEC
LDA DVEND+2
SBC DVSOR
TAY
LDA DVEND+3
SBC DVSOR+1
BCC DECCNT
STY DVEND+2
STA DVEND+3

;SAVE LOW BYTE IN REG Y
;SUBTRACT HIGH BYTES WITH RESULT IN REG A
;BRANCH IF DIVIDEND < DIVISOR AND CARRY
;ELSE


DECCNT:

DEX
BNE DIVLP

ROL DVEND
;SHIFT IN THE LAST CARRY FOR THE QUOTIENT

ROL DVEND+1
;NO ERRORS, CLEAR CARRY

DATA

DVSOR: .BLOCK 2
DVEND: .BLOCK 2
DECCNT: .BLOCK 2
RETADR: .BLOCK 2
SQUOT: .BLOCK 1
SREM: .BLOCK 1
RSLTIX: .BLOCK 1

;DIVISOR
;DIVIDEND[0] AND QUOTIENT
;DIVIDEND[1] AND REMAINDER
;RETURN ADDRESS
;SIGN OF QUOTIENT
;SIGN OF REMAINDER
;INDEX TO THE RESULT 0 IS QUOTIENT,
;2 IS REMAINDER

;PROGRAM SECTION
SC0604:

;SIGNED DIVIDE, OPRND1 / OPRND2, STORE THE QUOTIENT AT QUOT
LDA OPRND1+1
PHA
LDA OPRND1
PHA
LDA OPRND2+1
PHA
LDA OPRND2
PHA
JSR SDIV16
;SIGNED DIVIDE
PLA
STA QUOT
PLA
STA QUOT+1

;RESULT OF -1023 / 123 = -8
; IN MEMORY QUOT = F8 HEX
; QUOT+1 = FF HEX
6D 16-BIT DIVISION (SDIV16, UDIV16, SREM16, UREM16) 247

; UNSIGNED DIVIDE, OPRND1 / OPRND2, STORE THE QUOTIENT AT QUOT
LDA  OPRND1+1
PHA
LDA  OPRND1
PHA
LDA  OPRND2+1
PHA
LDA  OPRND2
PHA
JSR  UDIV16 ;UNSIGNED DIVIDE
PLA
STA  QUOT
PLA
STA  QUOT+1
BRK
; RESULT OF 64513 / 123 = 524
; IN MEMORY QUOT = 0C HEX
; QUOT+1 = 02 HEX

; SIGNED REMAINDER, OPRND1 / OPRND2, STORE THE REMAINDER AT REM
LDA  OPRND1+1
PHA
LDA  OPRND1
PHA
LDA  OPRND2+1
PHA
LDA  OPRND2
PHA
JSR  SREM16 ;REMAINDER
PLA
STA  REM
PLA
STA  REM+1
BRK
; THE REMAINDER OF -1023 / 123 = -39
; IN MEMORY REM = D9 HEX
; REM+1 = FF HEX

; UNSIGNED REMAINDER, OPRND1 / OPRND2, STORE THE REMAINDER AT REM
LDA  OPRND1+1
PHA
LDA  OPRND1
PHA
LDA  OPRND2+1
PHA
LDA  OPRND2
PHA
JSR  UREM16 ;REMAINDER
PLA
STA  REM
PLA
STA  REM+1
PLA
BRK
; THE REMAINDER OF 64513 / 123 = 61
; IN MEMORY REM = 3D HEX
; REM+1 = 00
248 ARITHMETIC

JMP SC0604

;DATA
OPRND1 .WORD -1023 ;DIVIDEND (64513 UNSIGNED)
OPRND2 .WORD 123 ;DIVISOR
QUOT: .BLOCK 2 ;QUOTIENT
REM: .BLOCK 2 ;REMAININDER

.END ;PROGRAM
**16-Bit Comparison (CMP16)**

Compares two 16-bit operands obtained from the stack and sets the flags accordingly. All 16-bit numbers are stored in the usual 6502 style with the less significant byte on top of the more significant byte. The comparison is performed by subtracting the top operand (or subtrahend) from the bottom operand (or minuend). The Zero flag always indicates whether the numbers are equal. If the numbers are unsigned, the Carry flag indicates which one is larger (Carry = 0 if top operand or subtrahend is larger and 1 otherwise). If the numbers are signed, the Negative flag indicates which one is larger (Negative = 1 if top operand or subtrahend is larger and 0 otherwise); two's complement overflow is considered and the Negative flag is inverted if it occurs.

**Procedure:** The program first compares the less significant bytes of the subtrahend and the minuend. It then subtracts the more significant byte of the subtrahend from the more significant byte of the minuend, thus setting the flags. If the less significant bytes of the operands are not equal, the program clears the Zero flag by logically ORing the accumulator with 01₁₀. If the subtraction results in two’s complement overflow, the program complements the Negative flag by logically Exclusive ORing the accumulator with 80₁₀ (10000000₂); it also clears the Zero flag by the method described earlier.

**Entry Conditions**

Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Less significant byte of subtrahend (top operand or WORD2)
- More significant byte of subtrahend (top operand or WORD2)
- Less significant byte of minuend (bottom operand or WORD1)
- More significant byte of minuend (bottom operand or WORD1)

**Exit Conditions**

Flags set as if subtrahend had been subtracted from minuend, with a correction if two’s complement overflow occurred.

- Zero flag = 1 if subtrahend and minuend are equal, 0 if they are not equal.
- Carry flag = 0 if subtrahend is larger than minuend in the unsigned sense, 1 if it is less than or equal to the minuend.
- Negative flag = 1 if subtrahend is larger than minuend in the signed sense, 0 if it is less than or equal to the minuend. This flag is corrected if two’s complement overflow occurs.
Examples

1. Data: Minuend (bottom operand) = 03E1\textsubscript{16}
   Subtrahend (top operand) = 07E4\textsubscript{16}
   Result: Carry = 0, indicating subtrahend is larger in unsigned sense.
           Zero = 0, indicating operands not equal
           Negative = 1, indicating subtrahend is larger in signed sense

2. Data: Minuend (bottom operand) = C51A\textsubscript{16}
   Subtrahend (top operand) = C51A\textsubscript{16}
   Result: Carry = 1, indicating subtrahend is not larger in unsigned sense
           Zero = 1, indicating operands are equal
           Negative = 0, indicating subtrahend is not larger in signed sense

3. Data: Minuend (bottom operand) = A45D\textsubscript{16}
   Subtrahend (top operand) = 77E1\textsubscript{16}
   Result: Carry = 1, indicating subtrahend is not larger in unsigned sense
           Zero = 0, indicating operands are not equal
           Negative = 1, indicating subtrahend is larger in signed sense

In Example 3, the bottom operand is a negative two's complement number, whereas the top operand is a positive two's complement number.

Title: 16 bit compare
Name: CMP16
Purpose: Compare 2 16 bit signed or unsigned words and return the C,Z,N flags set or cleared.
Entry: TOP OF STACK
         Low byte of return address,
         High byte of return address,
         Low byte of word 2 (subtrahend),
         High byte of word 2 (subtrahend),
         Low byte of word 1 (minuend),
         High byte of word 1 (minuend)
Exit: Flags returned based on word 1 - word 2
      IF WORD1 AND WORD2 ARE 2'S COMPLEMENT NUMBERS
      THEN
      IF WORD1 = WORD2 THEN
      Z=1, N=0
IF WORD1 > WORD2 THEN
    Z=0,N=0
ELSE
    IF WORD1 = WORD2 THEN
        Z=1,C=1
    IF WORD1 > WORD2 THEN
        Z=0,C=1
    IF WORD1 < WORD2 THEN
        Z=0,C=0

Registers used: A,P

Time: Approximately 90 cycles

Size: Program 65 bytes
      Data 6 bytes

CMP16:
;SAVE THE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET SUBTRAHEND
PLA
STA SUBTRA
PLA
STA SUBTRA+1

;GET MINUEND
PLA
STA MINEND
PLA
STA MINEND+1

;RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA

LDA MINEND
CMP SUBTRA ;COMPARE LOW BYTES
BEQ EQUAL ;BRANCH IF THEY ARE EQUAL

;LOW BYTES ARE NOT EQUAL - COMPARE HIGH BYTES
LDA MINEND+1
SBC SUBTRA+1 ;COMPARE HIGH BYTES
ORA #1 ;MAKE Z = 0, SINCE LOW BYTES ARE NOT EQUAL
BVS OVFLOW ;MUST HANDLE OVERFLOW FOR SIGNED ARITHMETIC
RTS ;EXIT
ARITHMETIC

; LOW BYTES ARE EQUAL - COMPARE HIGH BYTES
EQUAL:
LDA MINEND+1
SBC SUBTRA+1
BVS OVFLOW
RTS

; OVERFLOW WITH SIGNED ARITHMETIC SO COMPLEMENT THE NEGATIVE FLAG
; DO NOT CHANGE THE CARRY FLAG AND MAKE THE ZERO FLAG EQUAL 0.
; COMPLEMENT NEGATIVE FLAG BY EXCLUSIVE-ORING 80H AND ACCUMULATOR.
OVFLOW:
EOR #80H
ORA #1
RTS

; DATA
MINEND: .BLOCK 2
SUBTRA: .BLOCK 2
RETA: .BLOCK 2

; SAMPLE EXECUTION

SC0605:
; COMPARE OPRND1 AND OPRND2
LDA OPRND1+1
PHA
LDA OPRND1
PHA
LDA OPRND2+1
PHA
LDA OPRND2
PHA
JSR CMP16
BRK
JMP SC0605

OPRND1 .WORD 123
OPRND2 .WORD 1023

.END ; PROGRAM
Multiple-Precision Binary Addition (MPBADD)

Adds two multi-byte unsigned binary numbers. Both numbers are stored with their least significant bytes first (at the lowest address). The sum replaces one of the numbers (the one with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less.

Procedure: The program clears the Carry flag initially and adds the operands one byte at a time, starting with the least significant bytes. The final Carry flag reflects the addition of the most significant bytes. The sum replaces the operand with the starting address lower in the stack (array 1 in the listing). A length of 00 causes an immediate exit with no addition operations.

Registers Used: All
Execution Time: 23 cycles per byte plus 82 cycles overhead. For example, adding two 6-byte operands takes 23 × 6 + 82 or 220 cycles
Program Size: 48 bytes
Data Memory Required: Two bytes anywhere in RAM plus four bytes on page 0. The two bytes anywhere in RAM are temporary storage for the return address (starting at address RETADR). The four bytes on page 0 hold pointers to the two numbers (starting at addresses AY1PTR and AY2PTR, respectively). In the listing, AY1PTR is taken as address 00D0₁₆ and AY2PTR as address 00D2₁₆.
Special Case: A length of zero causes an immediate exit with the sum equal to the bottom operand (i.e., array 1 is unchanged). The Carry flag is set to 1.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Length of the operands in bytes

Less significant byte of starting address of second operand (address containing the least significant byte of array 2)
More significant byte of starting address of second operand (address containing the least significant byte of array 2)

Less significant byte of starting address of first operand and result (address containing the least significant byte of array 1)
More significant byte of starting address of first operand and result (address containing the least significant byte of array 1)

Exit Conditions

First operand (array 1) replaced by first operand (array 1) plus second operand (array 2).
Example

Data:     Length of operands (in bytes) = 6
          Top operand (array 2) = 19D028A193EA_{16}
          Bottom operand (array 1) = 293EABF059C7_{16}

Result:   Bottom operand (array 1) = Bottom
          operand (array 1) + Top operand
          (array 2) = 430ED491EDB_{16}
          Carry = 0

Title      Multiple-Precision Binary Addition
Name:      MPBADD

Purpose:   Add 2 arrays of binary bytes
Entry:     TOP OF STACK
            Low byte of return address,
            High byte of return address,
            Length of the arrays in bytes,
            Low byte of array 2 address,
            High byte of array 2 address,
            Low byte of array 1 address,
            High byte of array 1 address
            The arrays are unsigned binary numbers with a
            maximum length of 255 bytes, ARRAY[0] is the
            least significant byte, and ARRAY[LENGTH-1]
            the most significant byte.
Exit:      Array1 := Array1 + Array2
Registers used: All
Time:      23 cycles per byte plus 82 cycles
           overhead.
Size:      Program 48 bytes
           Data      2 bytes plus
           4 bytes in page zero

;EQUATES
AY1PTR:   .EQU  0D0H  ;PAGE ZERO FOR ARRAY 1 POINTER
AY2PTR:   .EQU  0D2H  ;PAGE ZERO FOR ARRAY 2 POINTER
MPBADD:   ;SAVE RETURN ADDRESS
PLA      RETADR
PLA      RETADR+1

;GET LENGTH OF ARRAYS
PLA
TAX

;GET STARTING ADDRESS OF ARRAY 2
PLA
STA      AY2PTR
PLA
STA      AY2PTR+1

;GET STARTING ADDRESS OF ARRAY 1
PLA
STA      AY1PTR
PLA
STA      AY1PTR+1

;RESTORE RETURN ADDRESS
LDA      RETADR+1
PHA
LDA      RETADR
PHA

;INITIALIZE
LDY      #0
CPX      #0
BEQ      EXIT
CLC

LOOP:
LDA      (AY1PTR),Y     ;GET NEXT BYTE
ADC      (AY2PTR),Y     ;ADD BYTES
STA      (AY1PTR),Y     ;STORE SUM
INY
DEX
BNE      LOOP           ;CONTINUE UNTIL COUNTER = 0

EXIT:
RTS

;DATA
RETDAR   .BLOCK 2       ;TEMPORARY FOR RETURN ADDRESS

;SAMPLE EXECUTION:

SC0606:
LDA AYLADR+1
PHA
LDA AYLADR
PHA ;PUSH AYL ADDRESS
LDA AYL2ADR+1
PHA
LDA AYL2ADR
PHA ;PUSH AYL2 ADDRESS
LDA #$SZAYS
PHA
JSR MPBADD ;MULTIPLE-PRECISION BINARY ADDITION
BRK
;RESULT OF 1234567H + 1234567H = 2468ACEH
;IN MEMORY
AY1 = CEH
; AY1+1 = 8AH
; AY1+2 = 46H
; AY1+3 = 02H
; AY1+4 = 00H
; AY1+5 = 00H
; AY1+6 = 00H

JMP SC0606

SZAYS: .EQU 7 ;SIZE OF ARRAYS
AY1ADR: .WORD AY1 ;ADDRESS OF ARRAY 1
AY2ADR: .WORD AY2 ;ADDRESS OF ARRAY 2

AY1:
.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

AY2:
.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

.END ;PROGRAM
Multiple-Precision Binary Subtraction
(MPBSUB)

Subtracts two multi-byte unsigned binary numbers. Both numbers are stored with their least significant byte at the lowest address. The starting address of the subtrahend (number to be subtracted) is stored on top of the starting address of the minuend (number from which the subtrahend is subtracted). The difference replaces the minuend in memory. The length of the numbers (in bytes) is 255 or less.

Procedure: The program sets the Carry flag (the inverted borrow) initially and subtracts the subtrahend from the minuend one byte at a time, starting with the least significant bytes. The final Carry flag reflects the subtraction of the most significant bytes. The difference replaces the minuend (the operand with the starting address lower in the stack, array 1 in the listing). A length of 00

<table>
<thead>
<tr>
<th>Registers Used: All</th>
</tr>
</thead>
<tbody>
<tr>
<td>Execution Time: 23 cycles per byte plus 82 cycles overhead. For example, subtracting two 6-byte operands takes $23 \times 6 + 82$ or 220 cycles.</td>
</tr>
<tr>
<td>Program Size: 48 bytes</td>
</tr>
<tr>
<td>Data Memory Required: Two bytes anywhere in RAM plus four bytes on page 0. The two bytes anywhere in RAM are temporary storage for the return address (starting at address RETADR). The four bytes on page 0 hold pointers to the two numbers (starting at addresses MINPTR and SUBPTR, respectively). In the listing, MINPTR is taken as address 00D016 and SUBPTR as address 00D216.</td>
</tr>
<tr>
<td>Special Case: A length of zero causes an immediate exit with the minuend unchanged (that is, the difference is equal to the bottom operand). The Carry flag is set to 1.</td>
</tr>
</tbody>
</table>

causes an immediate exit with no subtraction operations.

Entry Conditions

<table>
<thead>
<tr>
<th>Order in stack (starting from the top)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Less significant byte of return address</td>
</tr>
<tr>
<td>More significant byte of return address</td>
</tr>
<tr>
<td>Length of the operands in bytes</td>
</tr>
<tr>
<td>Less significant byte of starting address of subtrahend (address containing the least significant byte of array 2)</td>
</tr>
<tr>
<td>More significant byte of starting address of subtrahend (address containing the least significant byte of array 2)</td>
</tr>
<tr>
<td>Less significant byte of starting address of minuend (address containing the least significant byte of array 1)</td>
</tr>
<tr>
<td>More significant byte of starting address of minuend (address containing the least significant byte of array 1)</td>
</tr>
</tbody>
</table>

Exit Conditions

| Minuend replaced by minuend minus subtrahend. |
Example

Data:  Length of operands (in bytes) = 4
       Minuend = 2F5BA7C3₁₆
       Subtrahend = 14DF35B8₁₆

Result: Difference = 1A7C720B₁₆.
This number replaces the original minuend in memory. The
Carry flag is set to 1 in accordance with its usual role (in 6502 pro-
gramming) as an inverted borrow.

Title: Multiple-Precision Binary Subtraction
Name: MPBSUB

Purpose: Subtract 2 arrays of binary bytes
Minuend := Minuend - Subtrahend

Entry: TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Length of the arrays in bytes,
   Low byte of subtrahend address,
   High byte of subtrahend address,
   Low byte of minuend address,
   High byte of minuend address

The arrays are unsigned binary numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Minuend := Minuend - Subtrahend

Registers used: All

Time: 23 cycles per byte plus 82 cycles overhead.

Size: Program 48 bytes
Data 2 bytes plus
   4 bytes in page zero

;EQUIVATES
MINPTR: .EQU 0D0H ;PAGE ZERO FOR MINUEND POINTER
SUBPTR: .EQU 0D2H ;PAGE ZERO FOR SUBTRAHEND POINTER
MPBSUB:

;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

;GET LENGTH OF ARRAYS
PLA
TAX

;GET STARTING ADDRESS OF SUBTRAHEND
PLA
STA SUBPTR
PLA
STA SUBPTR+1

;GET STARTING ADDRESS OF MINUEND
PLA
STA MINPTR
PLA
STA MINPTR+1

;RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA

;INITIALIZE
LDY #0
CPX #0
BEQ EXIT
SEC

LOOP:
LDA (MINPTR),Y
SBC (SUBPTR),Y
STA (MINPTR),Y
INY
DEX
BNE LOOP

EXIT:
RTS

;DATA
RETAADR .BLOCK 2

;TEMPORARY FOR RETURN ADDRESS

;SAMPLE EXECUTION:
SC0607:

LDA AY1ADR+1
PHA
LDA AY1ADR
PHA ; PUSH AY1 ADDRESS

LDA AY2ADR+1
PHA
LDA AY2ADR
PHA ; PUSH AY2 ADDRESS

LDA #SZAYS
PHA ; PUSH SIZE OF ARRAYS
JSR MPBSUB ; MULTIPLE-PRECISION BINARY SUBTRACTION
BRK

; RESULT OF 7654321H - 1234567H = 641FDBAH
; IN MEMORY AY1 = 0BAH
; AY1+1 = 0FDH
; AY1+2 = 41H
; AY1+3 = 06H
; AY1+4 = 00H
; AY1+5 = 00H
; AY1+6 = 00H

JMP SC0607

SZAYS: .EQU 7 ; SIZE OF ARRAYS

AY1ADR: .WORD AY1 ; ADDRESS OF ARRAY 1 (MINUEND)
AY2ADR: .WORD AY2 ; ADDRESS OF ARRAY 2 (SUBTRAHEND)

AY1:

.BYTE 021H
.BYTE 043H
.BYTE 065H
.BYTE 007H
.BYTE 0
.BYTE 0
.BYTE 0

AY2:

.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

.END ; PROGRAM
Multiple-Precision Binary Multiplication
(MPBMUL)

Multiplies two multi-byte unsigned binary numbers. Both numbers are stored with their least significant byte at the lowest address. The product replaces one of the numbers (the one with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less. Only the least significant bytes of the product are returned to retain compatibility with other multiple-precision binary operations.

Procedure: The program uses an ordinary add-and-shift algorithm, adding the multiplicand (array 2) to the partial product each time it finds a 1 bit in the multiplier (array 1). The partial product and the multiplier are shifted through the bit length plus 1 with the extra loop being necessary to move the final carry into the product. The program maintains a full double-length unsigned partial product in memory locations starting at HIPROD (more significant bytes) and in array 1 (less significant bytes). The less significant bytes of the product replace the multiplier as the multiplier is shifted and examined for 1 bits. A length of 00 causes an exit with no multiplication.

<table>
<thead>
<tr>
<th>Registers Used: All</th>
</tr>
</thead>
<tbody>
<tr>
<td>Execution Time: Depends on the length of the operands and on the number of 1 bits in the multiplier (requiring actual additions). If the average number of 1 bits in the multiplier is four per byte, the execution time is approximately</td>
</tr>
<tr>
<td>$316 \times \text{LENGTH}^2 + 223 \times \text{LENGTH} + 150$</td>
</tr>
<tr>
<td>cycles where LENGTH is the number of bytes in the operands. If, for example, LENGTH = 4, the approximate execution time is</td>
</tr>
<tr>
<td>$316 \times 4^2 + 223 \times 4 + 150 = 316 \times 16 + 892 + 150 = 5056 + 1042 = 6,098$ cycles.</td>
</tr>
<tr>
<td>Program Size: 145 bytes</td>
</tr>
<tr>
<td>Data Memory Required: 260 bytes anywhere in RAM plus four bytes on page 0. The 260 bytes anywhere in RAM are temporary storage for the more significant bytes of the product (255 bytes starting at address HIPROD), the return address (two bytes starting at address RETADR), the loop counter (two bytes starting at address COUNT), and the length of the operands in bytes (one byte at address LENGTH). The four bytes on page 0 hold pointers to the two operands (the pointers start at addresses AY1PTR and AY2PTR, respectively). In the listing, AY1PTR is taken as address 00D016 and AY2PTR as address 00D216.</td>
</tr>
<tr>
<td>Special Case: A length of zero causes an immediate exit with the product equal to the original multiplier (that is, array 1 is unchanged) and the more significant bytes of the product (starting at address HIPROD) undefined.</td>
</tr>
</tbody>
</table>
Entry Conditions

Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Length of the operands in bytes
Less significant byte of starting address of multiplicand (address containing the least significant byte of array 2)
More significant byte of starting address of multiplicand (address containing the least significant byte of array 2)
Less significant byte of starting address of multiplier (address containing the least significant byte of array 1)
More significant byte of starting address of multiplier (address containing the least significant byte of array 1)

Exit Conditions

Multiplier (array 1) replaced by multiplier (array 1) times multiplicand (array 2).

Example

Data:
Length of operands (in bytes) = 04
Top operand (array 2 or multiplicand) = 0005D1F7_{16} = 381,431_{10}
Bottom operand (array 1 or multiplier) = 00000AB1_{16} = 2,737_{10}

Result:
Bottom operand (array 1) = Bottom operand (array 1) * Top operand (array 2) = 3E39D1C7_{16} = 1,043,976,647_{10}

Note that MPBMUL returns only the less significant bytes (that is, the number of bytes in the multiplicand and multiplier) of the product to maintain compatibility with other multiple-precision binary arithmetic operations. The more significant bytes of the product are available starting with their least significant byte at address HIPROD. The user may need to check those bytes for a possible overflow or extend the operands with additional zeros.
Title: Multiple-Precision Binary Multiplication
Name: MPBMUL

Purpose: Multiply 2 arrays of binary bytes
Array1 := Array1 * Array2

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Length of the arrays in bytes,
Low byte of array 2 (multiplicand) address,
High byte of array 2 (multiplicand) address,
Low byte of array 1 (multiplier) address,
High byte of array 1 (multiplier) address,

The arrays are unsigned binary numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Array1 := Array1 * Array2

Registers used: All

Time: Assuming the average number of 1 bits in array 1 is 4 * length then the time is approximately
(316 * length^2) + (223 * length) + 150 cycles

Size: Program 145 bytes
Data 260 bytes plus
4 bytes in page zero

;EQUATES
AY1PTR: .EQU 0D0H ;PAGE ZERO FOR ARRAY 1 POINTER
AY2PTR: .EQU 0D2H ;PAGE ZERO FOR ARRAY 2 POINTER

MPBMUL:
;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1 ;SAVE RETURN ADDRESS

;GET LENGTH OF ARRAYS
PLA
STA LENGTH

;GET ADDRESS OF ARRAY 2 AND SUBTRACT 1 SO THAT THE ARRAYS MAY BE INDEXED FROM 1 TO LENGTH RATHER THAN 0 TO LENGTH-1
PLA
SEC
SBC "1 " ;SUBTRACT 1 FROM LOW BYTE
STA AY2PTR
PLA
SBC "0 " ;SUBTRACT BORROW IF ANY
STA AY2PTR+1

;GET ADDRESS OF ARRAY 1 AND SUBTRACT 1
PLA
SEC
SBC "1 " ;SUBTRACT 1 FROM LOW BYTE
STA AY1PTR
PLA
SBC "0 " ;SUBTRACT BORROW IF ANY
STA AY1PTR+1

;RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA

;EXIT IF LENGTH IS ZERO
LDA LENGTH ;IS LENGTH OF ARRAYS = 0 ?
BEQ EXIT ;YES, EXIT

;SET COUNT TO NUMBER OF BITS IN ARRAY PLUS 1
; COUNT := (LENGTH * 8) + 1
STA COUNT ;INITIALIZE COUNTER TO LENGTH
LDA "0 "
ASL COUNT ;COUNT * 2
ROL A ;A WILL BE UPPER BYTE
ASL COUNT ;COUNT * 4
ROL A
ASL COUNT ;COUNT * 8
ROL A
STA COUNT+1 ;STORE UPPER BYTE OF COUNT
INC COUNT ;INCREMENT LOW BYTE OF COUNT
BNE ZEROPD
INC COUNT+1 ;INCREMENT HIGH BYTE IF LOW BYTE BECOMES, 0

;ZERO HIGH PRODUCT ARRAY
ZEROPD:
LDX LENGTH
LDA "0 "

ZEROLP:
STA HIPROD-1,X ;THE MINUS 1 FOR INDEXING FROM 1 TO LENGTH
DEX
BNE ZEROLP

;MULTIPLY USING THE SHIFT AND ADD ALGORITHM
; ARRAY 1 WILL BE THE MULTIPLIER AND ARRAY 2 THE MULTIPLICAND
CLC ;CLEAR CARRY FIRST TIME THROUGH

LOOP:
;SHIFT CARRY INTO THE UPPER PRODUCT ARRAY AND THE LEAST SIGNIFICANT
; BIT OF THE UPPER PRODUCT ARRAY TO CARRY
LDX LENGTH
SRPLP:

ROR HIPROD-1,X ;MINUS 1 FOR INDEXING FROM 1 TO LENGTH
DEX BNE SRPLP ;CONTINUE UNTIL INDEX = 0

;SHIFT CARRY WHICH IS THE NEXT BIT OF LOWER PRODUCT INTO THE MOST
;SIGNIFICANT BIT OF ARRAY 1. THIS IS THE NEXT BIT OF THE PRODUCT.
;THIS ALSO SHIFTS THE NEXT BIT OF MULTIPLIER TO CARRY.
LDY LENGTH

SRALLP:

LDA (AY1PTR),Y ;ROTATE NEXT BYTE
ROR A
STA (AY1PTR),Y
DEY BNE SRALLP ;CONTINUE UNTIL INDEX = 0

;IF NEXT BIT OF THE MULTIPLIER IS 1 THEN
;ADD ARRAY 2 AND UPPER ARRAY OF PRODUCT
BCC DECCNT ;BRANCH IF NEXT BIT IS ZERO

;ADD ARRAY 2 AND HIPROD
LDY #1
LDX LENGTH
CLC

ADDP:

LDA (AY2PTR),Y
ADC HIPROD-1,Y ;ADD BYTES
STA HIPROD-1,Y
INY ;INCREMENT INDEX
DEX ;DECREMENT COUNTER
BNE ADDLP ;CONTINUE UNTIL COUNT = 0

;DECREMENT BIT COUNTER AND EXIT IF DONE
;DOES NOT CHANGE CARRY!

DECCNT:

DEC COUNT ;DECREMENT LOW BYTE OF COUNT
BNE LOOP ;BRANCH IF IT IS NOT ZERO
LDX COUNT+1 ;GET HIGH BYTE
BEQ EXIT ;EXIT IF COUNT IS ZERO
DEX ;ELSE DECMENT HIGH BYTE OF COUNT
STX COUNT+1
JMP LOOP

EXIT:

RTS

;DATA

RETRADRF.BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS
COUNTER.BLOCK 2 ;TEMPORARY FOR LOOP COUNTER
LENGTH.BLOCK 1 ;LENGTH OF ARRAYS
HIPROD.BLOCK 255 ;HIGH PRODUCT BUFFER
SAMPLE EXECUTION:

```
; SC0608:
LDA AY1ADR+1
PHA
LDA AY1ADR
PHA
; PUSH AY1 ADDRESS
LDA AY2ADR+1
PHA
LDA AY2ADR
PHA
; PUSH AY2 ADDRESS
LDA #SZAYS
PHA
JSR MPBMUL
BRK
; PUSH SIZE OF ARRAYS
; MULTIPLE-PRECISION BINARY MULTIPLY
; RESULT OF 12345H * 1234H = 14B60404H
; IN MEMORY
AY1 = 04H
AY1+1 = 04H
AY1+2 = B6H
AY1+3 = 14H
AY1+4 = 00H
AY1+5 = 00H
AY1+6 = 00H
```

JMP SC0608

SZAYS: .EQU 7

AY1ADR: .WORD AY1
AY2ADR: .WORD AY2

AY1:
```plaintext
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
```

AY2:
```plaintext
.BYTE 034H
.BYTE 012H
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
```

.END ; PROGRAM
Divides two multi-byte unsigned binary numbers. Both numbers are stored with their least significant byte at the lowest address. The quotient replaces the dividend (the operand with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less. The remainder is not returned, but its starting address (least significant byte) is available in memory locations HDEPTR and HDEPTR + 1. The Carry flag is cleared if no errors occur; if a divide by zero is attempted, the Carry flag is set to 1, the dividend is left unchanged, and the remainder is set to zero.

**Procedure:** The program performs division by the usual shift-and-subtract algorithm, shifting quotient and dividend and placing a 1 bit in the quotient each time a trial subtraction is successful. An extra buffer is used to hold the result of the trial subtraction and that buffer is simply switched with the buffer holding the dividend if the trial subtraction is successful. The program exits immediately, setting the Carry flag, if it finds the divisor to be zero. The Carry flag is cleared otherwise.

**Registers Used:** All

**Execution Time:** Depends on the length of the operands and on the number of 1 bits in the quotient (requiring a buffer switch). If the average number of 1 bits in the quotient is four per byte, the execution time is approximately

\[480 \times \text{LENGTH}^2 + 438 \times \text{LENGTH} + 208\]

cycles where LENGTH is the number of bytes in the operands. If, for example, LENGTH = 4 (32-bit division), the approximate execution time is

\[480 \times 4^2 + 438 \times 4 + 208 = 480 \times 16 + 1752 + 208 = 7680 + 1960 = 9,640 \text{ cycles}\]

**Program Size:** 206 bytes

**Data Memory Required:** 519 bytes anywhere in RAM plus eight bytes on page 0. The 519 bytes anywhere in RAM are temporary storage for the high dividend (255 bytes starting at address HIDE1), the result of the trial subtraction (255 bytes starting at address HIDE2), the return address (two bytes starting at address RETADR), the loop counter (two bytes starting at address COUNT), the length of the operands (one byte at address LENGTH), and the addresses of the high dividend buffers (two bytes starting at address AHIDE1 and two bytes starting at address AHIDE2). The eight bytes on page 0 hold pointers to the two operands and to the two temporary buffers for the high dividend. The pointers start at addresses AY1PTR (00D016 in the listing), AY2PTR (00D216 in the listing), HDEPTR (00D416 in the listing), and ODEPTR (00D616 in the listing). HDEPTR contains the address of the least significant byte of the remainder at the conclusion of the program.

**Special Cases:**

1. A length of zero causes an immediate exit with the Carry flag cleared, the quotient equal to the original dividend, and the remainder undefined.

2. A divisor of zero causes an exit with the Carry flag set to 1, the quotient equal to the original dividend, and the remainder equal to zero.
**Entry Conditions**

Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Length of the operands in bytes
- Less significant byte of starting address of divisor (address containing the least significant byte of array 2)
- More significant byte of starting address of divisor (address containing the least significant byte of array 2)
- Less significant byte of starting address of dividend (address containing the least significant byte of array 1)
- More significant byte of starting address of dividend (address containing the least significant byte of array 1)

**Exit Conditions**

Dividend (array 1) replaced by dividend (array 1) divided by divisor (array 2).

- If the divisor is non-zero, Carry = 0 and the result is normal.
- If the divisor is zero, Carry = 1, the dividend is unchanged and the remainder is zero.
- The remainder is available with its least significant byte stored at the address in HDEPTR and HDEPTR+1

**Example**

**Data:**
- Length of operands (in bytes) = 03
- Top operand (array 2 or divisor) = 00F416 = 390910
- Bottom operand (array 1 or dividend) = 35A2F716 = 3,515,12710

**Result:**
- Bottom operand (array 1) = Bottom operand (array 1) / Top operand (array 2) = 00038316 = 89910
- Remainder (starting at address in HDEPTR and HDEPTR+1) = 0003A816 = 93610
- Carry flag is 0 to indicate no divide by zero error
Title: Multiple-Precision Binary Division

Name: MPBDIV

Purpose: Divide 2 arrays of binary bytes

Entry: TOP OF STACK

- Low byte of return address,
- High byte of return address,
- Length of the arrays in bytes,
- Low byte of array 2 (divisor) address,
- High byte of array 2 (divisor) address,
- Low byte of array 1 (dividend) address,
- High byte of array 1 (dividend) address

The arrays are unsigned binary numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Array1 := Array1 / Array2

If no errors then
- carry := 0
ELSE
- divide by 0 error
- carry := 1
- quotient := array 1 unchanged
- remainder := 0

Registers used: All

Time: Assuming there are length/2 1 bits in the quotient then the time is approximately

\( (480 \times \text{length}^2) + (438 \times \text{length}) + 208 \) cycles

Size: Program 206 bytes

Data 519 bytes plus

- 8 bytes in page zero

;EQUATES
AY1PTR: .EQU 0D0H ;PAGE ZERO FOR ARRAY 1 POINTER
AY2PTR: .EQU 0D2H ;PAGE ZERO FOR ARRAY 2 POINTER
HDEPTR: .EQU 0D4H ;PAGE ZERO FOR HIGH DIVIDEND POINTER
ODEPTR: .EQU 0D6H ;PAGE ZERO FOR OTHER HIGH DIVIDEND POINTER
MPBDIV: ;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1
;GET LENGTH OF ARRAYS
PLA
STA LENGTH

;GET STARTING ADDRESS OF DIVISOR
PLA
STA AY2PTR
PLA
STA AY2PTR+1

;GET STARTING ADDRESS OF DIVIDEND
PLA
STA AY1PTR
PLA
STA AY1PTR+1

;RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA

;INITIALIZE
LDA LENGTH ;IS LENGTH OF ARRAYS = 0 ?
BNE INIT
JMP OKEEXIT ;YES, EXIT

;SET COUNT TO NUMBER OF BITS IN THE ARRAYS
; COUNT := (LENGTH * 8) + 1

INIT:
STA COUNT ;INITIALIZE COUNTER TO LENGTH
LDA $0
ASL COUNT ;COUNT * 2
ROL A ;A WILL BE UPPER BYTE
ASL COUNT ;COUNT * 4
ROL A
ASL COUNT ;COUNT * 8
ROL A
STA COUNT+1 ;STORE UPPER BYTE OF COUNT
INC COUNT ;INCREMENT COUNT
BNE ZEROPD
INC COUNT+1

;ZERO BOTH HIGH DIVIDEND ARRAYS
ZEROPD:
LDX LENGTH
LDA $0

ZEROLP:
STA HIDE1-1,X ;THE MINUS 1 FOR INDEXING FROM 1 TO LENGTH
STA HIDE2-1,X
DEX
BNE ZEROLP

;SET HIGH DIVIDEND POINTER TO HIDE1
LDA AHIDE1
STA HDEPTR
LDA AHIDE1+1
STA HDEPTR+1
;SET OTHER HIGH DIVIDEND POINTER TO HIDE2
LDA AHIDE2
STA ODEPTR
LDA AHIDE2+1
STA ODEPTR+1
;CHECK IF DIVISOR IS ZERO
LDK LENGTH ;LOGICALLY OR ALL BYTES OF DIVISOR
LDY #0
TYA
CHK0LP:
ORA (AY2PTR),Y
INY ;INCREMENT INDEX
DEX
BNE CHK0LP ;CONTINUE UNTIL REGISTER X = 0
CMP #0
BNE DIV ;BRANCH IF DIVISOR IS NOT ZERO
JMP EEXIT ; ELSE EXIT INDICATING ERROR
;DIVIDE USING THE TRIAL SUBTRACTION ALGORITHM
DIV:
CLC ;CLEAR CARRY FOR THE FIRST TIME THROUGH
LOOP:
;SHIFT CARRY INTO LOWER DIVIDEND ARRAY AS THE NEXT BIT OF QUOTIENT
; AND THE MOST SIGNIFICANT BIT OF THE LOWER DIVIDEND TO CARRY.
LDX LENGTH
LDY #0
SLLP1:
LDA (AY1PTR),Y ;ROTATE NEXT BYTE
ROL A
STA (AY1PTR),Y ;INCREMENT THE INDEX
INY
DEX
BNE SLLP1 ;CONTINUE UNTIL REGISTER X = 0
;DECREMENT BIT COUNTER AND EXIT IF DONE
;CARRY IS NOT CHANGED !!
DECCNT:
DEC COUNT ;DECREMENT LOW BYTE OF COUNT
BNE SLUFR ;BRANCH IF IT IS NOT ZERO
LDX COUNT+1 ;GET HIGH BYTE
BEC OKEEXIT ;EXIT IF COUNT IS ZERO
DEX
STX COUNT+1 ;ELSE DECREMENT HIGH BYTE OF COUNT
;SHIFT THE CARRY INTO THE LEAST SIGNIFICANT BIT OF THE UPPER DIVIDEND
SLUFR:
LDX LENGTH
LDY #0
SLLP2:
LDA (HDEPTR),Y
ROL A
STA (HDEPTR),Y          ;INCREMENT INDEX
INY
DEX
BNE SLLP2              ;CONTINUE UNTIL REGISTER X = 0

;SUBTRACT ARRAY 2 FROM HIGH DIVIDEND PLACING THE DIFFERENCE INTO
;OTHER HIGH DIVIDEND ARRAY
LDY #0
LDX LENGTH
SEC

SUBLP:
LDA (HDEPTR),Y          ;SUBTRACT THE BYTES
SBC (AY2PTR),Y          ;STORE THE DIFFERENCE
INY                   ;INCREMENT INDEX
DEX
BNE SUBLP              ;CONTINUE UNTIL REGISTER X = 0

;IF NO CARRY IS GENERATED FROM THE SUBTRACTION THEN THE HIGH DIVIDEND
;IS LESS THAN ARRAY 2 SO THE NEXT BIT OF THE QUOTIENT IS 0.
;IF THE CARRY IS SET THEN THE NEXT BIT OF THE QUOTIENT IS 1
;AND WE REPLACE DIVIDEND WITH REMAINDER BY SWITCHING POINTERS.
BCC LOOP               ;WAS TRIAL SUBTRACTION SUCCESSFUL?
LDY HDEPTR             ;YES, EXCHANGE POINTERS THEUS REPLACING
LDX HDEPTR+1           ;DIVIDEND WITH REMAINDER
LDA ODEPTR             
STA HDEPTR             
LDA ODEPTR+1
STA HDEPTR+1
STY ODEPTR             
STX ODEPTR+1

;CONTINUE WITH NEXT BIT A 1 (CARRY = 1)
JMP LOOP

;CLEAR CARRY TO INDICATE NO ERRORS
OKEXIT:
CLC
BCC EXIT

;SET CARRY TO INDICATE A DIVIDE BY ZERO ERROR
EREXIT: SEC

EXIT:                ;ARRAY 1 IS THE QUOTIENT
;HDEPTR CONTAINS THE ADDRESS OF THE REMAINDER
RTS

;DATA
RETADR: .BLOCK 2      ;TEMPORARY FOR RETURN ADDRESS
COUNT: .BLOCK 2       ;TEMPORARY FOR LOOP COUNTER
LENGTH: .BLOCK 1      ;LENGTH OF ARRAYS
AHide1: .Word Hide1 ;ADDRESS OF HIGH DIVIDEND BUFFER 1
AHide2: .Word Hide2 ;ADDRESS OF HIGH DIVIDEND BUFFER 2
Hide1: .Block 255 ;HIGH DIVIDEND BUFFER 1
Hide2: .Block 255 ;HIGH DIVIDEND BUFFER 2

; SAMPLE EXECUTION:

SC0609:
LDA AY1ADR+1
PHA
LDA AY1ADR
PHA
;PUSH AY1 ADDRESS
LDA AY2ADR+1
PHA
LDA AY2ADR
PHA
;PUSH AY2 ADDRESS
LDA #SZAYS
PHA
JSR MPBDIV
;MULTIPLE-PRECISION BINARY DIVIDE
BRK
;RESULT OF 14B60404H / 1234H = 12345H
; IN MEMORY AY1 = 45H
; AY1+1 = 23H
; AY1+2 = 01H
; AY1+3 = 00H
; AY1+4 = 00H
; AY1+5 = 00H
; AY1+6 = 00H
JMP SC0609

SZAYS: .EQU 7 ;SIZE OF ARRAYS
AY1ADR: .Word AY1 ;ADDRESS OF ARRAY 1 (DIVIDEND)
AY2ADR: .Word AY2 ;ADDRESS OF ARRAY 2 (DIVISOR)

AY1:
BYTE 004H
BYTE 004H
BYTE 0B6H
BYTE 014H
BYTE 0
BYTE 0
BYTE 0

AY2:
BYTE 034H
 BYTE 012H
BYTE 0
BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.END ; PROGRAM
Multiple-Precision Binary Comparison
(MPBCMP)

Compares two multi-byte unsigned binary numbers and sets the Carry and Zero flags appropriately. The Zero flag is set to 1 if the operands are equal and to 0 if they are not equal. The Carry flag is set to 0 if the operand with the address higher in the stack (the subtrahend) is larger than the other operand (the minuend); the Carry flag is set to 1 otherwise. Thus, the flags are set as if the subtrahend had been subtracted from the minuend.

Procedure: The program compares the operands one byte at a time, starting with the most significant bytes and continuing until it finds corresponding bytes that are not equal. If all the bytes are equal, it exits with the Zero flag set to 1. Note that the comparison works through the operands starting with the most significant bytes, whereas the subtraction (Subroutine 6G) starts with the least significant bytes.

Registers Used: All
Execution Time: 17 cycles per byte that must be compared plus 90 cycles overhead. That is, the program continues until it finds corresponding bytes that are not equal; each pair of bytes it must examine requires 17 cycles.
Examples:
1. Comparing two 6-byte numbers that are equal
   \[17 \times 6 + 90 = 192 \text{ cycles}\]
2. Comparing two 8-byte numbers that differ in the next to most significant bytes
   \[17 \times 2 + 90 = 124 \text{ cycles}\]
Program Size: 54 bytes
Data Memory Required: Two bytes anywhere in RAM and four bytes on page 0. The two bytes anywhere in RAM are temporary storage for the return address (starting at address RETADR). The four bytes on page 0 hold pointers to the two numbers; the pointers start at addresses MINPTR (00D016 in the listing) and SUBPTR (00D216 in the listing).
Special Case: A length of zero causes an immediate exit with the Carry flag and the Zero flag both set to 1.

Entry Conditions
Order in stack (starting from top)
Less significant byte of return address
More significant byte of return address
Length of the operands in bytes
Less significant byte of starting address of subtrahend (address containing the least significant byte)
More significant byte of starting address of subtrahend (address containing the least significant byte)
Less significant byte of starting address of minuend (address containing the least sig-

Exit Conditions
Flags set as if subtrahend had been subtracted from minuend
Zero flag = 1 if subtrahend and minuend are equal, 0 if they are not equal
Carry flag = 0 if subtrahend is larger than minuend in the unsigned sense, 1 if it is less than or equal to the minuend.
significant byte)
More significant byte of starting address of minuend (address containing the least significant byte)

Examples

1. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 19D028A193EA16
   Bottom operand (minuend) = 4E67BC15A26616
   Result: Zero flag = 0 (operands are not equal)
            Carry flag = 1 (subtrahend is not larger than minuend)

2. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 19D028A193EA16
   Bottom operand (minuend) = 19D028A193EA16
   Result: Zero flag = 1 (operands are equal)
            Carry flag = 1 (subtrahend is not larger than minuend)

3. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 0F37E5991D7C16
   Bottom operand (minuend) = 0F37E5991D7C16
   Result: Zero flag = 0 (operands are not equal)
            Carry flag = 0 (subtrahend is larger than minuend)

Title
Name: Multiple-Precision Binary Comparison
MPBCMP

Purpose: Compare 2 arrays of binary bytes and return the CARRY and ZERO flags set or cleared

Entry: TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Length of the arrays in bytes,
   Low byte of array 2 (subtrahend) address,
   High byte of array 2 (subtrahend) address,
   Low byte of array 1 (minuend) address,
   High byte of array 1 (minuend) address
The arrays are unsigned binary numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit:

- IF ARRAY1 = ARRAY2 THEN
  - C = 1, Z = 1
- IF ARRAY1 > ARRAY2 THEN
  - C = 1, Z = 0
- IF ARRAY1 < ARRAY2 THEN
  - C = 0, Z = 0

Registers used: All

Time: 17 cycles per byte that must be examined plus 90 cycles overhead.

Size: Program 54 bytes

\[ \text{Data } 2 \text{ bytes plus } 4 \text{ bytes in page zero} \]

;EQUIVATES
MINPTR: .EQU 0D0H ; PAGE ZERO FOR ARRAY 1 POINTER
SUBPTR: .EQU 0D2H ; PAGE ZERO FOR ARRAY 2 POINTER

MPBCMP:

;SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1 ;SAVE RETURN ADDRESS

;GET LENGTH OF ARRAYS
PLA
TAY

;GET ADDRESS OF SUBTRAHEND AND SUBTRACT 1 TO SIMPLIFY INDEXING
PLA
SEC
SBC #1 ;SUBTRACT 1 FROM LOW BYTE
STA SUBPTR
PLA
SBC #0 ;SUBTRACT ANY BORROW FROM HIGH BYTE
STA SUBPTR+1

;GET ADDRESS OF MINUEND AND ALSO SUBTRACT 1
PLA
SEC
SBC #1 ;SUBTRACT 1 FROM LOW BYTE
STA MINPTR
PLA
SBC #0 ;SUBTRACT ANY BORROW FROM HIGH BYTE
STA MINPTR+1
; RESTORE RETURN ADDRESS
LDA   RETADR+1
PHA
LDA   RETADR
PHA

; INITIALIZE
CPY   #0 ; IS LENGTH OF ARRAYS = 0 ?
BEQ   EXIT ; YES, EXIT WITH C=1,Z=1

LOOP:
LDA   (MINPTR),Y ; GET NEXT BYTE
CMP   (SUBPTR),Y ; COMPARE BYTES
BNE   (MINPTR),Y ; EXIT IF THEY ARE NOT EQUAL, THE FLAGS ARE SET
DEY   ; DECREMENT INDEX
BNE   LOOP ; CONTINUE UNTIL COUNTER = 0
          ; IF WE FALL THROUGH THEN THE ARRAYS ARE EQUAL
          ; AND THE FLAGS ARE SET PROPERLY

EXIT:
RTS

; DATA
RETADR .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS

; SAMPLE EXECUTION:

; SC0610:
LDA   AY1ADR+1
PHA
LDA   AY1ADR
PHA
LDA   AY2ADR+1
PHA
LDA   AY2ADR
PHA
LDA   #SZAYS
PHA
JSR   MPBCMP ; MULTIPLE-PRECISION BINARY COMPARISON
BRK
JMP   SC0610

SZAYS:  .EQU    7 ; SIZE OF ARRAYS
AY1ADR: .WORD  AY1 ; ADDRESS OF ARRAY 1 (MINUEND)
AY2ADR: .WORD  AY2 ; ADDRESS OF ARRAY 2 (SUBTRAHEND)

AY1:
.BYTE 021H
.BYTE 043H
.BYTE 065H
.BYTE 007H
.BYTE 0
.BYTE 0
.BYTE 0

AY2:

.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

.END ; PROGRAM
Multiple-Precision Decimal Addition
(MPDADD) 6K

Adds two multi-byte unsigned decimal numbers. Both numbers are stored with their least significant digits at the lowest address. The sum replaces one of the numbers (the one with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less. The program returns with the Decimal Mode (D) flag cleared (binary mode).

Procedure: The program first enters the decimal mode by setting the D flag. It then clears the Carry flag initially and adds the operands one byte (two digits) at a time, starting with the least significant digits. The sum replaces the operand with the starting address lower in the stack (array 1 in the listing). A length of 00 causes an immediate exit with no addition operations. The program clears the D flag (thus placing the processor in the binary mode) before exiting. The final

Registers Used: All
Execution Time: 23 cycles per byte plus 82 cycles overhead. For example, adding two 8-byte (16-digit) operands takes $23 \times 8 + 86$ or 270 cycles.
Program Size: 50 bytes
Data Memory Required: Two bytes anywhere in RAM and four bytes on page 0. The two bytes anywhere in RAM are temporary storage for the return address (starting at address RETADR). The four bytes on page 0 hold pointers to the two operands; the pointers start at addresses AY1PTR (00D016 in the listing) and AY2PTR (00D216 in the listing).

Special Case: A length of zero causes an immediate exit with array 1 unchanged (that is, the sum is equal to bottom operand). The Decimal Mode flag is cleared (binary mode) and the Carry flag is set to 1.

Entry Conditions
Order in stack (starting from top)
Less significant byte of return address
More significant byte of return address
Length of the operands in bytes
Less significant byte of starting address of second operand (address containing the least significant byte of array 2)
More significant byte of starting address of second operand (address containing the least significant byte of array 2)
Less significant byte of starting address of first operand and result (address containing the least significant byte of array 1)

Exit Conditions
First operand (array 1) replaced by first operand (array 1) plus second operand (array 2).
D flag set to zero (binary mode).
More significant byte of starting address of first operand and result (address containing the least significant byte of array 1)

---

**Example**

**Data:**
- Length of operands (in bytes) = 6
- Top operand (array 2) = 19602881931516
- Bottom operand (array 1) = 29347160598716

**Result:**
- Bottom operand (array 1) = Bottom operand (array 1) + Top operand (array 2) = 48950042530216
- Carry = 0, Decimal Mode flag = 0 (binary mode)

---

```
Title: Multiple-Precision Decimal Addition
Name: MPDADD

Purpose: Add 2 arrays of BCD bytes
Array1 := Array1 + Array2

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Length of the arrays in bytes,
Low byte of array 2 address,
High byte of array 2 address,
Low byte of array 1 address,
High byte of array 1 address

The arrays are unsigned BCD numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Array1 := Array1 + Array2

Registers used: All

Time: 23 cycles per byte plus 86 cycles overhead.
```
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; Size: Program 50 bytes  ;
; Data 2 bytes plus  ;
; 4 bytes in page zero  ;
;
; EQUATES
AY1PTR: .EQU 0D0H ; PAGE ZERO FOR ARRAY 1 POINTER
AY2PTR: .EQU 0D2H ; PAGE ZERO FOR ARRAY 2 POINTER

MPDADD:
; SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

; GET LENGTH OF ARRAYS
PLA
TAX

; GET STARTING ADDRESS OF ARRAY 2
PLA
STA AY2PTR
PLA
STA AY2PTR+1

; GET STARTING ADDRESS OF ARRAY 1
PLA
STA AY1PTR
PLA
STA AY1PTR+1

; RESTORE RETURN ADDRESS
LDA .RETADR+1
PHA
LDA RETADR
PHA

; INITIALIZE SUM AND DECIMAL MODE, EXIT IF LENGTH = 0
LDY #0
CPX #0
; IS LENGTH OF ARRAYS = 0 ?
BEQ EXIT
; BRANCH IF LENGTH IS 0
SED
; SET DECIMAL MODE
CLC
; CLEAR CARRY

LOOP:
LDA (AY1PTR),Y
; GET NEXT BYTE
ADC (AY2PTR),Y
; ADD BYTES
STA (AY1PTR),Y
; STORE SUM
INY
; INCREMENT ARRAY INDEX
DEX
; DECREMENT COUNTER
BNE LOOP
; CONTINUE UNTIL COUNTER = 0

EXIT:
CLD
; RETURN IN BINARY MODE
RTS

; DATA
RETA DR .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS

; SAMPLE EXECUTION:

SC0611:
LDA AY1ADR +1 ; PUSH AY1 ADDRESS
PHA
LDA AY1ADR
PHA
LDA AY2ADR +1 ; PUSH AY2 ADDRESS
PHA
LDA AY2ADR
PHA
LDA #SZAYS ; PUSH SIZE OF ARRAYS
PHA
JSR MPDADD ; MULTIPLE-PRECISION BCD ADDITION
BRK ; RESULT OF 1234567 + 1234567 = 2469134
JMP SC0611

SZAYS: .EQU 7 ; SIZE OF ARRAYS
AY1ADR: .WORD AY1 ; ADDRESS OF ARRAY 1
AY2ADR: .WORD AY2 ; ADDRESS OF ARRAY 2

AY1:
.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

AY2:
.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

.END ;PROGRAM
Multiple-Precision Decimal Subtraction
(MPDSUB)

Subtracts two multi-byte unsigned decimal numbers. Both numbers are stored with their least significant digits at the lowest address. The starting address of the subtrahend (number to be subtracted) is stored on top of the starting address of the minuend (number from which the subtrahend is subtracted). The difference replaces the minuend in memory. The length of the numbers (in bytes) is 255 or less. The program returns with the Decimal Mode (D) flag cleared (binary mode).

Procedure: The program first enters the decimal mode by setting the D flag. It then sets the Carry flag (the inverted borrow) initially and subtracts the subtrahend from the minuend one byte (two digits) at a time, starting with the least significant digits. The final Carry flag reflects the subtraction of the most significant digits. The difference replaces the minuend (the operand with the starting address lower in the stack, array 1 in the listing). A length of 00 causes an immediate exit with no subtraction operations. The program clears the D flag (thus placing the processor in the binary mode) before exiting.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Length of the operands in bytes
Less significant byte of starting address of subtrahend (address containing the least significant byte of array 2)
More significant byte of starting address of subtrahend (address containing the least significant byte of array 2)
Less significant byte of starting address of subtrahend

Exit Conditions

Minuend (array 1) replaced by minuend (array 1) minus subtrahend (array 2).
D flag set to zero (binary mode).

Registers Used: All
Execution Time: 23 cycles per byte plus 86 cycles overhead. For example, subtracting two 8-byte (16-digit) operands takes $23 \times 8 + 86$ or 270 cycles.
Program Size: 50 bytes
Data Memory Required: Two bytes anywhere in RAM and four bytes on page 0. The two bytes anywhere in RAM are temporary storage for the return address (starting at address RETADR). The four bytes on page 0 hold pointers to the two operands; the pointers start at addresses AY1PTR (00D016 in the listing) and AY2PTR (00D216 in the listing).

Special Case: A length of zero causes an immediate exit with the difference equal to the original minuend, the Decimal Mode flag cleared (binary mode), and the Carry flag set to 1.
minuend (address containing the least significant byte of array 1)
More significant byte of starting address of minuend (address containing the least significant byte of array 1)

Example

Data: Length of operands (in bytes) = 6
Minuend (array 1) = 29347160598716
Subtrahend (array 2) = 19602881931516

Result: Difference (array 1) = 09744278667216.
This number replaces the original minuend in memory. The Carry flag is set to 1 in accordance with its usual role (in 6502 programming) as an inverted borrow.
Decimal Mode flag = 0 (binary mode)

Title Multiple-Precision Decimal Subtraction
Name: MPDSUB

Purpose: Subtract 2 arrays of BCD bytes
Minuend := Minuend - Subtrahend

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Length of the arrays in bytes,
Low byte of subtrahend address,
High byte of subtrahend address,
Low byte of minuend address,
High byte of minuend address

The arrays are unsigned BCD numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Array1 := Array1 - Array2

 Registers used: All
; Time: 23 cycles per byte plus 86 cycles overhead.
; Size: Program 50 bytes
; Data 2 bytes plus 4 bytes in page zero
;
; EQUATES
MINPTR: .EQU 0D0H ; PAGE ZERO FOR MINUEND POINTER
SUBPTR: .EQU 0D2H ; PAGE ZERO FOR SUBTRAHEND POINTER

MPDSUB:
; SAVE RETURN ADDRESS
PLA
STA RETADR
PLA
STA RETADR+1

; GET LENGTH OF ARRAYS
PLA
TAX

; GET STARTING ADDRESS OF SUBTRAHEND
PLA
STA SUBPTR
PLA
STA SUBPTR+1

; GET STARTING ADDRESS OF MINUEND
PLA
STA MINPTR
PLA
STA MINPTR+1

; RESTORE RETURN ADDRESS
LDA RETADR+1
PHA
LDA RETADR
PHA

; INITIALIZE
LDY #0
CPX #0 ; IS LENGTH OF ARRAYS = 0 ?
BEQ EXIT ; YES, EXIT
SED ; SET DECIMAL MODE
SEC ; SET CARRY

LOOP:
LDA (MINPTR),Y ; GET NEXT BYTE
SBC (SUBPTR),Y ; SUBTRACT BYTES
STA (MINPTR),Y ; STORE DIFFERENCE
INY ; INCREMENT ARRAY INDEX
DEX ; DECREMENT COUNTER
BNE LOOP ; CONTINUE UNTIL COUNTER = 0
EXIT:

CLD
RTS

; RETURN IN BINARY MODE

; DATA

RETA DR . BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS

; SAMPLE EXECUTION:

SC0612:

LDA AYLADR+1
PHA
LDA AYLADR
PHA
LDA AY2ADR+1
PHA
LDA AY2ADR
PHA

LDA #SZAYS ; PUSH SIZE OF ARRAYS
PHA
JSR MPDSUB ; MULTIPLE-PRECISION BCD SUBTRACTION
BRK

JMP SC0612

SZAYS: . EQU 7 ; SIZE OF ARRAYS

AY1ADR: . WORD AY1 ; ADDRESS OF ARRAY 1 (MINUEND)
AY2ADR: . WORD AY2 ; ADDRESS OF ARRAY 2 (SUBTRAHEND)

AY1:

.BYTE 034H
.BYTE 091H
.BYTE 046H
.BYTE 002H
.BYTE 0
.BYTE 0
.BYTE 0
AY2:

.BYTE 067H
.BYTE 045H
.BYTE 023H
.BYTE 001H
.BYTE 0
.BYTE 0
.BYTE 0

.END ;PROGRAM
Multiple-Precision Decimal Multiplication
(MPDMUL)

Multiplies two multi-byte unsigned decimal numbers. Both numbers are stored with their least significant digits at the lowest address. The product replaces one of the numbers (the one with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less. Only the least significant bytes of the product are returned to retain compatibility with other multiple-precision decimal operations. The program returns with the Decimal Mode (D) flag cleared (binary mode).

Procedure: The program handles each digit of the multiplicand (array 1) separately. It masks that digit off, shifts it (if it is in the upper nibble of a byte), and then uses it as a counter to determine how many times to add the multiplier to the partial product. The least significant digit of the partial product is saved as the next digit of the full product and the partial product is shifted right four bits. The program uses a flag to determine whether it is currently working with the upper or lower digit of a byte. A length of 00 causes an exit with no multiplication.

Registors Used: All

Execution Time: Depends on the length of the operands and on the size of the digits in the multiplicand (since those digits determine how many times the multiplier is added to the partial product).

If the average digit in the multiplicand has a value of 5, then the execution time is approximately

\[ 322 \times \text{LENGTH}^2 + 390 \times \text{LENGTH} + 100 \]

cycles where LENGTH is the number of bytes in the operand. If, for example, LENGTH = 6 (12 digits), the approximate execution time is

\[ 322 \times 6^2 + 390 \times 6 + 100 = 322 \times 36 + 2340 + 100 = 11,592 + 2440 = 14,032 \] cycles.

Program Size: 203 bytes

Data Memory Required: 517 bytes anywhere in RAM plus four bytes on page 0. The 517 bytes anywhere in RAM are temporary storage for the partial product (255 bytes starting at address PROD), the multiplicand (255 bytes starting at address MCAND), the return address (two bytes starting at address RETADR), the length of the operands in bytes (one byte at address LENGTH), the next digit in the operand (one byte at address NDIGIT), the digit counter (one byte at address DCNT), the byte index into the operands (one byte at address IDX), and the overflow byte (1 byte at address OVERFLW). The four bytes on page 0 hold pointers to the two operands; the pointers start at addresses AY1PTR (00D016 in the listing) and AY2PTR (00D216 in the listing).

Special Case: A length of zero causes an immediate exit with the product equal to the original multiplicand (array 1 is unchanged), the Decimal Mode flag cleared (binary mode), and the more significant bytes of the product (starting at address PROD) undefined.

Entry Conditions
Order in stack (starting from the top)
Less significant byte of return address
More significant byte of return address
Length of the operands in bytes

Exit Conditions

Multiplicand (array 1) replaced by multiplicand (array 1) times multiplier (array 2).
D flag set to zero (binary mode).
Less significant byte of starting address of multiplier (address containing the least significant byte of array 2)
More significant byte of starting address of multiplier (address containing the least significant byte of array 2)
Less significant byte of starting address of multiplicand (address containing the least significant byte of array 1)
More significant byte of starting address of multiplicand (address containing the least significant byte of array 1)

Example

Data: Length of operands (in bytes) = 04
Top operand (array 2 or multiplier) = 0000351816
Bottom operand (array 1 or multiplicand) = 000629416

Result: Bottom operand (array 1) = Bottom operand (array 1) * Top operand (array 2) = 2214229216
Decimal Mode flag = 0 (binary mode)

Note that MPDMUL returns only the less significant bytes of the product (that is, the number of bytes in the multiplicand and multiplier) to maintain compatibility with other multiple-precision decimal arithmetic operations. The more significant bytes of the product are available starting with their least significant digits at address PROD. The user may need to check those bytes for a possible overflow or extend the operands with additional zeros.
ARITHMETIC

Registers used: All

Time: Assuming the average digit value of ARRAY 1 is 5 then the time is approximately
(322 * length^2) + (390 * length) + 100 cycles

Size: Program 203 bytes
      Data 517 bytes plus
            4 bytes in page zero

;EQUATES
AY1PTR: .EQU 0D0H ;PAGE ZERO FOR ARRAY 1 POINTER
AY2PTR: .EQU 0D2H ;PAGE ZERO FOR ARRAY 2 POINTER

MPDMUL:
;SAVE RETURN ADDRESS
PLA
STA  RETADR
PLA
STA  RETADR+1

;GET LENGTH OF ARRAYS
PLA
STA  LENGTH

;GET STARTING ADDRESS OF ARRAY 2
PLA
STA  AY2PTR
PLA
STA  AY2PTR+1

;GET STARTING ADDRESS OF ARRAY 1
PLA
STA  AY1PTR
PLA
STA  AY1PTR+1

;RESTORE RETURN ADDRESS
LDA  RETADR+1
PHA
LDA  RETADR
PHA

;INITIALIZE
SED ;PUT PROCESSOR IN DECIMAL MODE
LDY  #0
LDX  LENGTH ;IS LENGTH ZERO ?
BNE  INITLP
JMP  EXIT ;YES, EXIT

;MOVE ARRAY 1 TO MULTIPLICAND ARRAY, ZERO ARRAY 1, AND ZERO PRODUCT ARRAY.
INITLP:
LDA  (AY1PTR),Y
STA  MCAND,Y ;MOVE AR Y1[Y] TO MCAND[Y]
LDA   #0  
STA   (AY1PTR),Y ;ZERO ARY1[Y] 
STA   PROD,Y ;ZERO PROD 
INY   
DEX   ;DECREMENT LOOP COUNTER 
BNE   INITLP ;CONTINUE UNTIL DONE 

;INITIALIZE CURRENT INDEX TO ZERO 
LDA   #0 
STA   IDX 

;LOOP THROUGH ALL THE BYTES OF THE MULTIPLICAND 
LOOP:  
LDA   #0 
STA   DCNT ;START WITH LOW DIGIT 

;LOOP THROUGH 2 DIGITS PER BYTE 
; DURING THE FIRST DIGIT DCNT = 0 
; DURING THE SECOND DIGIT DCNT = FF HEX (-1) 
DLOOP:  
LDA   #0 
STA   OVRFLW ;ZERO OVERFLOW 
LDY   IDX 
LDA   MCAND,Y ;GET NEXT BYTE 
LDX   DCNT 
BPL   DLOOP1 ;BRANCH IF FIRST DIGIT 
LSR   A ;SHIFT RIGHT 4 BITS 
LSR   A 
LSR   A 
DLOOP1:  
AND   #0FH ;AND OFF UPPER DIGIT 
BEQ   SDIGIT ;BRANCH IF NEXT DIGIT IS ZERO 
STA   NDIGIT ;SAVE 

;ADD MULTIPLIER TO PRODUCT NDIGIT TIMES 
ADDLP:  
LDY   #0 ;Y = INDEX INTO ARRAYS 
LDX   LENGTH ;X = LENGTH IN BYTES 
CLC ;CLEAR CARRY INITIALLY 
INNER:  
LDA   (AY2PTR),Y ;GET NEXT BYTE 
ADC   PROD,Y ;ADD TO PRODUCT 
STA   PROD,Y ;STORE 
INY   ;INCREMENT ARRAY INDEX 
DEX   ;DECREMENT LOOP COUNTER 
BNE   INNER ;CONTINUE UNTIL LOOP COUNTER = 0 
BCC   DECND ;BRANCH IF NO OVERFLOW FROM ADDITION 
INC   OVRFLW ;ELSE INCREMENT OVERFLOW BYTE 
DECND:  
DEC   NDIGIT 
BNE   ADDLP ;CONTINUE UNTIL NDIGIT = 0
; STORE THE LEAST SIGNIFICANT DIGIT OF PRODUCT
; AS THE NEXT DIGIT OF ARRAY 1

SDIGIT:
LDA PROD
AND #0FH
LDX DCNT
BPL SD1
ASL A
; STORE THE LEAST SIGNIFICANT DIGIT OF PRODUCT
ASL A
ASL A
ASL A

SD1:
LDY IDX
ORA (AY1PTR),Y
STA (AY1PTR),Y

; SHIF TRIGHT PRODUCT 1 DIGIT (4 BITS)
LDY LENGTH

SHFTLP:
DEY
LDA PROD,Y
PHA
AND #0F0H

; MAKE LOW DIG IT OF OVERFLOW = HIGH DIG IT OF PROD,Y
; MAKE HIGH DIG IT OF PROD,Y = LOW DIG IT OF PROD,Y
LSR OVRFLW
ORA OVRFLW

; CLEAR UPPER DIG IT
ROR
ROR
ROR
ROR A
STA PROD,Y

; STORE NEW PRODUCT
PLA
AND #0FH
STA OVRFLW

; CHECK FOR Y = 0
TYA
BNE SHFTLP

; CHECK IF WE ARE DONE WITH BOTH DIGITS OF THIS BYTE
DEC DCNT
LDA DCNT
CMP #0FFH
BEQ DLOOP

; INCREMENT TO NEXT BYTE AND SEE IF WE ARE DONE
INC IDX
LDA IDX
CMP LENGTH
BCS EXIT
JMP LOOP

EXIT:
CLD
RTS

; RETURN IN BINARY MODE

; DATA
RETA: .BLOCK 2 ; TEMPORARY FOR RETURN ADDRESS
LENG: .BLOCK 1 ; LENGTH OF ARRAYS
NDIG: .BLOCK 1 ; NEXT DIGIT IN ARRAY
DCNT: .BLOCK 1 ; DIGIT COUNTER FOR BYTES IN ARRAYS
IDX: .BLOCK 1 ; BYTE INDEX INTO ARRAYS
OVRFLW: .BLOCK 1 ; OVERFLOW BYTE
PROD: .BLOCK 255 ; PRODUCT BUFFER
MCAND: .BLOCK 255 ; MULTIPLICAND BUFFER

; SAMPLE EXECUTION:

SC0613:
LDA AY1ADR+1
PHA
LDA AY1ADR
PHA
LDA AY2ADR+1
PHA
LDA AY2ADR
PHA
LDA #SZAYS
PHA
JSR MPDMUL
BRK
JMP SC0613

SZAYS: .EQU 7 ; LENGTH OF ARRAYS
AY1ADR: .WORD AY1 ; ADDRESS OF ARRAY 1
AY2ADR: .WORD AY2 ; ADDRESS OF ARRAY 2

AY1:
.BYTE 034H
.BYTE 012H
.BYTE 0
.BYTE 0
AY2:

```assembly
.BYTE 034H
.BYTE 012H
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.END ;PROGRAM
```
Divides two multi-byte unsigned decimal numbers. Both numbers are stored with their least significant byte at the lowest address. The quotient replaces the dividend (the operand with the starting address lower in the stack). The length of the numbers (in bytes) is 255 or less. The remainder is not returned but the address of its least significant byte is available starting at memory location HDEPTR. The Carry flag is cleared if no errors occur; if a divide by zero is attempted, the Carry flag is set to 1, the dividend is left unchanged, and the remainder is set to zero.

The program returns with the Decimal Mode (D) flag cleared (binary mode).

Procedure: The program performs division by trial subtractions, a digit at a time. It determines how many times the divisor can be subtracted from the dividend and then saves that number in the quotient and makes the remainder into the new dividend. It then rotates the dividend and the quotient left one digit. The program exits immediately, setting the Carry flag, if it finds the divisor to be zero. The Carry flag is cleared otherwise.

Registers Used: All
Execution Time: Depends on the length of the operands and on the size of the digits in the quotient (determining how many trial subtractions must be performed). If the average digit in the quotient has a value of 5, then the execution time is approximately

\[ 440 \times \text{LENGTH}^2 + 765 \times \text{LENGTH} + 228 \]
cycles where LENGTH is the number of bytes in the operands. If, for example, \( \text{LENGTH} = 6 \) (12 digits), the approximate execution time is

\[ 440 \times 6^2 + 765 \times 6 + 228 = 440 \times 36 + 4590 + 228 = 15,840 + 4818 = 20,658 \text{ cycles}. \]

Program Size: 246 bytes
Data Memory Required: 522 bytes anywhere in RAM plus eight bytes on page 0. The522 bytes anywhere in RAM are temporary storage for the high dividend (255 bytes starting at address HIDE1), the result of the trial subtraction (255 bytes starting at address HIDE2), the return address (two bytes starting at address RETADR), a pointer to the dividend (two bytes starting at address AY1PTR), the length of the operands (one byte at address LENGTH), the next digit in the array (one byte at address NDIGIT), the divide loop counter (one byte at address COUNT), and the addresses of the high dividend buffers (two bytes each, starting at addresses AHIDE1 and AHIDE2). The eight bytes on page 0 hold pointers to the divisor (address AY2PTR, 00D016 in the listing), the current high dividend and remainder (address HDEPTR, 00D216 in the listing), the other high dividend (address ODEPTR, 00D416 in the listing), and the temporary array used in the left rotation (address RLPTR, 00D616 in the listing).

Special Cases:
1. A length of zero causes an immediate exit with the Carry flag cleared, the quotient equal to the original dividend (array 1 unchanged), the remainder undefined, and the Decimal Mode flag cleared (binary mode).
2. A divisor of zero causes an exit with the Carry flag set to 1, the quotient equal to the original dividend (array 1 unchanged), the remainder equal to zero, and the Decimal Mode flag cleared (binary mode).
Entry Conditions

Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Length of the operands in bytes
- Less significant byte of starting address of divisor (address containing the least significant byte of array 2)
- More significant byte of starting address of divisor (address containing the least significant byte of array 2)
- Less significant byte of starting address of dividend (address containing the least significant byte of array 1)
- More significant byte of starting address of dividend (address containing the least significant byte of array 1)

Exit Conditions

Dividend (array 1) replaced by dividend (array 1) divided by divisor (array 2)
- If the divisor is non-zero, Carry = 0 and the result is normal.
- If the divisor is zero, Carry = 1, the dividend is unchanged, and the remainder is zero.
- The remainder is available with its least significant digits stored at the address in HDEPTR and HDEPTR+1
- D flag set to zero (binary mode).

Example

Data:

<table>
<thead>
<tr>
<th>Length of operands (in bytes) = 04</th>
</tr>
</thead>
<tbody>
<tr>
<td>Top operand (array 2 or divisor) =</td>
</tr>
<tr>
<td>00006294₁₆</td>
</tr>
<tr>
<td>Bottom operand (array 1 or dividend) =</td>
</tr>
<tr>
<td>22142298₁₆</td>
</tr>
</tbody>
</table>

Result:

<table>
<thead>
<tr>
<th>Bottom operand (array 1) = Bottom operand (array 1)/Top operand (array 2) = 00003518₁₆</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remainder (starting at address in HDEPTR and HDEPTR+1) = 00000006₁₆ = 6₁₀</td>
</tr>
<tr>
<td>Decimal Mode flag = 0 (binary mode)</td>
</tr>
<tr>
<td>Carry flag is 0 to indicate no divide by zero error.</td>
</tr>
</tbody>
</table>
Title: Multiple-Precision Decimal Division
Name: MPDDIV

Purpose: Divide 2 arrays of BCD bytes
Array1 := Array1 / Array2

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Length of the arrays in bytes,
Low byte of array 2 (divisor) address,
High byte of array 2 (divisor) address,
Low byte of array 1 (dividend) address,
High byte of array 1 (dividend) address

The arrays are unsigned BCD numbers with a maximum length of 255 bytes, ARRAY[0] is the least significant byte, and ARRAY[LENGTH-1] the most significant byte.

Exit: Array1 := Array1 / Array2
Dvbuf := remainder
If no errors then
carry := 0
ELSE
divide by 0 error
carry := 1
ARRAY 1 := unchanged
remainder := 0

Registers used: All

Time: Assuming the average digit value in the quotient is 5 then the time is approximately
(440 * length^2) + (765 * length) + 228 cycles

Size: Program 246 bytes
Data 522 bytes plus
8 bytes in page zero

;EQUATES
AY2PTR: .EQU 0D0H ;PAGE ZERO FOR ARRAY 2 (DIVISOR) POINTER
HDEPTR: .EQU 0D2H ;PAGE ZERO WHICH POINTS TO THE CURRENT;
ODEPTR: .EQU 0D4H ;HIGH DIVIDEND POINTER
RLPTR: .EQU 0D6H ;PAGE ZERO WHICH POINTS TO THE OTHER;
        ;HIGH DIVIDEND POINTER
MPDDIV:
;GET RETURNS ADDRESS
PLA
STA  RETADR
PLA
STA  RETADR+1

;GET LENGTH OF ARRAYS
PLA
STA  LENGTH

;GET STARTING ADDRESS OF DIVISOR
PLA
STA  AY2PTR
PLA
STA  AY2PTR+1

;GET STARTING ADDRESS OF DIVIDEND
PLA
STA  AY1PTR
PLA
STA  AY1PTR+1

;RESTORE RETURN ADDRESS
LDA  RETADR+1
PHA
LDA  RETADR
PHA

;INITIALIZE
CLD  ;PUT PROCESSOR INTO BINARY MODE

;CHECK FOR ZERO LENGTH ARRAYS
LDA  LENGTH
BNE  INIT  ;BRANCH IF NOT ZERO
JMP  OKEXIT  ;ELSE EXIT

;ZERO BOTH DIVIDEND BUFFERS
INIT:  
LDA  #0  ;A = 0
LDY  LENGTH  ;X = LENGTH
INITLP:  
STA  HIDE1-1,Y
STA  HIDE2-1,Y
DEY
BNE  INITLP

;SET UP THE HIGH DIVIDEND POINTERS
LDA  AHIDE1
STA  HDEPTR
LDA  AHIDE1+1
STA  HDEPTR+1
LDA  AHIDE2
STA  ODEPTR
LDA  AHIDE2+1
STA  ODEPTR+1
; NDIGIT := 0
LDA   #0
STA   NDIGIT

; SET COUNT TO NUMBER OF DIGITS PLUS 1
; COUNT := (LENGTH * 2) + 1
LDA   LENGTH
ASL   A                ; LENGTH * 2
STA   COUNT
LDA   #0
ROL   A                ; MOVE OVERFLOW FROM * 2 INTO A
STA   COUNT+1          ; STORE HIGH BYTE OF COUNT
INC   COUNT
BNE   CHKDV0           ; BRANCH IF NO OVERFLOW
INC   COUNT+1

; CHECK FOR DIVIDE BY ZERO
CHKDV0:
LDX   LENGTH
LDY   #0
TYA
DV01:
ORA   (AY2PTR),Y
INY
DEX
BNE   DV01           ; CONTINUE ORING ALL THE BYTES
CMP   #0
BNE   DVLOOP         ; BRANCH IF DIVISCR IS NOT 0
JMP   EREXIT        ; ERROR EXIT

DVLOOP:
; PERFORM DIVISION BY TRIAL SUBTRACTIONS
; ROTATE LEFT THE LOWER DIVIDEND AND THE QUOTIENT (ARRAY 1)
; THE HIGH DIGIT OF NDIGIT BECOMES THE LEAST SIGNIFICANT DIGIT
; OF THE QUOTIENT (ARRAY 1) AND THE MOST SIGNIFICANT DIGIT
; OF ARRAY 1 (DIVIDEND) GOES TO THE HIGH DIGIT OF NDIGIT
LDA   AY1PTR+1
LDY   AY1PTR
JSR   RLARY          ; ROTATE ARRAY 1

; IF COUNT = 0 THEN WE ARE DONE
DEC   COUNT
BNE   ROLDVB         ; BRANCH IF LOWER BYTE IS NOT 0
LDA   COUNT+1        ; ELSE GET HIGH BYTE
BEQ   OKEXIT         ; CONTINUE UNTIL COUNT = 0
DEC   COUNT+1        ; DECREMENT UPPER BYTE OF COUNT

; ROTATE LEFT THE HIGH DIVIDEND WHERE THE LEAST SIGNIFICANT DIGIT
; OF HIGH DIVIDEND BECOMES THE HIGH DIGIT OF NDIGIT
ROLDVB:
LDA   HDEPTR+1
LDY   HDEPTR
JSR   RLARY
; See how many times the divisor will go into the high dividend.
; When we exit from this loop the high digit of NDIGIT is the next
; quotient digit and high dividend is the remainder.
LDA   #0
STA   NDIGIT  ; NDIGIT := 0
SED   ; Enter decimal mode

; See how many times the divisor will go into the high dividend.
; When we exit from this loop the high digit of NDIGIT is the next
; quotient digit and high dividend is the remainder.
SUBLP:
LDY   #0       ; Y = Index into arrays
LDX   LENGTH   ; X = Length
SEC   ; Set inverted borrow

INNER:
LDA   (HDEPTR),Y     ; Get next byte of dividend
SBC   (AY2PTR),Y     ; Subtract byte of divisor
STA   (ODEPTR),Y     ; Save difference for next subtraction
INY   ; Increment array index
DEX   ; Decrement loop counter
BNE   INNER         ; Continue through all the bytes
BCC   DVLOOP        ; Branch when borrow occurs at which time
                   ; NDIGIT is the number of times the divisor
                   ; goes into the original high dividend and
                   ; high dividend contains the remainder.

;/Increment next digit which is in the high digit of NDIGIT
LDA   NDIGIT
CLC
ADC   #10H
STA   NDIGIT

;/Exchange pointers, thus making remainder the new dividend
LDX   HDEPTR
LDY   HDEPTR+1
LDA   ODEPTR
STA   HDEPTR
LDA   ODEPTR+1
STA   HDEPTR+1
STX   ODEPTR
STY   ODEPTR+1

JMP   SUBLP        ; Continue until difference goes negative

;/No errors, clear carry
OKEXIT:
CLC
BCC   EXIT

;/Divide by zero error, set carry
EREXIT:
SEC

EXIT:     ; HDEPTR contains the address of the remainder
CLD     ; Return in binary mode
RTS
;*******************************************************************************
;SUBROUTINE: RLARY
;PURPOSE: RO Cornell an array one Digit (4 bits)
;ENTRY: A = HIGH BYTE OF ARRAY ADDRESS
; Y = LOW BYTE OF ARRAY ADDRESS
; THE HIGH DIGIT OF NDIGIT IS THE DIGIT TO ROTATE THROUGH
;EXIT: ARRAY ROTATED LEFT THROUGH THE HIGH DIGIT OF NDIGIT
;REGISTERS USED: ALL
;*******************************************************************************

RLARY:
;STORE ARRAY ADDRESS
STA RL PTR+1
STY RL PTR

;SHIFT NDIGIT INTO LOW DIGIT OF ARRAY AND
; SHIFT ARRAY LEFT
LDX LENGTH
LDY #0 ;START AT AR Y1[0]

SHIFT:
LDA (RL PTR), Y ;GET NEXT BYTE
PHA ;SAVE HIGH DIGIT
AND #0FH ;CLEAR HIGH DIGIT

ASL N DIGIT ;BITS 0..3 = LOW DIGIT OF ARRAY
ORA N DIGIT ;BITS 5..7 AND CARRY = NEXT DIGIT
ROL A
ROL A
ROL A
ROL A ;NOW NDIGIT IN BITS 0..3 AND
; LOW DIGIT IN HIGH DIGIT
STA (RL PTR), Y ;STORE IT
PLA ;GET OLD HIGH DIGIT
AND #0F0H ;CLEAR LOWER DIGIT
STA N DIGIT ;STORE IN NDIGIT
INY ;INCREMENT TO NEXT BYTE
DEX ;DECREMENT COUNT
BNE SHIFT ;BRANCH IF NOT DONE

RTS

;DATA
RETA DR: .BLOCK 2 ;TEMPORARY FOR RETURN ADDRESS
AYLPTR: .BLOCK 2 ;ARRAY 1 ADDRESS
LENGTH: .BLOCK 1 ;LENGTH OF ARRAYS
NDIGIT: .BLOCK 1 ;NEXT DIGIT IN ARRAY
COUNT: .BLOCK 2 ;DIVIDE LOOP COUNTER
AHIDE1: .WORD HIDE1 ;ADDRESS OF HIGH DIVIDEND BUFFER 1
AHIDE2: .WORD HIDE2 ;ADDRESS OF HIGH DIVIDEND BUFFER 2
HIDE1: .BLOCK 255. ;HIGH DIVIDEND BUFFER 1
HIDE2: .BLOCK 255. ;HIGH DIVIDEND BUFFER 2
SAMPLE EXECUTION:

SC0614:

LDA AY1ADR+1  ;PUSH AY1 ADDRESS
PHA
LDA AY1ADR
PHA
LDA AY2ADR+1  ;PUSH AY2 ADDRESS
PHA
LDA AY2ADR
PHA
LDA #SZAYS   ;PUSH LENGTH OF ARRAYS
PHA
JSR MPDDIV   ;MULTIPLE-PRECISION BCD DIVISION
BRK
JMP SC0614

SZAYS: .EQU 7  ;LENGTH OF ARRAYS
AY1ADR: .WORD AY1  ;ADDRESS OF ARRAY 1 (DIVIDEND)
AY2ADR: .WORD AY2  ;ADDRESS OF ARRAY 2 (DIVISOR)

AY1:

.BYTE 056H
.BYTE 027H
.BYTE 052H
.BYTE 01H
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0

AY2:

.BYTE 034H
.BYTE 012H
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0
.BYTE 0

END  ;PROGRAM
Multiple-Precision Decimal Comparison

Compares two multi-byte unsigned decimal (BCD) numbers and sets the Carry and Zero flags appropriately. The Zero flag is set to 1 if the operands are equal and to 0 if they are not equal. The Carry flag is set to 0 if the operand with the address higher in the stack (the subtrahend) is larger than the other operand (the minuend); the Carry flag is set to 1 otherwise. Thus the flags are set as if the subtrahend had been subtracted from the minuend.

Note: This program is exactly the same as Subroutine 6J, the multiple-precision binary comparison, since the CMP instruction operates the same in the decimal mode as in the binary mode. Hence, see Subroutine 6J for a listing and other details.

Examples

1. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 19652871934016
   Bottom operand (minuend) = 45678015326616
   Result: Zero flag = 0 (operands are not equal)
            Carry flag = 1 (subtrahend is not larger than minuend)

2. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 19652871934016
   Bottom operand (minuend) = 19652871934016
   Result: Zero flag = 1 (operands are equal)
            Carry flag = 1 (subtrahend is not larger than minuend)

3. Data: Length of operands (in bytes) = 6
   Top operand (subtrahend) = 19652871934016
   Bottom operand (minuend) = 073785991074I6
   Result: Zero flag = 0 (operands are not equal)
            Carry flag = 0 (subtrahend is larger than minuend)
**Bit Set (BITSET)**

Sets a specified bit in a 16-bit word to 1.

*Procedure:* The program uses bits 0 through 2 of register X to determine which bit position to set and bit 3 to select a particular byte of the original word-length data. It then logically ORs the selected byte with a mask containing a 1 in the chosen bit position and 0s elsewhere. The masks with one 1 bit are available in a table.

**Entry Conditions**
- More significant byte of data in accumulator
- Less significant byte of data in register Y
- Bit number to set in register X

**Exit Conditions**
- More significant byte of result in accumulator
- Less significant byte of result in register Y

**Examples**

1. **Data:**
   - \( A = 6E_{16} = 01101110_2 \) (more significant byte)
   - \( Y = 39_{16} = 00111001_2 \) (less significant byte)
   - \( X = 0C_{16} = 12_{10} \) (bit position to set)

   **Result:**
   - \( A = 7E_{16} = 01111110_2 \) (more significant byte, bit 12 set to 1)
   - \( Y = 39_{16} = 00111001_2 \) (less significant byte)

2. **Data:**
   - \( A = 6E_{16} = 01101110_2 \) (more significant byte)
   - \( Y = 39_{16} = 00111001_2 \) (less significant byte)
   - \( X = 02_{16} = 2_{10} \) (bit position to set)

   **Result:**
   - \( A = 6E_{16} = 01101110_2 \) (more significant byte)
   - \( Y = 3D_{16} = 00111101_2 \) (less significant byte, bit 2 set to 1)

Registers Used: All  
Execution Time: 57 cycles  
Program Size: 42 bytes  
Data Memory Required: Two bytes anywhere in RAM (starting at address VALUE).  
Special Case: Bit positions above 15 will be interpreted mod 16. That is, for example, bit position 16 is equivalent to bit position 0.
Title: Bit set
Name: BITSET

Purpose: Set a bit in a 16 bit word.

Entry: Register A = High byte of word
       Register Y = Low byte of word
       Register X = Bit number to set

Exit: Register A = High byte of word with bit set
      Register Y = Low byte of word with bit set

Registers used: All

Time: 57 cycles

Size: Program 42 bytes
      Data 2 bytes

BITSET:

;SAVE THE DATA WORD
STA VALUE+1
STY VALUE

;BE SURE THAT THE BIT NUMBER IS BETWEEN 0 AND 15
TXA
AND #0FH

;DETERMINE WHICH BYTE AND WHICH BIT IN THAT BYTE
TAX
AND #07H ;THE LOWER 3 BITS OF THE BIT NUMBER
TAX ;IS THE BIT IN THE BYTE, SAVE IN Y
TXA ;RESTORE BIT NUMBER
LSR A
LSR A
LSR A
TAX ;SAVE BYTE NUMBER (0 OR 1) IN X

;SET THE BIT
LDA VALUE,X ;GET THE BYTE
ORA BITMSK,Y ;SET THE BIT
STA VALUE,X

;RETURN THE RESULT IN REGISTERS A AND Y
LDA VALUE+1
LDY VALUE
RTS
BIT MANIPULATIONS AND SHIFTS

BITMSK: .BYTE 00000001B ;BIT 0 = 1
BYTE 00000010B ;BIT 1 = 1
BYTE 00000100B ;BIT 2 = 1
BYTE 00001000B ;BIT 3 = 1
BYTE 00010000B ;BIT 4 = 1
BYTE 00100000B ;BIT 5 = 1
BYTE 01000000B ;BIT 6 = 1
BYTE 10000000B ;BIT 7 = 1

;DATA
VALUE: .BLOCK 2 ;TEMPORARY FOR THE DATA WORD

;SAMPLE EXECUTION

SC0701:
LDA VAL+1 ;LOAD DATA WORD INTO A,Y
LDY VAL
LDX BITN
JSR BITSET
BRK
JMP SC0701

;TEST DATA, CHANGE FOR DIFFERENT VALUES
VAL: .WORD 5555H
BITN: .BYTE OFH

.END ;PROGRAM
**Bit Clear (BITCLR)**

Clears a specified bit in a 16-bit word.

*Procedure:* the program uses bits 0 through 2 of register X to determine which bit position to clear and bit 3 to select a particular byte of the original word-length data. It then logically ANDs the selected byte with a mask containing a 0 in the chosen bit position and 1s elsewhere. The masks with one 0 bit are available in a table.

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**Entry Conditions**

More significant byte of data in accumulator

Less significant byte of data in register Y

Bit number to clear in register X

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**Exit Conditions**

More significant byte of result in accumulator

Less significant byte of result in register Y

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**Examples**

1. Data:
   
   \[ \begin{align*}
   (A) &= 6E_{16} = 01101110_2 \\
   & \quad \text{(more significant byte)} \\
   (Y) &= 39_{16} = 00111001_{16} \\
   & \quad \text{(less significant byte)} \\
   (X) &= 0E_{16} = 14_{10} \\
   & \quad \text{(bit position to clear)}
   \end{align*} \]

   Result:
   
   \[ \begin{align*}
   (A) &= 2E_{16} = 01101110_2 \\
   & \quad \text{(more significant byte, bit 14 cleared)} \\
   (Y) &= 39_{16} = 00111001_{12} \\
   & \quad \text{(less significant byte)}
   \end{align*} \]

2. Data:
   
   \[ \begin{align*}
   (A) &= 6E_{16} = 01101110_{16} \\
   & \quad \text{(more significant byte)} \\
   (Y) &= 39_{16} = 00111001_{12} \\
   & \quad \text{(less significant byte)} \\
   (X) &= 04_{16} = 4_{10} \\
   & \quad \text{(bit position to clear)}
   \end{align*} \]

   Result:
   
   \[ \begin{align*}
   (A) &= 6E_{16} = 01101110_{16} \\
   & \quad \text{(more significant byte)} \\
   (Y) &= 29_{16} = 00101001_{12} \\
   & \quad \text{(less significant byte, bit 4 cleared)}
   \end{align*} \]
Title: Bit clear
Name: BITCLR

Purpose: Clear a bit in a 16 bit word.

Entry:
Register A = High byte of word
Register Y = Low byte of word
Register X = Bit number to clear

Exit:
Register A = High byte of word with bit cleared
Register Y = Low byte of word with bit cleared

Registers used: All

Time: 57 cycles

Size: Program 42 bytes
Data 2 bytes

BITCLR:

; SAVE THE DATA WORD
STA VALUE + 1
STY VALUE

; BE SURE THAT THE BIT NUMBER IS BETWEEN 0 AND 15
TXA
AND #0FH

; DETERMINE WHICH BYTE AND WHICH BIT IN THAT BYTE
TAX ; SAVE BIT NUMBER IN X
AND #07H ; THE LOWER 3 BITS OF THE BIT NUMBER
TAY ; IS THE BIT IN THE BYTE, SAVE IN Y
TXA ; RESTORE BIT NUMBER
LSR A ; DIVIDE BY 8 TO DETERMINE BYTE
LSR A
LSR A
TAX ; SAVE BYTE NUMBER (0 OR 1) IN X

; CLEAR THE BIT
LDA VALUE, X ; GET THE BYTE
AND BITMSK, Y ; CLEAR THE BIT
STA VALUE, X

; RETURN THE RESULT IN REGISTERS A AND Y

LDA VALUE + 1
LDY VALUE
RTS
BITMSK: .BYTE 11111110B ;BIT 0 = 0
      .BYTE 11111101B ;BIT 1 = 0
      .BYTE 11111011B ;BIT 2 = 0
      .BYTE 11110111B ;BIT 3 = 0
      .BYTE 11011111B ;BIT 4 = 0
      .BYTE 10111111B ;BIT 5 = 0
      .BYTE 01111111B ;BIT 6 = 0
      .BYTE 01111111B ;BIT 7 = 0

;DATA
VALUE: .BLOCK 2 ;TEMPORARY FOR THE DATA WORD

;SAMPLE EXECUTION

SC0702:
  LDA VAL+1 ;LOAD DATA WORD INTO A,Y
  LDY VAL
  LDX BITN ;GET BIT NUMBER IN X
  JSR BITCLR ;CLEAR THE BIT
  BRK ;RESULT OF VAL = 5555H AND BITN = 00H IS
  JMP SC0702 ;REGISTER A = 55H, REGISTER Y = 54H

;TEST DATA, CHANGE FOR DIFFERENT VALUES
VAL: .WORD 5555H
BITN: .BYTE 0

.END ;PROGRAM
Sets the Carry flag to the value of a specified bit in a 16-bit word.

Procedure: The program uses bits 0 through 2 of register X to determine which bit position to test and bit 3 to select a particular byte of the original word-length data. It then logically ANDs the selected byte with a mask containing a 1 in the chosen bit position and 0s elsewhere. Since the result is zero if the tested bit is 0 and non-zero if the tested bit is 1, the Zero flag is set to the complement of the tested bit. Finally, the program sets the Carry flag to the complement of the Zero flag, thus making it the same as the tested bit through a double inversion.

Entry Conditions

More significant byte of data in accumulator
Less significant byte of data in register Y
Bit position to test in register X

Exit Conditions

Carry set to value of specified bit position in data.

Examples

1. Data: \( (A) = 6E_{16} = 01101110_2 \) (more significant byte)
   \( (Y) = 39_{16} = 00111001_2 \) (less significant byte)
   \( (X) = 0B_{16} = 1110 \) (bit position to test)

   Result: Carry = 1 (value of bit 11)

2. Data:
   \( (A) = 6E_{16} = 01101110_2 \) (more significant byte)
   \( (Y) = 39_{16} = 00111001_2 \) (less significant byte)
   \( (X) = 06_{16} = 6_{10} \) (bit position to test)

   Result: Carry = 0 (value of bit 6)
Title: Bit test
Name: BITTST

Purpose: Test a bit in a 16 bit word.
Entry: Register A = High byte of word
        Register Y = Low byte of word
        Register X = Bit number to test
Exit: CARRY = value of the tested bit

Registers used: All
Time: Approximately 50 cycles
Size: Program 37 bytes
        Data  2 bytes

BITTST:
;SAVE THE DATA WORD
STA    VALUE+1
STY    VALUE

;BE SURE THAT THE BIT NUMBER IS BETWEEN 0 AND 15
TXA
AND    #0FH

;DETERMINE WHICH BYTE AND WHICH BIT IN THAT BYTE
TAX
AND    #07H
TAY
TXA
LSR    A
TAX
LSR    A
TAX

;SET THE ZERO FLAG TO THE COMPLEMENT OF THE BIT
LDA    VALUE,X
AND    BITMSK,Y

;SET THE CARRY FLAG TO THE COMPLEMENT OF THE ZERO FLAG
CLC
BNE    EXIT
SEC
EXIT:
RTS
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BITMSK: .BYTE 00000001B ;BIT 0 = 1
          00000010B ;BIT 1 = 1
          00000100B ;BIT 2 = 1
          00001000B ;BIT 3 = 1
          00010000B ;BIT 4 = 1
          00100000B ;BIT 5 = 1
          01000000B ;BIT 6 = 1
         10000000B ;BIT 7 = 1

;DATA
VALUE: .BLOCK 2 ;TEMPORARY FOR THE DATA WORD

;SAMPLE EXECUTION

SC0703:
LDA VAL+1 ;LOAD DATA WORD INTO A,Y
LDY VAL
LDX BITN ;GET BIT NUMBER IN X
JSR BITST ;TEST THE BIT
BRK
JMP SC0703

;TEST DATA, CHANGE FOR DIFFERENT VALUES
VAL: .WORD 5555H
BITN: .BYTE 01H

.END ;PROGRAM
Bit Field Extraction (BFE)

Extracts a field of bits from a word and returns the field in the least significant bit positions. The width of the field and its starting bit position are specified.

Procedure: The program obtains a mask with the specified number of 1 bits from a table, shifts the mask left to align it with the specified starting bit position, and obtains the field by logically ANDing the mask and the data. It then normalizes the bit field by shifting it right so that it starts in bit 0.

Registers Used: All
Execution Time: $34 \cdot \text{STARTING BIT POSITION} + 138$ cycles overhead. The starting bit position determines the number of times the mask must be shifted left and the bit field right. For example, if the field starts in bit 6, the execution time is

$$34 \cdot 6 + 138 = 204 + 138 = 342 \text{ cycles}$$

Program Size: 134 bytes

Data Memory Required: Six bytes anywhere in RAM for the index (one byte at address INDEX), the width of the field (one byte at address WIDTH), the data value (two bytes starting at address VALUE), and the mask (two bytes starting at address MASK).

Special Cases:
1. Requesting a field that would extend beyond the end of the word causes the program to return with only the bits through bit 15. That is, no wraparound is provided. If, for example, the user asks for a 10-bit field starting at bit 8, the program will return only 8 bits (bits 8 through 15).
2. Both the starting bit position and the number of bits in the field are interpreted mod 16. That is, for example, bit position 17 is equivalent to bit position 1 and a field of 20 bits is equivalent to a field of 4 bits.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Starting (lowest) bit position of field
Number of bits in the field
Less significant byte of data value
More significant byte of data value

Exit Conditions

More significant byte of bit field in accumulator
Less significant byte of bit field in register Y

Examples

1. Data: Value = F67C₁₆ = 11110110111100₂
Starting bit position = 4
Number of bits in the field = 8

Result: Bit field = 0067₁₆ = 00000000010011₁₂
We have extracted 8 bits from the original data, starting with bit 4 (that is, bits 4 through 11).
2. Data: \( \text{Value} = A2D_{16} = 1010001011010100_2 \)
   Starting bit position = 6
   Number of bits in the field = 5

Result: Bit field = \( 00B_{16} = 0000000000001011_2 \)
We have extracted 5 bits from the original data, starting with bit 6 (that is, bits 6 through 10).

---

Title: Bit Field Extraction
Name: BFE
Purpose: Extract a field of bits from a 16 bit word and return the field normalized to bit 0.
NOTE: IF THE REQUESTED FIELD IS TOO LONG, THEN ONLY THE BITS THROUGH BIT 15 WILL BE RETURNED. FOR EXAMPLE IF A 4 BIT FIELD IS REQUESTED STARTING AT BIT 15 THEN ONLY 1 BIT (BIT 15) WILL BE RETURNED.
Entry: TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Starting (lowest) bit position in the field (0..15),
   Number of bits in the field (1..16),
   Low byte of data word,
   High byte of data word,
Exit: Register A = High byte of field
      Register Y = Low byte of field
Registers used: All
Time: 138 cycles overhead plus 
      (34 * starting bit position) cycles
Size: Program 134 bytes
      Data 6 bytes

BFE:

;SAVE RETURN ADDRESS IN Y,X
PLA
TAY
PLA
TAX
; GET THE STARTING BIT POSITION OF THE FIELD
PLA
AND #0FH ; MAKE SURE INDEX IS A VALUE BETWEEN 0 AND 15
STA INDEX ; SAVE INDEX

; GET THE NUMBER OF BITS IN THE FIELD (MAP FROM 1..WIDTH TO 0..WIDTH-1)
PLA
SEC
SBC #1 ; SUBTRACT 1
AND #0FH ; MAKE SURE IT IS 0 TO 15
STA WIDTH ; SAVE WIDTH

; GET THE DATA WORD
PLA
STA VALUE
PLA
STA VALUE+1

; RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

; CONSTRUCT THE MASK
; INDEX INTO THE MASK ARRAY USING THE WIDTH PARAMETER
LDA WIDTH
ASL A ; MULTIPLY BY 2 SINCE MASKS ARE WORD-LENGTH
TAY
LDA MSKARY,Y
STA MASK
INY
LDA MSKARY,Y
STA MASK+1

; SHIFT MASK LEFT INDEX TIMES TO ALIGN IT WITH THE BEGINNING
; OF THE FIELD
LDY INDEX
BEQ GETFLD ; BRANCH IF INDEX = 0

SHFTLP:
ASL MASK ; SHIFT LOW BYTE, CARRY := BIT 7
ROL MASK+1 ; ROTATE HIGH BYTE, BIT 0 := CARRY
DEY
BNE SHFTLP ; CONTINUE UNTIL INDEX = 0

GETFLD:
LDA VALUE
AND MASK ; AND LOW BYTE OF VALUE WITH MASK
STA VALUE ; STORE IN VALUE
LDA VALUE+1
AND MASK+1 ; AND HIGH BYTE OF VALUE WITH MASK
STA VALUE+1 ; STORE IT
; NORMALIZE THE FIELD TO BIT 0 BY SHIFTING RIGHT INDEX TIMES
LDY INDEX
BEQ EXIT ; BRANCH IF INDEX = 0
NORMLP:
LSR VALUE+1 ; SHIFT HIGH BYTE RIGHT, CARRY := BIT 0
ROR VALUE ; ROTATE LOW BYTE RIGHT, BIT 7 := CARRY
DEY
BNE NORMLP ; CONTINUE UNTIL DONE
EXIT:
LDY VALUE
LDA VALUE+1
RTS

; MASK ARRAY WHICH IS USED TO CREATE THE MASK
MSKARY:
.WORD 0000000000000001B
.WORD 0000000000000011B
.WORD 0000000000000111B
.WORD 0000000000011111B
.WORD 0000000000111111B
.WORD 0000000001111111B
.WORD 0000000011111111B
.WORD 0000000111111111B
.WORD 0000001111111111B
.WORD 0000011111111111B
.WORD 0000111111111111B
.WORD 0001111111111111B
.WORD 0011111111111111B
.WORD 0111111111111111B
.WORD 1111111111111111B

INDEX: .BLOCK 1 ; INDEX INTO WORD
WIDTH: .BLOCK 1 ; WIDTH OF FIELD (NUMBER OF BITS)
VALUE: .BLOCK 2 ; DATA WORD TO EXTRACT THE FIELD FROM
MASK: .BLOCK 2 ; TEMPORARY FOR CREATING THE MASK

; ; ; SAMPLE EXECUTION:
; ; ;
; ;
SC0704:
LDA VAL+1
PHA
LDA VAL
PHA
LDA NBITS
PHA
LDA POS
; PUSH THE DATA WORD
; PUSH FIELD WIDTH (NUMBER OF BITS)
PHA ; PUSH INDEX TO FIRST BIT OF THE FIELD
JSR  BFE ; EXTRACT
BRK ; RESULT FOR VAL = 1234H, NBITS = 4, POS = 4 IS
        ; REGISTER A = 0, REGISTER Y = 3
JMP  SC0704

; TEST DATA, CHANGE FOR OTHER VALUES
VAL: .WORD 01234H
NBITS: .BYTE 4
POS: .BYTE 4

.END ; PROGRAM
Bit Field Insertion (BFI)

Inserts a field of bits into a word. The width of the field and its starting (lowest) bit position are specified.

Procedure: The program obtains a mask with the specified number of 0 bits from a table. It then shifts the mask and the bit field left to align them with the specified starting bit position. It logically ANDs the mask and the original data word, thus clearing the required bit positions, and then logically ORs the result with the shifted bit field.

Registers Used: All

Execution Time: 31 * STARTING BIT POSITION plus 142 cycles overhead. The starting bit position of the field determines how many times the mask and the field must be shifted left. For example, if the field is inserted starting in bit 10, the execution time is

$$31 \times 10 + 142 = 310 + 142 = 452$$

cycles.

Program Size: 130 bytes

Data Memory Required: Eight bytes anywhere in RAM for the index (one byte at address INDEX), the width of the field (one byte at address WIDTH), the value to be inserted (two bytes starting at address INSVAL), the data value (two bytes starting at address VALUE), and the mask (two bytes starting at address MASK).

Special Cases:
1. Attempting to insert a field that would extend beyond the end of the word causes the program to insert only the bits through bit 15. That is, no wraparound is provided. If, for example, the user attempts to insert a 6-bit field starting at bit 14, only 2 bits (bits 14 and 15) are actually replaced.
2. Both the starting bit position and the length of the bit field are interpreted mod 16. That is, for example, bit position 17 is the same as bit position 1 and a 20-bit field is the same as a 4-bit field.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address

Lowest bit position (starting position) of field
Number of bits in the field

Less significant byte of bit field (value to insert)
More significant byte of bit field (value to insert)

Less significant byte of original data value
More significant byte of original data value

Exit Conditions

More significant byte of result in accumulator
Less significant byte of result in register Y

The result is the original data value with the bit field inserted, starting at the specified bit position.
Examples

1. Data: Value = F67C\textsubscript{16} = 1111011001111100\textsubscript{2}
   Starting bit position = 4
   Number of bits in the field = 8
   Bit field = 008B\textsubscript{16} = 0000000001001011\textsubscript{2}

   Result: Value with bit field inserted = F8BC\textsubscript{16}
   = 1111100010111100\textsubscript{2}
   The 8-bit field has been inserted into the original value starting at bit 4
   (that is, into bits 4 through 11).

2. Data: Value = A2D4\textsubscript{16} = 1010001011010100\textsubscript{2}
   Starting bit position = 6
   Number of bits in the field = 5
   Bit field = 0015\textsubscript{16} = 0000000000010101\textsubscript{2}

   Result: Value with bit field inserted = A554\textsubscript{16}
   = 1010010101010100\textsubscript{2}
   The 5-bit field has been inserted into the original value starting at bit 6
   (that is, into bits 6 through 10). Those five bits were 01011\textsubscript{2} (0B\textsubscript{16})
   and are now 10101\textsubscript{2} (15\textsubscript{16}).

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Title
Name: Bit Field Insertion
Purpose: Insert a field of bits which is normalized to bit 0 into a 16 bit word.
NOTE: IF THE REQUESTED FIELD IS TOO LONG, THEN
ONLY THE BITS THROUGH BIT 15 WILL BE
INSERTED. FOR EXAMPLE IF A 4 BIT FIELD IS
TO BE INSERTED STARTING AT BIT 15 THEN
ONLY THE FIRST BIT WILL BE INSERTED AT
BIT 15.

Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Bit position at which inserted field will start (0..15),
Number of bits in the field (1..16),
Low byte of value to insert,
High byte of value to insert,
Low byte of value,
High byte of value

Exit: Register A = High byte of value with field inserted
Register Y = Low byte of value with field inserted

Registers used: All
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; Time: 142 cycles overhead plus (31 * starting bit position) cycles
; Size: Program 130 bytes, Data 8 bytes

BFI:

;SAVE RETURN ADDRESS IN Y,X
PLA
TAY
PLA
TAX

;GET THE LOWEST BIT NUMBER OF THE FIELD
PLA
AND  #$0F
STA INDEX

;GET THE NUMBER OF BITS IN THE FIELD (MAP FROM 1..WIDTH TO 0..WIDTH-1)
PLA
SEC
SRC  #1
AND  #$0F
STA  WIDTH

;GET THE VALUE TO BE INSERTED (BIT FIELD)
PLA
STA  INSVAL
PLA
STA  INSVAL+1

;GET THE DATA WORD
PLA
STA  VALUE
PLA
STA  VALUE+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

;CONSTRUCT THE MASK
; INDEX INTO THE MASK ARRAY USING THE WIDTH PARAMETER
LDA  WIDTH
ASL  A
TAY
LDA  MSKARY,Y
STA  MASK
INY
LDA  MSKARY,Y
STA  MASK+1
; SHIFT MASK AND BIT FIELD LEFT INDEX TIMES TO ALIGN THEM
; WITH THE BEGINNING OF THE FIELD
LDY INDEX
BEQ INSERT ; BRANCH IF INDEX = 0

SHFTLP:
SEC ; FILL THE MASK WITH ONES
ROL MASK ; ROTATE LOW BYTE SHIFTING A 1 TO BIT 0 AND
; BIT 7 TO CARRY
ROL MASK+1 ; ROTATE HIGH BYTE, BIT 0 := CARRY
ASL INSVAL ; SHIFT THE INSERT VALUE SHIFTING IN ZEROS
ROL INSVAL+1
DEY
BNE SHFTLP ; CONTINUE UNTIL INDEX = 0

INSERT:
LDA VALUE
AND MASK ; AND LOW BYTE OF VALUE WITH MASK
ORA INSVAL ; REGISTER Y = LOW BYTE OF THE NEW VALUE
TAY
LDA VALUE+1
AND MASK+1 ; AND HIGH BYTE OF VALUE WITH MASK
ORA INSVAL+1 ; REGISTER A = HIGH BYTE OF THE NEW VALUE

; RETURN
RTS

; MASK ARRAY WHICH IS USED TO CREATE THE MASK

MSKARY:
.WORD 1111111111111110B
.WORD 1111111111111100B
.WORD 1111111111111000B
.WORD 1111111111100000B
.WORD 1111111110000000B
.WORD 1111111100000000B
.WORD 1111111000000000B
.WORD 1111110000000000B
.WORD 1111000000000000B
.WORD 1100000000000000B
.WORD 1000000000000000B
.WORD 0000000000000000B

INDEX: .BLOCK 1 ; INDEX INTO WORD
WIDTH: .BLOCK 1 ; WIDTH OF FIELD
INSVAL: .BLOCK 2 ; VALUE TO INSERT
VALUE: .BLOCK 2 ; DATA WORD
MASK: .BLOCK 2 ; TEMPORARY FOR CREATING THE MASK
SAMPLE EXECUTION:

SC0705:

LDA VAL+1 ;PUSH THE DATA WORD
PHA
LDA VAL
PHA
LDA VALINS+1 ;PUSH THE VALUE TO INSERT
PHA
LDA VALINS
PHA
LDA NBITS ;PUSH THE FIELD WIDTH
PHA
LDA POS ;PUSH THE STARTING POSITION OF THE FIELD
PHA
JSR BFI ;INSERT
BRK
JMP SC0705

;TEST DATA, CHANGE FOR OTHER VALUES
VAL: .WORD 01234H
VALINS: .WORD 0EH
NBITS: .BYTE 04H
POS: .BYTE 0CH

.END ;PROGRAM
Multiple-Precision Arithmetic Shift Right
(MPASR)

Shifts a multi-byte operand right arithmetically by a specified number of bit positions. The length of the number (in bytes) is 255 or less. The Carry flag is set to the value of the last bit shifted out of the rightmost bit position. The operand is stored with its least significant byte at the lowest address.

Procedure: The program obtains the sign bit from the most significant byte, shifts that bit to the Carry, and then rotates the entire operand right one bit, starting with the most significant byte. It repeats the operation for the specified number of shifts.

Registers Used: All
Execution Time: NUMBER OF SHIFTS * (18 + 18 * LENGTH OF OPERAND IN BYTES) + 85 cycles.
If, for example, NUMBER OF SHIFTS = 6 and LENGTH OF OPERAND IN BYTES = 8, the execution time is
6 * (18 + 18 * 8) + 85 = 6 * 162 + 85 = 1057 cycles
Program Size: 69 bytes
Data Memory Required: Three bytes anywhere in RAM plus two bytes on page 0. The three bytes anywhere in RAM are temporary storage for the number of shifts (one byte at address NBITS) and the length of the operand (one byte at address LENGTH) and the most significant byte of the operand (one byte at address MSB). The two bytes on page 0 hold a pointer to the operand (starting at address PTR,00D0H in the listing).

Special Cases:
1. If the length of the operand is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.
2. If the number of shifts is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.

Entry Conditions
Order in stack (starting from the top)
Less significant byte of return address
More significant byte of return address
Number of shifts (bit positions)
Length of the operand in bytes
Less significant byte of starting address of operand (address of its least significant byte)
More significant byte of starting address of operand (address of its least significant byte)

Exit Conditions
Operand shifted right arithmetically by the specified number of bit positions. The original sign bit is extended to the right. The Carry flag is set according to the last bit shifted from the rightmost bit position (or cleared if either the number of shifts or the length of the operand is zero).
Examples

1. Data: Length of operand (in bytes) = 08
   Operand = 85A4C719FE06741E16
   Number of shifts = 04
   Result: Shifted operand = F85A4C719FE0674116.
   This is the original operand shifted right four bits arithmetically (the four most significant bits thus all take on the value of the original sign bit, which was 1).
   Carry = 1, since the last bit shifted from the rightmost bit position was 1.

2. Data: Length of operand (in bytes) = 04
   Operand = 3F6A42D316
   Number of shifts = 03
   Result: Shifted operand = 07ED485A16.
   This is the original operand shifted right three bits arithmetically (the three most significant bits thus all take on the value of the original sign bit, which was 0).
   Carry = 0, since the last bit shifted from the rightmost bit position was 0.

Title
Name: Multiple-precision arithmetic shift right

Purpose: Arithmetic shift right a multi-byte operand
          N bits.

Entry:
   TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Number of bits to shift,
   Length of the operand in bytes,
   Low byte of address of the operand,
   High byte of address of the operand

   The operand is stored with ARRAY[0] as its least significant byte and ARRAY[LENGTH-1]
   its most significant byte.

Exit: Operand shifted right with the most significant bit propagated.
      CARRY := Last bit shifted from least significant position.

Registers used: All

Time: 85 cycles overhead plus
      ((18 * length) + 18) cycles per shift

Size: Program 69 bytes
      Data 3 bytes plus
            2 bytes in page zero
MPASR:

;SAVE RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET NUMBER OF BITS
PLA
STA NBITS
;GET LENGTH OF OPERAND
PLA
STA LENGTH

;GET STARTING ADDRESS OF THE OPERAND
PLA
STA PTR
PLA
STA PTR+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

;RESTORE RETURN ADDRESS

;INITIALIZE
CLC
LDA LENGTH
BEQ EXIT
LDA NBITS
BEQ EXIT

;DECUMENT POINTER SO THAT THE LENGTH BYTE MAY BE USED BOTH
; AS A COUNTER AND THE INDEX
LDA PTR
BNE MPASR1
DEC PTR+1

;LOOP ON THE NUMBER OF SHIFTS TO PERFORM
LDY LENGTH
LDA (PTR),Y
STA MSB

ASRLP:

LDA MSB
ASL A
LDY LENGTH

;SHIFT RIGHT ONE BIT
LOOP:

LDA (PTR),Y ;GET NEXT BYTE
ROR A ;ROTATE BIT 7 := CARRY, CARRY := BIT 0
STA (PTR),Y ;STORE NEW VALUE
DEY ;DECREMENT COUNTER
BNE LOOP ;CONTINUE THROUGH ALL THE BYTES

;DECREMENT NUMBER OF SHIFTS
DEC NBITS ;DECREMENT SHIFT COUNTER
BNE ASRLP ;CONTINUE UNTIL DONE

EXIT:

RTS

;DATA SECTION
NBITS: .BLOCK 1 ;NUMBER OF BITS TO SHIFT
LENGTH: .BLOCK 1 ;LENGTH OF OPERAND IN BYTES
MSB: .BLOCK 1 ;MOST SIGNIFICANT BYTE

;SAMPLE EXECUTION:

SC0706:

LDA AYADR+1 ;PUSH STARTING ADDRESS OF OPERAND
PHA
LDA AYADR
PHA

LDA #$SZAY ;PUSH LENGTH OF OPERAND
PHA

LDA SHIFTS ;PUSH NUMBER OF SHIFTS
PHA
JSR MPASR ;SHIFT
BRK ;RESULT OF SHIFTING AY = EDCBA987654321H, 4 BITS IS
; IN MEMORY AY = 032H
; AY+1 = 054H
; AY+2 = 076H
; AY+3 = 098H
; AY+4 = 0BAH
; AY+5 = 0DCH
; AY+6 = 0FEH

JMP SC0706

;DATA SECTION
SZAY: .EQU 7 ;LENGTH OF OPERAND
SHIFTS: .BYTE 4 ;NUMBER OF SHIFTS
AYADR: .WORD AY ;STARTING ADDRESS OF OPERAND
AY .BYTE 21H,43H,65H,87H,0A9H,0CBH,0EDH

.END ;PROGRAM
Multiple-Precision Logical Shift Left (MPLSL)

Shifts a multi-byte operand left logically by a specified number of bit positions. The length of the operand (in bytes) is 255 or less. The Carry flag is set to the value of the last bit shifted out of the leftmost bit position. The operand is stored with its least significant byte at the lowest address.

Procedure: The program clears the Carry initially (to fill with a 0 bit) and then rotates the entire operand left one bit, starting with the least significant byte. It repeats the operation for the specified number of shifts.

Registers Used: All

Execution Time: NUMBER OF SHIFTS * (16 + 20 * LENGTH OF OPERAND IN BYTES) + 73 cycles.

If, for example, NUMBER OF SHIFTS = 4 and LENGTH OF OPERAND IN BYTES = 6 (i.e., a 4-bit shift of a byte operand) the execution time is

\[ 4 \times (6 + 20 \times 6) + 73 = 4 \times (136) + 73 = 617 \text{ cycles}. \]

Data Memory Required: Two bytes anywhere in RAM plus two bytes on page 0. The two bytes anywhere in RAM are temporary storage for the number of shifts (one byte at address NBITS) and the length of the operand in bytes (one byte at address LENGTH). The two bytes on page 0 hold a pointer to the operand (starting at address PTR, 00D016 in the listing).

Special Cases:
1. If the length of the operand is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.
2. If the number of shifts is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Number of shifts (bit positions)
Length of the operand in bytes
Less significant byte of starting address of operand (address of its least significant byte)
More significant byte of starting address of operand (address of its least significant byte)

Exit Conditions

Operand shifted left logically by the specified number of bit positions (the least significant bit positions are filled with zeros). The Carry flag is set according to the last bit shifted from the leftmost bit position (or cleared if either the number of shifts or the length of the operand is zero).
Examples

1. Data: Length of operand (in bytes) = 08
   Operand = 85A4C719FE06741E16
   Number of shifts = 04
   Result: Shifted operand = 5A4C719FE06741E016
   This is the original operand shifted left four bits logically; the four least significant bits are all cleared.
   Carry = 0, since the last bit shifted from the leftmost bit position was 0.

2. Data: Length of operand (in bytes) = 04
   Operand = 3F6A42D316
   Number of shifts = 03
   Result: Shifted operand = FB52169816.
   This is the original operand shifted left three bits logically; the three least significant bits are all cleared.
   Carry = 1, since the last bit shifted from the leftmost bit position was 1.

Title
Name: Multiple-precision logical shift left
MPLSL

Purpose: Logical shift left a multi-byte operand N bits

Entry:
TOP OF STACK
Low byte of return address,
High byte of return address,
Number of bits to shift,
Length of the operand in bytes,
Low byte of address of the operand,
High byte of address of the operand

The operand is stored with ARRAY[0] as its least significant byte and ARRAY[LENGTH-1] its most significant byte.

Exit: Operand shifted left filling the least significant bits with zeros.
CARRY := Last most significant bit

Registers used: All

Time: 73 cycles overhead plus
       ((20 * length) + 16) cycles per shift

Size: Program 54 bytes
Data 2 bytes plus
     2 bytes in page zero
;EQUATES
PTR:  .EQU  0D0H  ;PAGE ZERO FOR POINTER TO OPERAND

MPLSL:

;SAVE RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET NUMBER OF BITS
PLA
STA  NBITS

;GET LENGTH OF OPERAND
PLA
STA  LENGTH

;GET STARTING ADDRESS OF THE OPERAND
PLA
STA  PTR
PLA
STA  PTR+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

;RESTORE RETURN ADDRESS

;INITIALIZE
CLC
LDA  LENGTH
BEQ  EXIT
LDA  NBITS
BEQ  EXIT

;EXIT IF LENGTH OF THE OPERAND IS 0
;EXIT IF NUMBER OF BITS TO SHIFT IS 0
;WITH CARRY CLEAR

;LOOP ON THE NUMBER OF SHIFTS TO PERFORM
LSLLP:

LDY  $0
LDX  LENGTH
CLC

;Y = INDEX TO LOW BYTE OF THE OPERAND
;X = NUMBER OF BYTES
;CLEAR CARRY TO FILL WITH ZEROS

;SHIFT LEFT ONE BIT
LOOP:

LDA  (PTR),Y
ROL  A
STA  (PTR),Y
INY
DEX
BNE  LOOP

;GET NEXT BYTE
;ROTATE BIT 0 := CARRY, CARRY := BIT 7
;STORE NEW VALUE
;INCREMENT TO NEXT BYTE
;DECREMENT COUNTER
;CONTINUE THROUGH ALL THE BYTES

;DECREMENT NUMBER OF SHIFTS
DEC  NBITS
BNE  LSLLP

;DECREMENT SHIFT COUNTER
;CONTINUE UNTIL DONE
EXIT:
RTS

;DATA SECTION
NBITS: .BLOCK 1
LENGTH: .BLOCK 1

;SAMPLE EXECUTION:

SC0707:
LDA AYADR+1 ;PUSH STARTING ADDRESS OF OPERAND
PHA
LDA AYADR
PHA

LDA #SZAY ;PUSH LENGTH OF OPERAND
PHA

LDA SHIFTS ;PUSH NUMBER OF SHIFTS
PHA
JSR MPLSL ;SHIFT
BRK ;RESULT OF SHIFTING AY = EDCBA987654321H, 4 BITS IS
; AY = DCBA9876543210H, C=0

JMP SC0707

;DATA SECTION
SZAY: .EQU 7
SHIFTS: .BYTE 4
AYADR: .WORD AY
AY: .BYTE 21H,43H,65H,87H,0A9H,0CBH,0EDH

.END ;PROGRAM
Multiple-Precision Logical Shift Right (MPLSR) 7H

Shifts a multi-byte number right logically by a specified number of bit positions. The length of the operand (in bytes) is 255 or less. The Carry flag is set to the value of the last bit shifted out of the rightmost bit position. The operand is stored with its least significant byte at the lowest address.

Procedure: The program clears the Carry initially (to fill with a 0 bit) and then rotates the entire operand right one bit, starting with the most significant byte. It repeats the operation for the specified number of shifts.

Registers Used: All
Execution Time: NUMBER OF SHIFTS * (14 + 18 * LENGTH OF OPERAND IN BYTES) + 80 cycles.
If, for example, NUMBER OF SHIFTS = 4 and LENGTH OF OPERAND IN BYTES = 8 (i.e., a 4-bit shift of an 8-byte operand), the execution time is
4 * (14 + 18 * 8) + 80 = 4 * (158) + 80 = 712 cycles.
Program Size: 59 bytes
Data Memory Required: Two bytes anywhere in RAM plus two bytes on page 0. The two bytes anywhere in RAM are temporary storage for the number of shifts (one byte at address NBITS) and the length of the operand in bytes (one byte at address LENGTH). The two bytes on page 0 hold a pointer to the operand (starting at address PTR, 00D016 in the listing).

Special Cases:
1. If the length of the operand is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.
2. If the number of shifts is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.

Entry Conditions
Order in stack (starting from the top)
Less significant byte of return address
More significant byte of return address
Number of shifts (bit positions)
Length of the operand in bytes
Less significant byte of starting address of operand (address of its least significant byte)
More significant byte of starting address of operand (address of its least significant byte)

Exit Conditions
Operand shifted right logically by the specified number of bit positions (the most significant bit positions are filled with zeros). The Carry flag is set according to the last bit shifted from the rightmost bit position. (or cleared if either the the number of shifts or the length of the operand is zero).
Examples

1. Data: Length of operand (in bytes) = 08
   Operand = 85A4C719FE06741
   Number of shifts = 04

   Result: Shifted operand = 085A4C719FE06741.
   This is the original operand shifted right four bits logically; the four most
   significant bits are all cleared.
   Carry = 1, since the last bit shifted from
   the rightmost position was 1.

2. Data: Length of operand (in bytes) = 04
   Operand = 3F6A42D3
   Number of shifts = 03

   Result: Shifted operand = 07ED485A.
   This is the original operand shifted
   right three bits logically; the three least
   significant bits are all cleared.
   Carry = 0, since the last bit shifted
   from the rightmost bit position was 0.

Title

Name: Multiple-Precision logical shift right

Purpose: Logical shift right a multi-byte operand N bits

Entry:

   TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Number of bits to shift,
   Length of the operand in bytes,
   Low byte of address of the operand,
   High byte of address of the operand

   The operand is stored with ARRAY[0] as its
   least significant byte and ARRAY[LENGTH-1]
   its most significant byte.

Exit: Operand shifted right filling the most
       significant bits with zeros
       CARRY := Last bit shifted from the least
       significant position

Registers used: All

Time: 85 cycles overhead plus
       ((18 * length) + 14) cycles per shift

Size: Program 59 bytes
       Data 2 bytes plus
       2 bytes in page zero
; EQUATES
PTR:  .EQU  0D0H

; PAGE ZERO FOR POINTER TO OPERAND

MPLSR:

; SAVE RETURN ADDRESS
PLA
TAY
PLA
TAX

; GET NUMBER OF BITS
PLA
STA  NBITS

; GET LENGTH OF OPERAND
PLA
STA  LENGTH

; GET STARTING ADDRESS OF THE OPERAND
PLA
STA  PTR
PLA
STA  PTR+1

; RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

; RESTORE RETURN ADDRESS

; INITIALIZE
CLC
LDA  LENGTH
BEQ  EXIT
LDA  NBITS
BEQ  EXIT

; DECREMENT POINTER SO THAT THE LENGTH BYTE MAY BE USED BOTH
; AS A COUNTER AND THE INDEX
LDA  PTR
BNE  MLSR1
DEC  PTR+1

MPLSR1:
DEC  PTR+1

; LOOP ON THE NUMBER OF SHIFTS TO PERFORM

LSRLP:
LDY  LENGTH
CLC

; SHIFT RIGHT ONE BIT

LOOP:
LDA  (PTR),Y
ROR  A
STA  (PTR),Y
DEY
BNE LOOP

; DECREMENT COUNTER
; CONTINUE THROUGH ALL THE BYTES

; DECREMENT NUMBER OF SHIFTS
DEC NBITS
BNE LSRLP

; DECREMENT SHIFT COUNTER
; CONTINUE UNTIL DONE

EXIT:
RTS

; DATA SECTION
NBITS: .BLOCK 1
LENGTH: .BLOCK 1

; NUMBER OF BITS TO SHIFT
; LENGTH OF OPERAND

; SAMPLE EXECUTION:

SC0708:
LDA AYADR+1 ; PUSH STARTING ADDRESS OF OPERAND
PHA
LDA AYADR
PHA

LDA #SZAY ; PUSH LENGTH OF OPERAND
PHA

LDA SHIFTS ; PUSH NUMBER OF SHIFTS
PHA
JSR MPLSR ; SHIFTS
BRK

; RESULT OF SHIFTING AY = EDCBA987654321H, 4 BITS IS
; AY = 0EDCBA987654321H, C=0
; IN MEMORY AY = 032H
; AY+1 = 054H
; AY+2 = 076H
; AY+3 = 098H
; AY+4 = 0BAH
; AY+5 = 0DCH
; AY+6 = 00EH

JMP SC0708

; DATA SECTION
SZAY: .EQU 7
LENGTH: .BYTE 4
SHIFTS: .BYTE 4
AYADR: .WORD AY
AY: .BYTE 21H,43H,65H,87H,0A9H,0CBH,0EDH

.END ; PROGRAM
Multiple-Precision Rotate Right (MPRR)

Rotates a multi-byte operand right by a specified number of bit positions (as if the most significant bit and least significant bit were connected directly). The length of the operand in bytes is 255 or less. The Carry flag is set to the value of the last bit shifted out of the rightmost bit position. The operand is stored with its least significant byte at the lowest address.

Procedure: The program shifts bit 0 of the least significant byte of the operand to the Carry flag and then rotates the entire operand right one bit, starting with the most significant byte. It repeats the operation for the specified number of shifts.

Registers used: All

Execution Time: NUMBER OF SHIFTS * (21 + 18 * LENGTH OF OPERAND IN BYTES) + 85 cycles.

If for example, NUMBER OF SHIFTS = 6 and LENGTH OF OPERAND IN BYTES = 4 (i.e. a 6-bit shift of a 4-byte operand), the execution time is

\[ 6 \times (21 + 18 \times 4) + 85 = 6 \times (93) + 85 = 643 \text{ cycles}. \]

Program Size: 63 bytes

Data Memory Required: Two bytes anywhere in RAM plus two bytes on page 0. The two bytes anywhere in RAM are temporary storage for the number of shifts (one byte at address NBITS) and the length of the operand in bytes (one byte at address LENGTH). The two bytes on page 0 hold a pointer to the operand (starting at address PTR, 00D016 in the listing).

Special Cases:
1. If the length of the operand is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.
2. If the number of shifts is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Number of shifts (bit positions)
Length of the operand in bytes
Less significant byte of starting address of operand (address of its least significant byte)
More significant byte of starting address of operand (address of its least significant byte)

Exit Conditions

Operand rotated right by the specified number of bit positions (the most significant bit positions are filled from the least significant bit positions). The Carry flag is set according to the last bit shifted from the rightmost bit position (or cleared if either the number of shifts or the length of the operand is zero).
Examples

1. Data: Length of operand (in bytes) = 08
   Operand = 85A4C719FE06741E16
   Number of shifts = 04
   Result: Shifted operand = E85A4C719F30674116.
           This is the original operand rotated right four bits: the four most significant bits are equivalent to the original four least significant bits.
           Carry = 1, since the last bit shifted from the rightmost bit position was 1.

2. Data: Length of operand (in bytes) = 04
   Operand = 3F6A42D316
   Number of shifts = 03
   Result: Shifted operand = 67ED485A16. This is the original operand rotated right 3 bits; the three most significant bits (011) are equivalent to the original three least significant bits.
           Carry = 0, since the last bit shifted from the rightmost bit position was 0.

Title
Name: Multiple-precision rotate right

Purpose: Rotate right a multi-byte operand N bits

Entry:
   TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Number of bits to shift,
   Length of the operand in bytes,
   Low byte of address of the operand,
   High byte of address of the operand

   The operand is stored with ARRAY[0] as its least significant byte and ARRAY[LENGTH-1]
   its most significant byte.

Exit:
   Operand rotated right
   CARRY := Last bit shifted from the least significant position

Registers used: All

Time: 85 cycles overhead plus
      ((18 * length) + 21) cycles per shift

Size:
   Program 63 bytes
   Data 2 bytes plus
        2 bytes in page zero

;EQUATES
PTR: .EQU 0D0H ;PAGE ZERO FOR POINTER TO OPERAND
MPRR:

;SAVE RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET NUMBER OF BITS
PLA
STA NBITS

;GET LENGTH OF OPERAND

PLA
STA LENGTH

;GET STARTING ADDRESS OF THE OPERAND
PLA
STA PTR
PLA
STA PTR+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

;RESTORE RETURN ADDRESS

;INITIALIZE
CLC
LDA LENGTH
BEQ EXIT
LDA NBITS
BEQ EXIT

;DECREMENT POINTER SO THAT THE LENGTH BYTE MAY BE USED BOTH
;AS A COUNTER AND THE INDEX
LDA PTR
BNE MPRR1
DEC PTR+1

MPRR1:

DEC PTR

;DECREMENT HIGH BYTE IF A BORROW IS NEEDED

;ALWAYS DECREMENT LOW BYTE

;LOOP ON THE NUMBER OF SHIFTS TO PERFORM

RRLP:

LDY #1
LDA (PTR),Y
LSR A
LDY LENGTH

;GET LOW BYTE OF THE OPERAND
;CARRY := BIT 0 OF LOW BYTE
;y = INDEX TO HIGH BYTE AND COUNTER

;ROTATE RIGHT ONE BIT

LOOP:

LDA (PTR),Y
ROR A

;GET NEXT BYTE
;ROTATE BIT 7 := CARRY, CARRY := BIT 0
340 BIT MANIPULATIONS AND SHIFTS

STA (PTR),Y ;STORE NEW VALUE
DEY ;DECREMENT COUNTER
BNE LOOP ;CONTINUE THROUGH ALL THE BYTES

;DECREMENT NUMBER OF ShiftS
DEC NBITS ;DECREMENT SHIFT COUNTER
BNE RRLP ;CONTINUE UNTIL DONE

EXIT:
RTS

;DATA SECTION
NBITS: .BLOCK 1 ;NUMBER OF BITS TO SHIFT
LENGTH: .BLOCK 1 ;LENGTH OF OPERAND

;
;
;
SAMPLE EXECUTION:

;
;
;
;
;
;

SC0709:
LDA AYADR+1 ;PUSH STARTING ADDRESS OF OPERAND
PHA
LDA AYADR
PHA
LDA #SZAY ;PUSH LENGTH OF OPERAND
PHA
LDA SHIFTS ;PUSH NUMBER OF ShiftS
PHA
JSR MPRR ;ROTATE
;RESULT OF ROTATING AY = EDCBA987654321H 4 BITS IS
;AY = 1EDCBA98765432H C=0
;IN MEMORY AY = 032H
;AY+1 = 054H
;AY+2 = 076H
;AY+3 = 098H
;AY+4 = 0BAH
;AY+5 = 0DCH
;AY+6 = 01EH

JMP SC0709

;
;DATA SECTION
SZAY: .EQU 7 ;LENGTH OF OPERAND IN BYTES
SHIFTS: .BYTE 4 ;NUMBER OF ShiftS
AYADR: .WORD AY ;STARTING ADDRESS OF OPERAND
AY: .BYTE 21H,43H,65H,87H,0A9H,0CBH,0EDH

.END ;PROGRAM
Rotates a multi-byte operand left by a specified number of bit positions (i.e., as if the most significant bit and least significant bit were connected directly). The length of the operand in bytes is 255 or less. The Carry flag is set to the value of the last bit shifted out of the leftmost bit position. The operand is stored with its least significant byte at the lowest address.

Procedure: The program shifts bit 7 of the most significant byte of the operand to the Carry flag. It then rotates the entire operand left one bit, starting with the least significant byte. It repeats the operation for the specified number of shifts.

Registers Used: All
Execution Time: NUMBER OF SHIFTS * (27 + 20 * LENGTH OF OPERAND IN BYTES) + 73 cycles.
If, for example, NUMBER OF SHIFTS = 4 and LENGTH OF OPERAND IN BYTES = 8 (i.e., a 4-bit shift of an 8-byte operand), the execution time is
4 * (27 + 20 * 8) + 73 = 4 * (187) + 73 = 821 cycles.

Program Size: 60 bytes
Data Memory Required: Two bytes anywhere in RAM plus two bytes on page 0. The two bytes anywhere in RAM are temporary storage for the number of shifts (one byte at address NBITS) and the length of the operand in bytes (one byte at address LENGTH). The two bytes on page 0 hold a pointer to the operand (starting at address PTR, 00D016 in the listing).

Special Cases:
1. If the length of the operand is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.
2. If the number of shifts is zero, the program exits immediately with the operand unchanged and the Carry flag cleared.

Entry Conditions
Order in stack (starting from the top)
Less significant byte of return address
More significant byte of return address
Number of shifts (bit positions)
Length of the operand in bytes
Less significant byte of starting address of operand (address of its least significant byte)
More significant byte of starting address of operand (address of its least significant byte)

Exit Conditions
Operand rotated left by the specified number of bit positions (the least significant bit positions are filled from the most significant bit positions). The Carry flag is set according to the last bit shifted from the leftmost bit position (or cleared if either the number of shifts or the length of the operand is zero).
### Examples

1. **Data:** Length of operand (in bytes) = 08  
   Operand = 85A4C719FE06741E \(_{16}\)  
   Number of shifts = 04  
   **Result:** Shifted operand = 5A4C719FE06741E \(_{16}\).  
   This is the original operand rotated left four bits; the four least significant bits are equivalent to the original four most significant bits.  
   Carry = 0, since the last bit shifted from the leftmost bit position was 0.

2. **Data:** Length of operand (in bytes) = 04  
   Operand = 3F6A42D3 \(_{16}\)  
   Number of shifts = 03  
   **Result:** Shifted operand = FB521699 \(_{16}\). This is the original operand rotated left three bits; the three least significant bits (001) are equivalent to the original three most significant bits.  
   Carry = 1, since the last bit shifted from the leftmost bit position was 1.

---

#### Title
**Multiple-precision rotate left**

#### Name
**MPRL**

#### Purpose
Rotate left a multi-byte operand N bits

#### Entry
**TOP OF STACK**  
- Low byte of return address,  
- High byte of return address,  
- Number of bits to shift,  
- Length of the operand in bytes,  
- Low byte of address of the operand,  
- High byte of address of the operand

The operand is stored with ARRAY[0] as its least significant byte and ARRAY[LENGTH-1] its most significant byte.

#### Exit
Number rotated left  
CARRY := Last bit shifted from the most significant position

#### Registers used: All

#### Time
73 cycles overhead plus  
((20 \* length) + 27) cycles per shift

#### Size
Program 60 bytes  
Data 2 bytes plus  
2 bytes in page zero

;EQUATES  
PTR: .EQU 0D0H ;PAGE ZERO FOR POINTER TO OPERAND
MPRL:

;SAVE RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET NUMBER OF BITS
PLA
STA   NBITS

;GET LENGTH OF OPERAND
PLA
STA   LENGTH

;GET STARTING ADDRESS OF THE OPERAND
PLA
STA   PTR
PLA
STA   PTR+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

;RESTORE RETURN ADDRESS

;INITIALIZE
CLC

;CLEAR CARRY
LDA   LENGTH
BEQ   EXIT
LDA   NBITS
BEQ   EXIT

;EXIT IF NUMBER OF BITS TO SHIFT IS 0

;WITH CARRY CLEAR

;LOOP ON THE NUMBER OF SHIFTS TO PERFORM

RLLP:

LDY   LENGTH
DEY
LDA   (PTR),Y
ASL   A
LDY   #0
LDX   LENGTH

;GET HIGH BYTE OF THE OPERAND
;CARRY := BIT 7 OF HIGH BYTE
;Y = INDEX TO LEAST SIGNIFICANT BYTE
;X = NUMBER OF BYTES

;ROTATE LEFT ONE BIT

LOOP:

LDA   (PTR),Y
ROL   A
STA   (PTR),Y
INY
DEX
BNE   LOOP

;GET NEXT BYTE
;ROTATE BIT 7 := CARRY, CARRY := BIT 0
;STORE NEW VALUE
;INCREMENT TO NEXT BYTE
;DECREMENT COUNTER
;CONTINUE THROUGH ALL THE BYTES

;DECREMENT NUMBER OF SHIFTS
DEC   NBITS
BNE   RLLP

;DECREMENT SHIFT COUNTER
;CONTINUE UNTIL DONE
EXIT:
RTS

;DATA SECTION
NBITS: .BLOCK 1 ;NUMBER OF BITS TO SHIFT
LENGTH: .BLOCK 1 ;LENGTH OF OPERAND

;
;
SAMPLE EXECUTION:
;
;
SC0710:
LDA AYADR+1 ;PUSH STARTING ADDRESS OF OPERAND
PHA
LDA AYADR
PHA

LDA #SZAY ;PUSH LENGTH OF OPERAND
PHA

LDA SHIFTS ;PUSH NUMBER OF SHIFTS
PHA
JSR MPRL ;ROTATE
BRK ;RESULT OF ROTATING $AY = EDCBA987654321H$, 4 BITS IS
;
; IN MEMORY $AY = 01EH$
;
$AY+1 = 032H$
;
$AY+2 = 054H$
;
$AY+3 = 076H$
;
$AY+4 = 098H$
;
$AY+5 = 0BAH$
;
$AY+6 = 0DCH$

JMP SC0710

;
;DATA SECTION
SZAY: .EQU 7 ;LENGTH OF OPERAND IN BYTES
SHIFTS: .BYTE 4 ;NUMBER OF SHIFTS
AYADR: .WORD AY ;ADDRESS OF OPERAND
AY: .BYTE 21H, 43H, 65H, 87H, 0A9H, 0CBH, 0EDH

.END ;PROGRAM
String Compare (STRCMP)

Compares two strings and sets the Carry and Zero flags appropriately. The Zero flag is set to 1 if the strings are identical and to 0 otherwise. The Carry flag is set to 0 if the string with the address higher in the stack (string 2) is larger than the other string (string 1); the Carry flag is set to 1 otherwise. The strings are a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length. If the two strings are identical through the length of the shorter, then the longer string is considered to be larger.

Procedure: The program first determines which string is shorter from the lengths which precede the actual characters. It then compares the strings one byte at a time through the length of the shorter. If the program finds corresponding bytes that are not the same through the length of the shorter, the program sets the flags by comparing the lengths.

Registers Used: All
Execution Time:
1. If the strings are not identical through the length of the shorter, the approximate execution time is
   \[ 81 + 19 \times \text{NUMBER OF CHARACTERS COMPARED.} \]
   If, for example, the routine compares five characters before finding a difference, the execution time is
   \[ 81 + 19 \times 5 = 81 + 95 = 176 \text{ cycles.} \]
2. If the strings are identical through the length of the shorter, the approximate execution time is
   \[ 93 + 19 \times \text{LENGTH OF SHORTER STRING.} \]
   If, for example, the shorter string is eight bytes long, the execution time is
   \[ 93 + 19 \times 8 = 93 + 152 = 245 \text{ cycles.} \]
Program Size: 52 bytes
Data Memory Required: Four bytes on page 0, two bytes starting at address S1ADR (00D016 in the listing) for a pointer to string 1 and two bytes starting at address S2ADR (00D216 in the listing) for a pointer to string 2.

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of starting address of string 2
More significant byte of starting address of string 2
Less significant byte of starting address of string 1
More significant byte of starting address of string 1

Exit Conditions

Flags set as if string 2 had been subtracted from string 1 or, if the strings are equal through the length of the shorter, as if the length of string 2 had been subtracted from the length of string 1.

Zero flag = 1 if the strings are identical, 0 if they are not identical.

Carry flag = 0 if string 2 is larger than string 1, 1 if they are identical or string 1 is larger.
If the strings are the same through the length of the shorter, the longer one is considered to be larger.
Examples

1. Data: String 1 = 05'PRINT' (05 is the length of the string)
   String 2 = 03'END' (03 is the length of the string)
   Result: Zero flag = 0 (strings are not identical)
           Carry flag = 1 (string 2 is not larger than string 1)

2. Data: String 1 = 05'PRINT' (05 is the length of the string)
   String 2 = 02'PR' (02 is the length of the string)
   Result: Zero flag = 0 (strings are not identical)
           Carry flag = 1 (string 2 is not larger than string 1)

3. Data: String 1 = 05'PRINT' (05 is the length of the string)
   String 2 = 06'SYSTEM' (06 is the length of the string)
   Result: Zero flag = 0 (strings are not identical)
           Carry flag = 0 (string 2 is larger than string 1)

The longer string (string 1) is considered to be larger. If you want to determine whether string 2 is an abbreviation of string 1, you could use Subroutine 8C (FIND THE POSITION OF A SUBSTRING) and determine whether string 2 was part of string 1 and started at the first character.

We are assuming here that the strings consist of ASCII characters. Note that the byte preceding the actual characters contains a hexadecimal number (the length of the string), not a character. We have represented this byte as two hexadecimal digits in front of the string; the string itself is surrounded by single quotation marks.

Note also that this particular routine treats spaces like any other characters. If for example, the strings are ASCII, the routine will find that SPRINGMAID is larger than SPRING MAID, since an ASCII M (4D₁₆) is larger than an ASCII space (20₁₆).

---

Title
Name: String compare
   STRCMP

Purpose: Compare 2 strings and return C and Z flags set or cleared.

Entry: TOP OF STACK
   Low byte of return address,
   High byte of return address,
   Low byte of string 2 address,
   High byte of string 2 address,
   Low byte of string 1 address,
   High byte of string 1 address

   A string is a maximum of 255 bytes long plus a length byte which precedes it.

Exit: IF string 1 = string 2 THEN
      Z=1,C=1

IF string 1 > string 2 THEN
  Z=0, C=1
IF string 1 < string 2 THEN
  Z=0, C=0

Registers used: All

Time: Worst case timing for strings which are equal.
  93 cycles maximum overhead plus (19 * length)

Size: Program 52 bytes
  Data 4 bytes in page zero

;EQUATES
S1ADR .EQU 0D0H ; PAGE ZERO POINTER TO STRING 1
S2ADR .EQU 0D2H ; PAGE ZERO POINTER TO STRING 2

STRCMP:
;GET RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET THE STARTING ADDRESS OF STRING 2
PLA
STA S2ADR
PLA
STA S2ADR+1

;GET THE STARTING ADDRESS OF STRING 1
PLA
STA S1ADR
PLA
STA S1ADR+1

;RESTORE RETURN ADDRESS
TXA
PHA
TYA
PHA

; DETERMINE WHICH STRING IS SHORTER
LDY #0
LDA (S1ADR),Y ; GET LENGTH OF STRING #1
CMP (S2ADR),Y
BCC BEGCMP ; IF STRING #2 IS SHORTER THEN
LDA (S2ADR),Y ; USE ITS LENGTH INSTEAD

; COMPARE THE STRINGS THROUGH THE LENGTH OF THE SHORTER STRING
STRING MANIPULATIONS

BEGCMP:
TAX
BEQ TSTLEN ; X IS THE LENGTH OF THE SHORTER STRING
BEQ TSTLEN ; BRANCH IF LENGTH IS ZERO
LDY #1 ; POINT AT FIRST CHARACTER OF STRINGS
CMPLP:
LDA (S1ADR),Y
CMP (S2ADR),Y
BNE EXIT ; BRANCH IF CHARACTERS ARE NOT EQUAL
; Z,C WILL BE PROPERLY SET OR CLEARED
; ELSE
INY ; NEXT CHARACTER
DEX ; DECREMENT COUNTER
BNE CMPLP ; CONTINUE UNTIL ALL BYTES ARE COMPARED

; THE 2 STRINGS ARE EQUAL TO THE LENGTH OF THE SHORTER
; SO USE THE LengthS AS THE BASIS FOR SETTING THE FLAGS
TSTLEN:
LDY #0 ; COMPARE LENGTHS
LDA (S1ADR),Y
CMP (S2ADR),Y ; SET OR CLEAR THE FLAGS

; EXIT FROM STRING COMPARE
EXIT:
RTS
;
;
SAMPLE EXECUTION:
;
;
SC0801:
LDA SADR1+1 ; PUSH STARTING ADDRESS OF STRING 1
PHA
LDA SADR1
PHA
LDA SADR2+1 ; PUSH STARTING ADDRESS OF STRING 2
PHA
LDA SADR2
PHA
JSR STRCMP ; COMPARE
BKR ; RESULT OF COMPARING "STRING 1" AND "STRING 2"
; IS STRING 1 LESS THAN STRING 2 SO
; Z=0,C=0
JMP SC0801 ; LOOP FOR ANOTHER TEST

; TEST DATA, CHANGE TO TEST OTHER VALUES
SADR1 .WORD S1
SADR2 .WORD S2
S1 .BYTE 20H,"STRING 1"
S2 .BYTE 20H,"STRING 2"
.END ; PROGRAM
String Concatenation (CONCAT)

Combines (concatenates) two strings, placing the second immediately after the first in memory. If the concatenation would produce a string longer than a specified maximum, the program concatenates only enough of string 2 to give the combined string its maximum length. The Carry flag is cleared if all of string 2 can be concatenated and set to 1 if part of string 2 must be dropped. Both strings are a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length.

**Procedure:** The program uses the length of string 1 to determine where to start adding characters and the length of string 2 to determine how many characters to add. If the sum of the lengths exceeds the maximum, the program indicates an overflow and reduces the number of characters it must add (the number is the maximum length minus the length of string 1). It then moves the appropriate number of characters from string 2 to the end of string 1, updates the length of string 1, and sets the Carry flag to indicate whether any characters had to be discarded.

**Registers Used:** All
**Execution Time:** Approximately 40 * NUMBER OF CHARACTERS CONCATENATED plus 164 cycles overhead. The NUMBER OF CHARACTERS CONCATENATED is normally the length of string 2, but will be the maximum length of string 1 minus its current length if the combined string would be longer than the maximum. If, for example, NUMBER OF CHARACTERS CONCATENATED is $14_{16} (20_{10})$, the execution time is

$$40 \times 20 + 161 = 800 + 164 = 964 \text{ cycles.}$$

**Program Size:** 141 bytes

**Data Memory Required:** Seven bytes anywhere in RAM plus four bytes on page 0. The seven bytes anywhere in RAM are temporary storage for the maximum length of string 1 (1 byte at address MAXLEN), the length of string 1 (1 byte at address S1LEN), the length of string 2 (1 byte at address S2LEN), a running index for string 1 (1 byte at address S1IDX), a running index for string 2 (1 byte at address S2IDX), a concatenation counter (1 byte at address COUNT), and a flag that indicates whether the combined strings overflowed (1 byte at address STRGOV). The four bytes on page 0 hold pointers to string 1 (two bytes starting at address S1ADR, address 00D016 in the listing) and to string 2 (two bytes starting at address S2ADR, address 00D016 in the listing).

**Special Cases:**
1. If the concatenation would result in a string longer than the specified maximum length, the program concatenates only enough of string 2 to reach the maximum. If any of string 2 must be truncated, the Carry flag is set to 1.
2. If string 2 has a length of zero, the program exits with the Carry flag cleared (no errors) and string 1 unchanged. That is, a length of zero for either string is interpreted as zero, not 256.
3. If the original length of string 1 exceeds the specified maximum length, the program exits with the Carry flag set to 1 (indicating an error) and string 1 unchanged.
Entry Conditions
Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Maximum length of string 1
- Less significant byte of starting address of string 2
- More significant byte of starting address of string 2
- Less significant byte of starting address of string 1
- More significant byte of starting address of string 1

Exit Conditions

String 2 concatenated at the end of string 1 and the length of string 1 increased appropriately. If the resulting string would exceed the maximum length, only the part of string 2 that would give string 1 its maximum length is concatenated. If any part of string 2 must be dropped, the Carry flag is set to 1. Otherwise, the Carry flag is cleared.

Examples

1. Data: Maximum length of string 1 = 0E₁₆ = 14₁₀
   String 1 = 07'JOHNSON' (07 is the length of the string)
   String 2 = 05', DON' (05 is the length of the string)

   Result: String 1 = 0C'JOHNSON, DON'
           (0C₁₆ = 12₁₀ is the length of the combined string with string 2 placed after string 1).
           Carry = 0, since the concatenation did not produce a string exceeding the maximum length.

2. Data: Maximum length of string 1 = 0E₁₆ = 14₁₀
   String 1 = 07'JOHNSON' (07 is the length of the string)
   String 2 = 09', RICHARD' (09 is the length of the string)

   Result: String 1 = 0E'JOHNSON, RICHA'
           (0E₁₆ = 14₁₀ is the maximum length allowed, so the last two characters of string 2 have been dropped.)
           Carry = 1, since the concatenation produced a string longer than the maximum length.

Note that we are representing the initial byte (containing the length of the string) as two hexadecimal digits in both examples.
Title: String Concatenation
Name: CONCAT

Purpose: Concatenate 2 strings into one string.

Entry:
TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Maximum length of string 1,
- Low byte of string 2 address,
- High byte of string 2 address,
- Low byte of string 1 address,
- High byte of string 1 address

A string is a maximum of 255 bytes long plus a length byte which precedes it.

Exit:
string 1 := string 1 concatenated with string 2;
If no errors then
   CARRY := 0
else
   begin
      CARRY := 1
      if the concatenation makes string 1 too long concatenate only the part of string 2
      which will result in string 1 having its maximum length
      if length(string1) > maximum length then
         no concatenation is done
   end;

Registers used: All

Time: Approximately 40 * (length of string 2) cycles
- plus 161 cycles overhead

Size: Program 141 bytes
- Data 7 bytes plus
- 4 bytes in page zero

;EQUATES
S1ADR .EQU 0D0H ;PAGE ZERO POINTER TO STRING 1
S2ADR .EQU 0D2H ;PAGE ZERO POINTER TO STRING 2

CONCAT:
;GET RETURN ADDRESS
PLA
TAY ;SAVE LOW BYTE
PLA
TAX ;SAVE HIGH BYTE
; GET MAXIMUM LENGTH OF STRING 1
PLA
STA MAXLEN

; GET THE STARTING ADDRESS OF STRING 2
PLA
STA $2ADR
PLA
STA $2ADR+1

; GET THE STARTING ADDRESS OF STRING 1
PLA
STA $1ADR
PLA
STA $1ADR+1

; RESTORE RETURN ADDRESS
TXA
PHA

; RESTORE HIGH BYTE
TYA
PHA

; RESTORE LOW BYTE

; DETERMINE WHERE TO START CONCATENATING
LDY #0
LDA ($1ADR),Y
STAC $1LEN
STAC $1IDX
INC $1IDX
LDA ($1IDX),Y
STA $1IDX

; START CONCATENATING AT THE END OF STRING 1
LDA ($2ADR),Y
STA $2LEN
LDA $1
STA $2IDX

; START CONCATENATION AT BEGINNING OF STRING 2

; DETERMINE THE NUMBER OF CHARACTERS TO CONCATENATE
LDA $2LEN
CLC
ADC $1LEN

; ADD TO CURRENT LENGTH OF STRING 1

; BRANCH IF LENGTH WILL EXCEED 255 BYTES
CMP MAXLEN

; CHECK AGAINST MAXIMUM LENGTH
BCE TOOLNG

; BRANCH IF LENGTH DOES NOT EXCEED MAXIMUM

BCC LENOK

; RESULTING STRING WILL BE TOO LONG SO
; INDICATE A STRING OVERFLOW, STRGOV := 0FFH
; SET NUMBER OF CHARACTERS TO CONCATENATE = MAXLEN - $1LEN
; SET LENGTH OF STRING 1 TO MAXIMUM LENGTH

TOOLNG:

LDA #0FFH
STA STRGOV

; INDICATE OVERFLOW

LDA MAXLEN
SEC
SBC $1LEN
BCC EXIT

; EXIT IF MAXIMUM LENGTH < STRING 1 LENGTH
8B STRING CONCATENATION (CONCAT)

; (THE ORIGINAL STRING WAS TOO LONG !!)
STACOUNT
;SET COUNT TO S1LEN - MAXLEN
LDAMAXLEN
STAS1LEN
;SET LENGTH OF STRING 1 TO MAXIMUM
JMPDOCAT
;PERFORM CONCATENATION

;RESULTING LENGTH DOES NOT EXCEED MAXIMUM
;LENGTH OF STRING 1 = S1LEN + S2LEN
;INDICATE NO OVERFLOW, STRGOV := 0
;SET NUMBER OF CHARACTERS TO CONCATENATE TO LENGTH OF STRING 2
LENOK:
STAS1LEN
;SAVE THE SUM OF THE 2 LENGTHS
LDA#0
STASTRGOV
;INDICATE NO OVERFLOW
LDA S2LEN
STACOUNT
;COUNT := LENGTH OF STRING 2

;CONCATENATE THE STRINGS
DOCAT:
LDA COUNT
BEQEXIT
;EXIT IF NO BYTES TO CONCATENATE

CATLP:
LDYS2IDX
LDA (S2ADR),Y
;GET NEXT BYTE FROM STRING 2
LDYS1IDX
STAS1ADR,Y
;MOVE IT TO END OF STRING 1
INC S1IDX
;INCREMENT STRING 1 INDEX
INC S2IDX
;INCREMENT STRING 2 INDEX
DEC COUNT
;DECREMENT COUNTER
BNECATLP
;CONTINUE UNTIL COUNT = 0

EXIT:
LDA S1LEN
LDY#0
STASTS1ADR,Y
LDA STRGOV
;GET OVERFLOW INDICATOR
ROR A
;CARRY = 1 IF OVERLOW, 0 IF NOT
RTS

;DATA
MAXLEN:.BLOCK1
;MAXIMUM LENGTH OF S1
S1LEN:.BLOCK1
;LENGTH OF S1
S2LEN:.BLOCK1
;LENGTH OF S2
S1IDX:.BLOCK1
;RUNNING INDEX INTO S1
S2IDX:.BLOCK1
;RUNNING INDEX INTO S2
COUNT:.BLOCK1
;CONCATENATION COUNTER
STRGOV:.BLOCK1
;STRING OVERFLOW FLAG

; SAMPLE EXECUTION:
;
; SC0802:
LDA  SADR1+1 ;PUSH ADDRESS OF STRING 1
PHA
LDA  SADR1
PHA
LDA  SADR2+1 ;PUSH ADDRESS OF STRING 2
PHA
LDA  SADR2
PHA
LDA  $20H ;PUSH MAXIMUM LENGTH OF STRING 1
PHA
JSR  CONCAT ;CONCATENATE
BRK  ;RESULT OF CONCATENATING "LASTNAME" AND ", FIRSTNAME"
     ; IS S1 = 13H,"LASTNAME, FIRSTNAME"
JMP  SC0802 ;LOOP FOR ANOTHER TEST

;TEST DATA, CHANGE FOR OTHER VALUES
SADR1 .WORD  S1    ;STARTING ADDRESS OF STRING 1
SADR2 .WORD  S2    ;STARTING ADDRESS OF STRING 2
S1   .BYTE   8H    ;LENGTH OF S1
     .BYTE   "LASTNAME "    ;32 BYTE MAX LENGTH
S2   .BYTE   0BH   ;LENGTH OF S2
     .BYTE   ", FIRSTNAME"    ;32 BYTE MAX LENGTH
.END  ;PROGRAM
Find the Position of a Substring (POS) 8C

Searches for the first occurrence of a substring within a string. Returns the index at which the substring starts if it is found and 0 if it is not found. The string and the substring are both a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length. Thus, if the substring is found, its starting index cannot be less than 1 or more than 255.

Procedure: The program moves through the string searching for the substring until it either finds a match or the remaining part of the string is shorter than the substring and hence cannot possibly contain it. If the substring does not appear in the string, the program clears the accumulator; otherwise, the program places the starting index of the substring in the accumulator.

Registers Used: All

Execution Time: Data-dependent, but the overhead is 135 cycles, each successful match of one character takes 47 cycles, and each unsuccessful match of one character takes 50 cycles. The worst case occurs when the string and substring always match except for the last character in the substring, such as

String = 'AAAAAAAAB'
Substring = 'AAB'

The execution time in that case is

\[(\text{STRING LENGTH} - \text{SUBSTRING LENGTH} + 1) \times (47 \times (\text{SUBSTRING LENGTH} - 1) + 50) + 135\]

If, for example, STRING LENGTH = 9 and SUBSTRING LENGTH = 3, the execution time is

\[(9 - 3 + 1) \times (47 \times (3 - 1) + 50) + 135 = 7 \times 144 + 135 = 1008 + 135 = 1143\]

cycles.

Program Size: 124 bytes

Data Memory Required: Six bytes anywhere in RAM plus four bytes on page 0. The six bytes anywhere in RAM are temporary storage for the length of the string (one byte at address SLEN), the length of the substring (one byte at address SUBLEN), a running index into the string (one byte at address SIDX), a running index into the substring (one byte at address SUBIDX), a search counter (one byte at address COUNT), and an index into the string (one byte at address INDEX). The four bytes on page 0 hold pointers to the substring (two bytes starting at address SUBSTG, 00D016 in the listing) and to the string (two bytes starting at address STRING, 00D216 in the listing).

Special Cases:

1. If either the string or the substring has a length of zero, the program exits with zero in the accumulator, indicating that it did not find the substring.

2. If the substring is longer than the string, the program exits with zero in the accumulator, indicating that it did not find the substring.

3. If the program returns an index of 1, the substring may be regarded as an abbreviation of the string. That is, the substring occurs in the string, starting at the first character. A typical example would be a string PRINT and a substring PR.

4. If the substring occurs more than once in the string, the program will return only the index to the first occurrence (the occurrence with the lowest starting index).
Entry Conditions

Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of starting address of substring
More significant byte of starting address of substring
Less significant byte of starting address of string
More significant byte of starting address of string

Exit Conditions

Accumulator contains index at which first occurrence of substring starts if it is found; accumulator contains zero if substring is not found.

Examples

1. Data: String = 1D 'ENTER SPEED IN MILES PER HOUR' (1D₁₆ = 29₁₀ is the length of the string).
   Substring = 05 'MILES' (05 is the length of the substring)
   Result: Accumulator contains 10₁₆ (16₁₀), the index at which the substring 'MILES' starts.

2. Data: String = 1B 'SALES FIGURES FOR JUNE 1981' (1B₁₆ = 27₁₀ is the length of the string)
   Substring = 04 'JUNE' (04 is the length of the substring)
   Result: Accumulator contains 13₁₆ (19₁₀), the index at which the substring 'JUNE' starts.

3. Data: String = 10 'LET Y₁ = X₁ + R7' (10₁₆ = 16₁₀ is the length of the string)
   Substring = 02 'R4' (02 is the length of the substring)
   Result: Accumulator contains 00, since the substring 'R4' does not appear in the string LET Y₁ = X₁ + R7.

4. Data: String = 07 'RESTORE' (07 is the length of the string)
   Substring = 03 'RES' (03 is the length of the substring)
   Result: Accumulator contains 01, the index at which the substring ‘RES’ starts. An index of 01 indicates that the substring could be an abbreviation of the string; such abbreviations are, for example, often used in interactive programs (such as BASIC interpreters) to save on typing and storage.
Title: Find the position of a substring in a string

Name: POS

Purpose: Search for the first occurrence of a substring within a string and return its starting index. If the substring is not found a 0 is returned.

Entry: TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Low byte of substring address,
- High byte of substring address,
- Low byte of string address,
- High byte of string address

A string is a maximum of 255 bytes long plus a length byte which precedes it.

Exit: If the substring is found then
- Register A = its starting index
else
- Register A = 0

Registers used: All

Time: Since the algorithm is so data dependent a simple formula is impossible but the following statements are true and a worst case is given below:

135 cycles overhead.
- Each match of 1 character takes 47 cycles
- A mismatch takes 50 cycles.

Worst case timing will be when the string and substring always match except for the last character of the substring, Such as:
- string = 'AAAAAAAAAAAB'
- substring = 'AAB'

135 cycles overhead plus
- (length(string) - length(substring) + 1) * (((length(substring)-1) * 47) + 50)

Size:
- Program 124 bytes
- Data 6 bytes plus
- 4 bytes in page zero

;EQUATES
SUBSTG .EQU 0D0H ; PAGE ZERO POINTER TO SUBSTRING
STRING .EQU 0D2H ; PAGE ZERO POINTER TO STRING
POS:
; GET RETURN ADDRESS
PLA
TAY ; SAVE LOW BYTE
PLA
TAX ; SAVE HIGH BYTE
; GET THE STARTING ADDRESS OF SUBSTRING
PLA
STA SUBSTG
PLA
STA SUBSTG+1
; GET THE STARTING ADDRESS OF STRING
PLA
STA STRING
PLA
STA STRING+1
; RESTORE RETURN ADDRESS
TXA
PHA ; RESTORE HIGH BYTE
TYA
PHA ; RESTORE LOW BYTE
; SET UP TEMPORARY LENGTH AND INDEX BYTES
LDY #0
LDA (STRING),Y ; GET LENGTH OF STRING
BEQ NOTFND ; EXIT IF LENGTH OF STRING = 0
STA SLEN
LDA (SUBSTG),Y ; GET LENGTH OF SUBSTRING
BEQ NOTFND ; EXIT IF LENGTH OF SUBSTRING = 0
STA SUBLEN
; IF THE SUBSTRING IS LONGER THAN THE STRING DECLARE THE
; SUBSTRING NOT FOUND
LDA SUBLEN
CMP SLEN
BEQ LENOK ; CANNOT FIND SUBSTRING IF IT IS LONGER THAN
; STRING
BCS NOTFND ; START SEARCH, CONTINUE UNTIL REMAINING STRING SHORTER THAN SUBSTRING
LENOK:
LDA $1 ; START LOOKING AT FIRST CHARACTER OF STRING
STA INDEX
LDA SLEN ; CONTINUE UNTIL REMAINING STRING TOO SHORT
SEC
SBC SUBLEN
STA COUNT
INC COUNT
; SEARCH FOR SUBSTRING IN STRING
SLP1:
8C FIND THE POSITION OF A SUBSTRING (POS) 359

```
LDA INDEX
STA SIDX ;START STRING INDEX AT INDEX
LDA #1
STA SUBIDX ;START SUBSTRING INDEX AT 1

;LOOK FOR SUBSTRING BEGINNING AT INDEX
CMPLP:
LDY SIDX
LDA (STRING),Y ;GET NEXT CHARACTER FROM STRING
LDY SUBIDX
CMP (SUBSTG),Y ;COMPARE TO NEXT CHARACTER IN SUBSTRING
BNE SLP2 ;BRANCH IF SUBSTRING IS NOT HERE
LDY SUBIDX
CPY SUBLEN ;TEST IF WE ARE DONE
BEQ FOUND ;BRANCH IF ALL CHARACTERS WERE EQUAL
INY ;ELSE INCREMENT TO NEXT CHARACTER
STY SUBIDX
INC SIDX ;INCREMENT STRING INDEX
JMP CMPLP ;CONTINUE

;ARRIVE HERE IF THE SUBSTRING IS NOT YET FOUND
SLP2:
INC INDEX ;INCREMENT INDEX
DEC COUNT ;DECREMENT COUNT
BNE SLP1 ;BRANCH IF NOT DONE
BEQ NOTFND ;ELSE EXIT NOT FOUND

FOUND:
LDA INDEX ;SUBSTRING FOUND, A = STARTING INDEX
JMP EXIT

NOTFND:
LDA #0 ;SUBSTRING NOT FOUND, A = 0

EXIT
RTS

;DATA
SLEN: .BLOCK 1 ;LENGTH OF STRING
SUBLEN: .BLOCK 1 ;LENGTH OF SUBSTRING
SIDX: .BLOCK 1 ;RUNNING INDEX INTO STRING
SUBIDX: .BLOCK 1 ;RUNNING INDEX INTO SUBSTRING
COUNT: .BLOCK 1 ;SEARCH COUNTER
INDEX: .BLOCK 1 ;CURRENT INDEX INTO STRING

; SAMPLE EXECUTION:

SC0803:
LDA SADR+1 ;PUSH ADDRESS OF THE STRING
```
PHA
LDA SADR
PHA
LDA SUBADR+1 ;PUSH ADDRESS OF THE SUBSTRING
PHA
LDA SUBADR
PHA
JSR POS ;FIND POSITION OF SUBSTRING
BRK
;RESULT OF SEARCHING "AAAAAAAAAB" FOR "AAB" IS
JMP SC0803 ;REGISTER A=8
;LOOP FOR ANOTHER TEST

;TEST DATA, CHANGE FOR OTHER VALUES
SADR .WORD STG
SUBADR .WORD SSTG
STG .BYTE 0AH ;LENGTH OF STRING
   .BYTE "AAAAAAAAAB " ;32 BYTE MAX LENGTH
SSTG .BYTE 3H ;LENGTH OF SUBSTRING
   .BYTE "AAB " ;32 BYTE MAX LENGTH
.END ;PROGRAM
Copy a Substring from a String (COPY) 8D

Copies a substring from a string, given a starting index and the number of bytes to copy. The strings are a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length. If the starting index of the substring is zero (i.e., the substring would start in the length byte) or is beyond the end of the string, the substring is given a length of zero and the Carry flag is set to 1. If the substring would exceed its maximum length or would extend beyond the end of the string, then only the maximum number or the available number of characters (up to the end of the string) are placed in the substring, and the Carry flag is set to 1. If the substring can be formed as specified, the Carry flag is cleared.

Procedure: The program exits immediately if the number of bytes to copy, the maximum length of the substring, or the starting index is zero. It also exits immediately if the starting index exceeds the length of the string. If none of these conditions holds, the program checks if the number of bytes to copy exceeds either the maximum length of the substring or the number of characters available in the string. If either one is exceeded, the program reduces the number of bytes to copy appropriately. It then copies the proper number of bytes from the string to the substring. The program clears the Carry flag if the substring can be formed as specified and sets the Carry flag if it cannot.

Registers Used: All
Execution Time: Approximately 36 * NUMBER OF BYTES COPIED plus 200 cycles overhead.
NUMBER OF BYTES COPIED is the number specified (if no problems occur) or the number available or the maximum length of the substring if the copying would go beyond the end of either the string or the substring. If, for example, NUMBER OF BYTES COPIED = 1210 (0C16), the execution time is

\[36 \times 12 + 200 = 432 + 200 = 632\] cycles.

Program Size: 173 bytes.
Data Memory Required: Six bytes anywhere in RAM plus four bytes on page 0. The six bytes anywhere in RAM hold the length of the string (one byte at address SLEN), the length of the substring (one byte at address DLEN), the maximum length of the substring (one byte at address MAXLEN), the search counter (one byte at address COUNT), the current index into the string (one byte at address INDEX), and an error flag (one byte at address CPYERR). The four bytes on page 0 hold pointers to the string (two bytes starting at address DSTRG, 00D016 in the listing) and to the substring (two bytes starting at address SSTRG, 00D216 in the listing).

Special Cases:
1. If the number of bytes to copy is zero, the program assigns the substring a length of zero and clears the Carry flag, indicating no error.
2. If the maximum length of the substring is zero, the program assigns the substring a length of zero and sets the Carry flag to 1, indicating an error.
3. If the starting index of the substring is zero, the program assigns the substring a length of zero and sets the Carry flag to 1, indicating an error.
4. If the source string does not even reach the specified starting index, the program assigns the substring a length of zero and sets the Carry flag to 1, indicating an error.
5. If the substring would extend beyond the end of the source string, the program places all the available characters in the substring and sets the Carry flag to 1, indicating an error. The available characters are the ones from the starting index to the end of the string.
6. If the substring would exceed its specified maximum length, the program places only the specified maximum number of characters in the substring. It sets the Carry flag to 1, indicating an error.
Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Maximum length of substring (destination string)
Less significant byte of starting address of substring (destination string)
More significant byte of starting address of substring (destination string)
Number of bytes to copy
Starting index to copy from
Less significant byte of starting address of string (source string)
More significant byte of starting address of string (source string)

Exit Conditions
Substring contains characters copied from string. If the starting index is zero, the maximum length of the substring is zero, or the starting index is beyond the length of the string, the substring will have a length of zero and the Carry flag will be set to 1. If the substring would extend beyond the end of the string or would exceed its specified maximum length, only the available characters from the string (up to the maximum length of the substring) are copied into the substring; the Carry flag is set in this case also. If no problems occur in forming the substring, the Carry flag is cleared.

Examples

1. Data: String = 10'LET Y1 = R7 + X4'
   \(10_{16} = 16_{10}\) is the length of the string
   Maximum length of substring = 2
   Number of bytes to copy = 2
   Starting index = 5
   Result: Substring = 02'Y1' (2 is the length of the substring)
   Carry = 0, since no problems occur in forming the substring

2. Data: String = 0E'8657 POWELL ST'
   \(0E_{16} = 14_{10}\) is the length of the string
   Maximum length of substring = 10_{16} = 16_{10}
   Number of bytes to copy = 0D_{16} = 17_{10}
   Starting index = 06
   Result: Substring = 09'POWELL ST' (09 is the length of the substring)
   Carry = 1, since there were not enough characters available in the string to provide the specified number of bytes to copy.

3. Data: String = 16'9414 HEGENBERGER DRIVE'
   \(16_{16} = 22_{10}\) is the length of the string
   Maximum length of substring = 10_{16} = 16_{10}
   Number of bytes to copy = 11_{16} = 17_{10}
   Starting index = 06
   Result: Substring = 10'HEGENBERGER DRIV'
   \(10_{16} = 16_{10}\) is the length of the substring
   Carry = 1, since the number of bytes to copy exceeded the maximum length of the substring.
Title: Copy a substring from a string
Name: Copy

Purpose: Copy a substring from a string given a starting index and the number of bytes.

Entry: TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Maximum length of destination string,
- Low byte of destination string address,
- High byte of destination string address,
- Number of bytes to copy,
- Starting index to copy from,
- Low byte of source string address,
- High byte of source string address

A string is a maximum of 255 bytes long plus a length byte which precedes it.

Exit: Destination string := The substring from the string.
if no errors then
    CARRY := 0
else
    begin
        the following conditions cause an error and the CARRY flag = 1.
        if (index = 0) or (maxlen = 0) or
        (index > length(sstrg)) then
            the destination string will have a zero length.
        if (index + count) > length(sstrg)) then
            the destination string becomes everything from index to the end of source string.
    END;

Registers used: All

Time: Approximately (36 * count) cycles plus 200 cycles overhead.

Size: Program 173 bytes
Data 6 bytes plus 4 bytes in page zero

;EQUATES
DSTRG .EQU 0D0H  ;PAGE ZERO POINTER TO DESTINATION STRING
SSTRG .EQU 0D2H  ;PAGE ZERO POINTER TO SOURCE STRING
COPY:

; GET RETURN ADDRESS
PLA
TAY ; SAVE LOW BYTE
PLA
TAX ; SAVE HIGH BYTE

; GET MAXIMUM LENGTH OF DESTINATION STRING
PLA
STA MAXLEN

; GET STARTING ADDRESS OF DESTINATION STRING
PLA
STA DSTRG ; SAVE LOW BYTE
PLA
STA DSTRG+1 ; SAVE HIGH BYTE

; GET NUMBER OF BYTES TO COPY
PLA
STA COUNT

; GET STARTING INDEX OF SUBSTRING
PLA
STA INDEX

; GET STARTING ADDRESS OF SOURCE STRING
PLA
STA SSTRG ; SAVE LOW BYTE (NOTE SSTRG=SOURCE STRING)
PLA
STA SSTRG+1 ; SAVE HIGH BYTE

; RESTORE RETURN ADDRESS
TXA
PHA ; RESTORE HIGH BYTE
TYA
PHA ; RESTORE LOW BYTE

; INITIALIZE LENGTH OF DESTINATION STRING AND THE ERROR FLAG TO 0
LDA #0
STA DLEN ; LENGTH OF DESTINATION STRING IS ZERO
STA CPYERR ; ASSUME NO ERRORS

; CHECK FOR ZERO BYTES TO COPY OR ZERO MAXIMUM SUBSTRING LENGTH
LDA COUNT
BEQ OKEXIT ; BRANCH IF ZERO BYTES TO COPY, NO ERROR
; DSTRG WILL JUST HAVE ZERO LENGTH
LDA MAXLEN
BEQ EREXIT ; ERROR EXIT IF SUBSTRING HAS ZERO MAXIMUM LENGTH.

LDA INDEX
BEQ EREXIT ; ERROR EXIT IF STARTING INDEX IS ZERO

; CHECK IF THE SOURCE STRING REACHES THE STARTING INDEX
; IF NOT, EXIT
LDY #0
LDA (SSTRG),Y ;GET LENGTH OF SOURCE STRING
STA SLEN ;SAVE SOURCE LENGTH
CMP INDEX ;COMPARE TO STARTING INDEX
BCC EREXIT ;ERROR EXIT IF INDEX IS TOO LARGE

;CHECK THAT WE DO NOT COPY BEYOND THE END OF THE SOURCE STRING
;IF INDEX + COUNT - 1 > LENGTH(SSTRG) THEN
; COUNT := LENGTH(SSTRG) - INDEX + 1;
LDA INDEX
CLC
ADC COUNT ;BRANCH IF INDEX + COUNT > 255
TEX
DEX
CPX SLEN
BCC CNT1OK ;BRANCH IF INDEX + COUNT - 1 < LENGTH(SSTRG)
BEQ CNT1OK ;BRANCH IF EQUAL

;THE CALLER ASKED FOR TOO MANY CHARACTERS JUST RETURN EVERYTHING
; BETWEEN INDEX AND THE END OF THE SOURCE STRING.
; SO SET COUNT := LENGTH(SSTRG) - INDEX + 1;

RECALC:
LDA SLEN ;RECALCULATE COUNT
SEC
SBC INDEX
STA COUNT
INC COUNT ;COUNT := LENGTH(SSTRG) - INDEX + 1
LDA #0FFH
STA CPYERR ;INDICATE A TRUNCATION OF THE COUNT

;CHECK IF THE COUNT IS LESS THAN OR EQUAL TO THE MAXIMUM LENGTH OF THE
; DESTINATION STRING. IF NOT, THEN SET COUNT TO THE MAXIMUM LENGTH
; IF COUNT > MAXLEN THEN
; COUNT := MAXLEN

CNT1OK:
LDA COUNT ;IS COUNT > MAXIMUM SUBSTRING LENGTH ?
CMP MAXLEN
BCC CNT2OK ;BRANCH IF COUNT < MAX LENGTH
BEQ CNT2OK ;BRANCH IF COUNT = MAX LENGTH
LDA MAXLEN
STA COUNT ;ELSE COUNT := MAXLEN
LDA #0FFH
STA CPYERR ;INDICATE DESTINATION STRING OVERFLOW

;EVERYTHING IS SET UP SO MOVE THE SUBSTRING TO DESTINATION STRING

CNT2OK:
LDX COUNT ;REGISTER X WILL BE THE COUNTER
BEQ EREXIT ;ERROR EXIT IF COUNT IS ZERO
LDA #1 ;START WITH FIRST CHARACTER OF DESTINATION
STA DLEN ;DLEN IS RUNNING INDEX FOR DESTINATION
LDA #0FFH ;INDEX IS RUNNING INDEX FOR SOURCE

MVLP:
LDY INDEX
LDA (SSTRG),Y ;GET NEXT SOURCE CHARACTER
LDY DLEN
STA (DSTRG),Y ;MOVE NEXT CHARACTER TO DESTINATION
INC INDEX ;INCREASE SOURCE INDEX
INC DLEN ;INCREASE DESTINATION INDEX
DEX ;DECREASE COUNTER
BNE NVLP ;CONTINUE UNTIL COUNTER = 0
DEC DLEN ;SUBSTRING LENGTH = FINAL DESTINATION INDEX - 1
LDA CPYERR ;CHECK FOR ANY ERRORS
BNE EREXIT ;BRANCH IF A TRUNCATION OR STRING OVERFLOW

;GOOD EXIT
OKEXIT:
CLC
BCC EXIT

;ERROR EXIT
EREXIT:
SEC

;STORE LENGTH BYTE IN FRONT OF SUBSTRING
EXIT:
LDA DLEN
LDY $0
STA (DSTRG),Y ;SET LENGTH OF DESTINATION STRING
RTS

;DATA SECTION
SLEN: .BLOCK 1 ;LENGTH OF SOURCE STRING
DLEN: .BLOCK 1 ;LENGTH OF DESTINATION STRING
MAXLEN: .BLOCK 1 ;MAXIMUM LENGTH OF DESTINATION STRING
COUNT: .BLOCK 1 ;SEARCH COUNTER
INDEX: .BLOCK 1 ;CURRENT INDEX INTO STRING
CPYERR: .BLOCK 1 ;COPY ERROR FLAG

;SAMPLE EXECUTION:
SC0804:
LDA SADR+1 ;PUSH ADDRESS OF SOURCE STRING
PHA
LDA SADR
PHA
LDA IDX ;PUSH STARTING INDEX FOR COPYING
PHA
LDA CNT ;PUSH NUMBER OF CHARACTERS TO COPY
PHA
LDA DADR+1 ;PUSH ADDRESS OF DESTINATION STRING
PHA
LDA DADR
PHA
LDA MXLEN ;PUSH MAXIMUM LENGTH OF DESTINATION STRING
PHA
JSR COPY ;COPY
BRK
JMP SC0804

; RESULT OF COPYING 3 CHARACTERS STARTING AT INDEX 4
; FROM THE STRING "12.345E+10" IS 3,"345"
; LOOP FOR MORE TESTING

; DATA SECTION
IDX .BYTE 4
CNT .BYTE 3
MXLEN .BYTE 20H
SADR .WORD SSTG
DADR .WORD DSTG
SSTG .BYTE 0AH
    .BYTE "12.345E+10"
DSTG .BYTE 0
    .BYTE ""
Delete a Substring from a String (DELETE)

Deletes a substring from a string, given a starting index and a length. The string is a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length. The Carry flag is cleared if the deletion can be performed as specified. The Carry flag is set if the starting index is zero or beyond the length of the string; the string is left unchanged in either case. If the deletion extends beyond the end of the string, the Carry flag is set (to 1) and only the characters from the starting index to the end of the string are deleted.

Procedure: The program exits immediately if the starting index or the number of bytes to delete is zero. It also exits if the starting index is beyond the length of the string. If none of these conditions holds, the program checks to see if the string extends beyond the area to be deleted. If it does not, the program simply truncates the string by setting the new length to the starting index minus 1. If it does, the program compacts the resulting string by moving the bytes above the deleted area down. The program then determines the new string's length and exits with the Carry cleared if the specified number of bytes were deleted and set to 1 if any errors occurred.

Registers Used: All

Execution Time: Approximately

\[36 \times \text{NUMBER OF BYTES MOVED DOWN} + 165\]

where \text{NUMBER OF BYTES MOVED DOWN} is zero if the string can be truncated and is \text{STRING LENGTH - STARTING INDEX - NUMBER OF BYTES TO DELETE} + 1 if the string must be compacted.

Examples

1. \text{STRING LENGTH} = 20\text{16} (32\text{10})
   \text{STARTING INDEX} = 19\text{16} (25\text{10})
   \text{NUMBER OF BYTES TO DELETE} = 08

   Since there are exactly eight bytes left in the string starting at index 19\text{16}, all the routine must do is truncate the string. This takes
   \[36 \times 0 + 165 = 165\] cycles.

2. \text{STRING LENGTH} = 40\text{16} (64\text{10})
   \text{STARTING LENGTH} = 19\text{16} (25\text{10})
   \text{NUMBER OF BYTES TO DELETE} = 08

   Since there are 20\text{16} (32\text{16}) bytes above the truncated area, the routine must move them down eight positions. The execution time is
   \[36 \times 32 + 165 = 1152 + 165 = 1317\] cycles.

Data Memory Required: Five bytes anywhere in RAM plus two bytes on page 0. The five bytes anywhere in RAM hold the length of the string (one byte at address SLEN), the search counter (one byte at address COUNT), an index into the string (one byte at address INDEX), the source index for use during the move (one byte at address SIDX), and an error flag (one byte at address DELERR). The two bytes on page 0 hold a pointer to the string (starting at address STRG, 00D0\text{16} in the listing).

Special Cases:

1. If the number of bytes to delete is zero, the program exits with the Carry flag cleared (no errors) and the string unchanged.

2. If the string does not even extend to the specified starting index, the program exits with the Carry flag set to 1 (error indicated) and the string unchanged.

3. If the number of bytes to delete exceeds the number available, the program deletes all bytes from the starting index to the end of the string and exits with the Carry flag set to 1 (error indicated).
Entry Conditions

Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Number of bytes to delete
Starting index to delete from
Less significant byte of starting address of string
More significant byte of starting address of string

Exit Conditions

Substring deleted from string. If no errors occur, the Carry flag is cleared. If the starting index is zero or beyond the length of the string, the Carry flag is set and the string is unchanged. If the number of bytes to delete would go beyond the end of the string, the Carry flag is set and the characters from the starting index to the end of the string are deleted.

Examples

1. Data: String = 1E‘SALES FOR MARCH AND APRIL 1980’ (1E₁₆ = 30₁₀ is the length of the string)
   Number of bytes to delete = 0A₁₆ = 10₁₀
   Starting index to delete from = 10₁₆ = 16₁₀
   Result: String = 14‘SALES FOR MARCH 1980’ (14₁₆ = 20₁₀ is the length of the string with ten bytes deleted starting with the 16th character — the deleted material is ‘AND APRIL’).
   Carry = 0, since no problems occurred in the deletion.

2. Data: String = 28‘THE PRICE IS $3.00 ($2.00 BEFORE JUNE 1)’ (28₁₆ = 40₁₀ is the length of the string).
   Number of bytes to delete = 30₁₆ = 48₁₀
   Starting index to delete from = 13₁₆ = 19₁₀
   Result: String = 12‘THE PRICE IS $3.00’ (12₁₆ = 18₁₀ is the length of the string with all remaining bytes deleted).
   Carry = 1, since there were not as many bytes left in the string as were supposed to be deleted.
STRING MANIPULATIONS

; A string is a maximum of 255 bytes long plus a length byte which precedes it.
;
; Exit: Substring deleted.
; if no errors then
; CARRY := 0
; else
; begin
; the following conditions cause an error with the CARRY flag = 1.
; if (index = 0) or (index > length(string))
; then do not change the string
; if count is too large then
; delete only the characters from index to the end of the string
; end;
;
; Registers used: All
;
; Time: Approximately 36 * (LENGTH(STRG)−INDEX−COUNT+1)
; plus 165 cycles overhead.
;
; Size: Program 139 bytes
; Data 5 bytes plus
; 2 bytes in page zero
;
;
; EQUATES
STRG .EQU 0D0H ; PAGE ZERO POINTER TO SOURCE STRING

DELETE:
; GET RETURN ADDRESS
PLA
TAY
; SAVE LOW BYTE
PLA
TAX
; SAVE HIGH BYTE

; GET NUMBER OF BYTES TO DELETE
PLA
STA COUNT

; GET STARTING INDEX DELETION
PLA
STA INDEX

; GET STARTING ADDRESS OF STRING
PLA
STA STRG ; SAVE LOW BYTE
PLA
STA STRG+1 ; SAVE HIGH BYTE

; RESTORE RETURN ADDRESS
TXA
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PHA ;RESTORE HIGH BYTE
TYA ;RESTORE LOW BYTE
PHA ;INITIALIZE ERROR INDICATOR (DELERR) TO 0
;GET STRING LENGTH
LDY #0
STY DELERR
LDA (STRG), Y ;GET LENGTH OF STRING
STA SLEN ;SAVE STRING LENGTH

;CHECK FOR A NON ZERO COUNT AND INDEX
LDA COUNT
BEQ OKEXIT ;GOOD EXIT IF NOTHING TO DELETE
LDA INDEX
BEQ EREXIT ;ERROR EXIT IF STARTING INDEX = 0

;CHECK FOR STARTING INDEX WITHIN THE STRING
;EXIT IF IT IS NOT
LDA SLEN ;IS INDEX WITHIN THE STRING?
CMP INDEX
BCC EREXIT ;NO, TAKE ERROR EXIT

;BE SURE THE NUMBER OF CHARACTERS REQUESTED TO BE DELETED ARE PRESENT
;IF NOT THEN ONLY DELETE FROM THE INDEX TO THE END OF THE STRING
LDA INDEX
CLC
ADC COUNT ;TRUNCATE IF INDEX + COUNT > 255
BCS TRUNC ;ELSE JUST TRUNCATE THE STRING
STA SIDX ;SAVE INDEX + COUNT AS THE SOURCE INDEX
TAX ;X = INDEX + COUNT
DEX
CPX SLEN
BCC CNTOK ;BRANCH IF INDEX + COUNT - 1 < LENGTH(SSTRG)
BEQ TRUNC ;TRUNCATE BUT NO ERROR (EXACTLY ENOUGH
 ;CHARACTERS)
LDA #0FFH
STA DELERR ;INDICATE ERROR - NOT ENOUGH CHARACTERS TO
 ;DELETE

;TRUNCATE THE STRING - NO COMPACTING NECESSARY

TRUNC:
LDX INDEX ;STRING LENGTH = STARTING INDEX - 1
DEX
STX SLEN
LDA DELERR
BEQ OKEXIT ;GOOD EXIT
BNE EREXIT ;ERROR EXIT

;DELETE THE SUBSTRING BY COMPACTING
;MOVE ALL CHARACTERS ABOVE THE DELETED AREA DOWN

CNTOK:
;CALCULATE NUMBER OF CHARACTERS TO MOVE (SLEN - SIDX + 1)
LDA SLEN ;GET STRING LENGTH
SEC
SBC SIDX ;SUBTRACT STARTING INDEX
TAX
INX
BEQ OKEXIT ;BRANCH IF COUNT = 0

MVLP:
LDY SIDX
LDA (STRG),Y ;GET NEXT CHARACTER
LDY INDEX
STA (STRG),Y ;MOVE IT DOWN
INC INDEX ;INCREMENT DESTINATION INDEX
INC SIDX ;INCREMENT SOURCE INDEX
DEX ;DECREMENT COUNTER
BNE MVLP ;CONTINUE UNTIL COUNTER = 0
LDX INDEX ;STRING LENGTH = FINAL DESTINATION INDEX - 1
DEX
STX SLEN

;GOOD EXIT

OKEXIT:
CLC
BCC EXIT

;ERROR EXIT

EREEXIT:
SEC

EXIT:
LDA SLEN
LDY #0
STA (STRG),Y ;SET LENGTH OF STRING
RTS

;DATA
SLEN: .BLOCK 1 ;LENGTH OF SOURCE STRING
COUNT: .BLOCK 1 ;SEARCH COUNTER
INDEX: .BLOCK 1 ;CURRENT INDEX INTO STRING
SIDX: .BLOCK 1 ;SOURCE INDEX DURING MOVE
DELERR: .BLOCK 1 ;DELETE ERROR FLAG

;SAMPLE EXECUTION:

SC0805:
LDA SADR+1 ;PUSH STRING ADDRESS
PHA
LDA SADR
PHA
LDA IDX ;PUSH STARTING INDEX FOR DELETION
PHA
LDA CNT ;PUSH NUMBER OF CHARACTERS TO DELETE
PHA
JSR DELETE ;DELETE
BRK ;RESULT OF DELETING 4 CHARACTERS STARTING AT INDEX 1
; FROM "JOE HANOVER" IS "HANOVER"
JMP SC0805 ;LOOP FOR ANOTHER TEST

;DATA SECTION
IDX .BYTE 1 ;INDEX TO START OF DELETION
CNT .BYTE 4 ;NUMBER OF CHARACTERS TO DELETE
SADR .WORD SSTG
SSTG .BYTE 12 ;LENGTH OF STRING
    .BYTE "JOE HANOVER"
.END ;PROGRAM
Insert a Substring into a String (INSERT) 8F

Inserts a substring into a string, given a starting index. The string and substring are both a maximum of 255 bytes long and the actual characters are preceded by a byte containing the length. The Carry flag is cleared if the insertion can be accomplished with no problems. The Carry flag is set if the starting index is zero or beyond the length of the string. In the second case, the substring is concatenated to the end of the string. The Carry flag is also set if the string with the insertion would exceed a specified maximum length; in that case, the program inserts only enough of the substring to give the string its maximum length.

Procedure: The program exits immediately if the starting index is zero or if the length of the substring is zero. If neither of these conditions holds, the program checks to see if the insertion would produce a string longer than the maximum. If it would, the program truncates the substring. The program then checks to see if the starting index is within the string. If it is not, the program simply concatenates the substring by moving it to the memory locations immediately after the end of the string. If the starting index is within the string, the program must first open a space for the insertion by moving the remaining characters up in memory. This move must start at the highest address to avoid writing over any data. Finally, the program can move the substring into the open area. The program then determines the new string length and exits with the Carry flag set appropriately (to 0 if no problems occurred and to 1 if the starting index was zero, the substring had to be truncated, or the starting index was beyond the length of the string).

Registers Used: All

Execution Time: Approximately 36 • NUMBER OF BYTES MOVED + 36 • NUMBER OF BYTES INSERTED + 207

NUMBER OF BYTES MOVED is the number of bytes that must be moved to open up space for the insertion. If the starting index is beyond the end of the string, this is zero since the substring is simply concatenated to the string. Otherwise, this is STRING LENGTH — STARTING INDEX + 1, since the bytes at or above the starting index must be moved.

NUMBER OF BYTES INSERTED is the length of the substring if no truncation occurs. It is the maximum length of the string minus its current length if inserting the substring would produce a string longer than the maximum.

Examples
1. STRING LENGTH = 20₁₆ (32₁₀)
   STARTING INDEX = 19₁₆ (25₁₀)
   MAXIMUM LENGTH = 30₁₆ (48₁₀)
   SUBSTRING LENGTH = 06

   That is, we want to insert a substring six bytes long, starting at the 25th character. Since there are eight bytes that must be moved up (20₁₆ — 19₁₆ + 1 = NUMBER OF BYTES MOVED) and six bytes that must be inserted, the execution time is approximately

   36 • 8 + 36 • 6 + 207 = 288 + 216 + 207 = 711 cycles.

2. STRING LENGTH = 20₁₆ (32₁₀)
   STARTING INDEX = 19₁₆ (25₁₀)
   MAXIMUM LENGTH = 24₁₆ (36₁₀)
   SUBSTRING LENGTH = 06

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As opposed to Example 1, here only four bytes of the substring can be inserted without exceeding the maximum length of the string. Thus \( \text{NUMBER OF BYTES MOVED} = 8 \) and \( \text{NUMBER OF BYTES INSERTED} = 4 \). The execution time is approximately
\[
36 \times 8 + 36 \times 4 + 207 = 288 + 144 + 207 = 639 \text{ cycles.}
\]

**Program Size:** 212 bytes

**Data Memory Required:** Seven bytes anywhere in RAM plus four bytes on page 0. The seven bytes anywhere in RAM hold the length of the string (one byte at address SLEN), the length of the substring (one byte at address SUBLEN), the maximum length of the string (one byte at address MAXLEN), the current index into the string (one byte at address INDEX), running indexes for use during the move (one byte at address SIDX and one byte at address DIDX), and an error flag (one byte at address INSERR). The four bytes on page 0 hold pointers to the substring (two bytes starting at address SUBSTG, 00D016 in the listing) and the string (two bytes starting at address STRG, 00D216 in the listing).

**Special Cases:**
1. If the length of the substring (the insertion) is zero, the program exits with the Carry flag cleared (no error) and the string unchanged.
2. If the starting index for the insertion is zero (i.e., the insertion begins in the length byte), the program exits with the Carry flag set to 1 (indicating an error) and the string unchanged.
3. If the string with the substring inserted exceeds the specified maximum length, the program inserts only enough characters to reach the maximum length. The Carry flag is set to 1 to indicate that the insertion has been truncated.
4. If the starting index of the insertion is beyond the end of the string, the program concatenates the insertion at the end of the string and indicates an error by setting the Carry flag to 1.
5. If the original length of the string exceeds its specified maximum length, the program exits with the Carry flag set to 1 (indicating an error) and the string unchanged.

**Entry Conditions**

**Order in stack (starting from the top)**

- Less significant byte of return address
- More significant byte of return address
- Less significant byte of starting address of substring
- More significant byte of starting address of substring
- Maximum length of string
- Starting index at which to insert the substring
- Less significant byte of starting address of string
- More significant byte of starting address of string

**Exit Conditions**

Substring inserted into string. If no errors occur, the Carry flag is cleared. If the starting index is zero or the length of the substring is zero, the Carry flag is set and the string is not changed. If the starting index is beyond the length of the string, the Carry flag is set and the substring is concatenated to the end of the string. If the string with the substring inserted would exceed the specified maximum length, the Carry flag is set and only those characters from the substring which bring the string to maximum length are inserted.
Examples

1. Data: String = 0A'JOHN SMITH' (0A₁₀ = 10₁₀ is the length of the string)
   Substring = 08'WILLIAM ' (08 is the length of the substring)
   Maximum length of string = 14₁₀ = 20₁₀
   Starting index = 06

   Result: String = 12'JOHN WILLIAM SMITH'
   (12₁₀ = 18₁₀ is the length of the string with the substring inserted).
   Carry = 0, since no problems occurred in the insertion.

2. Data: String = 0A'JOHN SMITH' (0A₁₀ = 10₁₀ is the length of the string)
   Substring = 0C'ROCKEFELLER ' (0C₁₀ = 12₁₀ is the length of the substring)
   Maximum length of string = 14₁₀ = 20₁₀
   Starting index = 06

   Result: String = 14'JOHN ROCKEFELLESMITH' (14₁₀ = 20₁₀ is the length of the string with as much of the substring inserted as the maximum length would allow)
   Carry = 1, since some of the substring could not be inserted without exceeding the maximum length of the string.

Title: Insert a substring into a string
Name: Insert

Purpose: Insert a substring into a string given a starting index.

Entry:
TOP OF STACK
Low byte of return address,
High byte of return address,
Low byte of substring address,
High byte of substring address,
Maximum length of (source) string,
Starting index to insert the substring,
Low byte of (source) string address,
High byte of (source) string address,
A string is a maximum of 255 bytes long plus a length byte which precedes it.

Exit:
Substring inserted into string.
if no errors then
  CARRY = 0
else
  begin
    the following conditions cause the CARRY flag to be set.
    if index = 0 then
do not insert the substring
    if length(strg) > maximum length then
do not insert the substring
if index > length(strg) then
  concatenate substg onto the end of the source string
if length(strg)+length(substring) > maxlen
  then insert only enough of the substring
  to reach maximum length
end;

Registers used: All

Time: Approximately
  36 * (LENGTH (STRG) - INDEX + 1) +
  36 * (LENGTH (SUBSTG)) +
  207 cycles overhead.

Size: Program 214 bytes
  Data 7 bytes plus
    4 bytes in page zero

;EQUATES
SUBSTG .EQU 0D0H ;PAGE ZERO POINTER TO SUBSTRING
STRG .EQU 0D2H ;PAGE ZERO POINTER TO STRING

INSERT:
;GET RETURN ADDRESS
PLA
TAY ;SAVE LOW BYTE
PLA
TAX ;SAVE HIGH BYTE

;GET STARTING ADDRESS OF SUBSTRING
PLA
STA SUBSTG ;SAVE LOW BYTE
PLA
STA SUBSTG+1 ;SAVE HIGH BYTE

;GET MAXIMUM LENGTH OF STRING
PLA
STA MAXLEN

;GET STARTING INDEX for insertion
PLA
STA INDEX

;GET STARTING ADDRESS OF SOURCE STRING
PLA
STA STRG ;SAVE LOW BYTE
PLA
STA STRG+1 ;SAVE HIGH BYTE

;RESTORE RETURN ADDRESS
TXA
PHA ;RESTORE HIGH BYTE
TYA
PHA

;ASSUME NO ERRORS
LDA #0
STA INSERR

;GET SUBSTRING AND STRING LENGTHS
; IF LENGTH(SUBSTG) = 0 THEN EXIT BUT NO ERROR
LDA (STRG),Y
STA SLEN
LDA (SUBSTG),Y
STA SUBLEN
BNE IDX0
JMP OKEXIT

; IF STARTING INDEX IS ZERO THEN ERROR EXIT
IDX0:

LDA INDEX
BNE CHKLEN
JMP EREXIT

;CHECK THAT THE RESULTING STRING AFTER THE INSERTION FITS IN THE
; SOURCE STRING. IF NOT THEN TRUNCATE THE SUBSTRING AND SET THE
; TRUNCATION FLAG.

CHKLEN:

LDA SUBLEN
CLC
ADC SLEN
BCS TRUNC
CMP MAXLEN
BCC IDXLEN
BEQ IDXLEN

;SUBSTRING DOES NOT FIT, SO TRUNCATE IT
TRUNC:

LDA MAXLEN

;SUBSTRING LENGTH = MAXIMUM LENGTH - STRING LENGTH
SEC
SBC SLEN
BCC EREXIT
BEQ EREXIT

;ERROR EXIT IF MAXIMUM LENGTH < STRING LENGTH

;ERROR EXIT IF SUBSTRING LENGTH IS ZERO

; (THE ORIGINAL STRING WAS TOO LONG !)

STA SUBLEN
LDA #0FFH
STA INSERR

;INDICATE SUBSTRING WAS TRUNCATED

;CHECK THAT INDEX IS WITHIN THE STRING. IF NOT CONCATENATE THE
; SUBSTRING ONTO THE END OF THE STRING.
IDXLEN:

LDA SLEN
CMP INDEX
BCS LENOK
LDX SLEN

;ELSE JUST CONCATENATE (PLACE SUBSTRING AT
; END OF STRING)

INX
8F INSERT A SUBSTRING INTO A STRING (INSERT)

```
STX    INDEX                  ;START RIGHT AFTER END OF STRING
LDA    #$0FFH                ;INDICATE ERROR IN INSERT
STA    INSERR                ;ADD SUBSTRING LENGTH TO STRING LENGTH
CLC
ADC    SUBLEN                ;JUST PERFORM MOVE, NOTHING TO OPEN UP
STA    SLEN
JMP    MVESUB

;OPEN UP A SPACE IN SOURCE STRING FOR THE SUBSTRING BY MOVING THE
; CHARACTERS FROM THE END OF THE SOURCE STRING DOWN TO INDEX, UP BY
; THE SIZE OF THE SUBSTRING.

LENOK:

;CALCULATE NUMBER OF CHARACTERS TO MOVE
; COUNT := STRING LENGTH - STARTING INDEX + 1
LDA    SLEN
SEC
SBC    INDEX
TAX
INX

;SET THE SOURCE INDEX AND CALCULATE THE DESTINATION INDEX
LDA    SLEN
STA    SIDX                   ;SOURCE ENDS AT END OF ORIGINAL STRING
CLC
ADC    SUBLEN                ;DESTINATION ENDS FURTHER BY SUBSTRING LENGTH
STA    DIDX
STA    SLEN                   ;SET THE NEW LENGTH TO THIS VALUE ALSO

OPNLP:

LDY    SIDX                   ;GET NEXT CHARACTER
LDA    (STRG),Y
LDY    DIDX                   ;MOVE IT UP IN MEMORY
STA    (STRG),Y
DEC    SIDX                   ;DECREMENT SOURCE INDEX
DEC    DIDX                   ;DECREMENT DESTINATION INDEX
DEX
BNE    OPNLP

;CONTINUE UNTIL COUNTER = 0

MVESUB:

LDA    #1
STA    SIDX                   ;START AT ONE IN THE SUBSTRING
LDX    SUBLEN                 ;START AT INDEX IN THE STRING

MVELP:

LDY    SIDX                   ;GET NEXT CHARACTER
LDA    (SUBSTG),Y
LDY    INDEX
STA    (STRG),Y
INC    SIDX                   ;STORE CHARACTER
INC    INDEX
DEC    DIDX                   ;INCREMENT SUBSTRING INDEX
DEX
BNE    MVELP

;CONTINUE UNTIL COUNTER = 0
LDA    INSERR                ;GET ERROR FLAG
```
STRING MANIPULATIONS

BNE EREXIT ; BRANCH IF SUBSTRING WAS TRUNCATED

OKEXIT:
  CLC
  BCC EXIT ; NO ERROR

EREXIT:
  SEC ; ERROR EXIT

EXIT:
  LDA SLEN
  LDY $0
  STA (STRG),Y ; SET NEW LENGTH OF STRING
  RTS

; DATA SECTION
SLEN: .BLOCK 1 ; LENGTH OF STRING
SUBLEN: .BLOCK 1 ; LENGTH OF SUBSTRING
MAXLEN: .BLOCK 1 ; MAXIMUM LENGTH OF STRING
INDEX: .BLOCK 1 ; CURRENT INDEX INTO STRING
SIDX: .BLOCK 1 ; A RUNNING INDEX
DIDX: .BLOCK 1 ; A RUNNING INDEX
INSERR: .BLOCK 1 ; FLAG USED TO INDICATE IF AN ERROR

; SAMPLE EXECUTION:

SC0806:
  LDA SADR+1 ; PUSH ADDRESS OF SOURCE STRING
  PHA
  LDA SADR
  PHA
  LDA IDX ; PUSH STARTING INDEX FOR INSERTION
  PHA
  LDA MXLEN ; PUSH MAXIMUM LENGTH OF SOURCE STRING
  PHA
  LDA SUBADR+1 ; PUSH ADDRESS OF THE SUBSTRING
  PHA
  LDA SUBADR
  PHA
  JSR INSERT ; INSERT
  BRK ; RESULT OF INSERTING "-" INTO "123456" AT
  ; INDEX 1 IS "-123456"
  JMP SC0806 ; LOOP FOR ANOTHER TEST

; DATA SECTION
IDX .BYTE 1 ; INDEX TO START INSERTION
MXLEN .BYTE 20H ; MAXIMUM LENGTH OF DESTINATION
SADR .WORD STG ; STARTING ADDRESS OF STRING
SUBADR .WORD SSTG ; STARTING ADDRESS OF SUBSTRING
STG .BYTE 06H ; LENGTH OF STRING
.BYTE "123456"
.BYTE 1
.BYTE ":" ;LENGTH OF SUBSTRING
.END ;PROGRAM

"" ;32 BYTE MAX LENGTH
"" ;32 BYTE MAX LENGTH
8-Bit Array Summation (ASUM8)

Adds the elements of a byte-length array, producing a 16-bit sum. The size of the array is specified and is a maximum of 255 bytes.

Procedure: The program clears both bytes of the sum initially. It then adds the elements successively to the less significant byte of the sum, starting with the element at the highest address. Whenever an addition produces a carry, the program increments the more significant byte of the sum.

Registers Used: All
Execution Time: Approximately 16 cycles per byte plus 39 cycles overhead. If, for example, \( (X) = 1A_{16} = 26_{10} \), the execution time is approximately
\[
16 \times 26 + 39 = 416 + 39 = 455 \text{ cycles.}
\]
Program Size: 30 bytes
Data Memory Required: Two bytes on page 0 to hold a pointer to the array (starting at address ARYADR, 00D0\text{16} in the listing).
Special Case: An array size of zero causes an immediate exit with the sum equal to zero.

---

**Entry Conditions**

(A) = More significant byte of starting address of array  
(Y) = Less significant byte of starting address of array  
(X) = Size of array in bytes

**Exit Conditions**

(A) = More significant byte of sum  
(Y) = Less significant byte of sum

---

**Example**

Data:  
Size of array (in bytes) = (X) = 08  
Array elements  
F7\text{16} = 247_{10}  
23\text{16} = 35_{10}  
31\text{16} = 49_{10}  
70\text{16} = 112_{10}  
5A\text{16} = 90_{10}  
16\text{16} = 22_{10}  
CB\text{16} = 203_{10}  
E1\text{16} = 225_{10}

Result:  
Sum = 03D7\text{16} = 983_{10}  
(A) = more significant byte of sum  
= 03_{16}  
(Y) = less significant byte of sum = D7\text{16}
Title: 8 BIT ARRAY SUMMATION
Name: ASUM8
Purpose: SUM the data of an array, yielding a 16 bit result. Maximum size is 255.
Entry: Register A = High byte of starting array address
       Register Y = Low byte of starting array address
       Register X = Size of array in bytes
Exit: Register A = High byte of sum
      Register Y = Low byte of sum
Registers used: All
Time: Approximately 16 cycles per byte plus 39 cycles overhead.
Size: Program 30 bytes
      Data 2 bytes in page zero

;EQUATES SECTION
ARYADR: .EQU 0D0H ;PAGE ZERO POINTER TO ARRAY

ASUM8:

;STORE STARTING ADDRESS
STY ARYADR
STA ARYADR+1

;DECREMENT STARTING ADDRESS BY 1 FOR EFFICIENT PROCESSING
TYA ;GET LOW BYTE OF STARTING ADDRESS
BNE ASUM81 ;IS LOW BYTE ZERO ?
DEC ARYADR+1 ;YES, BORROW FROM HIGH BYTE

ASUM81: DEC ARYADR ;ALWAYS DECREMENT LOW BYTE

;EXIT IF LENGTH OF ARRAY IS ZERO
TXA
TAY
BEQ EXIT ;EXIT IF LENGTH IS ZERO

;INITIALIZATION
LDA #0 ;INITIALIZE SUM TO 0
TAX

;SUMMATION LOOP
SUMLP:

CLC
ADC (ARYADR),Y ;ADD NEXT BYTE TO LSB OF SUM
BCC DECCNT
INX ;INCREMENT MSB OF SUM IF A CARRY OCCURS
ARRAY OPERATIONS

DECCNT:
  DEY
  BNE SUMLP ;DECREMENT COUNT
  BNE SUMLP ;CONTINUE UNTIL REGISTER Y EQUALS 0
EXIT:
  TAY
  TXA
  RTS
  ;REGISTER Y = LOW BYTE OF SUM
  ;REGISTER A = HIGH BYTE OF SUM

; SAMPLE EXECUTION

; SC09U1:
  LDY BUFADR ;Y IS LOW BYTE OF BUFFER ADDRESS
  LDA BUFADR+1 ;A IS HIGH BYTE OF BUFFER ADDRESS
  LDX BUFSZ ;X IS SIZE OF BUFFER
  JSR ASUM8 ;SUM OF THE INITIAL TEST DATA IS 07F8 HEX,
  BRK ; REGISTER A = 07, REGISTER Y = F8H
  JMP SC09U1 ;TEST DATA, CHANGE FOR OTHER VALUES

SIZE .EQU 010H ;SIZE OF BUFFER
BUFADR: .WORD BUF ;STARTING ADDRESS OF BUFFER
BUFSZ: .BYTE SIZE ;SIZE OF BUFFER
BUF: .BYTE 00H ;BUFFER
  .BYTE 11H ;DECIMAL ELEMENTS ARE 0,17,34,51,68
  .BYTE 22H ; 85,102,119,136,153,170,187,204
  .BYTE 33H ; 221,238,255
  .BYTE 44H
  .BYTE 55H
  .BYTE 66H
  .BYTE 77H
  .BYTE 88H
  .BYTE 99H
  .BYTE 0AAH
  .BYTE 0BBH
  .BYTE 0CCH
  .BYTE 0DDH
  .BYTE 0EEH
  .BYTE 0FFH ;SUM = 07F8 (2040 DECIMAL)
.END ;PROGRAM
16-Bit Array Summation (ASUM16) 9B

Add the elements of a word-length array, producing a 24-bit sum. The size of the array is specified and is a maximum of 255 16-bit words. The 16-bit elements are stored in the usual 6502 style with the less significant byte first.

Procedure: The program clears a 24-bit accumulator in three bytes of memory and then adds the elements to the memory accumulator, starting at the lowest address. The most significant byte of the memory accumulator is incremented each time the addition of the more significant byte of an element and the middle byte of the sum produces a carry. If the array occupies more than one page of memory, the program must increment the more significant byte of the array pointer before proceeding to the second page.

Registers Used: All
Execution Time: Approximately 43 cycles per byte plus 46 cycles overhead. If, for example, (X) = 12_16 = 18_10, the execution time is approximately
43 * 18 + 46 = 774 + 46 = 820 cycles.

Program Size: 60 bytes

Data Memory Required: Three bytes anywhere in RAM plus two bytes on page 0. The three bytes anywhere in RAM hold the memory accumulator (starting at address SUM); the two bytes on page 0 hold a pointer to the array (starting at address ARYADR, 00D0_16 in the listing).

Special Case: An array size of 0 causes an immediate exit with the sum equal to zero.

**Entry Conditions**

(A) = More significant byte of starting address of array
(Y) = Less significant byte of starting address of array
(X) = Size of array in 16-bit words

**Example**

Data: Size of array (in 16-bit words) = (X) = 08

Array elements
F7A1_16 = 63,393_10
239B_16 = 9,115_10
31D5_16 = 12,757_10
70F2_16 = 28,914_10
5A36_16 = 23,094_10
166C_16 = 5,740_10
CBF5_16 = 52,213_10
E107_16 = 57,607_10

Result: Sum = 03DBA1_16 = 252,833_10
(X) = most significant byte of sum = 03_16
(A) = middle byte of sum = DB_16
(Y) = least significant byte of sum = A1_16

Exit Conditions

(X) = Most significant byte of sum
(A) = Middle byte of sum
(Y) = Least significant byte of sum
Title: 16 BIT ARRAY SUMMATION
Name: ASUM16

Purpose: Sum the data of an array, yielding a 24 bit result. Maximum size is 255 16 bit elements.

Entry: Register A = High byte of starting array address;
       Register Y = Low byte of starting array address;
       Register X = size of array in 16 bit elements;

Exit: Register X = High byte of sum
       Register A = Middle byte of sum
       Register Y = Low byte of sum

Registers used: All

Time: Approximately 43 cycles per byte plus 46 cycles overhead.

Size: Program 60 bytes
      Data 3 bytes plus 2 bytes in page zero

;EQUATES SECTION
ARYADR: .EQU 0D0H ;PAGE ZERO POINTER TO ARRAY

ASUM16:

;STORE STARTING ADDRESS
STY ARYADR
STA ARYADR+1

;ZERO SUM AND INITIALIZE INDEX
LDA #0
STA SUM ;SUM = 0
STA SUM+1
STA SUM+2
TAY ;INDEX = 0

;EXIT IF THE ARRAY LENGTH IS ZERO
TXA
BEQ EXIT

;SUMMATION LOOP
SUMLP:
LDA SUM
CLC
ADC (ARYADR),Y ;ADD LOW BYTE OF ELEMENT TO SUM
STA SUM
LDA SUM+1
INY
ADC (ARYADR),Y
STA SUM+1
BCC NXTELM
INC SUM+2

NXTELM:
INY
BNE DECCNT
INC ARYADR+1

DECCNT:
DEX
BNE SUMLP

EXIT:
LDY SUM
LDA SUM+1
LDX SUM+2
RTS

; DATA SECTION
SUM: .BLOCK 3

; TEMPORARY 24 BIT ACCUMULATOR IN MEMORY

; SAMPLE EXECUTION

; SC0902:
LDY BUFADR
LDA BUFADR+1
LDX BUFSZ
JSR ASUM16
BRK
JMP SC0902

; A,Y = STARTING ADDRES OF BUFFER
; X = BUFFER SIZE IN WORDS
; RESULT OF THE INITIAL TEST DATA IS 12570
; REGISTER X = 0, REGISTER A = 31H,
; REGISTER Y = 1AH
; LOOP FOR MORE TESTING

; SIZE .EQU 010H
BUFADR: .WORD Buf
BUFSZ: .BYTE SIZE
BUF: .WORD 0
; SIZE OF BUFFER IN WORDS
; STARTING ADDRESS OF BUFFER
; SIZE OF BUFFER IN WORDS
; BUFFER
ARRAY OPERATIONS

.WORD 1313
.WORD 1414
.WORD 1515

;SUM = 12570 = 311AH

.END ;PROGRAM
Find Maximum Byte-Length Element (MAXELM) 9C

Finds the maximum element in an array of unsigned byte-length elements. The size of the array is specified and is a maximum of 255 bytes.

Procedure: The program exits immediately (setting Carry to 1) if the array size is zero. If the size is non-zero, the program assumes that the last byte of the array is the largest and then proceeds backward through the array, comparing the supposedly largest element to the current element and retaining the larger value and its index. Finally, the program clears the Carry to indicate a valid result.

Registers Used: All

Execution Time: Approximately 15 to 23 cycles per byte plus 52 cycles overhead. The extra eight cycles are used whenever the supposed maximum and its index must be replaced by the current element and its index. If, on the average, that replacement occurs half the time, the execution time is approximately

$38 \times \text{ARRAY SIZE}/2 + 52$ cycles.

If, for example, ARRAY SIZE = $18_{16} = 24_{10}$, the approximate execution time is

$38 \times 12 + 52 = 456 + 52 = 508$ cycles.

Program Size: 45 bytes

Data Memory Required: One byte anywhere in RAM plus two bytes on page 0. The one byte anywhere in RAM holds the index of the largest element (at address INDEX). The two bytes on page 0 hold a pointer to the array (starting at address ARYADR, 00D016 in the listing).

Special Cases:
1. An array size of 0 causes an immediate exit with the Carry flag set to 1 to indicate an invalid result.
2. If more than one element has the largest unsigned value, the program returns with the smallest possible index. That is, the index designates the occurrence of the maximum value closest to the starting address.

Entry Conditions
(A) = More significant byte of starting address of array
(Y) = Less significant byte of starting address of array
(X) = Size of array in bytes

Exit Conditions
(A) = Largest unsigned element
(Y) = Index to largest unsigned element
Carry = 0 if result is valid, 1 if size of array is 0 and result is meaningless.

Example
Data: Size of array (in bytes) = (X) = 08

<table>
<thead>
<tr>
<th>Array elements</th>
<th>(A)</th>
<th>(Y)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$35_{16}$ = 53$_{10}$</td>
<td>$44_{16}$ = 68$_{10}$</td>
<td></td>
</tr>
<tr>
<td>$A6_{16}$ = 166$_{10}$</td>
<td>$59_{16}$ = 89$_{10}$</td>
<td></td>
</tr>
<tr>
<td>$D2_{16}$ = 210$_{10}$</td>
<td>$7A_{16}$ = 122$_{10}$</td>
<td></td>
</tr>
<tr>
<td>$1B_{16}$ = 27$_{10}$</td>
<td>$CF_{16}$ = 207$_{10}$</td>
<td></td>
</tr>
</tbody>
</table>

Result: The largest unsigned element is element #2 ($D2_{16}$ = 210$_{10}$)
(A) = largest element ($D2_{16}$)
(Y) = index to largest element (02)
Carry flag = 0, indicating that array size is non-zero and the result is valid.
Title

Find the maximum element in an array of unsigned bytes.

Name: MAXELM

Purpose: Given the starting address of an array and the size of the array, find the largest element.

Entry: Register A = High byte of starting address
       Register Y = Low byte of starting address
       Register X = Size of array in bytes

Exit: If size of the array is not zero then
      CARRY FLAG = 0
      Register A = Largest element
      Register Y = Index to that element
      if there are duplicate values of the largest element, register Y will have the index nearest to the first array element
      else
      CARRY flag = 1

Registers used: All

Time: Approximately 15 to 23 cycles per byte
      plus 52 cycles overhead.

Size: Program 45 bytes
      Data 1 byte plus
            2 bytes in page zero

;EQUATES
ARYADR: .EQU 0D0H ;PAGE ZERO FOR ARRAY POINTER

MAXELM:

;STORE STARTING ARRAY ADDRESS
STA ARYADR+1
STY ARYADR

;SUBTRACT 1 FROM STARTING ADDRESS TO INDEX FROM 1 TO SIZE
TYA
BNE MAX1
DEC ARYADR+1 ;BORROW FROM HIGH BYTE IF LOW BYTE = 0

MAX1:
DEC ARYADR ;ALWAYS DECREMENT THE LOW BYTE

;TEST FOR SIZE EQUAL TO ZERO AND INITIALIZE TEMPORARIES
TXA
BEQ EREXIT ;ERROR EXIT IF SIZE IS ZERO
TAY ;REGISTER Y = SIZE AND INDEX
LDA (ARYADR),Y ;GET LAST BYTE OF ARRAY
STY INDEX ;SAVE ITS INDEX
DEY          ;EXIT IF ONLY ONE ELEMENT
BEQ         OKEXIT          ;WORK FROM THE END OF THE ARRAY TOWARDS THE BEGINNING COMPARING
          ; AGAINST THE CURRENT MAXIMUM WHICH IS IN REGISTER A
MAXLP:
    CMP        (ARYADR),Y     ;REPLACE INDEX ONLY IF ELEMENT = MAXIMUM
    BEQ       NEWIDX
    BCS       NXTBYT          ;ELSE ARY[Y] >= CURRENT MAXIMUM SO
    LDA        (ARYADR),Y     ; NEW CURRENT MAXIMUM AND
    STY INDEX  ; NEW INDEX
    DEY MAXLP ; DECREMENT TO NEXT ELEMENT
    BNE MAXLP ; CONTINUE
    DEY         ;EXIT
OKEXIT:
    LDY INDEX  ;GET INDEX OF THE MAXIMUM ELEMENT
    DEY         ;NORMALIZE INDEX TO (0,SIZE-1)
    CLC         ;NO ERRORS
    RTS         ;ERROR, NO ELEMENTS IN THE ARRAY
EREEXIT:
    SEC         ;DATA SECTION
    RTS
INDEX: .BLOCK 1 ;INDEX OF LARGEST ELEMENT
    INCLUDE SC0903
;SAMPLE EXECUTION:

SC0903:
    LDA AADR+1 ;A,Y = STARTING ADDRESS OF ARRAY
    LDY AADR
    LDX #SZARY
    JSR MAXELM
    BRK
    JMP SC0903 ;RESULT FOR THE INITIAL TEST DATA IS
SZARY: .EQU 10H ; A = FF HEX (MAXIMUM), Y=08 (INDEX TO MAXIMUM)
AADR: .WORD ARY ;LOOP FOR MORE TESTING
ARY: .BYTE 8 ;SIZE OF ARRAY
    .BYTE 7 ;STARTING ADDRESS OF ARRAY
    .BYTE 6
    .BYTE 5
.BYTE 4
.BYTE 3
.BYTE 2
.BYTE 1
.BYTE OFFH
.BYTE OFEH
.BYTE OFDH
.BYTE OFCH
.BYTE OFBH
.BYTE OFAH
.BYTE OF9H
.BYTE OF8H

.END ; PROGRAM
Find Minimum Byte-Length Element (MINELM) 9D

Finds the minimum element in an array of unsigned byte-length elements. The size of the array is specified and is a maximum of 255 bytes.

Procedure: The program exits immediately, setting Carry to 1, if the array size is zero. If the size is non-zero, the program assumes that the last byte of the array is the smallest and then proceeds backward through the array, comparing the supposedly smallest element to the current element and retaining the smaller value and its index. Finally, the program clears the Carry flag to indicate a valid result.

Registers Used: All

Execution Time: Approximately 15 to 23 cycles per byte plus 52 cycles overhead. The extra eight cycles are used whenever the supposed minimum and its index must be replaced by the current element and its index. If, on the average, that replacement occurs half the time, the execution time is approximately

\[ 38 \times \text{ARRAY SIZE}/2 + 52 \text{ cycles}. \]

If, for example, \( \text{ARRAY SIZE} = 14_{16} = 20_{10} \), the approximate execution time is

\[ 38 \times 10 + 52 = 380 + 52 = 432 \text{ cycles}. \]

Program Size: 45 bytes

Data Memory Required: One byte anywhere in RAM plus two bytes on page 0. The one byte anywhere in RAM holds the index of the smallest element (at address INDEX). The two bytes on page 0 hold a pointer to the array (starting at address ARYADR, 00D0_{16} in the listing).

Special Cases:

1. An array size of 0 causes an immediate exit with the Carry flag set to 1 to indicate an invalid result.
2. If more than one element has the smallest unsigned value, the program returns with the smallest possible index. That is, the index designates the occurrence of the minimum value closest to the starting address.

Entry Conditions

\( (A) = \) More significant byte of starting address of array
\( (Y) = \) Less significant byte of starting address of array
\( (X) = \) Size of array in bytes

Exit Conditions

\( (A) = \) Smallest unsigned element
\( (Y) = \) Index to smallest unsigned element
Carry = 0 if result is valid, 1 if size of array is zero and result is meaningless.

Example

Data:

Size of array (in bytes) = \( (X) = 08 \)

Array elements

\[
\begin{align*}
35_{16} &= 53_{10} \\
A6_{16} &= 166_{10} \\
D2_{16} &= 210_{10} \\
1B_{16} &= 27_{10}
\end{align*}
\]

\[
\begin{align*}
44_{16} &= 68_{10} \\
59_{16} &= 89_{10} \\
7A_{16} &= 122_{10} \\
\text{CF}_{16} &= 207_{10}
\end{align*}
\]

Result:

The smallest unsigned element is element \( \#3 \) (\( 1B_{16} = 27_{10} \))

\( (A) = \) smallest element (\( 1B_{16} \))

\( (Y) = \) index to smallest element (03)

Carry flag = 0, indicating that array size is non-zero and the result is valid.
Title: Find the minimum element in an array of unsigned bytes.

Name: MINELM

Purpose: Given the STARTING ADDRESS and the size of an array, find the smallest element.

Entry:
- Register A = High byte of starting address
- Register Y = Low byte of starting address
- Register X = Size of array in bytes

Exit:
If size of the array is not zero then
- CARRY FLAG = 0
- Register A = Smallest element
- Register Y = Index to that element
- if there are duplicate values of the smallest element Register Y will have the index nearest to the first array element
else
- CARRY flag = 1

Registers used: All

Time: Approximately 15 to 23 cycles per byte
- plus 52 cycles overhead.

Size:
Program 45 bytes
- Data 1 bytes plus
- 2 bytes in page zero

;EQUATES
ARYADR: .EQU 0D0H ;PAGE ZERO POINTER TO ARRAY

MINELM:
;STORE STARTING ARRAY ADDRESS
STA ARYADR+1
STY ARYADR

;DECREMENT ARRAY ADDRESS BY 1 TO INDEX FROM 1 TO SIZE
TYA
BNE MIN1
DEC ARYADR+1 ;BORROW FROM HIGH BYTE IF LOW BYTE = 0

MIN1:
DEC ARYADR ;ALWAYS DECREMENT THE LOW BYTE

;TEST FOR SIZE EQUAL TO ZERO AND INITIALIZE TEMPORARIES
TXA
BEQ EREXIT ;ERROR EXIT IF SIZE IS ZERO
TAY ;REGISTER Y = SIZE AND INDEX
LDA (ARYADR),Y ;GET LAST BYTE OF ARRAY
STY INDEX ;SAVE ITS INDEX
; WORK FROM THE END OF THE ARRAY TOWARDS THE BEGINNING COMPARING AGAINST THE CURRENT MINIMUM WHICH IS IN REGISTER A

MINLP:
  CMP  (ARYADR),Y
  BEQ  NEWIDX
  BCC  NXTBYT
  LDA  (ARYADR),Y

NEWIDX:
  STY  INDEX

NXTBYT:
  DEY  MINLP
  BNE  NEWIDX
  DEY
  BNE

; EXIT

OKEXIT:
  LDY  INDEX
  DEY
  CLC

EREXIT:
  SEC
  RTS

; DATA SECTION
INDEX:  .BLOCK 1

; SAMPLE EXECUTION:

SC0904:
  LDA  AADR+1
  LDY  AADR
  LDX  #SZARY
  JSR  MINELM
  BRK
  JMP  SC0904

SZARY:  .EQU  10H
AADR:  .WORD  ARY
ARY:  .BYTE  8
      .BYTE  7
      .BYTE  6
      .BYTE  5
      .BYTE  4

; A, Y = STARTING ADDRESS OF ARRAY
; X = SIZE OF ARRAY
; RESULT FOR THE INITIAL TEST DATA IS
; A = 01H (MINIMUM), Y=07 (INDEX TO MINIMUM)
; LOOP FOR MORE TESTING

SIZE OF ARRAY
; STARTING ADDRESS OF ARRAY
.BYTE 3
.BYTE 2
.BYTE 1
.BYTE OFFH
.BYTE OFEH
.BYTE OFDH
.BYTE OFCH
.BYTE OFBH
.BYTE OFAH
.BYTE OF9H
.BYTE OF8H

.END ;PROGRAM
Searches an array of unsigned byte-length elements for a particular value. The array is assumed to be ordered with the smallest element at the starting (lowest) address. Returns the index to the value and the Carry flag cleared if it finds the value; returns the Carry flag set to 1 if it does not find the value. The size of the array is specified and is a maximum of 255 bytes. The approach used is a binary search in which the value is compared with the middle element in the remaining part of the array; if the two are not equal, the part of the array that cannot possibly contain the value (because of the ordering) is discarded and the process is repeated.

Procedure: The program retains upper and lower bounds (indexes) that specify the part of the array still being searched. In each iteration, the new trial index is the average of the upper and lower bounds. The program compares the value and the element with the trial index; if the two are not equal, the program discards the part of the array that could not possibly contain the element. That is, if the value is larger than the element with the trial index, the part at or below the trial index is discarded. If the value is smaller than the element with the trial index, the part at or above the trial index is discarded. The program exits if it finds a match or if there are no elements left to be searched (that is, if the part of the array being searched no longer contains anything). The program sets the Carry flag to 1 if it finds the value and to 0 if it does not.

In the case of Example 1 shown later (the value is \textbf{0D}_{16}), the procedure works as follows:

In the first iteration, the lower bound is zero and the upper bound is the length of the array minus 1 (since we have started our indexing at zero). So we have

\begin{align*}
\text{LOWER BOUND} &= 0 \\
\text{UPPER BOUND} &= \text{LENGTH} - 1 = \text{0F}_{16} = 15_{10} \\
\text{GUESS} &= \frac{\text{UPPER BOUND} + \text{LOWER BOUND}}{2} = 07_{16} \quad \text{(the result is truncated)} \\
\text{ARRAY(GUESS)} &= \text{ARRAY(7)} = \text{10}_{16} = 16_{10}
\end{align*}

Since our value (\textbf{0D}_{16}) is less than \text{ARRAY(7)}, there is no use looking at the elements with indexes of 7 or more, so we have

\begin{align*}
\text{LOWER BOUND} &= 0 \\
\text{UPPER BOUND} &= \text{GUESS} - 1 = 06_{16}
\end{align*}
398 ARRAY OPERATIONS

GUESS = (UPPER BOUND + LOWER BOUND)/2 = 03
ARRAY(GUESS) = ARRAY(3) = 07

Since our value (0D₁₆) is greater than ARRAY(3), there is no use looking at the elements with indexes of 3 or less, so we have

LOWER BOUND = GUESS + 1 = 04
UPPER BOUND = 06
GUESS = (UPPER BOUND + LOWER BOUND)/2 = 05
ARRAY(GUESS) = ARRAY(5) = 09

Since our value (0D₁₆) is greater than ARRAY(5), there is no use looking at the elements with indexes of 5 or less, so we have

LOWER BOUND = GUESS + 1 = 06
UPPER BOUND = 06
GUESS = (UPPER BOUND + LOWER BOUND)/2 = 06
ARRAY(GUESS) = ARRAY(6) = 0D₁₆

Since our value (0D₁₆) is equal to ARRAY(6), we have found the element. If, on the other hand, our value were 0E₁₆, the new lower bound would be 07 and there would no longer be any elements in the part of the array left to be searched.

---

**Entry Conditions**

Order in stack (starting from the top)

- Less significant byte of return address
- More significant byte of return address
- Value to find
- Size of the array (in bytes)
- Less significant byte of starting address of array (address of smallest unsigned element)
- More significant byte of starting address of array (address of smallest unsigned element)

**Exit Conditions**

Carry = 0 if the value is found, Carry = 1 if it is not found. If the value is found, (A) = index to the value in the array.

---

**Examples**

Length of array = 10₁₆ = 16₁₀
Elements of array are 01₁₆, 02₁₆, 05₁₆, 07₁₆, 09₁₆, 09₁₆, 0D₁₆, 10₁₆, 2E₁₆, 37₁₆, 5D₁₆, 7E₁₆, A1₁₆, B4₁₆, D7₁₆, E0₁₆

1. Data: Value to find = 0D₁₆
   Result: Carry = 0, indicating value found
   (A) = 06, the index of the value in the array

2. Data: Value to find = 9B₁₆
   Result: Carry = 1, indicating value not found
Title: Binary Search
Name: BINSCH

Purpose: Search an ordered array of unsigned bytes, with a maximum size of 255 elements.

Entry: TOP OF STACK
- Low byte of return address,
- High byte of return address,
- Value to find,
- Length (size) of array,
- Low byte of starting array address,
- High byte of starting array address

Exit: If the value is found then
- CARRY flag = 0
- Register A = index to the value in the array
ELSE
- CARRY flag = 1

Registers used: All

Time: Approximately 52 cycles for each time through the search loop plus 80 cycles overhead. A binary search will take on the order of log base 2 of N searches, where N is the number of elements in the array.

Size: Program 89 bytes
Data 3 bytes plus 2 bytes in page zero

;EQUATES SECTION
ARYADR: .EQU 0D0H ;PAGE ZERO POINTER TO ARRAY

BINSCH:
;GET RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET THE VALUE TO SEARCH FOR
PLA
STA VALUE

;GET THE LENGTH OF THE ARRAY
PLA
STA UBDN
;GET THE STARTING ADDRESS OF ARRAY
PLA
STA ARYADR
PLA
STA ARYADR+1

;RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

; CHECK THAT LENGTH IS NOT ZERO
LDX UBND ; GET LENGTH
BEQ NOTFND ; EXIT NOT FOUND IF LENGTH EQUALS ZERO

; SET UPPER AND LOWER SEARCH BOUNDS
DEX
STX UBND ; UPPER BOUND EQUALS LENGTH MINUS 1
LDA #0
STA LBND ; LOWER BOUND EQUALS 0

; SEARCH LOOP
; COMPUTE NEXT INDEX TO BE HALF WAY BETWEEN UPPER BOUND AND
; LOWER BOUND
NXTBYT:
LDA UBND
CLC
ADC LBND ; ADD LOWER AND UPPER BOUNDS
ROR A ; DIVIDE BY 2, TRUNCATING FRACTION
TAY ; REGISTER Y BECOMES INDEX

; IF INDEX IS GREATER THAN UPPER BOUND THEN THE ELEMENT IS NOT HERE
CPY UBND
BEQ TSTLB ; BRANCH IF INDEX EQUALS UPPER BOUND
BCS NOTFND ; BRANCH IF INDEX IS GREATER THAN UPPER BOUND

; IF INDEX IS LESS THAN LOWER BOUND THEN THE ELEMENT IS NOT HERE
TSTLB:
CPY LBND
BCC NOTFND ; BRANCH IF INDEX IS LESS THAN LOWER BOUND

; TEST IF WE HAVE FOUND THE ELEMENT
LDA VALUE
CMP (ARYADR),Y
BCC SMALL ; BRANCH IF VALUE IS SMALLER THAN ARYADR[Y]
BEQ FND ; BRANCH IF FOUND

; VALUE IS LARGER THAN ARYADR[Y] SO SET LOWER BOUND TO BE
; Y + 1 (VALUE CAN ONLY BE FURTHER UP)
INY
STY LBND
BNE NXTBYT ; CONTINUE SEARCHING IF LOWER BOUND DOES NOT
; OVERFLOW
BEQ NOTFND ; BRANCH IF LOWER BOUND OVERFLOWED FROM OFFH
; TO 0
9E BINARY SEARCH (BINSCH) 401

; VALUE IS SMALLER THAN ARYADR[Y] SO SET UPPER BOUND TO BE
; Y - 1 (VALUE CAN ONLY BE FURTHER DOWN)

SMALL:
DEY
STY UBND
CPY #0FFH
BNE NXTBYT ; CONTINUE SEARCHING IF UPPER BOUND DOES NOT
; UNDERFLOW
BEQ NOTFND ; BRANCH IF INDEX UNDERFLOWED

FND:
CLC ; INDICATE VALUE FOUND
TYA ; GET INDEX OF VALUE TO REGISTER A
RTS

; FOUND THE VALUE

NOTFND:
SEC ; INDICATE VALUE NOT FOUND
RTS

; DID NOT FIND THE VALUE

; DATA SECTION
VALUE .BLOCK 1 ; VALUE TO FIND
LBND .BLOCK 1 ; INDEX OF LOWER BOUND
UBND .BLOCK 1 ; INDEX OF UPPER BOUND

; SAMPLE EXECUTION

; SC0905:
; SEARCH FOR A VALUE WHICH IS IN THE ARRAY
LDA BFADR+1 ; PUSH HIGH BYTE OF STARTING ADDRESS
PHA
LDA BFADR ; PUSH LOW BYTE OF STARTING ADDRESS
PHA
LDA BFSZ ; PUSH LENGTH (SIZE OF ARRAY)
PHA
LDA #7 ; PUSH VALUE TO FIND
PHA
JSR BINSCH ; SEARCH
BRK ; CARRY FLAG SHOULD BE 0 AND REGISTER A = 4

; SEARCH FOR A VALUE WHICH IS NOT IN THE ARRAY
LDA BFADR+1 ; PUSH HIGH BYTE OF STARTING ADDRESS
PHA
LDA BFADR ; PUSH LOW BYTE OF STARTING ADDRESS
PHA
LDA BFSZ ; PUSH LENGTH (SIZE OF ARRAY)
PHA
LDA #0 ; PUSH VALUE TO FIND
PHA
JSR  BINSCH ; SEARCH
BRK
JMP  SC0905 ; LOOP FOR MORE TESTS

; DATA
SIZE  .EQU  010H ; SIZE OF BUFFER
BFADR: .WORD  BF ; STARTING ADDRESS OF BUFFER
BFSZ: .BYTE  SIZE ; SIZE OF BUFFER
BF:
   .BYTE  1
   .BYTE  2
   .BYTE  4
   .BYTE  5
   .BYTE  7
   .BYTE  9
   .BYTE  10
   .BYTE  11
   .BYTE  23
   .BYTE  50
   .BYTE  81
   .BYTE  123
   .BYTE  191
   .BYTE  199
   .BYTE  250
   .BYTE  255

.END  ; PROGRAM
Bubble Sort (BUBSRT)

Arranges an array of unsigned byte-length elements into ascending order using a bubble sort algorithm. An iteration of this algorithm moves the largest remaining element to the top by comparisons with all other elements, performing interchanges if necessary along the way. The algorithm continues until it has either worked its way through all elements or has completed an iteration without interchanging anything. The size of the array is specified and is a maximum of 255 bytes.

Procedure: The program starts by considering the entire array. It examines pairs of elements, interchanging them if they are out of order and setting a flag to indicate that the interchange occurred. At the end of an iteration, the program checks the interchange flag to see if the array is already in order. If it is not, the program performs another iteration, reducing the number of elements examined by one since the largest remaining element has been bubbled to the top. The program exits immediately if the length of the array is less than two, since no ordering is then necessary. Note that the number of pairs is always one less than the number of elements being considered, since the last element has no successor.

---

Registers Used: All
Execution Time: Approximately
\[ 34 \times N \times N + 25 \times N + 70 \] cycles, where \( N \) is the size (length) of the array in bytes. If, for example, \( N \) is \( 20_{16} (32_{10}) \), the execution time is approximately
\[ 34 \times 32 \times 32 + 25 \times 32 + 70 = 34 \times 1024 + 870 = 34,816 + 870 = 35,686 \text{ cycles.} \]
Program Size: 79 bytes
Data Memory Required: Two bytes anywhere in RAM plus four bytes on page 0. The two bytes anywhere in RAM hold the length of the array (one byte at address LEN) and the interchange flag (one byte at address XCHGFG). The four bytes on page 0 hold pointers to the first and second elements of the array (two bytes starting at address A1ADR, 00D016 in the listing, and two bytes starting at address A2ADR, 00D216 in the listing).
Special Case: A size (or length) of 00 or 01 causes an immediate exit with no sorting.

---

Entry Conditions
Order in stack (starting from the top)
Less significant byte of return address
More significant byte of return address
Length (size) of array in bytes
Less significant byte of starting address of array
More significant byte of starting address of array

Exit Conditions
Array sorted into ascending order, considered the elements as unsigned bytes. Thus, the smallest unsigned byte is now in the starting address.
Example

Data: Length (size) of array = 06
Elements = 35₁₆, 6A₁₆, 2B₁₆, 3E₁₆, D₄₁₆, 4F₁₆

Result: After the first iteration, we have
35₁₆, 2B₁₆, 3E₁₆, 6A₁₆, 4F₁₆, D₄₁₆.
The largest element is now at the end of the array and need not be considered further.

After the second iteration, we have
2B₁₆, 35₁₆, 3E₁₆, 4F₁₆, 6A₁₆, D₄₁₆.
The next to largest element is now in the correct position and need not be considered further.

The third iteration leaves the array unchanged, since the elements are already in ascending order.

Title
Name: BUBSRT
Purpose: Arrange an array of unsigned bytes into ascending order using a bubble sort, with a maximum size of 255 bytes.
Entry: TOP OF STACK
Low byte of return address,
High byte of return address,
Length (size) of array,
Low byte of starting array address,
High byte of starting array address
Exit: The array is sorted into ascending order.
Registers used: All
Time: Approximately (34 * N * N) + (25 * N) cycles plus 70 cycles overhead, where N is the size of the array.
Size: Program 79 bytes
Data 2 bytes plus
4 bytes in page zero

;EQUATES SECTION
A1ADR:.EQU OD0H ;ADDRESS OF FIRST ELEMENT
A2ADR:.EQU OD2H ;ADDRESS OF SECOND ELEMENT

BUBSRT:
;GET THE PARAMETERS FROM THE STACK
PLA
TAY ;SAVE LOW BYTE OF RETURN ADDRESS
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PLA      ;SAVE HIGH BYTE OF RETURN ADDRESS
TAX
PLA
STA LEN   ;SAVE THE LENGTH (SIZE)
PLA
STA A1ADR ;SAVE THE LOW BYTE OF THE ARRAY ADDRESS
CLC
ADC 
STA A2ADR ;SET LOW BYTE OF A2ADR TO A1ADR + 1
PLA
STA A1ADR+1 ;SAVE THE HIGH BYTE OF THE ARRAY ADDRESS
ADC 
STA A2ADR+1 ;SET HIGH BYTE OF A2ADR
TXA
PHA
TYA
PHA

;BE SURE THE LENGTH IS GREATER THAN 1
LDA LEN
CMP #2
BCC DONE ;EXIT IF THE LENGTH OF THE ARRAY IS<br />&lt; 2

;REDUCE LENGTH BY 1 SINCE THE LAST ELEMENT HAS NO SUCCESSOR
DEC LEN

;BUBBLE SORT LOOP
SRTLP:
LDX LEN ;X BECOMES NUMBER OF TIMES THROUGH INNER LOOP
LDY #0 ;Y BECOMES BEGINNING INDEX
STY XCHGFG ;INITIALIZE EXCHANGE FLAG TO 0

INLOOP:
LDA (A2ADR),Y ;COMPARE 2 ELEMENTS
CMP (A1ADR),Y
BCS AFTSWP ;BRANCH IF SECOND ELEMENT &gt;= FIRST ELEMENT
PHA ;SECOND ELEMENT LESS, SO EXCHANGE ELEMENTS
LDA (A1ADR),Y ;GET SECOND ELEMENT
STA (A2ADR),Y ;STORE IT INTO THE FIRST ELEMENT
PLA
STA (A1ADR),Y ;STORE FIRST ELEMENT INTO SECOND
LDA #1
STA XCHGFG ;SET EXCHANGE FLAG SINCE AN EXCHANGE OCCURRED

AFTSWP:
INY ;INCREMENT TO NEXT ELEMENT
DEX
BNE INLOOP ;BRANCH NOT DONE WITH INNER LOOP

;INNER LOOP IS COMPLETE IF THERE WERE NO EXCHANGES THEN EXIT
LDA XCHGFG ;GET EXCHANGE FLAG
BEQ DONE ;EXIT IF NO EXCHANGE WAS PERFORMED
DEC LEN
BNE SRTLP ;CONTINUE IF LENGTH IS NOT ZERO
DONE:

   RTS

; DATA SECTION
LEN:  .BLOCK 1 ; LENGTH OF THE ARRAY
XCHGFG: .BLOCK 1 ; EXCHANGE FLAG (1=EXCHANGE, 0=NO EXCHANGE)

; SAMPLE EXECUTION

; PROGRAM SECTION
SC0906:

; SORT AN ARRAY
LDA  BFADR+1
PHA
LDA  BFADR
PHA
LDA  BFSZ
PHA
JSR  BUBSRT
BRK
JMP  SC0906

; THE RESULT FOR THE INITIAL TEST DATA IS
; 0,1,2,3, ...,14,15
; LOOP FOR MORE TESTS

; DATA SECTION
SIZE .EQU  010H ; SIZE OF BUFFER
BFADR: .WORD BF ; STARTING ADDRESS OF BUFFER
BFSZ:   .BYTE SIZE ; SIZE OF BUFFER
BF:
   .BYTE  15
   .BYTE  14
   .BYTE  13
   .BYTE  12
   .BYTE  11
   .BYTE  10
   .BYTE   9
   .BYTE   8
   .BYTE   7
   .BYTE   6
   .BYTE   5
   .BYTE   4
   .BYTE   3
   .BYTE   2
   .BYTE   1
   .BYTE   0

. END ; PROGRAM
PERFORMS a test of an area of RAM memory specified by a starting address and a length in bytes. Writes the values 00, FF₁₆, AA₁₆ (10101010₂), and 55₁₆ (01010101₂) into each byte and checks to see if they can be read back correctly. Places a single 1 bit in each position of each byte and sees if that can be read back correctly. Clears the Carry flag if all tests can be performed; if it finds an error it immediately exits, setting the Carry flag and returning the address in which the error occurred and the value that was being used in the test.

Procedure: The program performs the single value checks (with 00, FF₁₆, AA₁₆, and 55₁₆) by first filling the memory area and then comparing each byte with the specified value. Filling the entire area first should provide enough delay between writing and reading to detect a failure to retain data (perhaps caused by improperly designed refresh circuitry). The program then performs the walking bit test, starting with bit 7; here it writes the data into memory and immediately attempts to read it back for a comparison. In all the tests, the program handles complete pages first and then handles the remaining partial page; the program can thus use 8-bit counters rather than a 16-bit counter. This approach reduces execution time but increases memory usage as compared to handling the entire area with one loop. Note that the program exits immediately if it finds an error, setting the Carry flag to 1 and returning the location and the value being used in the test. If all the tests can be performed correctly, the program clears the Carry flag before exiting.

Registers Used: All

Execution Time: Approximately 245 cycles per byte tested plus 650 cycles overhead. Thus, for example, to test an area of size 0400₁₆ = 1024₁₀ would take

\[
245 \times 1024 + 650 = 250,880 + 650 = 251,530 \text{ cycles.}
\]

Program Size: 229 bytes

Data Memory Required: Six bytes anywhere in RAM plus two bytes on page 0. The six bytes anywhere in RAM hold the address of the first element (two bytes starting at address ADDR), the length of the tested area (two bytes starting at address LEN), and the temporary length (two bytes starting at address TLEN). The two bytes on page 0 hold a pointer to the tested area (starting at address TADDR, 00D0₁₆ in the listing).

Special Cases:

1. An area size of 0000₁₆ causes an immediate exit with no memory tested. The Carry flag is cleared to indicate no errors.

2. Since the routine changes all bytes in the tested area, using it to test an area that includes its own temporary storage will produce unpredictable results.

Special Case: Note that Case 1 means you cannot ask this routine to test the entire memory, but such a request would be meaningless anyway since it would require the routine to test its own temporary storage.

3. Attempting to test a ROM area will cause a return with an error indication as soon as the program attempts to store a value in a ROM location that is not already there.
Array Operations

Entry Conditions
Order in stack (starting from the top)

Less significant byte of return address
More significant byte of return address
Less significant byte of size (length) of area in bytes
More significant byte of size (length) of area in bytes
Less significant byte of starting address of test area
More significant byte of starting address of test area

Exit Conditions

1. If an error is found,
   Carry = 1
   (A) = More significant byte of address containing error
   (Y) = Less significant byte of address containing error
   (X) = Expected value (value being used in test)
2. If no error is found,
   Carry = 0
   All bytes in test area contain 00.

Example

Data: Starting address = 0380<sub>16</sub>
Length (size) of area = 0200<sub>16</sub>
Result: Area tested is the 0200<sub>16</sub> bytes, starting at addresses 0380<sub>16</sub>. That is, address 0380<sub>16</sub> through 057F<sub>16</sub>. The order of the tests is:
1. Write and read 00
2. Write and read FF<sub>16</sub>
3. Write and read AA<sub>16</sub> (10101010<sub>2</sub>)
4. Write and read 55<sub>16</sub> (01010101<sub>2</sub>)
5. Walking bit test, starting with bit 7 and moving right. That is, starting with 80<sub>16</sub> (10000000<sub>2</sub>) and moving the 1 bit one position right in each subsequent test of a single byte.

Title
Name: RAM test
Purpose: Perform a test of RAM memory
1) Write all 00 hex and test
2) Write all FF hex and test
3) Write all AA hex and test
4) Write all 55 hex and test
5) Shift a single 1 bit through all of memory
If the program finds an error, it exits immediately with the CARRY flag set and indicates where the error occurred and what value it used in the test.
; Entry: 
; TOP OF STACK
; Low byte of return address,
; High byte of return address,
; Low byte of length in bytes,
; High byte of length in bytes,
; Low byte of starting address of test area,
; High byte of starting address of test area
; 
; Exit: 
; If there are no errors then
; CARRY flag equals 0
; test area contains 00 in all bytes
; else
; CARRY flag equals 1
; Register A = High byte of the address
; containing the error
; Register Y = Low byte of the address
; containing the error
; Register X = Expected value
; 
; Registers used: All
; 
; Time: 
; Approximately 245 cycles per byte plus
; 650 cycles overhead.
; 
; Size: 
; Program 228 bytes
; Data 6 bytes plus
; 2 bytes in page zero
; 
; ;EQUATES SECTION

TADDR: .EQU 0D0H ; PAGE ZERO POINTER TO TEST AREA

;RAMTST:
;GET THE RETURN ADDRESS
PLA
TAY
PLA
TAX

;GET THE LENGTH OF THE TEST AREA
PLA
STA LEN
PLA
STA LEN+1

;GET THE STARTING ADDRESS OF THE TEST AREA
PLA
STA ADDR
PLA
STA ADDR+1
; RESTORE THE RETURN ADDRESS
TXA
PHA
TYA
PHA

; BE SURE THE LENGTH IS NOT ZERO
LDA LEN
ORA LEN+1
BEQ EXITOK ; EXIT WITH NO ERRORS IF LENGTH IS ZERO

; FILL MEMORY WITH FF HEX (ALL 1'S) AND COMPARE
LDA #0FFH
JSR FILCMP
BCS EXITER ; EXIT IF AN ERROR

; FILL MEMORY WITH AA HEX (ALTERNATING 1'S AND 0'S) AND COMPARE
LDA #0AAH
JSR FILCMP
BCS EXITER ; EXIT IF AN ERROR

; FILL MEMORY WITH 55 HEX (ALTERNATING 0'S AND 1'S) AND COMPARE
LDA #55H
JSR FILCMP
BCS EXITER ; EXIT IF AN ERROR

; FILL MEMORY WITH 0 AND COMPARE
LDA #0
JSR FILCMP
BCS EXITER

; PERFORM WALKING BIT TEST
JSR ITEMPS ; INITIALIZE TEMPORARIES

; WALK THROUGH THE 256 BYTE PAGES
LDX TLEN+1 ; CHECK IF ANY FULL PAGES TO DO
BEQ WLKPRT ; BRANCH IF NONE
LDY #0 ; REGISTER Y IS INDEX

WLKLP:
LDA #80H ; SET BIT 7 TO 1, ALL OTHER BITS TO ZERO

WLKLP1:
STA (TADDR),Y ; STORE TEST PATTERN IN MEMORY
CMP (TADDR),Y ; COMPARE VALUE WITH WHAT IS READ BACK
BNE EXITER ; EXIT INDICATING ERROR IF NOT THE SAME
LSR A ; SHIFT TEST PATTERN RIGHT ONE BIT
BNE WLKLP1 ; BRANCH IF NOT DONE WITH BYTE
STA (TADDR),Y ; STORE A ZERO BACK INTO THE LAST BYTE
INY ; INCREMENT TO NEXT BYTE IN PAGE
BNE WLKLP ; BRANCH IF NOT DONE WITH PAGE
INC TADDR+1 ; INCREMENT TO NEXT PAGE
DEX ; DECREMENT PAGE COUNTER
BNE WLKLP ; BRANCH IF NOT DONE WITH ALL OF THE PAGES

; WALK THROUGH LAST PARTIAL PAGE
WLKPRT:
LDX TLEN ;GET NUMBER OF BYTES IN LAST PAGE
BEQ EXITOK ;EXIT IF NONE
LDY #0 ;INITIALIZE INDEX TO ZERO

WLKL3:
LDA #80H ;START WITH BIT 7 EQUAL TO 1

WLKLP:
STA (TADDR),Y ;STORE TEST PATTERN IN MEMORY
CMP (TADDR),Y ;COMPARE VALUE WITH WHAT IS READ BACK
BNE EXITER ;EXIT INDICATING ERROR IF NOT THE SAME
LSR A ;SHIFT TEST PATTERN RIGHT
BNE WLKL3 ;BRANCH IF NOT DONE
STA (TADDR),Y ;STORE A ZERO BACK INTO THE LAST BYTE
INY ;INCREMENT TO NEXT BYTE
DEX ;DECREMENT BYTE COUNTER
BNE WLKL2 ;BRANCH IF NOT DONE

EXITOK:
CLC ;RETURN WITH NO ERROR
RTS

EXITER:
JSR ERROR ;RETURN WITH AN ERROR
RTS

;*************************************************;
;ROUTINE: FILCMP
;PURPOSE: FILL MEMORY WITH A VALUE AND TEST
; THAT MEMORY CONTAINS THAT VALUE
;ENTRY: REGISTER A = VALUE
; ADDR = STARTING ADDRESS
; LEN = LENGTH
;EXIT: IF NO ERRORS THEN
; CARRY FLAG EQUALS 0
; ELSE
; CARRY FLAG EQUALS 1
; REGISTER A = HIGH BYTE OF ERROR LOCATION
; REGISTER Y = LOW BYTE OF ERROR LOCATION
; REGISTER X = EXPECTED VALUE
;REGISTERS USED: ALL
;*************************************************

FILCMP:
JSR ITEMPS ;INITIALIZE TEMPORARIES

;FILL MEMORY WITH THE VALUE IN REGISTER A
;FILL FULL PAGES
LDX TLEN+1
BEQ FILLPRT
LDY #0 ;START AT INDEX 0

FILLP:
STA (TADDR),Y ;STORE THE VALUE
INY ;INCREMENT TO NEXT LOCATION
BNE FILLP ;BRANCH IF NOT DONE WITH THIS PAGE
ARRAY OPERATIONS

INC     TADDR+1 ; INCREMENT HIGH BYTE OF TEMPORARY ADDRESS
DEX     ; DECREMENT PAGE COUNT
BNE     FILLP ; BRANCH IF NOT DONE WITH FILL

FILPRT:
; FILL PARTIAL PAGE
LDX     TLEN
LDY     #0

FILLP1:
STA     (TADDR),Y
INY
DEX
BNE     FILLP1 ; CONTINUE

; COMPARE MEMORY AGAINST THE VALUE IN REGISTER A
CMPARE:
JSR     ITEMPRT ; INITIALIZE TEMPORARIES

; COMPARE MEMORY WITH THE VALUE IN REGISTER A
; COMPARE FULL PAGES FIRST
LDX     TLEN+1
BEQ     CMPPRT
LDY     #0 ; START AT INDEX 0

CMPLP:
CMP     (TADDR),Y ; CAN THE STORED VALUE BE READ BACK ?
BNE     CMPPR ; NO, EXIT INDICATING ERROR
INY
BNE     CMPLP ; BRANCH IF NOT DONE WITH THIS PAGE
INC     TADDR+1 ; INCREMENT HIGH BYTE OF TEMPORARY ADDRESS
DEX
BNE     CMPLP ; BRANCH IF NOT DONE WITH FILL

CMPPRT:
; COMPARE THE LAST PARTIAL PAGE
LDX     TLEN ; REGISTER Y = SIZE OF PARTIAL PAGE
LDY     #0

CMPLP1:
CMP     (TADDR),Y ; CAN THE STORED VALUE BE READ BACK ?
BNE     CMPPR ; NO, EXIT INDICATING ERROR
INY
DEX
BNE     CMPLP1 ; CONTINUE

CMPOK:
CLC ; INDICATE NO ERROR
RTS

CMPER:
JSR     ERROR
RTS

;**********************************************************
; ROUTINE: ITEMPRT
; PURPOSE: INITIALIZE TEMPORARIES
;ENTRY: ADDR IS BEGINNING ADDRESS
; LEN IS NUMBER OF BYTES
;EXIT: TADDR IS SET TO ADDR
; TLEN IS SET TO LEN
;REGISTERS USED: Y,P
;********************************************************************************
ITEMPS:
    LDY ADDR
    STY TADDR
    LDY ADDR+1
    STY TADDR+1
    LDY LEN
    STY TLEN
    LDY LEN+1
    STY TLEN+1
RTS

;********************************************************************************
;ROUTINE: ERROR
;PURPOSE: SET UP THE REGISTERS FOR AN ERROR EXIT
;ENTRY: REGISTER A IS EXPECTED BYTE
; TADDR IS BASE ADDRESS
; REGISTER Y IS INDEX
;EXIT REGISTER X IS SET TO EXPECTED BYTE
; REGISTER A IS SET TO HIGH BYTE OF THE ADDRESS CONTAINING THE ERROR
; REGISTER Y IS SET TO LOW BYTE OF THE ADDRESS CONTAINING THE ERROR
; CARRY FLAG IS SET TO 1
;REGISTERS USED: ALL
;********************************************************************************
ERROR:
    TAX ;REGISTER X = EXPECTED BYTE
    TYA ;GET INDEX
    CLC ;ADDRESS OF ERROR = BASE + INDEX
    ADC TADDR
    TAY ;REGISTER Y = LOW BYTE OF ERROR LOCATION
    LDA TADDR+1
    ADC $0 ;REGISTER A = HIGH BYTE OF ERROR LOCATION
    SEC ;INDICATE AN ERROR BY SETTING CARRY TO 1
    RTS

;DATA SECTION
ADDR: .BLOCK 2 ;ADDRESS OF FIRST ELEMENT
LEN: .BLOCK 2 ;LENGTH
TLEN: .BLOCK 2 ;TEMPORARY LENGTH

; SAMPLE EXECUTION

;
SC0907:

; TEST MEMORY
LDA ADR+1 ; PUSH HIGH BYTE OF STARTING ADDRESS
PHA
LDA ADR ; PUSH LOW BYTE OF STARTING ADDRESS
PHA
LDA Sz+1 ; PUSH HIGH BYTE OF LENGTH
PHA
LDA Sz ; PUSH LOW BYTE OF LENGTH
PHA
JSR RAMTST ; TEST
BRK ; CARRY FLAG SHOULD BE 0
JMP SC0907 ; LOOP FOR MORE TESTING

ADR .WORD 2000H
SZ .WORD 1010H

.END ; PROGRAM
Jump Table (JTAB)

Transfers control to an address selected from a table according to an index. The addresses are stored in the usual 6502 style (less significant byte first), starting at address TABLE. The size of the table (number of addresses) is a constant LENSUB, which must be less than or equal to 128. If the index is greater than or equal to LENSUB, the program returns control immediately with the Carry flag set to 1.

Procedure: The program first checks if the index is greater than or equal to the size of the table (LENSUB). If it is, the program returns control with the Carry flag set. If it is not, the program obtains the starting address of the appropriate subroutine from the table, stores it in memory, and jumps to it indirectly.

**Entry Conditions**

(A) = index

**Exit Conditions**

If (A) is greater than LENSUB, an immediate return with Carry = 1. Otherwise, control transferred to appropriate subroutine as if an indexed call had been performed. The return address remains at the top of the stack.

**Example**

Data: LENSUB (size of subroutine table) = 03.
Table consists of addresses SUB0, SUB1, and SUB2.
Index = (A) = 02
Result: Control transferred to address SUB2
(PC = SUB2).
Title: Jump table
Name: JTAB

Purpose: Given an index, jump to the subroutine with that index in a table

Entry: Register A is the subroutine number 0 to LENSUB-1, the number of subroutines, LENSUB must be less than or equal to 128.

Exit: If the routine number is valid then execute the routine else CARRY flag equals 1

Registers used: A, P

Time: 31 cycles plus execution time of subroutine

Size: Program 23 bytes plus size of table (2*LENSUB) Data 2 bytes

JTAB:

CMP #LENSUB ;BRANCH IF REGISTER A IS TOO LARGE
BCS JTABER ;MULTIPLY VALUE BY 2 FOR WORD-LENGTH INDEX
ASL A
TAY
LDA TABLE,Y ;MOVE STARTING ADDRESS TO TEMPORARY STORAGE
STA TMP
LDA TABLE+1,Y STA TMP+1
JMP (TMP) ;JUMP INDIRECTLY TO SUBROUTINE

JTABER:

SEC
RTS

LENSUB .EQU 3 ;INDICATE A BAD ROUTINE NUMBER

TABLE:

.WORD SUB1 ;ROUTINE 0
.WORD SUB2 ;ROUTINE 1
.WORD SUB3 ;ROUTINE 2

TMP: .BLOCK 2 ;TEMPORARY ADDRESS TO JUMP INDIRECT THROUGH
;THREE SUBROUTINES WHICH ARE IN THE JUMP TABLE

SUB1:
  LDA #1
  RTS

SUB2:
  LDA #2
  RTS

SUB3:
  LDA #3
  RTS

;SAMPLE EXECUTION
;

;PROGRAM SECTION

SC0908:
  LDA #0
  JSR JTAB
  BRK #1
  LDA #1
  JSR JTAB
  BRK
  LDA #2
  JSR JTAB
  BRK
  LDA #3
  JSR JTAB
  BRK
  JMP SC0908

.END ;PROGRAM
Read a Line of Characters from a Terminal
(RDLINE)

Reads ASCII characters from a terminal and saves them in a buffer until it encounters a carriage return character. Defines the control characters Control H (08 hex), which deletes the character most recently entered into the buffer, and Control X (18 hex), which deletes all characters in the buffer. Sends a bell character (07 hex) to the terminal if the buffer becomes full. Echoes to the terminal each character placed in the buffer. Sends a new line sequence (typically carriage return, line feed) to the terminal before exiting.

RDLINE assumes the existence of the following system-dependent subroutines:

1. RDCHAR reads a single character from the terminal and places it in the accumulator.
2. WRCHAR sends the character in the accumulator to the terminal.
3. WRNEWL sends a new line sequence (typically consisting of carriage return and line feed characters) to the terminal.

These subroutines are assumed to change the contents of all the user registers.

RDLINE is intended as an example of a typical terminal input handler. The specific control characters and I/O subroutines in a real system will, of course, be computer-dependent. A specific example in the listing describes an Apple II computer with the following features:

1. The entry point for the routine that reads a character from the keyboard is FD0C16. This routine returns with bit 7 set, so that bit must be cleared for normal ASCII operations.

2. The entry point for the routine that sends a character to the monitor is FDED16. This routine requires bit 7 of the character (in the accumulator) to be set.

3. The entry point for the routine that issues the appropriate new line character (a carriage return) is FD8E16.

4. An 0816 character moves the cursor left one position.

**Procedure:** The program first reads a character using the RDCHAR routine and exits if the character is a carriage return. If the character is not a carriage return, the program checks for the special characters Control H and Control X. In response to Control H, the program decrements the buffer index and sends a backspace string (consisting of cursor left, space, cursor left) to the terminal if there is anything in the buffer. In response to Control X, the program repeats the response to Control H until it empties the buffer. If the character is not special, the program checks to see if the buffer is full. If the buffer is full, the program sends a bell character to the terminal and continues. If the buffer is not full, the program stores the character in the buffer, echoes it to the terminal, and adds one to the buffer index. Before exiting, the program sends a new line sequence to the terminal using the WRNEWL routine.

---

**Entry Conditions**

(A) = More significant byte of starting address of buffer  
(Y) = Less significant byte of starting address of buffer  
(X) = Length (size) of the buffer in bytes.

---

**Exit Conditions**

(X) = Number of characters in the buffer.

---

**Examples**

1. Data: Line (from keyboard is ‘ENTERcr’)  
   Result: Buffer index = 5 (length of line)  
   Buffer contains ‘ENTER’  
   ‘ENTER’ echoed to terminal, followed by the new line sequence (typically either carriage return, line feed or just carriage return)  
   Note that the ‘cr’ (carriage return) character does not appear in the buffer.

2. Data: Line (from keyboard) is ‘DMcontrolHcontrolXENTETcontrolHRcr’.
   Result: Buffer index = 5 (length of actual line)  
   Buffer contains ‘ENTER’  
   ‘ENTER’ echoed to terminal, followed by the new line sequence (typically either carriage return, line feed or just carriage return)

The sequence of operations is as follows:

<table>
<thead>
<tr>
<th>Character Typed</th>
<th>Initial Buffer</th>
<th>Final Buffer</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>empty</td>
<td>‘D’</td>
</tr>
<tr>
<td>M</td>
<td>‘D’</td>
<td>‘DM’</td>
</tr>
<tr>
<td>control H</td>
<td>‘DM’</td>
<td>‘D’</td>
</tr>
<tr>
<td>N</td>
<td>‘D’</td>
<td>‘DN’</td>
</tr>
<tr>
<td>control X</td>
<td>‘DN’</td>
<td>empty</td>
</tr>
<tr>
<td>E</td>
<td>empty</td>
<td>‘E’</td>
</tr>
<tr>
<td>N</td>
<td>‘E’</td>
<td>‘EN’</td>
</tr>
<tr>
<td>T</td>
<td>‘EN’</td>
<td>‘ENT’</td>
</tr>
<tr>
<td>E</td>
<td>‘ENT’</td>
<td>‘ENTE’</td>
</tr>
<tr>
<td>T</td>
<td>‘ENTE’</td>
<td>‘ENTE’</td>
</tr>
<tr>
<td>control H</td>
<td>‘ENTE’</td>
<td>‘ENTER’</td>
</tr>
<tr>
<td>R</td>
<td>‘ENTER’</td>
<td>‘ENTER’</td>
</tr>
</tbody>
</table>


What has happened is the following:

a. The operator types 'D', 'M'

b. The operator recognizes that 'M' is incorrect (should be 'N'), types control H to delete it, and types 'N'.

c. The operator then recognizes that the initial 'D' is incorrect also (should be 'E'). Since the character to be deleted is not the latest one, the operator types control X to delete the entire line, and then types 'ENTET'.

d. The operator recognizes that the second 'T' is incorrect (should be 'R'), types control H to delete it, and types 'R'.

e. The operator types a carriage return to conclude the line.

---

; Title Read line
; Name: RDLINE

; Purpose: Read characters from the input device until a carriage return is found. RDLINE defines the following control characters:
; Control H -- Delete the previous character.
; Control X -- Delete all characters.

; Entry: Register A = High byte of buffer address
; Register Y = Low byte of buffer address
; Register X = Length of the buffer

; Exit: Register X = Number of characters in the buffer

; Registers used: All

; Time: Not applicable.

; Size: Program 138 bytes
; Data 4 bytes plus
; 2 bytes in page zero

;PAGE ZERO POINTER
BUFADR .EQU 0D0H ;INPUT BUFFER ADDRESS

;EQUATES
DELEKEY .EQU 018H ;DELETE LINE KEYBOARD CHARACTER
BSKEY .EQU 08H ;BACKSPACE KEYBOARD CHARACTER
CRKEY .EQU ODH ;CARRIAGE RETURN KEYBOARD CHARACTER
SPACE .EQU 020H ;SPACE CHARACTER
BELL .EQU 07H ;BELL CHARACTER TO RING THE BELL ON THE TERMINAL

RDLINE:
;SAVE PARAMETERS
STA BUFADR+1 ;SAVE HIGH BYTE OF INPUT BUFFER ADDRESS
STY BUFADR ;SAVE LOW BYTE OF INPUT BUFFER ADDRESS
STX BUFLEN ;SAVE MAXIMUM LENGTH

;INITIALIZE BUFFER INDEX TO ZERO
INIT:
LDA #0
STA BUFIDX

;READ LOOP
;READ CHARACTERS UNTIL A CARRIAGE RETURN OCCURS
RDLOOP:
JSR RDCHAR ;READ A CHARACTER FROM THE KEYBOARD
;DOES NOT ECHO

;CHECK FOR CARRIAGE RETURN AND EXIT IF FOUND
CMP #CRKEY
BEQ EXITRD

;CHECK FOR BACKSPACE AND BACK UP IF FOUND
CMP #BSKEY
BNE RDLP1 ;BRANCH IF NOT BACKSPACE CHARACTER
JSR BACKSP ;IF BACKSPACE, BACK UP ONE CHARACTER
JMP RDLOOP ;THEN START READ LOOP AGAIN

;CHECK FOR DELETE LINE CHARACTER AND DELETE LINE IF FOUND
RDLP1:
CMP #DELKEY
BNE RDLP2 ;BRANCH IF NOT DELETE LINE CHARACTER

DELL:
JSR BACKSP ;DELETE A CHARACTER
LDA BUFIDX ;CONTINUE DELETING UNTIL BUFFER IS EMPTY
BNE DEL1
BEQ RDLP2 ;THEN GO READ THE NEXT CHARACTER

;NOT A SPECIAL CHARACTER
; CHECK IF BUFFER IS FULL
; IF NOT FULL STORE CHARACTER AND ECHO
RDLP2:
LDY BUFIDX ;IS BUFFER FULL?
CPY BUFLEN
BCC STRCH ;BRANCH IF NOT
LDA #BELL ;YES IT IS FULL, RING THE TERMINAL'S BELL
JSR WRCHAR
JMP RDLOOP ;THEN CONTINUE THE READ LOOP

STRCH:
STA (BUFADR),Y ;STORE THE CHARACTER
JSR WRCHAR ;ECHO CHARACTER TO TERMINAL
Increment Buffer Index

```
;INCREMENT BUFFER INDEX
INC BUFXIDX
;THEN CONTINUE THE READ LOOP
JMP RDLPLP

;EXIT SEQUENCE
;ECHO NEW LINE SEQUENCE (USUALLY CR, LF)
;GET LENGTH OF BUFFER
EXITRD:
JSR WRNEWL
LDX BUFXIDX
RTS

;******************************
;
; THE FOLLOWING SUBROUTINES ARE SYSTEM SPECIFIC,
; THE APPLE II WAS USED IN THESE EXAMPLES.
;
;******************************

;******************************
;ROUTINE: RDCHAR
;PURPOSE: READ A CHARACTER BUT DO NOT ECHO TO OUTPUT DEVICE
;ENTRY: NONE
;EXIT: REGISTER A = CHARACTER
;REGISTERS USED: ALL
;******************************

RDCHAR:
JSR 0FD0CH ;APPLE MONITOR READ KEYBOARD
AND #0111111B ;ZERO BIT 7
RTS

;******************************
;ROUTINE: WRCHAR
;PURPOSE: WRITE A CHARACTER TO THE OUTPUT DEVICE
;ENTRY: REGISTER A = CHARACTER
;EXIT: NONE
;REGISTERS USED: ALL
;******************************

WRCHAR:
ORA #1000000B ;SET BIT 7
JSR 0FD6DH ;APPLE MONITOR CHARACTER OUTPUT ROUTINE
RTS

;******************************
;ROUTINE: WRNEWL
;PURPOSE: ISSUE THE APPROPRIATE NEW LINE CHARACTER OR
; CHARACTERS. NORMALLY, THIS IS A CARRIAGE RETURN
; AND LINE FEED, BUT SOME COMPUTERS (SUCH AS APPLE II)
; REQUIRE ONLY A CARRIAGE RETURN.
;ENTRY: NONE
;EXIT: NONE
;REGISTERS USED: ALL
;******************************
WRNEWL:
    JSR 0FD8EH ; ECHO CARRIAGE RETURN AND LINE FEED
    RTS

; *************************************************
; ROUTINE: BACKSP
; PURPOSE: PERFORM A DESTRUCTIVE BACKSPACE
; ENTRY: BUFIDX = INDEX TO NEXT AVAILABLE LOCATION IN BUFFER
; EXIT: CHARACTER REMOVED FROM BUFFER
; REGISTERS USED: ALL
; *************************************************

BACKSP:

; CHECK FOR EMPTY BUFFER
LDA BUFIDX
BEQ EXITBS ; EXIT IF NO CHARACTERS IN BUFFER

; BUFFER IS NOT EMPTY SO DECREMENT BUFFER INDEX
DEC BUFIDX ; DECREMENT BUFFER INDEX

; OUTPUT BACKSPACE STRING
LDA #LENBSS
STA COUNT ; COUNT = LENGTH OF BACKSPACE STRING
LDA #0
STA INDEX ; INDEX = INDEX TO FIRST CHARACTER

BSLOOP:

LDA COUNT
BEQ EXITBS ; EXIT IF ALL CHARACTERS HAVE BEEN SENT
LDY INDEX
LDA BSSTRG,Y ; GET NEXT CHARACTER
JSR WRCHAR ; OUTPUT CHARACTER
INC INDEX
DEC COUNT
JMP BSLOOP

EXITBS:

RTS

CSRLFT .EQU 08H ; CHARACTER WHICH MOVES CURSOR LEFT ONE LOCATION
LENBSS .EQU 3 ; LENGTH OF BACKSPACE STRING
BSSTRG .BYTE CSRLFT, SPACE, CSRLFT

; DATA
BUFIDX .BLOCK 1 ; INDEX TO NEXT AVAILABLE CHARACTER IN BUFFER
BUFLEN .BLOCK 1 ; BUFFER LENGTH
COUNT .BLOCK 1 ; COUNT FOR BACKSPACE AND RETYPE
INDEX .BLOCK 1 ; INDEX FOR BACKSPACE AND RETYPE

; SAMPLE EXECUTION:
; ; ; ; ;
SC1001:

;READ LINE
LDA "?" ;OUTPUT PROMPT (QUESTION MARK)
JSR WRCHAR
LDA ADRBUF+1 ;GET THE BUFFER ADDRESS
LDY ADRBUF
LDX #LINBUF ;GET THE BUFFER LENGTH
JSR RDLINE ;READ A LINE

;ECHO LINE
STX CNT
LDA #0
STA IDX

TLOOP:
LDA CNT
BNE TLOOP1 ;BRANCH IF THERE ARE MORE CHARACTERS TO SEND
JSR WRNEWL ;IF NOT ISSUE NEW LINE (CR,LF)
JMP SC1001 ;AND START OVER

TLOOP1:
LDY IDX
LDA INBUFF,Y ;GET THE NEXT CHARACTER
JSR WRCHAR ;OUTPUT IT
INC IDX
DEC CNT ;DECREMENT LOOP COUNTER
JMP TLOOP

;DATA SECTION
IDX: .BLOCK 1 ;INDEX
CNT: .BLOCK 1 ;COUNTER
ADRBUF: .WORD INBUFF ;ADDRESS OF INPUT BUFFER
LINBUF: .EQU 10H ;LENGTH OF INPUT BUFFER
INBUFF: .BLOCK LINBUF ;DEFINE THE INPUT BUFFER

.END ;PROGRAM
Write a Line of Characters to an Output Device
(WRLINE)

Writes characters to an output device using the computer-dependent subroutine WRCHAR, which writes the character in the accumulator on the output device. Continues until it empties a buffer with given length and starting address. This subroutine is intended as an example of a typical output driver. The specific I/O subroutines will, of course, be computer-dependent. The specific example described is the Apple II computer with the following features:

1. The entry point for the routine that sends a character to the monitor is FDED₁₆.

2. The character to be written must be placed in the accumulator with bit 7 set to 1.

Procedure: The program exits immediately if the buffer length is zero. Otherwise, the program sends characters to the output device one at a time until the buffer is emptied. The program saves all its temporary data in memory rather than in registers to avoid dependence on the WRCHAR routine.

Entry Conditions

\[(A) = \text{More significant byte of starting address of buffer}\]
\[(Y) = \text{Less significant byte of starting address of buffer}\]
\[(X) = \text{Length (size) of the buffer in bytes}\]

Exit Conditions

None

Example

Data:  
Buffer length = 5  
Buffer contains ‘ENTER’

Result:  ‘ENTER’ sent to the output device.

Registers Used: All

Execution Time: 24 cycles overhead plus 25 cycles per byte (besides the execution time of subroutine WRCHAR).

Program Size: 37 bytes

Data Memory Required: Two bytes anywhere in RAM plus two bytes on page 0. The two bytes anywhere in RAM hold the buffer index (one byte at address BUFIDX) and the buffer length (one byte at address BUFLEN). The two bytes on page 0 hold a pointer to the output buffer (starting at address BUFADR, 00D0₁₆ in the listing).

Special Case:

A buffer length of zero causes an immediate exit with no characters sent to the output device.
Title: Write line
Name: WRLINE

Purpose: Write characters to the output device
Entry:
Register A = High byte of buffer address
Register Y = Low byte of buffer address
Register X = Length of the buffer in bytes
Exit: None

Registers used: All

Time: 24 cycles overhead plus
(25 + execution time of WRCHAR) cycles per byte
Size:
Program 37 bytes
Data 2 bytes plus
2 bytes in page zero

; PAGE ZERO POINTER
BUFADR .EQU 0DOH ; OUTPUT BUFFER ADDRESS

WRLINE:
; SAVE PARAMETERS
STA BUFADR+1 ; SAVE HIGH BYTE OF OUTPUT BUFFER ADDRESS
STY BUFADR ; SAVE LOW BYTE OF OUTPUT BUFFER ADDRESS
STX BUFLEN ; SAVE LENGTH
BEQ EXIT ; EXIT IF LENGTH = 0

; INITIALIZE BUFFER INDEX TO ZERO
LDA #0
STA BUFIDX

WRLOOP:
LDY BUFIDX
LDA (BUFADR),Y ; GET NEXT CHARACTER
JSR WRCHAR ; OUTPUT CHARACTER
INC BUFIDX ; INCREMENT BUFFER INDEX
DEC BUFLEN ; DECREMENT BUFFER LENGTH
BNE WRLOOP ; BRANCH IF NOT DONE

EXIT:
RTS

; ***********************
; THE FOLLOWING SUBROUTINES ARE SYSTEM SPECIFIC,
; THE APPLE II WAS USED IN THIS EXAMPLE.
; ***********************
**Routine: WRCHAR**

**Purpose:** Write a character to the output device

**Entry:** Register A = Character

**Exit:** None

**Registers Used:** All

---

**WRCHAR:**

```
ORA #10000000B ; SET BIT 7
JSR 0FD6DH ; APPLE MONITOR CHARACTER OUTPUT ROUTINE
RTS
```

---

**Data Section**

```
BUFIDX: .BLOCK 1 ; INDEX TO NEXT AVAILABLE CHARACTER IN BUFFER
BUFSLEN: .BLOCK 1 ; BUFFER LENGTH
```

---

**Sample Execution:**

```
SC1002:
; READ LINE USING THE APPLE MONITOR GETLN ROUTINE AT 0FD6AH
; 33H = ADDRESS CONTAINING APPLE PROMPT CHARACTER
; 200H = BUFFER ADDRESS
LDA #"?" OR 80H ; USE ? FOR PROMPT WITH BIT 7 SET
STA 033H ; SET UP APPLE PROMPT CHARACTER
JSR 0FD6AH ; CALL APPLE MONITOR GETLN ROUTINE
STX LENGTH ; RETURN LENGTH IN REGISTER X

; WRITE THE LINE
LDA #02H ; A = HIGH BYTE OF BUFFER ADDRESS
LDY #0 ; Y = LOW BYTE OF BUFFER ADDRESS
LDX LENGTH ; X = LENGTH OF BUFFER
JSR WRLINE ; OUTPUT THE BUFFER
JSR 0FD8EH ; OUTPUT CARRIAGE RETURN VIA APPLE MONITOR
JMP SC1002 ; CONTINUE
```

---

**Data Section**

```
LENGTH: .BLOCK 1
```

---

.END ; PROGRAM
Generate Even Parity (GEPRTY)

Generates even parity for a seven-bit character and places it in bit 7. Even parity for a seven-bit character is a bit that makes the total number of 1 bits in the byte even.

Procedure: The program generates even parity by counting the number of 1 bits in the seven least significant bits of the accumulator. The counting is accomplished by shifting the data left logically and incrementing the count by one if the bit shifted into the Carry is 1. The least significant bit of the count is an even parity bit; the program concludes by shifting that bit to the Carry and then to bit 7 of the original data.

---

**Entry Conditions**

Data in the accumulator (bit 7 is not used).

**Exit Conditions**

Data with even parity in bit 7 in the accumulator.

---

**Examples**

1. Data: \( (A) = 42_{16} = 01000010_2 \) (ASCII B)
   
   Result: \( (A) = 42_{16} = 01000010_2 \) (ASCII B with bit 7 cleared)
   
   Even parity is 0, since 01000010_2 has an even number (2) of 1 bits.

2. Data: \( (A) = 43_{16} = 01000011_2 \) (ASCII C)
   
   Result: \( (A) = C3_{16} = 11000011_2 \) (ASCII C with bit 7 set)

---

; ; Title Generate even parity
; ; Name: GEPRTY
; ; Purpose: Generate even parity in bit 7 for a 7-bit character.
; ; Entry: Register A = Character

Program Size: 39 bytes

Data Memory Required: One byte anywhere in RAM (at address VALUE) for the data.
Exit:  
Register A = Character with even parity

Registers used: A,F

Time:  114 cycles maximum

Size:  Program 39 bytes
      Data    1 byte

GEPTY:

;SAVE THE DATA
STA VALUE

;SAVE X AND Y REGISTERS
PHA
TXA
PHA
TYA

;COUNT THE NUMBER OF 1 BITS IN BITS 0 THROUGH 6 OF THE DATA
LDY #0  ;INITIALIZE NUMBER OF 1 BITS TO ZERO
LDA VALUE  ;GET DATA
ASL A  ;DROP BIT 7 OF THE DATA, NEXT BIT TO BIT 7
STA VALUE

GELOOP:  BPL SHFT  ;BRANCH IF NEXT BIT (BIT 7) IS 0
INY  ;ELSE INCREMENT NUMBER OF 1 BITS

SHFT:  ASL A
BNE GELOOP  ;BRANCH IF THERE ARE MORE 1 BITS IN THE BYTE

TYA  ;BIT 0 OF NUMBER OF 1 BITS IS EVEN PARITY
LSR VALUE  ;MOVE PARITY TO CARRY
LDA VALUE  ;ROTATE ONCE TO FORM BYTE WITH PARITY IN BIT 7
STA VALUE

;RESTORE X AND Y AND EXIT
PLA
TAY
PLA
TAX
LDA VALUE  ;GET VALUE WITH PARITY
RTS  ;RETURN

;DATA SECTION
VALUE:  .BLOCK 1  ;TEMPORARY DATA STORAGE

;SAMPLE EXECUTION:
; GENERATE PARITY FOR VALUES FROM 0..127 AND STORE THEM IN BUFFER
SC1003:

LDX #0
SC1LP:
TXA
JSR GEPRTY ; GENERATE EVEN PARITY
STA BUFFER,X ; STORE THE VALUE WITH EVEN PARITY
INX
CPX #80H
BNE SC1LP ; BRANCH IF NOT DONE
BRK

BUFFER .BLOCK 128

.END ; PROGRAM
Sets the Carry flag to 0 if a data byte has even parity and to 1 if it has odd parity. A byte has even parity if it has an even number of 1 bits and odd parity if it has an odd number of 1 bits.

Procedure: The program counts the number of 1 bits in the data by shifting the data left logically and incrementing a count if the bit shifted into the Carry is 1. The program quits as soon as the shifted data becomes zero (since zero obviously does not contain any 1 bits). The least significant bit of the count is 0 if the data byte contains an even number of 1 bits and 1 if the data byte contains an odd number of 1 bits. The program concludes by shifting the least significant bit of the count to the Carry flag.

Entry Conditions
Data byte in the accumulator (bit 7 is included in the parity generation).

Exit Conditions
Carry = 0 if the parity of the data byte is even, 1 if the parity is odd.

Examples
1. Data: (A) = 42₁₆ = 01000010₂ (ASCII B)
   Result: Carry = 0, since 42₁₆ (01000010₂) has an even number (2) of 1 bits.

2. Data: A) = 43₁₆ = 01000011₂ (ASCII C)
   Result: Carry = 1, since 43₁₆ (01000011₂) has an odd number (3) of 1 bits.
Title: Check parity
Name: CKPRTY

Purpose: Check parity of a byte

Entry: Register A = Byte with parity in bit 7

Exit: Carry = 0 if parity is even.
      Carry = 1 if parity is odd.

Registers used: A, F

Time: 111 cycles maximum

Size: Program 25 bytes
      Data 1 byte

CKPRTY:

;SAVE DATA VALUE
STA VALUE

;SAVE REGISTERS X AND Y
TXA
PHA
TYA
PHA

;COUNT THE NUMBER OF 1 BITS IN THE VALUE
LDY #0 ;NUMBER OF 1 BITS = 0
LDA VALUE

CKLOOP: BPL SHFT ;BRANCH IF NEXT BIT = 0 (BIT 7)
INY ;ELSE INCREMENT NUMBER OF 1 BITS

SHFT: ASL A ;SHIFT NEXT BIT TO BIT 7
BNE CKLOOP ;CONTINUE UNTIL ALL BITS ARE 0

TYA
LSR A ;CARRY FLAG = LSB OF NUMBER OF 1 BITS

;RESTORE REGISTERS X AND Y AND EXIT
PLA
TAY
PLA
TAX
RTS
VALUE .BLOCK 1 ; DATA BYTE

; CHECK PARITY FOR VALUES FROM 0..255 AND STORE THEM IN BUFFER
; BUFFER[VALUE] = 0 FOR EVEN PARITY
; BUFFER[VALUE] = 1 FOR ODD PARITY
SC1004:
  LDX #0
  SCLP:
  TXA
  JSR CKPRTY ; CHECK PARITY
  LDA #0
  ROL A ; GET PARITY TO BIT 0
  STA BUFFER,X ; STORE THE PARITY
  INX ; INCREMENT VALUE
  BNE SCLP ; CONTINUE THROUGH ALL THE VALUES
  BRK
  JMP SC1004

BUFFER .BLOCK 256

.END ; PROGRAM
Generates a 16-bit cyclic redundancy check (CRC) based on the IBM Binary Synchronous Communications (BSC or Bisync) protocol. Uses the polynomial \( X^{16} + X^{15} + X^2 + 1 \) to generate the CRC. The entry point ICRC16 initializes the CRC to 0 and the polynomial to the appropriate bit pattern. The entry point CRC16 combines the previous CRC with the CRC generated from the next byte of data. The entry point GCRC16 returns the CRC.

Procedure: Subroutine ICRC16 initializes the CRC to zero and the polynomial to the appropriate value (one in each bit position corresponding to a power of \( X \) present in the polynomial). Subroutine CRC16 updates the CRC according to a specific byte of data. It updates the CRC by shifting the data and the CRC left one bit and exclusive-ORing the CRC with the polynomial whenever the exclusive-OR of the data bit and the most significant bit of the CRC is 1. Subroutine CRC16 leaves the CRC in memory locations CRC (less significant byte) and CRC+1 (more significant byte). Subroutine GCRC16 loads the CRC into the accumulator (more significant byte) and index register Y (less significant byte).

Entry Conditions

1. For ICRC16: none
2. For CRC16: data byte in the accumulator, previous CRC in memory locations CRC (less significant byte) and CRC+1 (more significant byte), CRC polynomial in memory locations PLY (less significant byte) and PLY+1 (more significant byte)
3. For GCRC16: CRC in memory locations CRC (less significant byte), and CRC+1 (more significant byte).
Exit Conditions

1. For ICRC16: zero (initial CRC value) in memory locations CRC (less significant byte) and CRC+1 (more significant byte) CRC polynomial in memory locations PLY (less significant byte) and PLY+1 (more significant byte)

2. For CRC16: CRC with current data byte included in memory locations CRC (less significant byte) and CRC+1 (more significant byte)

3. For GCRC16: CRC in the accumulator (more significant byte) and index register Y (less significant byte).

Examples

1. Generating a CRC.
   Call ICRC16 to initialize the polynomial and start the CRC at zero.
   Call CRC16 to update the CRC for each byte of data for which the CRC is to be generated.
   Call GCRC16 to obtain the resulting CRC (more significant byte in A, less significant byte in Y).

2. Checking a CRC.
   Call ICRC16 to initialize the polynomial and start the CRC at zero.
   Call CRC16 to update the CRC for each byte of data (including the stored CRC) for checking.
   Call GCRC16 to obtain the resulting CRC (more significant byte in A, less significant byte in Y). If there were no errors, both bytes should be zero.

Note that only subroutine ICRC16 depends on the particular CRC polynomial being used. To change the polynomial requires only a change of the data that ICRC16 loads into memory locations PLY (less significant byte) and PLY+1 (more significant byte).

Reference

Title: Generate CRC-16
Name: CRC16

Purpose: Generate a 16 bit CRC based on the IBM binary synchronous communications protocol. The CRC is based on the following polynomial:

\( x^{16} + x^{15} + x^2 + 1 \)

To generate a CRC:
1) Call ICRC16 to initialize the CRC to 0 and the CRC polynomial.
2) Call CRC16 for each byte of data for which the CRC is to be generated.
3) Call GCRC16 to get the resulting CRC. It should then be appended to the data, high byte first.

To check a CRC:
1) Call ICRC16 to initialize the CRC.
2) Call CRC16 for each byte of data and the 2 bytes of CRC previously generated.
3) Call GCRC16 to obtain the CRC. It will be zero if no errors have occurred.

Entry: Register A = Data byte
Exit: CRCLO and CRCHI updated
Register A = Data byte

Registers used: None

Time: 302 cycles minimum if no 1 bits are generated.
454 cycles maximum if all 1 bits are generated.

Size: Program 53 bytes
Data 5 bytes

CRC16:

;SAVE THE DATA BYTE
STA VALUE

;SAVE ALL REGISTERS
PHP
PHA
TYA
PHA
TXA
PHA
; LOOP THROUGH EACH BIT GENERATING THE CRC
LDX #8 ; 8 BITS PER BYTE

CRCLP:
ASL VALUE ; MOVE BIT 7 TO CARRY
ROR A ; MOVE CARRY TO BIT 7
AND #10000000B ; MASK OFF ALL OTHER BITS
EOR CRC+1 ; EXCLUSIVE OR BIT 7 WITH BIT 16 OF THE CRC
ASL CRC ; SHIFT CRC LEFT 1 BIT (FIRST THE LOW BYTE,
ROL A ; THEN THE HIGH BYTE)
BCC CRCLP1 ; BRANCH IF THE MSB OF THE CRC IS 1

; BIT 7 IS 1 SO EXCLUSIVE-OR THE CRC WITH THE POLYNOMIAL
TAY ; SAVE CRC HIGH IN Y
LDA CRC
EOR PLY ; EXCLUSIVE OR LOW BYTE WITH THE POLYNOMIAL
STA CRC
TYA
EOR PLY+1 ; DO HIGH BYTE ALSO

CRCLP1:
STA CRC+1 ; STORE THE HIGH BYTE OF THE CRC
DEX
BNE CRCLP ; BRANCH IF NOT DONE WITH ALL 8 BITS

; RESTORE THE REGISTERS AND EXIT
PLA
TAX
PLA
TAY
PLA
PLP
RTS

; -----------------------------------------------
; ROUTINE: ICRC16
; PURPOSE: INITIALIZE CRCHI, CRCLO, PLYHI, PLYLO
; ENTRY: NONE
; EXIT: CRC AND POLYNOMIAL INITIALIZED
; REGISTERS USED: A, F
; -----------------------------------------------

ICRC16:
LDA #0 ; CRC = 0
STA CRC
STA CRC+1
LDA #5
STA PLY ; PLY = 8005H
; 8005H IS FOR X^16+X^15+X^2+1
; (1 IN EACH POSITION FOR WHICH A POWER
; APPEARS IN THE FORMULA)

LDA #80H
STA PLY+1
RTS
;ROUTINE: GCRC16
;PURPOSE: GET THE CRC16 VALUE
;ENTRY: NONE
;EXIT: REGISTER A = CRC16 HIGH BYTE
; REGISTER Y = CRC16 LOW BYTE
;REGISTERS USED: A,F,Y

;**************************************************
GCRC16:
LDA CRC+1 ;A = HIGH BYTE
LDY CRC  ;Y = LOW BYTE
RTS

VALUE: .BLOCK 1 ;DATA BYTE
CRC:  .BLOCK 2 ;CRC VALUE
PLY:  .BLOCK 2 ;POLYNOMIAL VALUE USED TO GENERATE THE CRC

;SAMPLE EXECUTION:

;GENERATE A CRC FOR A VALUE OF 1 AND CHECK IT
SC1005:
JSR ICRC16 ;GENERATE CRC
LDA #1
JSR CRC16 ;SAVE CRC HIGH BYTE IN REGISTER X
JSR GCRC16 ;INITIALIZE AGAIN
TAX
JSR ICRC16 ;CHECK CRC BY GENERATING IT FOR DATA
LDA #1
JSR CRC16 ;AND THE STORED CRC ALSO
TYA
JSR CRC16
BRK ;THE CRC SHOULD BE ZERO IN REGISTERS A AND Y

;GENERATE A CRC FOR THE VALUES FROM 0..255 AND CHECK IT
JSR ICRC16
LDX #0

GENLP:
TXA ;GET NEXT BYTE
JSR CRC16 ;UPDATE CRC
INX
BNE GENLP ;BRANCH IF NOT DONE
JSR GCRC16 ;GET RESULTING CRC
STA CRCVAL+1 ;AND SAVE IT
STY CRCVAL
; CHECK THE CRC BY GENERATING IT AGAIN
JSR ICRC16
LDX #0

CHKLP:
TXA
JSR CRC16
INX
BNE CHKLP

; ALSO INCLUDE STORED CRC IN CHECK
LDA CRCVAL+1
JSR CRC16 ; HIGH BYTE OF CRC FIRST
LDA CRCVAL ; THEN LOW BYTE OF CRC
JSR GCRC16 ; GET RESULTING CRC
BRK ; IT SHOULD BE 0
JMP SC1005

CRCVAL: BLOCK 2

.END
I/O Device Table Handler (IOHDLR)

Performs input and output in a device-independent manner using I/O control blocks and an I/O device table. The I/O device table consists of a linked list; each entry contains a link to the next entry, the device number, and starting addresses for routines that initialize the device, determine its input status, read data from it, determine its output status, and write data to it. An I/O control block is an array containing the device number, the operation number, device status, the starting address of the device’s buffer, and the length of the device’s buffer. The user must provide IOHDLR with the address of an appropriate I/O control block and the data if only one byte is to be written. IOHDLR will return a copy of the status byte and the data if only one byte is read.

This subroutine is intended as an example of how to handle input and output in a device-independent manner. The I/O device table must be constructed using subroutines INITIO, which initializes the device list to empty, and ADDDL, which adds a device to the list. A specific example for the Apple II sets up the Apple II console as device 1 and the printer as device 2; a test routine reads a line from the console and echoes it to the console and the printer.

A general purpose program will perform input or output by obtaining or constructing an I/O control block and then calling IOHDLR. Subroutine IOHDLR will then determine which device to use and how to transfer control to its I/O driver by using the I/O device table.

Procedure: The program first initializes the status byte to zero, indicating no errors. It then searches the device table, looking for the device number in the I/O control block. If it does not find a match in the table, it exits with an appropriate error number in the status byte. If the program finds a device with the proper device number, it checks for a valid operation and transfers control to the appropriate routine from the entry in the device table. That routine must then transfer control back to the original calling routine. If the operation is invalid (the operation number is too large or the starting address for the routine is zero), the program returns with an error indication in the status byte.
Subroutine INITDL initializes the device list, setting the initial link to zero.
Subroutine ADDDL adds an entry to the device list, making its address the head of the list and setting its link field to the old head of the list.

---

**Entry Conditions**

1. For IOHDLR:
   (A) = More significant byte of starting address of input/output control block
   (Y) = Less significant byte of starting address of input/output control block
   (X) = Byte of data if the operation is to write one byte.
   
2. For INITL: None

3. For ADDDL:
   (A) = More significant byte of starting address of a device table entry
   (Y) = Less significant byte of starting address of a device table entry.

---

**Exit Conditions**

1. For IOHDLR:
   (A) = I/O control block status byte if an error is found; otherwise, the routine exits to the appropriate I/O driver.
   (X) = Byte of data if the operation is to read one byte.

2. For INITL:
   Device list header (addresses DVLST and DVLST+1) cleared to indicate empty list.

3. For ADDDL:
   Device table entry added to list.

---

**Example**

In the example provided, we have the following structure:

<table>
<thead>
<tr>
<th>INPUT/OUTPUT OPERATIONS</th>
<th>INPUT/OUTPUT CONTROL BLOCK</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Operation Number</strong></td>
<td><strong>Index</strong></td>
</tr>
<tr>
<td><strong>Operation</strong></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
</tr>
<tr>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>6</td>
<td>6</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Operation Number</th>
<th>Operation</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Initialize device</td>
<td>Device number</td>
</tr>
<tr>
<td>1</td>
<td>Determine input status</td>
<td>Operation number</td>
</tr>
<tr>
<td>2</td>
<td>Read 1 byte from input device</td>
<td>Status</td>
</tr>
<tr>
<td>3</td>
<td>Read N bytes from input device</td>
<td>Less significant byte of starting address of buffer</td>
</tr>
<tr>
<td>4</td>
<td>Determine output status</td>
<td>More significant byte of starting address of buffer</td>
</tr>
<tr>
<td>5</td>
<td>Write one byte to output device</td>
<td>Less significant byte of buffer length</td>
</tr>
<tr>
<td>6</td>
<td>Write N bytes to output device</td>
<td>More significant byte of buffer length</td>
</tr>
</tbody>
</table>
### DEVICE TABLE ENTRY

<table>
<thead>
<tr>
<th>Index</th>
<th>Contents</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Less significant byte of link field (starting address of next element)</td>
<td>12</td>
<td>More significant byte of starting address of output status determination routine</td>
</tr>
<tr>
<td>1</td>
<td>More significant byte of link field (starting address of next element)</td>
<td>13</td>
<td>Less significant byte of starting address of output driver routine (write 1 byte only)</td>
</tr>
<tr>
<td>2</td>
<td>Device number</td>
<td>14</td>
<td>More significant byte of starting address of output driver routine (write 1 byte only)</td>
</tr>
<tr>
<td>3</td>
<td>Less significant byte of starting address of device initialization routine</td>
<td>15</td>
<td>Less significant byte of starting address of output driver routine (N bytes or 1 line)</td>
</tr>
<tr>
<td>4</td>
<td>More significant byte of starting address of device initialization routine</td>
<td>16</td>
<td>More significant byte of starting address of output driver routine (N bytes or 1 line)</td>
</tr>
<tr>
<td>5</td>
<td>Less significant byte of starting address of input status determination routine</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>More significant byte of starting address of input status determination routine</td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>Less significant byte of starting address of input driver routine (read 1 byte only)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>More significant byte of starting address of input driver routine (read 1 byte only)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>Less significant byte of starting address of input driver routine (N bytes or 1 line)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>More significant byte of starting address of input driver routine (N bytes or 1 line)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>Less significant byte of starting address of output status determination routine</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

If an operation is irrelevant or undefined for a particular device (e.g., output status determination for a keyboard or an input driver routine for a printer), the corresponding starting address in the device table must be set to zero (i.e., 0000<sub>16</sub>).

### STATUS VALUES

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>No errors</td>
</tr>
<tr>
<td>1</td>
<td>Bad device number (no such device)</td>
</tr>
<tr>
<td>2</td>
<td>Data available from input device, no such operation for I/O</td>
</tr>
<tr>
<td>3</td>
<td>Output device ready</td>
</tr>
</tbody>
</table>

---

**Title:** I/O Device table handler

**Name:** IOHDLR

**Purpose:** Perform I/O in a device independent manner. This can only be implemented by accessing all devices in the same way using an I/O Control Block (IOCB) and a device table. The routines here will allow the following operations:
Entry:

Register A = High byte of IOCBL
Register Y = Low byte of IOCBL
Register X = For write 1 byte contains the byte to write, a buffer is not used.

Exit:

Register A = a copy of the IOCBL status byte
Register X = For read 1 byte contains the byte read, a buffer is not used.
Status byte of IOCBL is 0 if the operation was
completed successfully; otherwise it contains the error number.

<table>
<thead>
<tr>
<th>Status value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>No errors</td>
</tr>
<tr>
<td>1</td>
<td>Bad device number</td>
</tr>
<tr>
<td>2</td>
<td>Input data available, no such operation</td>
</tr>
<tr>
<td>3</td>
<td>Output ready</td>
</tr>
</tbody>
</table>

Registers used: All

Time: 93 cycles minimum plus 59 cycles for each device in the list which is not the requested device.

Size:
- Program 131 bytes
- Data 3 bytes plus 6 bytes in page zero

;IOCB AND DEVICE TABLE EQUATES
IOCB: .EQU 0 ;IOCB DEVICE NUMBER
IOCBOP: .EQU 1 ;IOCB OPERATION NUMBER
IOCBST: .EQU 2 ;IOCB STATUS
IOCBBBA: .EQU 3 ;IOCB BUFFER ADDRESS
IOCBBBL: .EQU 5 ;IOCB BUFFER LENGTH
DTLNK: .EQU 0 ;DEVICE TABLE LINK FIELD
DTTN: .EQU 2 ;DEVICE TABLE DEVICE NUMBER
DTSR: .EQU 3 ;BEGINNING OF DEVICE TABLE SUBROUTINES

;OPERATION NUMBERS
NUMOP: .EQU 7 ;NUMBER OF OPERATIONS
INIT: .EQU 0 ;INITIALIZATION
ISTAT: .EQU 1 ;INPUT STATUS
R1BYTE: .EQU 2 ;READ 1 BYTE
RNBYTE: .EQU 3 ;READ N BYTES
OSTAT: .EQU 4 ;OUTPUT STATUS
W1BYTE: .EQU 5 ;WRITE 1 BYTE
WNBYTE: .EQU 6 ;WRITE N BYTES

;PAGE ZERO DEFINITIONS
IOCBA: .EQU 0D0H ;ADDRESS OF THE IOCB
DVLST: .EQU 0D2H ;ADDRESS OF A LIST OF DEVICES
CURDEV: .EQU 0D4H ;STARTING ADDRESS OF THE CURRENT DEVICE TABLE ENTRY

IOHDLR:
;SAVE IOCB ADDRESS AND X REGISTER
STA IOCB+1
STY IOCB
STX SVXREG
; INITIALIZE STATUS BYTE TO ZERO (NO ERRORS)
LDY #IOCBST
LDA #0
STA (IOCBA), Y ; STATUS := 0

; SEARCH DEVICE LIST FOR THIS DEVICE
LDA DVLST ; START AT THE BEGINNING OF THE DEVICE LIST
STA CURDEV
LDA DVLST+1
STA CURDEV+1

; GET DEVICE NUMBER FROM IOC B TO REGISTER X
LDY #IOCBDN
LDA (IOCBA), Y
TAX

SRCHLP:

; CHECK IF AT END OF DEVICE TABLE LIST (LINK FIELD = 0000)
LDA CURDEV
ORA CURDEV+1
BEQB ADDN ; BRANCH IF NO MORE DEVICES

; CHECK IF THIS IS THE CORRECT DEVICE
TXA
LDY #D TDN
CMP (CURDEV), Y ; COMPARE THIS DEVICE NUMBER WITH THE REQUESTED
; NUMBER
BEQ FOUND ; BRANCH IF THE DEVICE IS FOUND

; ADVANCE TO THE NEXT DEVICE TABLE ENTRY THROUGH THE LINK FIELD
; MAKE CURRENT DEVICE = LINK
LDY #D TLNK
LDA (CURDEV), Y ; GET LOW BYTE OF LINK FIELD
PHA ; SAVE ON STACK
INY
LDA (CURDEV), Y ; GET HIGH BYTE OF LINK FIELD
STA CURDEV+1
PLA ; RECOVER LOW BYTE OF LINK FIELD
STA CURDEV
JMP SRCHLP ; CONTINUE SEARCHING

FOUND:

; CHECK THAT THE OPERATION IS VALID
LDY #IOCBO P
LDA (IOCBA), Y ; GET OPERATION NUMBER
CMP #NUMOP
BCS BADOP ; BRANCH IF OPERATION NUMBER IS TOO LARGE

; GET OPERATION ADDRESS (ZERO INDICATES INVALID OPERATION)
ASL A ; MULTIPLY OPERATION NUMBER BY 2 TO INDEX
CLC ; ADDRESSES
ADC #DTSR ; ADD TO OFFSET FOR DEVICE TABLE SUBROUTINES
TAY ; USE AS INDEX INTO DEVICE TABLE
LDA  (CURDEV), Y  ;STORE LOW BYTE
STA  OPADR  
INY
LDA  (CURDEV), Y  ;STORE HIGH BYTE
STA  OPADR+1
ORA  OPADR  ;CHECK FOR NON-ZERO OPERATION ADDRESS
BEQ  BADO P  ;BRANCH IF OPERATION IS INVALID (ADDRESS = 0)
LDX  SVXREG  ;RESTORE X REGISTER
JMP  (OPADR)  ;GOTO ROUTINE

BADD N:
LDA  $1  ;ERROR CODE 1 -- NO SUCH DEVICE
BNE  ERE X IT

BADOP:
LDA  $2  ;ERROR CODE 2 -- NO SUCH OPERATION

ERE X IT:
LDY  #IOCBST  ;STORE ERROR STATUS
STA  (IOCB A), Y  ;STORE ERROR STATUS
RTS

;***************************************************************
;ROUTINE: INIT DL  
;PURPOSE: INITIALIZE THE DEVICE LIST TO EMPTY  
;ENTRY: NONE  
;EXIT: THE DEVICE LIST SET TO NO ITEMS  
;REGISTERS USED: A,F  
;***************************************************************

INIT DL:
;INITIALIZE DEVICE LIST TO 0 TO INDICATE NO DEVICES
LDA  #0
STA  DVLST
STA  DVLST+1
RTS

;***************************************************************
;ROUTINE: ADD DL  
;PURPOSE: ADD A DEVICE TO THE DEVICE LIST  
;ENTRY: REGISTER A = HIGH BYTE OF A DEVICE TABLE ENTRY  
;  REGISTER Y = LOW BYTE OF A DEVICE TABLE ENTRY  
;EXIT: THE DEVICE TABLE ADDED TO THE DEVICE LIST  
;REGISTERS USED: ALL  
;***************************************************************

AD D DL:
;X,Y = NEW DEVICE TABLE ENTRY
TAX

;PUSH CURRENT HEAD OF DEVICE LIST ON TO STACK
LDA  DVLST+1
PHA
LDA   DVLST
PHA

;MAKE NEW DEVICE TABLE ENTRY THE HEAD OF THE DEVICE LIST
STY   DVLST
STX   DVLST+1

;SET LINK FIELD OF THE NEW DEVICE TO THE OLD HEAD OF THE DEVICE LIST
PLA
LDY   #0
STA   (DVLST),Y ;STORE THE LOW BYTE
PLA
INY
STA   (DVLST),Y ;STORE THE HIGH BYTE
RTS

;DATA SECTION
OPADR:  .BLOCK 2 ;OPERATION ADDRESS USED TO VECTOR TO
               ;SUBROUTINE
SVXREG: .BLOCK 1 ;TEMPORARY STORAGE FOR X REGISTER

;SAMPLE EXECUTION:

;This test routine will set up the APPLE II console as device 1 and an APPLE II printer which is assumed to be
;in slot 1 as device 2. The test routine will then read
;a line from the console and echo it to the console and the printer.

;EQUATE
CR   .EQU  06DH   ;APPLE II CARRIAGE RETURN CHARACTER
CBUF .EQU  0D6H   ;STARTING ADDRESS OF I/O BUFFER

SC1006:  ;INITIALIZE DEVICE LIST
JSR   INITDL

;SET UP APPLE CONSOLE AS DEVICE 1
LDA   CONDA+1
LDY   CONDA
JSR   ADDDL   ;ADD CONSOLE DEVICE TO DEVICE LIST
LDA   #INIT
STA   IOCB+IOCBOP
LDA   #1
STA   IOCB+IOCBDN   ;DEVICE NUMBER = 1
LDA   AIOCB+1
LDY   AIOCB
JSR   IOHDLR   ;PERFORM INITIALIZATION
; SET UP APPLE PRINTER AS DEVICE 2
LDA  PRTDVA+1
LDY  PRTDVA
JSR  ADDDL ; ADD PRINTER DEVICE TO DEVICE LIST
LDA  #INIT ; INITIALIZE OPERATION
STA  IOCB+IOCBOP
LDA  #2
STA  IOCB+IOCBDN ; DEVICE NUMBER = 2
LDA  AIOCB+1
LDY  AIOCB
JSR  IOHDLR ; INITIALIZE PRINTER DEVICE

; LOOP READING LINES FROM CONSOLE, AND ECHOING THEM TO
; THE CONSOLE AND PRINTER UNTIL A BLANK LINE IS ENTERED
TSTLP:
LDA  #1 ; SET DEVICE TO NUMBER 1 (CONSOLE)
STA  IOCB+IOCBDN
LDA  #RNBYTE ; SET OPERATION TO READ N BYTES
STA  IOCB+IOCBOP
LDA  #LENBUF ; SET BUFFER LENGTH TO LENBUF
STA  IOCB+IOCBBL
LDA  #0 ; THE HIGH BYTE OF LENBUF IS 0 IN OUR EXAMPLE
STA  IOCB+IOCBBL+1
LDA  AIOCB+1 ; SET REGISTERS A,Y TO THE IOCB ADDRESS
LDY  AIOCB
JSR  IOHDLR ; READ A LINE

; ECHO THE LINE TO THE CONSOLE
; DEVICE IS STILL CONSOLE FROM THE READ LINE ABOVE
LDA  #WBYTE ; SET OPERATION TO WRITE N BYTES
STA  IOCB+IOCBOP
LDA  AIOCB+1 ; SET REGISTERS A,Y TO THE IOCB ADDRESS
LDY  AIOCB
JSR  IOHDLR ; WRITE N BYTES

; OUTPUT A CARRIAGE RETURN TO CONSOLE
LDX  #CR ; SET REGISTER X TO CARRIAGE RETURN CHARACTER
LDA  #W1BYTE ; SET OPERATION TO WRITE 1 BYTE
STA  IOCB+IOCBOP
LDA  AIOCB+1 ; SET REGISTERS A,Y TO THE IOCB ADDRESS
LDY  AIOCB
JSR  IOHDLR ; WRITE 1 BYTE

; ECHO THE LINE TO THE PRINTER ALSO
LDA  #2 ; SET DEVICE TO NUMBER 2 (PRINTER)
STA  IOCB+IOCBBDN
LDA  #WBYTE ; SET OPERATION TO WRITE N BYTES
STA  IOCB+IOCBOP
LDA  AIOCB+1 ; SET REGISTERS A,Y TO THE IOCB ADDRESS
LDY  AIOCB
JSR  IOHDLR ; WRITE N BYTES

; WRITE A CARRIAGE RETURN TO THE PRINTER
LDX  #8DH ; SET REGISTER X TO CARRIAGE RETURN CHARACTER
LDA  #W1BYTE ; SET OPERATION TO WRITE 1 BYTE
STA IOCB+IOCBOP
LDA AIOCB+1
LDY AIOCB
JSR IOHDLR
LDA IOCB+IOCBBL
LDY #1
ORA IOCB+IOCBBL,Y
BNE TSTLP
BRK
JMP SC1006

;IOCB FOR PREFORMING THE IO
AIOCB: .WORD IOCB
IOCB .BLOCK 1
.IOCB .BLOCK 1
.IOCB .BLOCK 1
.IOCB .WORD BUFFER
.IOCB .WORD LENBUF

;BUFFER
LENBUF .EQU 127
BUFFER .BLOCK LENBUF

;DEVI CE TABLE ENTRIES
CONDVA: .WORD CONDV
CONDV: .WORD 0
.CONDV .BYTE 1
.CONDV .WORD CINIT
.CONDV .WORD CISTAT
.CONDV .WORD CIN
.CONDV .WORD CINN
.CONDV .WORD COSTAT
.CONDV .WORD COUT
.CONDV .WORD COUTN

PRTDVA: .WORD PRTDV
PRTDV: .WORD 0
.PRTDV .BYTE 2
.PRTDV .WORD PINIT
.PRTDV .WORD 0
.PRTDV .WORD 0
.PRTDV .WORD 0
.PRTDV .WORD POSTAT
.PRTDV .WORD POUT
.PRTDV .WORD POUTN

;****************************************
;CONSOLE I/O ROUTINES
;****************************************
;CONSOLE INITIALIZE
CINIT:
  LDA  #0
  ;A = STATUS NO ERRORS
  RTS
  ;NO INITIALIZATION NECESSARY

;CONSOLE INPUT STATUS (READY IS BIT 7 OF ADDRESS 0C000H)
CISTAT:
  LDA  0C000H
  ;GET KEYBOARD STATUS BYTE
  BPL  CNONE
  ;BRANCH IF CHARACTER IS NOT READY
  LDA  #2
  ;INDICATE CHARACTER IS READY
  BNE  CIS1
  ;BRANCH ALWAYS TAKEN

CNONE:
  LDA  #0
  ;NOT READY

CIS1:
  LDY  #IOCBST
  STA  (IOCB),Y
  ;STORE STATUS AND LEAVE IT IN REGISTER A
  RTS

;CONSOLE READ 1 BYTE
CIN:
  LDA  C000H
  ;WAIT FOR CHARACTER TO BECOME READY
  BPL  CIN
  ;MOVE CHARACTER TO REGISTER X
  TXA
  LDA  #0
  ;STATUS = NO ERRORS
  RTS

;CONSOLE READ N BYTES
CINN:
  ;READ LINE USING THE APPLE MONITOR GETLN ROUTINE AT 0FD6AH
  ;33H = PROMPT LOCATION
  ;200H = BUFFER ADDRESS
  LDA  #"?" OR 80H
  STA  033H
  ;SET UP APPLE PROMPT CHARACTER
  JSR  0FD6AH
  ;CALL APPLE MONITOR GETLN ROUTINE
  ;VERIFY THAT THE NUMBER OF BYTES READ WILL FIT INTO THE CALLERS BUFFER
  LDY  #IOCBBL+1
  LDA  (IOCB),Y
  BNE  CINN1
  ;GET HIGH BYTE
  DEY
  TXA
  CMP  (IOCB),Y
  BCC  CINN1
  ;BRANCH IF THE NUMBER OF CHARACTERS READ IS
  BEQ  CINN1
  ;LESS THAN THE BUFFER LENGTH
  ;BRANCH IF THE LENGTHS ARE EQUAL
  LDA  (IOCB),Y
  TAX
  STA  (IOCB),Y
  ;OTHERWISE TRUNCATE THE NUMBER OF CHARACTERS
  ;READ TO THE BUFFER LENGTH

CINN1:
  TXA
  STA  (IOCB),Y
  ;SET BUFFER LENGTH TO NUMBER OF CHARACTERS READ
  LDA  #0
  INY
  STA  (IOCB),Y
  ;ZERO UPPER BYTE OF BUFFER LENGTH
;MOVE THE DATA FROM APPLE BUFFER AT 200H TO CALLER'S BUFFER
LDY  #IOCBBA
LDA  (IOCBBA),Y
STA  CBUF
INY
LDA  (IOCBBA),Y
STA  CBUF+1
TXA
BEQ  CINN3
LDY  #0

;NOW MOVE THE DATA TO CALLER'S BUFFER
CINN2:
LDA  200H,Y
STA  (CBUF),Y
INY
DEX
BNE  CINN2

;GOOD STATUS (0) - NO ERRORS
CINN3:
LDA  #0
STA  INY
DEX
BNE  CINN2

;CONSOLE OUTPUT STATUS
COSTAT:
LDA  #3
RTS

;CONSOLE OUTPUT 1 BYTE
COUT:
TXA
COUT1:
JSR  0FD6DH
LDA  #0
RTS
COUT1A: .WORD COUT1

;CONSOLE OUTPUT N BYTE
COUTN:
LDA  COUT1A+1
LDY  COUT1A
JSR  OUTN
LDA  #0
RTS

;PRINTER ROUTINES
; ASSUME PRINTER CARD IS IN SLOT 1
;PRINTER INITIALIZE
PINIT:
   LDA #0 ; NOTHING TO DO, RETURN NO ERRORS
   RTS

;PRINTER OUTPUT STATUS
POSTAT:
   LDA #0 ; ASSUME IT IS ALWAYS READY
   RTS

;PRINTER OUTPUT 1 BYTE
POUT:
   TXA
POUT1:
   JSR 0C107H ; CHARACTER OUTPUT ROUTINE
   LDA #0
   RTS

POUT1A: .WORD POUT1 ; ADDRESS OF CHARACTER OUTPUT ROUTINE TO BE
    ; PLACED IN A,Y

;PRINTER OUTPUT N BYTES
POUTN:
   LDA POUT1A+1
   LDY POUT1A ; A,Y = ADDRESS OF OUTPUT ROUTINE
   JSR OUTN ; CALL OUTPUT N CHARACTERS
   LDA #0 ; NO ERRORS
   RTS

;******************************************************
; ROUTINE: OUTN
; PURPOSE: OUTPUT N CHARACTERS
; ENTRY: REGISTER A = HIGH BYTE OF CHARACTER OUTPUT SUBROUTINE ADDRESS
;         REGISTER Y = LOW BYTE OF CHARACTER OUTPUT SUBROUTINE ADDRESS
;         IOCBA = STARTING ADDRESS OF AN IOCB
; EXIT: DATA OUTPUT
; REGISTERS USED: ALL
;******************************************************
OUTN:
   ; STORE ADDRESS OF THE CHARACTER OUTPUT SUBROUTINE
   STA COSR+1
   STY COSR

   ; GET OUTPUT BUFFER ADDRESS FROM IOCB, SAVE ON PAGE ZERO
   LDY #IOCBB
   LDA (IOCBA),Y
   STA CBUF
   INY
   LDA (IOCBA),Y
   STA CBUF+1
;GET BUFFER LENGTH FROM IOCBA, EXIT IF IT IS ZERO
LDY   $IOCBBL
LDA   (IOCBA),Y
STA   BUFLEN
INY
LDA   (IOCBA),Y
STA   BUFLEN+1
ORA   BUFLEN
BEQ   OUT3   ;BRANCH IF BUFFER LENGTH IS ZERO

;START AT BEGINNING OF BUFFER
LDA   #0
STA   IDX

OUTLP:
LDY   IDX
LDA   (CBUF),Y   ;GET NEXT CHARACTER FROM BUFFER
JSR   LP0       ;WRITE CHARACTER TO OUTPUT DEVICE
JMP   LP1

LP0:  JMP   (COSR)   ;OUTPUT THE CHARACTER VIA THE CURRENT
       ; OUTPUT SUBROUTINE

LP1:
;INCREMENT TO THE NEXT CHARACTER IN THE BUFFER
INC   IDX
BNE   LP2
INC   CBUF+1   ;INCREMENT THE HIGH BYTE IS NECESSARY

;DECREMENT BUFFER LENGTH, CONTINUE LOOPING IF IT IS NOT ZERO

LP2:
LDA   BUFLEN
BNE   DECLS
DEC   BUFLEN+1   ;BORROW FROM HIGH BYTE IF NECESSARY
DECLS:
DEC   BUFLEN   ;ALWAYS DECREMENT LOW BYTE
BNE   OUTLP
LDA   BUFLEN+1
BNE   OUTLP   ;CONTINUE UNLESS ALL CHARACTERS SENT

OUT3:
RTS

COSR: .WORD 0   ;ADDRESS OF THE CHARACTER OUTPUT SUBROUTINE
BUFLEN: .WORD 0   ;TEMPORARY BUFFER LENGTH
IDX:   .BYTE 0   ;TEMPORARY INDEX
.END
**Initialize I/O Ports** (IOPORTS)

Initializes a set of I/O ports from an array of port addresses and initial values. Examples are given of initializing programmable I/O devices such as the 6520 Peripheral Interface Device (Adapter), the 6522 Versatile Interface Adapter, the 6530 Multifunction Device, the 6532 Multifunction Device, the 6551 Asynchronous Communications Device Adapter, and the 6850 Asynchronous Communications Device Adapter.

This subroutine is intended as a generalized method for initializing I/O sections. The initialization may involve data ports, data direction registers that determine whether bits are inputs or outputs, control or command registers that determine the operating modes of programmable devices, counters (in timers), priority registers, and other external registers or storage locations.

Some of the tasks the user may perform with this routine are:

1. Assign bidirectional I/O lines as inputs or outputs.
2. Initialize output ports to known starting values.
3. Enable or disable interrupts from peripheral chips.
4. Determine operating modes, such as whether inputs are latched, whether strobes are produced, how priorities are assigned, whether timers operate continuously or only on demand, etc.
5. Load initial counts into timers.

7. Clear or reset devices that are not tied to the overall system reset line.
8. Initialize priority registers or assign initial priorities to interrupts or other operations.
9. Initialize vectors used in servicing interrupts, DMA requests, and other inputs.

**Procedure:** The program loops through the specified number of ports, obtaining the port address and the initial value from the array and storing the initial value in the port address. This procedure does not depend on the type of devices used in the I/O section or on the number of devices. Additions and deletions can be made by means of appropriate changes in the array and in the parameters of the routine, without changing the routine itself.
Entry Conditions

(A) = More significant byte of starting address of array of ports and initial values

(Y) = Less significant byte of starting address of array of ports and initial values

(X) = Number of entries in array (number of ports to initialize).

Exit Conditions

All ports initialized.

Example

Data:  Number of ports to initialize = 3
Array elements are:
  High byte of port 1 address
  Low byte of port 1 address
  Initial value for port 1
  High byte of port 2 address
  Low byte of port 2 address
  Initial value for port 2
  High byte of port 3 address
  Low byte of port 3 address
  Initial value for port 3

Result: Initial value for port 1 stored in port 1 address
         Initial value for port 2 stored in port 2 address
         Initial value for port 3 stored in port 3 address.

Note that each element in the array consists of 3 bytes containing:
Less significant byte of port address
More significant byte of port address
Initial value for port

---

Title: Initialize I/O ports
Name: IPORTS

Purpose: Initialize I/O ports from an array of port addresses and values.

Entry: Register A = High byte of array address
Register Y = Low byte of array address
Register X = Number of ports to initialize

The array consists of 3 byte elements.
array+0 = High byte of port 1 address
array+1 = Low byte of port 1 address
array+2 = Value to store in port 1 address
array+3 = High byte of port 2 address
array+4 = Low byte of port 2 address
array+5 = Value to store in port 2 address

Exit: None

Registers used: All

Time: 16 cycles overhead plus
52 cycles per port to initialize

Size: Program 40 bytes
Data 2 bytes in page zero

;PAGE ZERO POINTERS
ARYADR .EQU 0D0H ;ARRAY ADDRESS
PRTADR .EQU 0D2H ;PORT ADDRESS

;PORTS:
;SAVE STARTING ADDRESS OF INITIALIZATION ARRAY
STA AMARYADR+1
STY AMARYADR

;EXIT IF THE NUMBER OF PORTS IS ZERO
TXA ;SET FLAGS
BEQ EXITIP ;EXIT IF NUMBER OF PORTS = 0

;LOOP PICKING UP THE PORT ADDRESS AND
;SENDING THE VALUE UNTIL ALL PORTS ARE INITIALIZED
LOOP:
;GET PORT ADDRESS FROM ARRAY AND SAVE IT
LDY $0
LDA (ARYADR),Y ;GET LOW BYTE OF PORT ADDRESS
STA PRTADR
INY
LDA (ARYADR),Y ;GET HIGH BYTE OF PORT ADDRESS
STA PRTADR+1

;GET THE INITIAL VALUE AND SEND IT TO THE PORT
INY
LDA (ARYADR),Y ;GET INITIAL VALUE
LDY $0
STA (PRTADR),Y ;OUTPUT TO PORT
;POINT TO THE NEXT ARRAY ELEMENT
LDA   ARYADR
CLC
ADC   #3 ;ADD 3 TO LOW BYTE OF THE ADDRESS
STA   ARYADR
BCC   LOOP1
INC   ARYADR+1 ;INCREMENT HIGH BYTE IF A CARRY

LOOP1:

;DECREMENT NUMBER OF PORTS TO DO, EXIT WHEN ALL PORTS ARE INITIALIZED
DEX
BNE   LOOP

EXITIP:
RTS

;SAMPLE EXECUTION:

;INITIALIZE
; 6520 PIA
; 6522 VIA
; 6530 ROM/RAM/IO/TIMER
; 6532 RAM/IO/TIMER
; 6850 SERIAL INTERFACE(ACIA)
; 6551 SERIAL INTERFACE(ACIA)
SC1007:
LDA   ARRARY+1
LDY   ARRARY
LDX   SZARY
JSR   IPORTS ;INITIALIZE THE PORTS
BRK

ARRAY:

;INITIALIZE 6520, ASSUME BASE ADDRESS FOR REGISTERS AT 2000H
; PORT A = INPUT
; CA1 = DATA AVAILABLE, SET ON LOW TO HIGH TRANSITION, NO INTERRUPTS
; CA2 = DATA ACKNOWLEDGE HANDSHAKE
.WORD  2001H ;6520 CONTROL REGISTER A ADDRESS
.BYTE  00000010B ;DATA AVAILABLE, SET ON LOW TO HIGH TRANSITION, NO INTERRUPTS
.dropdown
; PORT B = OUTPUT
; CB1 = DATA ACKNOWLEDGE, SET ON HIGH TO LOW TRANSITION, NO INTERRUPTS
; CB2 = DATA AVAILABLE, CLEARED BY WRITING DATA REGISTER B
; SET TO 1 BY HIGH TO LOW Transition ON CB1
; 6520 CONTROL REGISTER B ADDRESS
; INDICATE NEXT ACCESS TO DATA DIRECTION REGISTER
.WORD 2003H
.BYTE 00000000B

; 6520 DATA REGISTER B ADDRESS
; ALL BITS = OUTPUT
.WORD 2002H
.BYTE 11111111B

; 6520 CONTROL REGISTER B ADDRESS
; SET UP CB1, CB2 AND SET BIT 2 TO DATA REGISTER
.WORD 2003H
.BYTE 00100100B

; INITIALIZE 6522, ASSUME BASE ADDRESS FOR REGISTERS AT 2010H
; PORT A = BITS 0..3 = OUTPUT, BITS 4..7 = INPUT
; CA1, CA2 ARE NOT USED.
; PORT B = LATCHED INPUT
; CB1 = DATA AVAILABLE, SET ON LOW TO HIGH TRANSITION
; CB2 = DATA ACKNOWLEDGE HANDSHAKE
.WORD 2013H
.BYTE 00001111B

; 6522 DATA DIRECTION REGISTER A
; BITS 0..3 = OUTPUT, 4..7 = INPUT
.WORD 2012H
.BYTE 00000000B

; 6522 DATA DIRECTION REGISTER B
; ALL BITS = INPUT
.WORD 201CH
.BYTE 00110000B

; 6522 PERIPHERAL CONTROL REGISTER
; SETUP CB1, CB2
.BYTE 10010000B

; 6522 AUXILIARY CONTROL REGISTER
; MAKE PORT B LATCH THE INPUT DATA
.BYTE 00000010B

; INITIALIZE 6530, ASSUME BASE ADDRESS FOR REGISTERS AT 2020H
; PORT A = OUTPUT
; PORT B = INPUT
.WORD 2021H
.BYTE 11111111B

; 6530 DATA DIRECTION REGISTER A
; ALL BITS = OUTPUT
.WORD 2023H
.BYTE 00000000B

; 6530 DATA DIRECTION REGISTER B
; ALL BITS = INPUT

; INITIALIZE 6532, ASSUME BASE ADDRESS FOR REGISTERS AT 2030H
; PORT A = BITS 0..6 = OUTPUT
; BIT 7 = INPUT FOR PORT B DATA AVAILABLE.
; PORT B = INPUT
.WORD 2031H
.BYTE 01111111B

; 6532 DATA DIRECTION REGISTER A
; BITS 0..6 = OUTPUT, BIT 7 = INPUT
.WORD 2033H
.BYTE 00000000B

; 6532 DATA DIRECTION REGISTER B
; ALL BITS = INPUT

; INITIALIZE 6551, ASSUME BASE ADDRESS FOR REGISTERS AT 2040H
; 8 BIT DATA, NO PARITY
; 1 STOP BIT
; 9600 BAUD FROM ON BOARD BAUD RATE GENERATOR
; NO INTERRUPTS
.WORD 2041H
.BYTE 0

; WRITE TO 6551 STATUS REGISTER TO RESET
; THIS VALUE COULD BE ANYTHING
.WORD 2042H
.BYTE 10011110B

; 1 STOP, 8 BIT DATA, INTERNAL 9600 BAUD
; 6551 COMMAND REGISTER
.WORD 2043H
.BYTE 00000011B

; NO PARITY, NO ECHO, NO RECEIVER INTERRUPT, DTR LOW

; INITIALIZE 6850, ASSUME BASE ADDRESS FOR REGISTERS AT 2050H
; 8 BIT DATA, NO PARITY
; 1 STOP BIT
; DIVIDE MASTER CLOCK BY 1
; NO INTERRUPTS
.WORD 2050H ; WRITE TO 6850 CONTROL REGISTER
.BYTE 00000011B ; PERFORM A MASTER RESET
.WORD 2050H ; 6850 CONTROL REGISTER
.BYTE 00010101B ; NO INTERRUPTS, RTS LOW,
; 8 BITS, 1 STOP, DIVIDE BY 1

ENDARY: ; END OF ARRAY
ADRARY: .WORD ARRAY ; ADDRESS OF ARRAY
SZARY: .BYTE (ENDARY - ARRAY) / 3 ; NUMBER OF PORTS TO INITIALIZE

.END ; PROGRAM


**Delay Milliseconds (DELAY)**

Provides a delay of between 1 and 255 milliseconds, depending on the parameter supplied. The user must calculate the value MSCNT to fit a particular computer.

\[ \text{MSCENT} = \frac{(100/\text{CYCLETIME} - 10)}{5} = \frac{200/\text{CYCLETIME} - 2}{5} \]

\[ \text{CYCLETIME} \] is the number of microseconds per clock period for a particular computer (1 for KIM-1, SYM-1, and AIM-65, 0.9799269 for APPLE II™).

**Procedure:** The program simply counts down the index registers for the appropriate amount of time as determined by the user-supplied constant. A few extra NOPs take account of the call instruction, the return instruction, and the routine overhead.

**Entry Conditions**

(Y) = Number of milliseconds to delay (1 to 255).

**Exit Conditions**

Returns after the specified number of milliseconds with (X) = (Y) = 0.

**Example**

Data: \( (Y) = \text{number of milliseconds} = 2A_{16} = 42_{10} \)

Result: Software delay of 2A₁₆ (42₁₀) milliseconds, assuming that user supplies the proper value of MSCNT.

Title: Delay milliseconds

Name: Delay

Purpose: Delay from 1 to 255 milliseconds
Entry: Register Y = number of milliseconds to delay.

Exit: Returns to calling routine after the specified delay.

Registers used: X, Y, P

Time: 1 millisecond * Register Y.
If Y = 0 then the minimum time is 17 cycles including the JSR overhead.

Size: Program 29 bytes
Data NONE

HERE IS THE FORMULA FOR COMPUTING THE DELAY COUNTS MSCNT1 AND MSCNT2

MSCNT = 200/CYCLETIME - 2 WHERE CYCLE TIME IS THE LENGTH OF A PARTICULAR COMPUTER’S CLOCK PERIOD IN MICROSECONDS

EXAMPLES: KIM, SYM, AIM HAVE 1 MHz CLOCKS, SO MSCNT = 198, APPLE HAS A 1.023 MHz CLOCK, SO MSCNT = 202.

IN THE LAST ITERATION, WE REDUCE THE COUNT BY 3 (MSCNT) TO DELAY 1 MILLISECOND LESS THE OVERHEAD WHERE THE OVERHEAD IS:

6 CYCLES ==> JSR DELAY
2 CYCLES ==> CPY #0
2 CYCLES ==> BEQ EXIT (ASSUMED NOT TAKEN)
2 CYCLES ==> NOP
2 CYCLES ==> CPY #1
3 CYCLES ==> BNE DELAYA (ASSUMED TAKEN)
2 CYCLES ==> DEY
-1 CYCLE ==> THE LAST BNE DELAY1 NOT TAKEN
2 CYCLES ==> LDX #MSCNT2
-1 CYCLE ==> THE LAST BNE DELAY2 NOT TAKEN
6 CYCLES ==> RTS

---------
25 CYCLES OVERHEAD

;EQUATES
; 1 MHZ CLOCK
MSCNT .EQU 0C6H ;198 TIMES THROUGH DELAY1

APPLE (1.023 MHZ)
MSCNT .EQU 0CAH ;202 TIMES THROUGH DELAY1

DELAY:
CPY #0 ; 2 CYCLES
BEQ EXIT ; 2 CYCLES (EXIT IF DELAY = 0)
NOP ; 2 CYCLES (TO MAKE OVERHEAD = 25 CYCLES)
; IF DELAY IS TO BE 1 MILLISECOND THEN GOTO LAST1
; THIS LOGIC IS DESIGNED TO BE 5 CYCLES THROUGH EITHER PATH
CPY   #1 ; 2 CYCLES
BNE   DELAYA ; 3 CYCLES (IF TAKEN ELSE 2 CYCLES)
JMP   LAST1 ; 3 CYCLES

; DELAY 1 MILLISECOND TIMES (Y-1)

DELAYA:
DEY ; 2 CYCLES (PREDECREMENT Y)

DELAY0:
LDX   #MSCNT ; 2 CYCLES

DELAY1:
DEX ; 2 CYCLES
BNE   DELAY1 ; 3 CYCLES
NOP ; 2 CYCLES
NOP ; 2 CYCLES
DEY ; 2 CYCLES
BNE   DELAY0 ; 3 CYCLES

LAST1:
; DELAY THE LAST TIME 25 CYCLES LESS TO TAKE THE
; CALL, RETURN, AND ROUTINE OVERHEAD INTO ACCOUNT
LDX   #MSCNT-3 ; 2 CYCLES

DELAY2:
DEX ; 2 CYCLES
BNE   DELAY2 ; 3 CYCLES

EXIT:
RTS ; 6 CYCLES

; ; ;
; ; ;
; SAMPLE EXECUTION:
; ;

SC1008:
; DELAY 10 SECONDS
; CALL DELAY 40 TIMES AT 250 MILLISECONDS EACH
LDA   #40 ; 40 TIMES (28 HEX)
STA   COUNT

; DELAY 1/4 SECOND

QTRSCD:
LDY   #250 ; 250 MILLISECONDS (FA HEX)
JSR   DELAY
DEC   COUNT
BNE   QTRSCD
BRK ; STOP AFTER 10 SECONDS
JMP   SC1008
; DATA SECTION
COUNT .BYTE 0

.END ; PROGRAM
Unbuffered Interrupt-Driven Input/Output
Using a 6850 ACIA (SINTIO)

Performs interrupt-driven input and output using a 6850 ACIA and single-character input and output buffers. Consists of the following subroutines:

1. INCH reads a character from the input buffer.

2. INST determines whether there is a character available in the input buffer.

3. OUTCH writes a character into the output buffer.

4. OUTST determines whether the output buffer is full.

5. INIT initializes the 6850 ACIA, the interrupt vectors, and the software flags (used to transfer data between the main program and the interrupt service routine).

6. IOSRVC determines which interrupt occurred and provides the proper input or output service. In response to the input interrupt, it reads a character from the ACIA into the input buffer. In response to the output interrupt, it writes a character from the output buffer into the ACIA.

Examples describe a 6850 ACIA on an Apple II serial I/O board in slot 1.

Procedures:

1. INCH waits for a character to become available, clears the Data Ready flag (RECDF), and loads the character into the accumulator.

2. INST sets the Carry flag from the Data Ready flag (memory location RECDF).

3. OUTCH waits for the character buffer to empty, places the character in the buffer, and sets the Character Available flag (TRNDF).

4. OUTST sets the Carry flag from the Character Available flag (memory location TRNDF).

5. INIT clears the software flags, sets up the interrupt vector, resets the ACIA (a master reset, since the ACIA has no reset input), and initializes the ACIA by placing the appropriate value in its control register (input interrupts enabled, output interrupts disabled).

6. IOSRVC determines whether the interrupt was an input interrupt (bit 0 of the ACIA status register = 1), an output interrupt (bit
1 of the ACIA status register = 1), or the product of some other device. If the input interrupt occurred, the program reads the data, saves it in memory, and sets the Data Ready flag (RECDF). If the output interrupt occurred, the program determines whether data is available. If not, the program simply disables the output interrupt. If data is available, the program sends it to the ACIA, clears the Character Available flag (TRNDF), and enables both the input and the output interrupts.

The only special problem in using these routines is that an output interrupt may occur when no data is available. We cannot ignore the interrupt or it will assert itself indefinitely, creating an endless loop. The solution is to disable output interrupts. But now we create a new problem when data is ready to be sent. That is, if we have disabled output interrupts, the system cannot learn from an interrupt that the ACIA is ready to transmit. The solution to this is to create an additional, non-interrupt-driven entry to the routine that sends a character to the ACIA. Since this entry is not caused by an interrupt, we must check the ACIA to see that its output register is actually empty before sending it a character.

The special sequence of operations is the following:

1. Output interrupt occurs before new data is available (that is, the ACIA becomes ready for data). The response is to disable the output interrupt, since there is no data to be sent. Note that this sequence will not occur initially, since INIT disables the output interrupt. Otherwise, the output interrupt would occur immediately, since the ACIA surely starts out empty and therefore ready to transmit data.

2. Output data becomes available. That is, the system now has data to transmit. But there is no use sitting back and waiting for the output interrupt, since it has been disabled.

3. The main program calls the routine (OUTDAT) that sends data to the ACIA. Checking the ACIA’s status shows that it is, in fact, ready to transmit a character (it told us it was when the output interrupt occurred). The routine then sends the character and reenables the interrupts.

The basic problem here is that output devices may request service before the computer is ready for them. That is, the devices can accept data but the computer has nothing to send. In particular, we have an initialization problem caused by output interrupts asserting themselves and expecting service. Input devices, on the other hand, request service only when they have data. They start out in the not ready state; that is, an input device has no data to send initially, while the computer is ready to accept data. Thus output devices cause more initialization and sequencing problems in interrupt-driven systems than do input devices.

Our solution may, however, result in an odd situation. Let us assume that the system has some data ready for output but the ACIA is not yet ready for it. Then the system must wait with interrupts disabled for the ACIA to become ready; that is, an interrupt-driven system must disable its interrupts and wait idly, polling the output device. We could eliminate this drawback by keeping a software flag that would be changed when the output interrupt occurred at a time when there was no data. Then the system could check the software flag and determine whether the output interrupt had already occurred. (See Subroutine 11C.)
Entry Conditions

1. INCH: none
2. INST: none
3. OUTCH: character to transmit in accumulator
4. OUTST: none
5. INIT: none

Exit Conditions

1. INCH: character in accumulator
2. INST: Carry flag = 0 if no character is available, 1 is a character is available
3. OUTCH: none
4. OUTST: Carry flag = 0 if output buffer is empty, 1 if it is full.

Title
Simple interrupt input and output using a 6850 ACIA and a single character buffer.

Name:
SINTIO

Purpose:
This program consists of 5 subroutines which perform interrupt driven input and output using a 6850 ACIA.

INCH
Read a character.

INST
Determine input status (whether the input buffer is empty).

OUTCH
Write a character.

OUTST
Determine output status (whether the output buffer is full).

INIT
Initialize.

Entry:
INCH
No parameters.

INST
No parameters.

OUTCH
Register A = character to transmit

OUTST
No parameters.

INIT
No parameters.

Exit:
INCH
Register A = character.

INST
Carry flag equals 0 if input buffer is empty, 1 if character is available.
OUTCH
    No parameters

OUTST
    Carry flag equals 0 if output buffer is
easy, 1 if it is full.

INIT
    No parameters.

Registers used: INCH
    A,F,Y
INST
    A,F
OUTCH
    A,F,Y
OUTST
    A,F
INIT
    A,F

Time: INCH
    33 cycles if a character is available
INST
    12 cycles
OUTCH
    92 cycles if the output buffer is empty and
    the ACIA is ready to transmit
OUTST
    12 cycles
INIT
    73 cycles
IOSRVC
    24 cycles minimum if the interrupt is not ours;
    39 cycles to service a input interrupt
    59 cycles to service a output interrupt

Size: Program 168 bytes
    Data    6 bytes

;EXAMPLE 6850 ACIA PORT DEFINITIONS FOR AN APPLE SERIAL BOARD IN SLOT 1
ACIASR .EQU 0C094H ;ACIA STATUS REGISTER
ACIADR .EQU 0C095H ;ACIA DATA REGISTER
ACIACR .EQU 0C094H ;ACIA CONTROL REGISTER
IRQVEC .EQU 03FEH ;APPLE IRQ VECTOR ADDRESS

;READ A CHARACTER
INCH:
    JSR     INST      ;GET INPUT STATUS
    BCC     INCH      ;WAIT IF CHARACTER IS NOT AVAILABLE
    PHP     ;SAVE CURRENT STATE OF INTERRUPT SYSTEM
    SEI     ;DISABLE INTERRUPTS
    LDA     #0
    STA     RECDAT   ;GET THE CHARACTER FROM THE BUFFER
    LDA     RECDF    ;INDICATE BUFFER IS NOW EMPTY
    PLP     ;RESTORE FLAGS
INTERRUPTS

;RETURN INPUT STATUS (CARRY = 1 IF DATA IS AVAILABLE)
INST:
LDA  RECDF ;GET THE DATA READY FLAG
LSR   A ;SET CARRY FROM FLAG
; CARRY = 1 IF CHARACTER IS AVAILABLE
RTS

;WRITE A CHARACTER
OUTCH:
PHP ;SAVE STATE OF INTERRUPT FLAG
PHA ;SAVE CHARACTER TO OUTPUT

;WAIT FOR THE CHARACTER BUFFER TO EMPTY, THEN STORE THE NEXT CHARACTER
WAITOC:
JSR  OUTST ;GET THE OUTPUT STATUS
BCS  WAITOC ;WAIT IF THE OUTPUT BUFFER IS FULL
SEI ;DISABLE INTERRUPTS WHILE LOOKING AT THE
     ; SOFTWARE FLAGS
PLA ;GET THE CHARACTER
STA  TRNDF ;STORE THE CHARACTER
LDA  #0FFH ;INDICATE CHARACTER AVAILABLE (BUFFER FULL)
STA  TRNDF
JSR  OUTCH ;SEND THE DATA TO THE PORT
PLP ;RESTORE FLAGS
RTS

;OUTPUT STATUS (CARRY = 1 IF BUFFER IS FULL)
OUTST:
LDA  TRNDF ;CARRY = 1 IF CHARACTER IS IN THE BUFFER
LSR   A
RTS

;INITIALIZE
INIT:
PHP ;SAVE CURRENT STATE OF FLAGS
SEI ;DISABLE INTERRUPTS DURING INITIALIZATION

;INITIALIZE THE SOFTWARE FLAGS
LDA  #0
STA  RECDF ;NO INPUT DATA AVAILABLE
STA  TRNDF ;OUTPUT BUFFER EMPTY

;SAVE THE CURRENT IRQ VECTOR IN NEXTSR
LDA  IRQVEC
STA  NEXTSR
LDA  IRQVEC+1
STA  NEXTSR+1

;SET THE IRQ VECTOR TO OUR INPUT SERVICE ROUTINE
LDA  AIOS
STA  IRQVEC
LDA  AIOS+1
STA  IRQVEC+1

;INITIALIZE THE 6850
LDA  #011B
STA  ACIACR ;MASTER RESET ACIA
LDA  #10010001B
STA  ACIACR ;INITIALIZE ACIA MODE TO
11A UNBUFFERED INTERRUPT-DRIVEN I/O USING A 6850 ACIA (SINTIO) 469

; DIVIDE BY 16
; 8 DATA BITS
; 2 STOP BITS
; OUTPUT INTERRUPTS DISABLED (NOTE THIS)
; INPUT INTERRUPTS ENABLED

PLP ;RESTORE CURRENT STATE OF THE FLAGS
RTS

AIOS: .WORD IOSRVC ;ADDRESS OF INPUT OUTPUT SERVICE ROUTINE

;INPUT OUTPUT INTERRUPT SERVICE ROUTINE
IOSRVC:

PHA ;SAVE REGISTER A
CLD ;BE SURE PROCESSOR IS IN BINARY MODE

;GET THE ACIA STATUS: BIT 0 = 1 IF AN INPUT INTERRUPT
;BIT 1 = 1 IF AN OUTPUT INTERRUPT
LDA ACIASR
LSR A ;BIT 0 TO CARRY
BCS IINT ;BRANCH IF AN INPUT INTERRUPT
LSR A ;BIT 1 TO CARRY
BCS OINT ;BRANCH IF AN OUTPUT INTERRUPT

;THE INTERRUPT WAS NOT CAUSED BY THIS ACIA
PLA
JMP (NEXTSR) ;GOTO THE NEXT SERVICE ROUTINE

;SERVICE INPUT INTERRUPTS
IINT:

LDA ACIADR ;READ THE DATA
STA RECDAT ;STORE IT AWAY
LDA #0FFH
STA RECDF ;INDICATE WE HAVE A CHARACTER IN RECDAT
JMP EXIT ;EXIT IOSRVC

;SERVICE OUTPUT INTERRUPTS
OINT:

LDA TRNDF ;GET DATA AVAILABLE FLAG
BEQ NODATA ;BRANCH IF NO DATA TO SEND
JSR OUTDT1 ;ELSE OUTPUT THE DATA,
; (WE DO NOT NEED TO TEST THE STATUS)
JMP EXIT

;IF AN OUTPUT INTERRUPT OCCURS WHEN NO DATA IS AVAILABLE,
; WE MUST DISABLE THE INTERRUPT TO AVOID AN ENDLESS LOOP.
; LATER WHEN A CHARACTER BECOMES AVAILABLE, WE CALL THE
; OUTPUT ROUTINE, OUTDAT, WHICH MUST TEST ACIA STATUS BEFORE
; SENDING THE DATA. THE OUTPUT ROUTINE MUST ALSO REENABLE THE OUTPUT
; INTERRUPT AFTER SENDING THE DATA. THIS PROCEDURE OVERCOMES THE
; PROBLEMS OF AN UNSERVICED OUTPUT INTERRUPT ASSERTING ITSELF
; REPEATEDLY, WHILE STILL ENSURING THAT OUTPUT INTERRUPTS ARE
; RECOGNIZED AND THAT DATA IS NEVER SENT TO AN ACIA THAT IS
; NOT READY FOR IT. THE BASIC PROBLEM HERE IS THAT AN OUTPUT
; DEVICE MAY REQUEST SERVICE BEFORE THE COMPUTER HAS
; ANYTHING TO SEND (WHEREAS AN INPUT DEVICE HAS DATA WHEN IT
INTERRUPTS

; REQUESTS SERVICE)

; NODATA:
;DISABLE OUTPUT INTERRUPTS, ENABLE INPUT
; INTERRUPTS, 8 DATA BITS, 2 STOP BITS, "DIVIDE
; BY 16 CLOCK
;TURN OFF OUTPUT INTERRUPTS

; EXIT:
; RESTORE REGISTER A
;RETURN FROM INTERRUPT

;********************************************************************************
;ROUTINE: OUTDAT, OUTDT1 (OUTDAT IS NON-INTERRUPT DRIVEN ENTRY POINT)
;PURPOSE: SEND A CHARACTER TO THE ACIA
;ENTRY: TRNDAT = CHARACTER TO SEND
;EXIT: NONE
;REGISTERS USED: A, F
;********************************************************************************

; NON-INTERUPT ENTRY. MUST CHECK IF ACIA IS READY OR WAIT FOR IT

; OUTDAT:
; CAME HERE WITH INTERRUPTS DISABLED
LDA ACIASR
AND #0000000010B
BEQ OUTDAT

; TEST THE ACIA OUTPUT REGISTER FOR EMPTY
; BRANCH IF IT IS NOT EMPTY

; GET THE CHARACTER
LDA TRNDAT

; OUTPUT DATA
STA ACIADR
LDA #0
STA TRNDF
LDA #10100001B
STA ACIACR

; ENABLE 6850 OUTPUT AND INPUT INTERRUPTS,
; 8 DATA BITS, 2 STOP BITS, DIVIDE BY 16 CLOCK

; RTS

; DATASECTION
RECDAT .BLOCK 1
RECDF .BLOCK 1
TRNDAT .BLOCK 1
TRNDF .BLOCK 1
NEXTSR .BLOCK 2

; RECEIVE DATA
; RECEIVE DATA FLAG (0 = NO DATA, FF = DATA)
; TRANSMIT DATA
; TRANSMIT DATA FLAG (0 = BUFFER EMPTY,
; FF = BUFFER FULL)
; ADDRESS OF THE NEXT INTERRUPT SERVICE ROUTINE

; ; ; ; ; ; SAMPLE EXECUTION:
; ; ; ; ; ;
; ; ; ; ; ;

; SC1101:
JSR INIT ; INITIALIZE
CLI ; ENABLE INTERRUPTS
; SIMPLE EXAMPLE

LOOP:
JSR INCH ; READ A CHARACTER
PHA
JSR OUTCH ; ECHO IT
PLA
CMP #1BH ; IS IT AN ESCAPE CHARACTER?
BNE LOOP ; STAY IN LOOP IF NOT
BRK

; AN ASYNCHRONOUS EXAMPLE
; OUTPUT "A" TO THE CONSOLE CONTINUOUSLY BUT ALSO LOOK AT THE
; INPUT SIDE, READING AND ECHOING ANY INPUT CHARACTERS.

ASYNLP:
; OUTPUT AN "A" IF OUTPUT IS NOT BUSY
JSR OUTST ; IS OUTPUT BUSY?
BCS ASYNLP ; BRANCH IF IT IS
LDA #"A" ; OUTPUT THE CHARACTER
JSR OUTCH

; GET A CHARACTER FROM THE INPUT PORT IF ANY
JSR INST ; IS INPUT DATA AVAILABLE?
BCC ASYNLP ; BRANCH IF NOT (SEND ANOTHER "A")
JSR INCH ; GET THE CHARACTER
CMP #1BH ; IS IT AN ESCAPE CHARACTER?
BEQ DONE ; BRANCH IF IT IS
JSR OUTCH ; ELSE ECHO IT
JMP ASYNLP ; AND CONTINUE

DONE:
BRK
JMP SC1101

.END ; PROGRAM
Unbuffered Interrupt-Driven Input/Output
Using a 6522 VIA (PINTIO)

Performs interrupt-driven input and output using a 6522 VIA and single-character input and output buffers. Consists of the following subroutines:

1. **INCH** reads a character from the input buffer.

2. **INST** determines whether there is a character available in the input buffer.

3. **OUTCH** writes a character into the output buffer.

4. **OUTST** determines whether the output buffer is full.

5. **INIT** initializes the 6522 VIA, the interrupt vectors, and the software flags.

6. **IOSRVC** determines which interrupt occurred and provides the proper input or output service (i.e., it reads a character from the VIA into the input buffer in response to the input interrupt and it writes a character from the output buffer into the VIA in response to the output interrupt).

Examples describe a 6522 VIA attached to an Apple II computer.

**Procedure:**

1. **INCH** waits for a character to be available in the input buffer, clears the Data Ready flag (RECDF), and loads the character from the buffer into the accumulator.

2. **INST** sets the Carry flag from the Data Ready flag (memory location RECDF).

3. **OUTCH** waits for the output buffer to be emptied, places the character (from the accumulator) in the buffer, and sets the character available (buffer full) flag (TRNDF). If an unserviced output interrupt has occurred (i.e., the output device has requested service when no data was available), **OUTCH** actually sends the data to the VIA.

4. **OUTST** sets the Carry flag from the Character Available flag (memory location TRNDF).

5. **INIT** clears the software flags, sets up the interrupt vector, and initializes the 6522 VIA. It makes port A an input port, port B an output port, control lines CA1 and CB1 active low-to-high, control line CA2 a brief...
output pulse indicating input acknowledge (active-low after the CPU reads the data), and control line CB2 a write strobe (active-low after the CPU writes the data and lasting until the peripheral becomes ready again). INIT also enables the input interrupt on CA1 and the output interrupt on CB1.

6. IOSRVC determines whether the interrupt was an input interrupt (bit 1 of the VIA interrupt flag register = 1), an output interrupt (bit 4 of the VIA interrupt flag register = 1), or the product of some other device. If the input interrupt occurred, the program reads the data, saves it in the input buffer, and sets the Data Ready flag (RECDF). If the output interrupt occurred, the program determines whether any data is available. If not, the program simply clears the interrupt and clears the flag (OIE) that indicates the output device is actually ready (that is, an output interrupt has occurred at a time when no data was available). If data is available, the program sends it from the output buffer to the VIA, clears the Character Available flag (TRNDF), sets the Output Interrupt flag (OIE), and enables both the input and the output interrupts.

The only special problem in using these routines is that an output interrupt may occur when no data is available to send. We cannot ignore the interrupt or it will assert itself indefinitely, creating an endless loop. The solution is to simply clear the interrupt by reading the data register in port B. But now we create a new problem when the main program has data ready to be sent. The interrupt indicating that the output device is ready has already occurred (and been cleared), so there is no use waiting for it. The solution is to establish an extra flag that indicates (with a 0) that the output interrupt has occurred without being serviced. We call this flag OIE, the Output Interrupt flag. The initialization routine sets it initially (since the output device has not requested service), and the output service routine clears it when an output interrupt occurs that cannot be serviced (no data is available) and sets it after sending data to the VIA (in case it might have been cleared). Now the output routine OUTCH can check OIE to determine whether the output interrupt has already occurred (a 0 value indicates it has, FF hex that it has not).

Note that we can clear a VIA interrupt without actually sending any data. We cannot do this with a 6850 ACIA (see Subroutines 11A and 11C), so the procedures there are somewhat different. This problem of unserviced interrupts occurs only with output devices, since input devices request service only when they have data ready to transfer.
Entry Conditions

1. INCH: none
2. INST: none
3. OUTCH: character to transmit in accumulator
4. OUTST: none
5. INIT: none

Exit Conditions

1. INCH: character in accumulator
2. INST: Carry flag = 0 if no character is available, 1 if a character is available
3. OUTCH: none
4. OUTST: Carry flag = 0 if output buffer is empty, 1 if it is full.
5. INIT: none

Title
Simple interrupt input and output using a 6522 VIA and a single character buffer.

Purpose
This program consists of 5 subroutines which perform interrupt driven input and output using a 6522 VIA.

INCH
Read a character.
INST
Determine input status (whether the input buffer is empty).
OUTCH
Write a character.
OUTST
Determine output status (whether the output buffer is full).
INIT
Initialize.

Entry:
INCH
No parameters.
INST
No parameters.
OUTCH
Register A = character to transmit
OUTST
No parameters.
INIT
No parameters.

Exit:
INCH
Register A = character.
INST
Carry flag equals 0 if input buffer is empty, 1 if character is available.

OUTCH
No parameters
OUTST
Carry flag equals 0 if output buffer is empty, 1 if it is full.

INIT
No parameters.

Registers used: INCH
A,F,Y
INST
A,F
OUTCH
A,F,Y
OUTST
A,F
INIT
A,F

Time:
INCH
33 cycles if a character is available
INST
12 cycles
OUTCH
83 cycles if the output buffer is empty and the VIA is ready to transmit
OUTST
12 cycles
INIT
93 cycles
IORSRC
24 cycles minimum if the interrupt is not ours;
43 cycles to service a input interrupt;
81 cycles to service a output interrupt

Size:
Program 194 bytes
Data 7 bytes

;EXAMPLE 6522 VIA PORT DEFINITIONS
VIA .EQU 0C090H ;VIA BASE ADDRESS
VIABDR .EQU VIA ;VIA PORT B DATA REGISTER
VIAADR .EQU VIA+1 ;VIA PORT A DATA REGISTER, WITH HANDSHAKING
VIAADD .EQU VIA+2 ;VIA PORT B DATA DIRECTION REGISTER
VIAACR .EQU VIA+3 ;VIA PORT A DATA DIRECTION REGISTER
VIAACR .EQU VIA+11 ;VIA AUXILIARY CONTROL REGISTER
VIAPCR .EQU VIA+12 ;VIA PERIPHERAL CONTROL REGISTER
VIAIFR .EQU VIA+13 ;VIA INTERRUPT FLAG REGISTER
VIAIER .EQU VIA+14 ;VIA INTERRUPT ENABLE REGISTER
IRQVEC .EQU 03FEH ;APPLE IRQ VECTOR ADDRESS

;READ A CHARACTER
INTERRUPTS

INCH:

JSR INST ;GET INPUT STATUS
BCC INCH ;WAIT IF CHARACTER IS NOT AVAILABLE
PHP ;SAVE CURRENT STATE OF INTERRUPT SYSTEM
SEI ;DISABLE INTERRUPTS
LDA RECDAT ;GET THE CHARACTER FROM THE BUFFER
LDA #0
STA RECDF ;INDICATE BUFFER IS NOW EMPTY
LDA RECDAT ;GET THE CHARACTER FROM THE BUFFER
PLP ;RESTORE FLAGS
RTS

;RETURN INPUT STATUS (CARRY = 1 IF DATA IS AVAILABLE)

INST:

LDA RECDF ;GET THE DATA READY FLAG
LSR A ;SET CARRY FROM FLAG
; CARRY = 1 IF CHARACTER IS AVAILABLE
RTS

;WRITE A CHARACTER

OUTCH:

PHP ;SAVE STATE OF INTERRUPT FLAG
PHA ;SAVE CHARACTER TO OUTPUT

;WAIT FOR THE CHARACTER BUFFER TO EMPTY, THEN STORE THE NEXT CHARACTER

WAITOC:

JSR OUTST ;GET THE OUTPUT STATUS
BCS WAITOC ;WAIT IF THE OUTPUT BUFFER IS FULL
SEI ;DISABLE INTERRUPTS WHILE LOOKING AT THE SOFTWARE FLAGS
PLA ;GET THE CHARACTER
STA TRNDAT ;STORE THE CHARACTER
LDA #$0FH ;INDICATE CHARACTER AVAILABLE (BUFFER FULL)
STA TRNDF
LDA OIE ;HAS THE OUTPUT DEVICE ALREADY REQUESTED SERVICE?
BNE OUTCH1 ; NO, BRANCH AND WAIT FOR AN INTERRUPT
JSR OUTDAT ; YES, SEND THE DATA TO THE PORT NOW
OUTCH1: PLP ;RESTORE FLAGS
RTS

;OUTPUT STATUS (CARRY = 1 IF BUFFER IS FULL)

OUTST:

LDA TRNDF ;CARRY = 1 IF CHARACTER IS IN THE BUFFER
LSR A
RTS

;INITIALIZE

INIT:

PHP ;SAVE CURRENT STATE OF FLAGS
SEI ;DISABLE INTERRUPTS

;INITIALIZE THE SOFTWARE FLAGS
11B UNBUFFERED INTERRUPT-DRIVEN I/O USING A 6522 VIA (PINTIO)

LDA  #0
STA  RECDF
STA  TRNDF
LDA  #0FFH
STA  OIE

;SAVE THE CURRENT IRQ VECTOR IN NEXTSR
LDA  IRQVEC
STA  NEXTSR
LDA  IRQVEC+1
STA  NEXTSR+1

;SET THE IRQ VECTOR TO OUR INPUT SERVICE ROUTINE
LDA  AIOS
STA  IRQVEC
LDA  AIOS+1
STA  IRQVEC+1

;INITIALIZE THE 6522 VIA
LDA  #00000000B
STA  VIAADD
LDA  #1111111B
STA  VIABDD
LDA  #10001010B
STA  VIAPCR

LDA  #00000001B
STA  VIAACR

LDA  #00010010B
STA  VIAIER

PLP
RTS

AIOS:  .WORD IOSRVC

;ADDRESS OF INPUT/OUTPUT SERVICE ROUTINE

;INPUT OUTPUT INTERRUPT SERVICE ROUTINE

IOSRVC:

PHA
C LD

;SAVE REGISTER A
;BE SURE PROCESSOR IS IN BINARY MODE

;GET THE VIA STATUS: BIT 1 = 1 IF AN INPUT INTERRUPT
;BIT 4 = 1 IF AN OUTPUT INTERRUPT
LDA  VIAIFR
AND  #10B
BNE  INT

;TEST BIT 1
;GOTO INPUT INTERRUPT IF BIT 1 = 1
LDA  VIAIFR
AND  #1000B
BNE  OINT

;TEST BIT 4
;GOTO OUTPUT INTERRUPT IF BIT 4 = 1
; THE INTERRUPT WAS NOT CAUSED BY THIS VIA
PLA
JMP (NEXTSR) ; GOTO THE NEXT SERVICE ROUTINE

; SERVICE INPUT INTERRUPTS
IINT:
LDA VIAADR ; READ THE DATA
(STA RECDAT ; (WHICH PULSES CA2 FOR THE HANDSHAKE AND
LDA #0FH ; STORE INTERRUPT FLAG)
STA RECDF ; INDICATE WE HAVE A CHARACTER IN RECDAT
JMP EXIT ; EXIT IOSRVC

; SERVICE OUTPUT INTERRUPTS
; NOTE THAT WE CAN CLEAR A 6522 INTERRUPT BY READING THE DATA
; REGISTER. THUS WE CAN CLEAR AN OUTPUT INTERRUPT WITHOUT
; SERVICING IT OR DISABLING IT. HOWEVER, IF WE DO THIS, WE
; MUST HAVE A FLAG (OIE) THAT INDICATES THE OUTPUT INTERRUPT
; HAS OCCURRED BUT HAS NOT BEEN SERVICED. OUTCH CAN THEN USE
; THE OIE FLAG TO DETERMINE WHETHER TO SEND THE DATA IMMEDIATELY
; OR WAIT FOR AN OUTPUT INTERRUPT TO SEND IT.
OINT:
LDA TRNDF ; GET DATA AVAILABLE FLAG
BNE NODATA ; BRANCH IF THERE IS NO DATA TO SEND
JSR OUTDAT ; ELSE OUTPUT THE DATA
JMP EXIT

NODATA:
LDA VIABDR ; READ THE PORT B DATA REGISTER TO CLEAR THE
(LDA #0 ; INTERRUPT.
STA OIE ; INDICATE OUTPUT INTERRUPT HAS OCCURRED
; BUT HAS NOT BEEN SERVICED

EXIT:
PLA ; RESTORE REGISTER A
RTI ; RETURN FROM INTERRUPT

; *************************************************
; ROUTINE: OUTDAT
; PURPOSE: SEND A CHARACTER TO THE VIA
; ENTRY: TRNDAT = CHARACTER TO SEND
; EXIT: NONE
; REGISTERS USED: A,F
; *************************************************

OUTDAT:
LDA TRNDAT ; GET THE CHARACTER
STA VIABDR ; OUTPUT DATA TO PORT B
LDA #0
STA TRNDF ; INDICATE BUFFER EMPTY
LDA #0FFH
STA OIE ; INDICATE NO UNSERVICED OUTPUT INTERRUPT
RTS
;DATA SECTION
RECDAT .BLOCK 1 ;RECEIVE DATA
RECDF .BLOCK 1 ;RECEIVE DATA FLAG (0 = NO DATA, FF = DATA)
TRNDAT .BLOCK 1 ;TRANSMIT DATA
TRNDF .BLOCK 1 ;TRANSMIT DATA FLAG (0 = BUFFER EMPTY
OIE .BLOCK 1 ;OUTPUT INTERRUPT FLAG
; (0 = INTERRUPT OCCURRED WITHOUT SERVICE
; FF = INTERRUPT SERVICED)
NEXTSR .BLOCK 2 ;ADDRESS OF THE NEXT INTERRUPT SERVICE ROUTINE

; SAMPLE EXECUTION:

; SIMPLE EXAMPLE

LOOP:
JSR INCH ;READ A CHARACTER
PHA
JSR OUTCH ;ECHO IT
PLA
CMP #1BH ;IS IT AN ESCAPE CHARACTER ?
BNE LOOP ;STAY IN LOOP IF NOT
BRK

; AN ASYNCHRONOUS EXAMPLE
; OUTPUT "A" TO THE CONSOLE CONTINUOUSLY BUT ALSO LOOK AT THE
; INPUT SIDE, READING AND ECHOING ANY INPUT CHARACTERS.

ASYNLP:
JSR OUTST ;IS OUTPUT BUSY ?
BCC ASYNLP ;BRANCH IF IT IS
LDA #$A
JSR OUTCH ;OUTPUT THE CHARACTER

; GET A CHARACTER FROM THE INPUT PORT IF ANY
JSR INST ;IS INPUT DATA AVAILABLE ?
BCC ASYNLP ;BRANCH IF NOT (SEND ANOTHER "A")
JSR INCH ;GET THE CHARACTER
CMP #1BH ;IS IT AN ESCAPE CHARACTER ?
BEQ DONE ;BRANCH IF IT IS
JSR OUTCH ;ELSE ECHO IT
JMP ASYNLP ;AND CONTINUE

DONE:
BRK
JMP SC1102

.END ;PROGRAM
Buffered Interrupt-Driven Input/Output
Using a 6850 ACIA (SINTB)

Performs interrupt-driven input and output using a 6850 ACIA and multiple-character buffers. Consists of the following subroutines:

1. INCH reads a character from the input buffer.
2. INST determines whether there are any characters in the input buffer.
3. OUTCH writes a character into the output buffer.
4. OUTST determines whether the output buffer is full.
5. INIT initializes the buffers and the 6850 device.
6. IOSRVC determines which interrupt occurred and provides the proper input or output service.

Procedures:

1. INCH waits for a character to become available, gets the character from the head of the input buffer, moves the head of the buffer up one position, and decreases the input buffer counter by 1.
2. INST sets the Carry to 0 if the input buffer counter is zero and to 1 if the counter is non-zero.
3. OUTCH waits until there is empty space in the output buffer (that is, until the output buffer is not full), stores the character at the tail of the output buffer, moves the tail of the buffer up one position, and increases the output buffer counter by 1.
4. OUTST sets the Carry flag to 1 if the output buffer counter is equal to the buffer's length and to 0 if it is not.

Registers Used:
1. INCH: A, F, Y
2. INST: A, F
3. OUTCH: A, F, Y
4. OUTST: A, F
5. INIT: A, F

Execution Time:
1. INCH: 70 cycles if a character is available
2. INST: 18 cycles
3. OUTCH: 75 cycles minimum, 105 cycles maximum if the output buffer is not full and the ACIA is ready to transmit
4. OUTST: 12 cycles
5. INIT: 89 cycles
6. IOSRVC: 73 cycles to service an input interrupt, 102 cycles to service an output interrupt, 27 cycles to determine the interrupt is from another device.

Program Size: 258 bytes

Data Memory Required: Seven bytes anywhere in RAM plus the input and output buffers. The seven bytes anywhere in RAM hold the input buffer counter (one byte at address ICNT), the index to the head of the input buffer (one byte at address IHEAD), the index to the tail of the input buffer (one byte at address ITAIL), the output buffer counter (one byte at address OCNT), the index to the head of the output buffer (one byte at address OHEAD), the index to the tail of the output buffer (one byte at address OIE), and an Output Interrupt Enable flag (one byte at address OIE). The input buffer starts at address IBUF and its size is IBSZ; the output buffer starts at address OBUF and its size is OBSZ.

5. INIT clears the buffer counters, sets both the heads and the tails of the buffers to zero, sets up the interrupt vector, resets the ACIA by performing a master reset on its control register (the ACIA has no reset input), and places the ACIA in its required operating mode by storing the appropriate
value in its control register. INIT enables the input interrupt and disables the output interrupt. It does, however, clear the output interrupt enable flag, thus indicating that the ACIA is ready to transmit data, although it cannot cause an output interrupt.

6. IOSRVC determines whether the interrupt was an input interrupt (bit 0 of the ACIA status register = 1), an output interrupt (bit 1 of the ACIA status register = 1), or the product of some other device. If the input interrupt occurred, the program reads the data and determines if there is room for it in the buffer. If there is room, the processor stores the character at the tail of the input buffer, moves the tail of the buffer up one position, and increases the input buffer counter by 1. If the output interrupt occurred, the program determines whether there is any data in the output buffer. If there is none, the program disables the output interrupt (so it will not interrupt repeatedly) and clears an Output Interrupt flag that indicates the ACIA is actually ready. The flag lets the main program know that the ACIA is ready even through it cannot declare its readiness by forcing an interrupt. If there is data in the output buffer, the program obtains a character from the head of the buffer, sends it to the ACIA, moves the head of the buffer up one position, and decreases the output buffer counter by 1. It then enables both input and output interrupts and sets the Output Interrupt flag (in case that flag had been cleared earlier).

The new problem that occurs in using multiple-character buffers is the management of queues. The main program must read the data in the same order in which the input interrupt service routine receives it. Similarly, the output interrupt service routine must send the data in the same order that the main program stores it. Thus we have the following requirements for handling input:

1. The main program must know whether there is anything in the input buffer.
2. If the input buffer is not empty, the main program must know where the oldest character is (that is, the one that was received first).
3. The input interrupt service routine must know whether the input buffer is full.
4. If the input buffer is not full, the input interrupt service routine must know where the next empty place is (that is, it must know where it should store the new character).

The output interrupt service routine and the main program have a similar set of requirements for the output buffer, although the roles of sender and receiver are reversed.

We meet requirements 1 and 3 by maintaining a counter ICNT. INIT initializes ICNT to zero, the interrupt service routine adds 1 to it whenever it receives a character (assuming the buffer is not full), and the main program subtracts 1 from it whenever it removes a character from the buffer (assuming the buffer is not empty). Thus the main program can determine whether the input buffer is empty by checking if ICNT is zero. Similarly, the interrupt service routine can determine whether the input buffer is full by checking if ICNT is equal to the size of the buffer.

We meet requirements 2 and 4 by maintaining two indexes, IHEAD and ITAIL, defined as follows:

1. ITAIL is the index of the next empty location in the buffer.
2. IHEAD is the index of the oldest character in the buffer.

INIT initializes IHEAD and ITAIL to zero. Whenever the interrupt service routine receives a character, it places it in the buffer at index ITAIL and increments ITAIL by 1 (assuming that the buffer is not full). Whenever the main program reads a character, it removes it from the buffer at index IHEAD and increments IHEAD by 1 (assuming that the buffer is not empty). Thus IHEAD "chases" ITAIL across the buffer with the service routine entering characters at one end (the tail) while the main program removes them from the other end (the head). The occupied part of the buffer thus could start and end anywhere. If either IHEAD or ITAIL reaches the physical end of the buffer, we simply set it back to zero. Thus we allow wraparound on the buffer; that is, the occupied part of the buffer could start near the end (say, at byte #195 of a 200-byte buffer) and continue back to the beginning (say, to byte #10). Thus IHEAD would be 195, ITAIL would be 10, and the buffer would contain 15 characters occupying bytes #195 through 199 and 0 through 9.

---

**Entry Conditions**

1. INCH: none
2. INST: none
3. OUTCH: character to transmit in accumulator
4. OUTST: none
5. INIT: none

---

**Exit Conditions**

1. INCH: character in accumulator
2. INST: Carry flag = 0 if no characters are available, 1 if a character is available
3. OUTCH: none
4. OUTST: Carry flag = 0 if output buffer is not full, 1 if it is full
5. INIT: none

---

; Title                          Interrupt input and output using a 6850 ACIA and a multiple character buffer.
; Name:                          SINTB
; Purpose:                       This program consists of 5 subroutines which perform interrupt driven input and output using a 6850 ACIA.
; INCH                           Read a character.
Determine input status (whether a character is available).

Write a character.

Determine output status (whether the output buffer is full).

Initialize.

Entry:

INCH
No parameters.

INST
No parameters.

OUTCH
Register A = character to transmit

OUTST
No parameters.

INIT
No parameters.

Exit:

INCH
Register A = character.

INST
Carry flag equals 0 if no characters are available, 1 if character is available.

OUTCH
No parameters

OUTST
Carry flag equals 0 if output buffer is empty, 1 if it is full.

INIT
No parameters.

Registers used: INCH
A,F,Y

INST
A,F

OUTCH
A,F,Y

OUTST
A,F

INIT
A,F

Registers used: INCH
A,F,Y

INST
A,F

OUTCH
A,F,Y

OUTST
A,F

INIT
INTERRUPTS

; A,F
; Time:
; INCH
; 70 cycles if a character is available
; INST
; 18 cycles
; OUTCH
; 75 cycles minimum, if the output buffer is not full and the ACIA is ready to transmit
; OUTST
; 12 cycles
; INIT
; 89 cycles
; IOSRVC
; 27 cycles minimum if the interrupt is not ours;
; 73 cycles to service a input interrupt
; 102 cycles to service a output interrupt
; Size:
; Program 258 bytes
; Data 7 bytes plus size of buffers
; Buffers:
; The routines assume two buffers starting at addresses IBUF and OBUF. The lengths of the buffers in bytes are IBSZ and OBSZ. For the input buffer, IHEAD is the index of the oldest character (the next one the main program should read), ITAIL is the index of the next empty element (the next one the service routine should fill), and ICNT is the number of bytes currently filled with characters. For the output buffer, OHEAD is the index of the oldest character (the next one the service routine should send), OTAIL is the index of the next empty element (the next one the main program should fill), and OCNT is the number of bytes currently filled with characters.
; Note:
; Wraparound is provided on both buffers, so that the currently filled area may start anywhere and extend through the end of the buffer and back to the beginning. For example, if the output buffer is 40 hex bytes long, the section filled with characters could extend from OBUF+32H (OHEAD=32H) to OBUF+10H (OTAIL=11H). That is, there are 19H filled bytes occupying addresses OBUF+32H through OBUF+39H and continuing to OBUF through OBUF+10H. The buffer thus looks like a television picture with the vertical hold skewed, so that the frame starts above the bottom of the screen, leaves off at the top, and continues at the bottom.

;EXAMPLE 6850 ACIA PORT DEFINITIONS FOR AN APPLE SERIAL BOARD IN SLOT 1
ACIASR .EQU 0C094H ;ACIA STATUS REGISTER
ACIADR .EQU 0C095H ;ACIA DATA REGISTER
ACIACR .EQU 0C094H ;ACIA CONTROL REGISTER
IRQVEC .EQU 03FEH ;APPLE IRQ VECTOR ADDRESS

;READ A CHARACTER
INCH:
JSR INST ;IS A CHARACTER AVAILABLE ?
BCC INCH ;BRANCH IF NOT
PHP ;SAVE CURRENT STATE OF INTERRUPTS
SEI ;DISABLE INTERRUPTS
LDY IHEAD
LDA IBUF,Y ;GET CHARACTER AT HEAD OF BUFFER
INY
CPY #$IBSZ ;DO WE NEED WRAPAROUND IN BUFFER ?
BCC INCH1 ;BRANCH IF NOT
LDY #0 ;ELSE SET HEAD BACK TO ZERO
INCH1:
STY IHEAD ;DECLREMENT CHARACTER COUNT
DEC ICNT ;RESTORE FLAGS
PLP
RTS

;RETURN INPUT STATUS (CARRY = 1 IF CHARACTERS ARE AVAILABLE, 0 IF NOT)
INST:
CLC ;CLEAR CARRY (ASSUME NO CHARACTERS AVAILABLE)
LDA ICNT ;BRANCH IF THERE ARE NONE
BEQ INST1 ;CARRY = 1 (CHARACTERS ARE AVAILABLE)
INST1:
RTS

;WRITE A CHARACTER
OUTCH:
PHP ;SAVE STATE OF INTERRUPT FLAG
PHA ;SAVE CHARACTER TO OUTPUT

;WAIT UNTIL THERE IS EMPTY SPACE IN THE OUTPUT BUFFER
WAITOC:
JSR OUTST ;IS THE OUTPUT BUFFER FULL ?
BCS WAITOC ;BRANCH IF IT IS FULL
SEI ;DISABLE INTERRUPTS WHILE LOOKING AT THE
;SOFTWARE FLAGS
PLA
LDY OTAIL
STA OBUF,Y ;STORE CHARACTER IN THE BUFFER
INY
CPY #$OBSZ ;DO WE NEED WRAPAROUND ON THE BUFFER ?
BCC OUTCH1 ;BRANCH IF NOT
LDY #0 ;ELSE SET TAIL BACK TO ZERO
OUTCH1:
STY OTAIL
INC OCNT ;INCREMENT BUFFER COUNTER
LDA 01E ;ARE INTERRUPTS DISABLED BUT THE ACIA IS
; ACTUALLY READY ?
BNE OUTCH2 ;EXIT IF ACIA INTERRUPTS NOT READY AND ENABLED
LDA OCNT
CMP #OBSZ

; IS OUTPUT BUFFER FULL?
; IF OCNT >= OBSZ THEN
; CARRY = 1 INDICATING THAT THE OUTPUT
; BUFFER IS FULL
; ELSE
; CARRY = 0 INDICATING THAT THE CHARACTER
; CAN BE PLACED IN THE BUFFER

LDA ICNT
STA IHEAD
STA ITAIL
STA OCNT
STA OHEAD
STA OTAIL
STA OIE

; SAVE CURRENT STATE OF FLAGS
; DISABLE INTERRUPTS

LDA #0
STA ICNT
; NO INPUT DATA

LDA IROVEC
STA NEXTSR
LDA IROVEC+1
STA NEXTSR+1

; SET THE IRQ VECTOR TO OUR INPUT SERVICE ROUTINE

LDA AIOS
STA IROVEC
LDA AIOS+1
STA IROVEC+1

; INITIALIZE THE 6850 ACIA

LDA #011B
STA ACIACR
; MASTER RESET ACIA
LDA #10010001B
STA ACIACR
; INITIALIZE ACIA MODE TO
; DIVIDE BY 16
; 8 DATA BITS
; 2 STOP BITS
11C BUFFERED INTERRUPT-DRIVEN I/O USING A 6850 ACIA (SINTB)

; OUTPUT INTERRUPTS DISABLED (NOTE THIS !!)
; INPUT INTERRUPTS ENABLED

PLP
RTS

; RESTORE CURRENT STATE OF THE FLAGS

AIOS: .WORD IOSRVC

; ADDRESS OF INPUT OUTPUT SERVICE ROUTINE

; INPUT OUTPUT INTERRUPT SERVICE ROUTINE

IOSRVC:

PHA ; SAVE REGISTER A
CLD ; BE SURE PROCESSOR IS IN BINARY MODE

; GET THE ACIA STATUS: BIT 0 = 1 IF AN INPUT INTERRUPT
; BIT 1 = 1 IF AN OUTPUT INTERRUPT

LDA ACIASR
LSR A
BCS IINT ; BRANCH IF AN INPUT INTERRUPT
LSR A
BCS OINT ; BRANCH IF AN OUTPUT INTERRUPT

; THE INTERRUPT WAS NOT OURS
PLA
JMP (NEXTSR) ; GOTO THE NEXT SERVICE ROUTINE

; SERVICE INPUT INTERRUPTS

IINT:

TYA
PHA ; SAVE REGISTER Y

; GET THE DATA AND STORE IT IN THE BUFFER IF THERE IS ROOM
LDA ACIADR ; READ THE DATA
LDY ICNT ; IS THERE ROOM IN THE BUFFER ?
CPY #IBSZ
BCS EXIT ; EXIT, NO ROOM IN THE BUFFER
LDY ITAIL ; ELSE STORE THE DATA IN THE BUFFER
STA IBUF,Y
INY
CPY #IBSZ ; DO WE NEED WRAPAROUND ON THE BUFFER ?
BCC IINT1 ; BRANCH IF NOT
LDY #0 ; ELSE SET TAIL BACK TO ZERO

IINT1:

STY ITAIL ; STORE NEW TAIL INDEX
INC ICNT ; INCREMENT INPUT BUFFER COUNTER
JMP EXIT ; EXIT IOSRVC

; SERVICE OUTPUT INTERRUPTS

OINT:

TYA
PHA ; SAVE REGISTER Y

LDA OCNT ; IS THERE ANY DATA IN THE OUTPUT BUFFER ?
BEQ NODATA ; BRANCH IF NOT (DISABLE THE INTERRUPTS)
JSR OUTDAT ; ELSE SEND A CHARACTER
JMP EXIT
INTERRUPTS

NODATA:

LDA #1001001B ;DISABLE OUTPUT INTERRUPTS, ENABLE INPUT
; INTERRUPTS, 8 DATA BITS, 2 STOP BITS, DIVIDE
; BY 16 CLOCK
STA ACIACR ;TURN OFF INTERRUPTS
LDA #0
STA OIE ;INDICATE OUTPUT INTERRUPTS ARE DISABLED
; BUT ACIA IS ACTUALLY READY
EXIT:

PLA
TAY
PLA
RTI ;RESTORE REGISTER Y
;RESTORE REGISTER A
;RETURN FROM INTERRUPT

;*****************************************************************************
;ROUTINE: OUTDAT
;PURPOSE: SEND A CHARACTER TO THE ACIA FROM THE OUTPUT BUFFER
;ENTRY: OHEAD IS THE INDEX INTO OBUF OF THE CHARACTER TO SEND
;EXIT: NONE
;REGISTERS USED: A,F
;*****************************************************************************

OUTDAT:

LDA ACIASR
AND #00000010B ;IS ACIA OUTPUT REGISTER EMPTY ?
BEQ OUTDAT ;BRANCH IF NOT EMPTY (BIT 1 = 0)
LDY OHEAD
LDA OBUF,Y ;GET THE CHARACTER FROM THE BUFFER
STA ACIADR ;SEND THE DATA
INY
CPY #OBSZ ;DO WE NEED WRAPAROUND ON THE BUFFER ?
BCC OUTD1 ;BRANCH IF NOT
LDY #0 ;ELSE SET HEAD BACK TO ZERO
OUTD1:

STY OHEAD ;SAVE NEW HEAD INDEX
DEC OCNT ;DECREMENT OUTPUT BUFFER COUNTER
LDA #10110001B ;ENABLE 6850 OUTPUT AND INPUT INTERRUPTS,
STA ACIACR ; 8 DATA BITS, 2 STOP BITS, DIVIDE BY 16 CLOCK
LDA #0FFH ;INDICATE THE OUTPUT INTERRUPTS ARE ENABLED
STA OIE

RTS

;DATA SECTION
ICNT .BLOCK 1 ;INPUT BUFFER COUNTER
IHEAD .BLOCK 1 ;INDEX TO HEAD OF INPUT BUFFER
ITAIL .BLOCK 1 ;INDEX TO TAIL OF INPUT BUFFER
OCNT .BLOCK 1 ;OUTPUT BUFFER COUNTER
OHEAD .BLOCK 1 ;INDEX TO HEAD OF OUTPUT BUFFER
OTAIL .BLOCK 1 ;INDEX TO TAIL OF OUTPUT BUFFER
OIE .BLOCK 1 ;OUTPUT INTERRUPT ENABLE FLAG
IBSZ .EQU 80 ;INPUT BUFFER SIZE
IBUF .BLOCK IBSZ ;INPUT BUFFER
11C BUFFERED INTERRUPT-DRIVEN I/O USING A 6850 ACIA (SINTB)

OBSZ .EQU 80 ; OUTPUT BUFFER SIZE
OBUF .BLOCK OBSZ ; OUTPUT BUFFER
NEXTSR .BLOCK 2 ; ADDRESS OF THE NEXT INTERRUPT SERVICE ROUTINE

; SAMPLE EXECUTION:

SC1103:
JSR INIT ; INITIALIZE
CLI ; ENABLE INTERRUPTS

; SIMPLE EXAMPLE
LOOP:
JSR INCH ; READ A CHARACTER
PHA
JSR OUTCH ; ECHO IT
PLA
CMP #1BH ; IS CHARACTER AN ESCAPE ?
BNE LOOP
BRK

; AN ASYNCHRONOUS EXAMPLE
; OUTPUT "A" TO THE CONSOLE CONTINUOUSLY BUT ALSO LOOK AT THE
; INPUT SIDE, READING AND ECHOING ANY INPUT CHARACTERS.
ASYNLP:
JSR OUTCH ; OUTPUT AN "A" IF OUTPUT IS NOT BUSY
BCS ASYNLP ; BRANCH IF IT IS
LDA #$A
JSR OUTCH ; OUTPUT THE CHARACTER

; GET A CHARACTER FROM THE INPUT PORT IF ANY
JSR INST ; IS INPUT AVAILABLE ?
BCC ASYNLP ; BRANCH IF NOT (SEND ANOTHER "A")
JSR INCH ; GET THE CHARACTER
CMP #1BH ; IS CHARACTER AN ESCAPE ?
BEQ DONE ; BRANCH IF IT IS
JSR OUTCH ; ELSE ECHO IT
JMP ASYNLP ; AND CONTINUE

DONE:
BRK

.END ; PROGRAM
Maintains a time-of-day 24-hour clock and a calendar based on a real-time clock interrupt. Consists of the following subroutines:

1. CLOCK returns the starting address of the clock variables.
2. ICLK initializes the clock interrupt and initializes the clock variables to their default values.
3. CLKINT updates the clock after each interrupt (assumed to be spaced one tick apart).

A long example in the listing describes a time display routine for the Apple II computer. The routine prompts the operator for an initial date and time. It then continuously displays the date and time in the center of the monitor screen. The routine assumes an interrupt board in slot 2.

Procedure:

1. CLOCK loads the starting address of the clock variables into the accumulator (more significant byte) and index register Y (less significant byte). The clock variables are stored in the following order (lowest address first): ticks, seconds, minutes, hours, days, months, less significant byte of year, more significant byte of year.
2. ICLK loads the clock variables with their default values (8 bytes starting at address DFLTS) and initializes the clock interrupt (this would be mostly system-dependent).
3. CLKINT decrements the remaining tick count by one and updates the rest of the clock if necessary. Of course, the number of seconds and minutes must be less than 60 and the number of hours must be less than 24. The day of the month must be less than or equal to the last day for the current month; an array of the last days of each month begins at address LASTDY. If the month is February (that is, month 2), the program must check to see if the current year is a leap year. This requires a determination of whether the two least significant bits of memory location YEAR are both zeros. If the current year is a leap year, the last day of February is the 29th, not the 28th. The month number may not exceed 12 (December) or a carry to the year number is necessary. The program must reinitialize the variables properly when carries occur; that is, TICK to DTICK; seconds, minutes, and hours to zero; day and month to 1 (meaning the first day and January, respectively).
11D REAL-TIME CLOCK AND CALENDAR (CLOCK)

Entry Conditions

1. CLOCK: none
2. ICLK: none
3. CLKINT: none

Exit Conditions

1. CLOCK: more significant byte of starting address of clock variables in accumulator, less significant byte in register Y
2. ICLK: none
3. CLKINT: none

Examples

These examples assume that the tick rate is DTICK Hz (less than 256 Hz — typical values would be 60 Hz or 100 Hz) and that the clock and calendar are saved in memory locations:

- **TICK**: number of ticks remaining before a carry occurs, counted down from DTICK
- **SEC**: seconds (0 to 59)
- **MIN**: minutes (0 to 59)
- **HOUR**: hour of day (0 to 23)
- **DAY**: day of month (1 to 28, 30, or 31, depending on month)
- **MONTH**: month of year (1 through 12 for January through December)
- **YEAR & YEAR+1**: current year

1. Starting values are March 7, 1982. 11:59.59 and 1 tick left.

That is,

- (TICK) = 1
- (SEC) = 59
- (MIN) = 59
- (HOUR) = 23
- (DAY) = 07
- (MONTH) = 03
- (YEAR) = 1982

Result (after the tick): March 8, 1982 12:00.00 and DTICK ticks

That is,

- (TICK) = DTICK
- (SEC) = 0
- (MIN) = 0
- (HOUR) = 0
- (DAY) = 08
- (MONTH) = 03
- (YEAR) = 1982

2. Starting values are Dec. 31, 1982. 11:59.59 p.m. and 1 tick left

That is,

- (TICK) = 1
- (SEC) = 59
- (MIN) = 59
- (HOUR) = 23
- (DAY) = 31
- (MONTH) = 12
- (YEAR) = 1982

Result (after the tick): Jan. 1, 1983. 12:00.00 a.m. and DTICK ticks

That is,

- (TICK) = DTICK
- (SEC) = 0
- (MIN) = 0
- (HOUR) = 0
- (DAY) = 1
- (MONTH) = 1
- (YEAR) = 1983
; Title Real time clock and calendar
; Name: CLOCK
;
; Purpose: This program maintains a time of day 24 hour clock and a calendar based on a real time clock interrupt.
; CLOCK Returns the address of the clock variables
; ICLK Initialize the clock interrupt
;
; Entry: CLOCK
; None
; ICLK
; None
;
; Exit: CLOCK
; Register A = High byte of the address of the time variables.
; Register Y = Low byte of the address of the time variables.
; ICLK
; None
;
; Registers used: All
;
; Time: CLOCK
; 14 cycles
; ICLK
; 166 cycles
; CLKINT
; 22 cycles minimum if the interrupt is not ours;
; 33 cycles normally if decrementing tick
; 184 cycles maximum if changing to a new year
;
; Size: Program 191 bytes
; Data 18 bytes
;
IRQVEC: .EQU 03FEH ;APPLE IRQ VECTOR
CLKPRT: .EQU 0C0A0H ;SLOT 2 IO LOCATION OF AN INTERRUPT BOARD
CLKIM: .EQU 01H ;BIT 0 = INTERRUPT REQUEST BIT
TRUE: .EQU 0FFH ;NOT ZERO = TRUE
FALSE: .EQU 0 ;ZERO = FALSE

;RETURN ADDRESS OF THE CLOCK VARIABLES
CLOCK:
LDA ACVAR+1
LDY ACVAR
RTS ;GET ADDRESS OF CLOCK VARIABLES
; INITIALIZE CLOCK INTERRUPT
ICLK:
PHP ; SAVE FLAGS
SEI ; DISABLE INTERRUPTS

; INITIALIZE CLOCK VARIABLES TO THE DEFAULT VALUES
LDY #8
ICLK1:
LDA DPLTS-1,Y
STA CLKVAR-1,Y
DEY
BNE ICLK1

; SAVE CURRENT IRQ VECTOR
LDA IRQVEC
STA NEXTSR
LDA IRQVEC+1
STA NEXTSR

; SET IRQ VECTOR TO CLKINT
LDA ACINT
STA IRQVEC
LDA ACINT+1
STA IRQVEC+1

; HERE SHOULD BE CODE TO INITIALIZE INTERRUPT HARDWARE

; EXIT
PLP ; RESTORE FLAGS
RTS

; HANDLE THE CLOCK INTERRUPT
CLKINT:
PHA ; SAVE REGISTER A
CLD ; BE SURE PROCESSOR IS IN BINARY MODE

; CHECK IF THIS IS OUR INTERRUP
; THIS IS AN EXAMPLE ONLY
LDA CLKPRT
AND #CLKIM ; LOOK AT THE INTERRUPT REQUEST BIT
BNE OURINT ; BRANCH IF IS OUR INTERRUPT
PLA ; RESTORE REGISTER A
JMP (NEXTSR) ; WAS NOT OUR INTERRUPT,
; TRY NEXT SERVICE ROUTINE

; PROCESS OUR INTERRUPT
OURINT:
DEC TICK ; BRANCH IF TICK DOES NOT EQUAL ZERO YET
BNE EXIT1 ; EXIT1 RESTORES ONLY REGISTER A
LDA DTICK
STA TICK ; RESET TICK TO DEFAULT VALUE

; SAVE X AND Y NOW ALSO
TYA
PHA
INTERRUPTS

TXA
PHA

; INCREMENT SECONDS
INC SEC
LDA SEC
CMP #60 ; SECONDS = 60 ?
BCC EXIT ; EXIT IF LESS THAN 60 SECONDS
LDY #0 ; ELSE
STY SEC ; ZERO SECONDS, GO TO NEXT MINUTE

; INCREMENT MINUTES
INC MIN
LDA MIN
CMP #60 ; MINUTES = 60 ?
BCC EXIT ; EXIT IF LESS THAN 60 MINUTES
STY MIN ; ELSE

; INCREMENT HOURS
INC HOUR
LDA HOUR
CMP #24 ; HOURS = 24 ?
BCC EXIT ; EXIT IF LESS THAN 24 HOURS
STY HOUR ; ELSE

; INCREMENT DAYS
INC DAY
LDA DAY
LDX MONTH ; GET CURRENT MONTH
CMP LASTDY-1,X ; DAY = LAST DAY OF THE MONTH ?
BCC EXIT ; EXIT IF LESS THAN LAST DAY

; INCREMENT MONTH (HANDLE 29TH OF FEBRUARY)
CPX #2 ; IS THIS FEBRUARY ?
BNE INCMT ; BRANCH IF NOT FEBRUARY
LDA YEAR ; IS IT A LEAP YEAR?
AND #0000001B
BNE INCMT ; BRANCH IF YEAR IS NOT LEAP YEAR

; THIS IS A FEBRUARY AND A LEAP YEAR SO 29 DAYS NOT 28 DAYS
LDA DAY
CMP #29
BEQ EXIT ; EXIT IF NOT 29TH OF FEBRUARY

INCMTH:
LDY #1 ; CHANGE DAY TO 1, INCREMENT MONTH
STY DAY
INC MONTH
LDA MONTH
CMP #13 ; DONE WITH DECEMBER ?
BCC EXIT ; EXIT IF NOT
STY MONTH ; ELSE

; CHANGE MONTH TO 1 (JANUARY)
INCREASE YEAR
IN IC YEAR
BE NE EXIT
IN C YEAR+1

EXIT:

;RESTORE REGISTERS
PLA
TAX
PLA
TAY
EXIT1:
PLA
RTI

;RETURN FROM INTERRUPT

;ARRAY OF THE LAST DAYS OF EACH MONTH
LASTDY:

.BYTE 31 ;JANUARY
.BYTE 28 ;FEBRUARY (EXCEPT LEAP YEARS)
.BYTE 31 ;MARCH
.BYTE 30 ;APRIL
.BYTE 31 ;MAY
.BYTE 30 ;JUNE
.BYTE 31 ;JULY
.BYTE 31 ;AUGUST
.BYTE 30 ;SEPTEMBER
.BYTE 31 ;OCTOBER
.BYTE 30 ;NOVEMBER
.BYTE 31 ;DECEMBER

;CLOCK VARIABLES
ACVAR: .WORD CLKVAR

;BASE ADDRESS OF CLOCK VARIABLES
CLKVAR:
TICK: .BLOCK 1 ;TICKS LEFT IN CURRENT SECOND
SEC: .BLOCK 1 ;SECONDS
MIN: .BLOCK 1 ;MINUTES
HOUR: .BLOCK 1 ;HOURS
DAY: .BLOCK 1 ;DAY = 1 THROUGH NUMBER OF DAYS IN A MONTH
MONTH: .BLOCK 1 ;MONTH 1=JANUARY.. 12=DECEMBER
YEAR: .WORD 0 ;YEAR

;DEFAULTS
DPLTS:
DTICK: .BYTE 60 ;DEFAULT TICK (60HZ INTERRUPT)
DSEC: .BYTE 0 ;DEFAULT SECONDS
DMIN: .BYTE 0 ;DEFAULT MINUTES
DHR: .BYTE 0 ;DEFAULT HOURS
DDAY: .BYTE 1 ;DEFAULT DAY
DMTH: .BYTE 1 ;DEFAULT MONTH
DYEAR: .WORD 1981 ;DEFAULT YEAR

NEXTSR: .BLOCK 2 ;ADDRESS OF THE NEXT INTERRUPT SERVICE ROUTINE
ACINT: .WORD CLKINT ;ADDRESS OF THE CLOCK INTERRUPT ROUTINE
SAMPLE EXECUTION:

This routine prompts the operator for an initial date and time, it then continuously displays the date and time in the center of the screen.

The operator may use the escape key to abort the routine. Any other key will reprompt for another initial date and time.

;CLK VARIABLE OFFSETS
OTICK: .EQU 0 ;OFFSET TO TICK
OSEC: .EQU 1 ;OFFSET TO SECONDS
OMIN: .EQU 2 ;OFFSET TO MINUTES
OHR: .EQU 3 ;OFFSET TO HOURS
ODAY: .EQU 4 ;OFFSET TO DAY
OMTH: .EQU 5 ;OFFSET TO MONTH
OYEAR: .EQU 6 ;OFFSET TO YEAR

;PAGE ZERO TEMPORARY
CVARS: .EQU 0D0H ;PAGE ZERO TEMPORARY FOR THE CLOCK VARIABLES

;jAPPLE EQUATES FOR THE EXAMPLE
ESC: .EQU 1BH ;ESCAPE CHARACTER
CH .EQU 24H ;APPLE MONITOR CURSOR HORIZONTAL POSITION
CV .EQU 25H ;APPLE MONITOR CURSOR VERTICAL POSITION
HOME: .EQU 0PC58H ;APPLE MONITOR HOME ROUTINE
VTAB: .EQU 0PC22H ;APPLE MONITOR VTAB ROUTINE
RCHAR: .EQU 0PD0CH ;APPLE MONITOR CHARACTER INPUT ROUTINE
COUT: .EQU 0FD6DH ;APPLE MONITOR CHARACTER OUTPUT ROUTINE
GETLN1: .EQU 0FD6FH ;APPLE MONITOR GET LINE WITH OUR PROMPT ROUTINE

SC1104:
JSR ICLK ;INITIALIZE

;GET TODAYS DATE AND TIME MM/DD/YY HR:MIN:SEC
;PRINT PROMPT
PROMPT:
JSR HOME ;HOME AND CLEAR SCREEN
LDA #0
STA MSGIDX
PMTLP:
LDY MSGIDX
LDA MSG,Y
BEQ RDTIME ;BRANCH IF END OF MESSAGE
INC MSGIDX ;INCREMENT TO NEXT CHARACTER
JSR WRCHAR ;OUTPUT CHARACTER THROUGH APPLE MONITOR
JMP PMTLP ;CONTINUE

;READ THE TIME STRING
RDTIME:

JSR  RDLINE ; READ A LINE INTO THE APPLE LINE BUFFER AT ; 200H. RETURNS WITH LENGTH IN X

; GET THE ADDRESS OF THE CLOCK VARIABLES
JSR  CLOCK ; GET CLOCK VARIABLES
STA  CVARS+1
STY  CVARS ; STORE ADDRESS

; INITIALIZE VARIABLES FOR READING NUMBERS
STX  LLEN ; SAVE LENGTH OF LINE
LDA  #0
STA  LIDX ; INITIALIZE LINE INDEX TO ZERO

; GET MONTH
JSR  NXTNUM ; GET NEXT NUMBER FROM INPUT LINE
LDY  #OMTH
STA  (CVARS),Y ; SET MONTH

; GET DAY
JSR  NXTNUM
LDY  #ODAY
STA  (CVARS),Y

; GET YEAR
JSR  NXTNUM
LDY  #OYEAR
STA  (CVARS),Y
CLC
ADC  CEN20 ; ADD 1900 TO ENTRY
STA  (CVARS),Y ; SET LOW BYTE OF YEAR
LDA  CEN20+1
ADC  #0
INY
STA  (CVARS),Y ; SET HIGH BYTE OF YEAR

; GET HOUR
JSR  NXTNUM
LDY  #OHR
STA  (CVARS),Y

; GET MINUTES
JSR  NXTNUM
LDY  #OMIN
STA  (CVARS),Y

; GET SECONDS
JSR  NXTNUM
LDY  #OSEC
STA  (CVARS),Y

; ENABLE INTERRUPTS
CLI ; ENABLE INTERRUPTS

; HOME AND CLEAR THE SCREEN
JSR  HOME

;LOOP PRINTING THE TIME EVERY SECOND
;MOVE CURSOR TO LINE 12 CHARACTER 12
LOOP:
LDA  #11  ;SET CURSOR VERTICAL POSITION
STA  CV   ;SET CURSOR HORIZONTAL POSITION
STA  CH   ;POSITION CURSOR
JSR  VTAB

;PRINT MONTH
LDY  #OMTH
LDA  (CVARS),Y
JSR  PRTNUM  ;PRINT THE NUMBER
LDA  "/"  ;PRINT A SLASH
JSR  WRCHAR

;PRINT DAY
LDY  #ODAY
LDA  (CVARS),Y
JSR  PRTNUM  ;PRINT THE NUMBER
LDA  "/"  ;PRINT A SLASH
JSR  WRCHAR

;PRINT YEAR
LDY  #OYEAR
LDA  (CVARS),Y
SEC
SBC  CEN20  ;NORMALIZE YEAR TO 20TH CENTURY
JSR  PRTNUM  ;PRINT THE NUMBER

;PRINT SPACE AS DELIMITER
LDA  "  ";PRINT A SPACE BETWEEN DATE AND TIME
JSR  WRCHAR

;PRINT HOURS
LDY  #OHR
LDA  (CVARS),Y
JSR  PRTNUM  ;PRINT THE NUMBER
LDA  ":"  ;PRINT A COLON
JSR  WRCHAR

;PRINT MINUTES
LDY  #OMIN
LDA  (CVARS),Y
JSR  PRTNUM  ;PRINT THE NUMBER
LDA  ":"  ;PRINT A COLON
JSR  WRCHAR

;PRINT SECONDS
LDY  #OSEC
LDA  (CVARS),Y
JSR  PRTNUM  ;PRINT THE NUMBER

;WAIT UNTIL SECONDS CHANGE THEN PRINT AGAIN
;EXIT IF OPERATOR PRESSES A KEY
LDY  #OSEC
LDA  (CVARS),Y
STA  CURSEC

WAIT:
; CHECK KEYBOARD
JSR  KEYPRS
BCS  RDKEY
LDA  (CVARS),Y
CMP  CURSEC
BEQ  WAIT
JMP  LOOP

; OPERATOR PRESSED A KEY - DONE IF ESCAPE, PROMPT OTHERWISE

RDKEY:
JSR  RDCHAR
CMP  #ESC
BEQ  DONE
JMP  PROMPT

DONE:
LDA  #0
STA  CH
LDA  #12
STA  CV
JSR  VTab
BRK
JMP  SC1104

;**************************************************************************
; ROUTINE: KEYPRS
; PURPOSE: DETERMINE IF OPERATOR HAS PRESSED A KEY
; ENTRY: NONE
; EXIT: IF OPERATOR HAS PRESSED A KEY THEN
;       CARRY = 1
;       ELSE
;       CARRY = 0
; REGISTERS USED: P
;**************************************************************************

KEYPRS:
PHA
LDA  0C000H
ASL  A
PLA
RTS

;**************************************************************************
; ROUTINE: RDCHAR
; PURPOSE: READ A CHARACTER
; ENTRY: NONE
; EXIT: REGISTER A = CHARACTER
; REGISTERS USED: A,P
;**************************************************************************
RDCHAR:

PHA ;SAVE A,X,Y
TYA
PHA
TXA
PHA

JSR RCHAR ;APPLE MONITOR RDCHAR
TSX
AND #01111111B ;ZERO BIT 7
STA 103H,X ;STORE CHARACTER IN STACK SO IT WILL BE
             ;RESTORED TO REGISTER A
PLA
TAX
PLA
TAY
PLA
RTS

;**************************************************************
;ROUTINE: WRCHAR
;PURPOSE: WRITE A CHARACTER
;ENTRY: REGISTER A = CHARACTER
;EXIT: NONE
;REGISTERS USED: P
;**************************************************************

WRCHAR:

PHA ;SAVE A,X,Y
TYA
PHA
TXA
PHA

TSX
LDA 103H,X ;GET REGISTER A BACK FROM STACK
ORA #10000000B ;SET BIT 7
JSR COUT ;OUTPUT VIA APPLE MONITOR
PLA
TAX
PLA
TAY
PLA
RTS

;**************************************************************
;ROUTINE: RDLINE
;PURPOSE: READ A LINE TO 200H USING THE APPLE MONITOR
;ENTRY: NONE
;EXIT: REGISTER X = LENGTH OF LINE
;REGISTERS USED: ALL
;**************************************************************
RDLINE:
JSR GETLN1 ;CALL THE APPLE MONITOR GETLN1
RTS

;*********************************************************************
;ROUTINE: NXTNUM
;PURPOSE: GET A NUMBER FROM THE INPUT LINE IF ANY
; ENTRY: LLEN = LENGTH OF THE LINE
; LIDX = INDEX INTO THE LINE OF NEXT CHARACTER
; EXIT: REGISTERS A = LOW BYTE OF NUMBER
; Y = HIGH BYTE OF NUMBER
; LIDX = INDEX OF THE FIRST NON NUMERICAL CHARACTER
;REGISTERS USED: ALL
;*********************************************************************

NXTNUM:
LDA #0 ;INITIALIZE NUMBER TO 0
STA NUM
STA NUM+1

;WAIT UNTIL A DECIMAL DIGIT IS FOUND (A CHARACTER BETWEEN 30H AND 39H)
JSR GETCHR ;GET NEXT CHARACTER
BCS EXITNN ;EXIT IF END OF LINE
CMP #"0"
BCC NXTNUM ;WAIT IF LESS THAN "0"
CMP #"9"+1
BCS NXTNUM ;WAIT IF GREATER THAN "9"

;FOUND A NUMBER
PHA ;SAVE CHARACTER ON STACK

;MULTIPLY NUM BY TEN
LDA NUM
ASL A
ROL NUM+1
STA NUM ;NUM = LOW BYTE OF NUM * 2
LDX NUM+1 ;REGISTER X = HIGH BYTE OF NUM * 2
ASL A
ROL NUM+1
ASL A ;REGISTER A = LOW BYTE OF NUM * 8
ROL NUM+1 ;NUM + 1 = HIGH BYTE OF NUM * 8
CLC
ADC NUM
STA NUM
TXA
ADC NUM+1
STA NUM+1

;ADD THE CHARACTER TO NUM
PLA ;GET NEXT CHARACTER
AND #00001111B ;NORMALIZE THE CHARACTER TO 0..9
CLC
ADC NUM
STA NUM
BCC   GETNM1
INC   NUM+1

GETNM1:

;GET THE NEXT CHARACTER
JSR   GETCHR
BCC   EXITNN    ;EXIT IF END OF LINE
CMP   #$0
BCC   EXITNN    ;EXIT IF LESS THAN "0"
CMP   #$9+1
BCC   GETNUM    ;STAY IN LOOP IF DIGIT (BETWEEN "0" AND "9")

EXITNN:

LDA   NUM   ;RETURN THE NUMBER
LDY   NUM+1
RTS

;*********************************
;ROUTINE: GETCHR
;PURPOSE: GET A CHARACTER FOR THE LINE
;ENTRY: LIDX = NEXT CHARACTER TO GET
;       LLEN = LENGTH OF LINE
;EXIT: IF NO MORE CHARACTERS THEN
;       CARRY = 1
;       ELSE
;       CARRY = 0
;       REGISTER A = CHARACTER
;REGISTERS USED: ALL
;*********************************

GETCHR:

LDA   LIDX
CMP   LLEN
BCS   EXITGC     ;EXIT CHARACTER GET WITH CARRY = 1 TO
                 ;INDICATE END OF LINE (LIDX >= LLEN) 
                 ;OTHERWISE, CARRY IS CLEARED

TAY
LDA   200H,Y
AND   #01111111B
INY
STY   LIDX

EXITGC:

RTS

;*******************************
;ROUTINE: PRTNUM
;PURPOSE: PRINT A NUMBER BETWEEN 0..99
;ENTRY: A = NUMBER TO PRINT
;EXIT: NONE
;REGISTERS USED: ALL
;*******************************
1D REAL-TIME CLOCK AND CALENDAR (CLOCK) 503

PRTNUM:
LDY #"0"-1 ; INITIALIZE Y TO "0" - 1
SEC ; Y WILL BE THE 10'S PLACE

DIV10:
INY ; INCREMENT 10'S
SBC #10
BCS DIV10
ADC #10+"0" ; MAKE REGISTER A AN ASCII DIGIT

; REG A = 1'S PLACE
; REG Y = 10'S PLACE
TAX ; SAVE 1'S
TYA
JSR WRCHAR ; OUTPUT 10'S PLACE
TXA
JSR WRCHAR ; OUTPUT 1'S PLACE
RTS

; DATA SECTION
CR .EQU 0DH ; ASCII CARRIAGE RETURN
MSGIDX .BLOCK 1 ; INDEX INTO MESSAGE
NUM: .BLOCK 2 ; NUMBER
LLLEN: .BLOCK 1 ; LENGTH OF INPUT LINE
LIDX: .BLOCK 1 ; INDEX OF INPUT LINE
CEN20: .WORD 1900 ; 20TH CENTURY
CURSEC: .BLOCK 1 ; CURRENT SECOND

.END ; PROGRAM
# Appendix A 6502 Instruction Set Summary

Table A-1. 6502 Instructions in Alphabetical Order

<table>
<thead>
<tr>
<th>INSTRUCTIONS</th>
<th>IMMEDIATE</th>
<th>ABSENCE</th>
<th>ZERO/PAGE</th>
<th>ACCUM</th>
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### Table A-1. 6502 Instructions in Alphabetical Order (Continued)

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(1) ADD TO "N" IF PAGE BOUNDARY IS CROSSED
(2) ADD TO "N" IF BRANCH OCCURS TO SAME PAGE
(3) CARRY NOT = BORROW
(4) IF IN DECIMAL MODE Z FLAG IS INVALID

### Table A-2. 6502 Operation Codes in Numerical Order

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<td>ADC X</td>
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<td>ADC X</td>
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<td>ADD X</td>
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<td>68</td>
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Table A-3. Summary of 6502 Addressing Modes

<table>
<thead>
<tr>
<th>Addressing Mode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IMM</td>
<td>IMMEDIATE ADDRESSING</td>
</tr>
<tr>
<td>ABS</td>
<td>ABSOLUTE ADDRESSING</td>
</tr>
<tr>
<td>Z. Page</td>
<td>ZERO PAGE ADDRESSING</td>
</tr>
<tr>
<td>A.</td>
<td>ACCUMULATOR</td>
</tr>
<tr>
<td>Z. Page, Y</td>
<td>ZERO PAGE INDEXED</td>
</tr>
<tr>
<td>IND, X</td>
<td>INDEXED INDIRECT</td>
</tr>
<tr>
<td>IND, Y</td>
<td>INDIRECT INDEXED</td>
</tr>
</tbody>
</table>

Table A-4. 6502 Assembler Directives, Labels, and Special Characters

Assembler Directives

- **OPT** - Specifies options for assembly
- **NOC (COU or CNT)** - Do not list all instructions and their usage.
- **NOG (GEN)** - Do not generate more than one line of code for ASCII strings.
- **XRE (NOX)** - Produce a cross-reference list in the symbol table.
- **ERR (NOE)** - Create an error file.
- **MEM (NOM)** - Create an assembler object output file.
- **LIS (NOD)** - Produce a full assembly listing.
- **BYTE** - Produces a single byte in memory equal to each operand specified.
- **WORD** - Produces an address (2 bytes) in memory equal to each operand specified.
- **BYTE** - Produces two bytes in memory equal to each operand specified.
- **PAGE** - Advances the listing to the top of a new page and change title.
- **END** - Defines the end of a source program.
- **-** - Defines the beginning of a new program counter sequence.

Labels

Labels are the first field and must be followed by at least one space or a colon. Labels can be up to 6 alphanumeric characters long and must begin with an alpha character.

A, Y, S, P and the 56 opcodes are reserved and cannot be used as labels. Label expression can be used to equate labels to values.

Label ***/*** in can be used to reserve areas in memory.

Characters used as special prefixes:

- **IND** - Indicates an assembler directive
- **S** - Specifies the immediate mode of addressing
- **$** - Specifies a hexadecimal number
- **@** - Specifies an octal number
- **%** - Specifies a binary number
- **'** - Specifies an ASCII literal character
- () - Indicates indirect addressing
- **/** - Indicates following text are comments
- < specifies lower half of a 16 bit value
- > specifies upper half of a 16 bit value
Figure A-1. Response to IRQ and NMI Inputs and Operation of the RTI and BRK Instructions

Figure A-2. Operation of the JSR and RTS Instructions
Figure A-3. Programming Model of the 6502 Microprocessor
Figure B-1. 6522 Pin Assignments
Figure B-2. Block Diagram of the 6522 Versatile Interface Adapter (VIA)

Table B-1. 6522 Internal Registers

<table>
<thead>
<tr>
<th>Register Number</th>
<th>RS Coding</th>
<th>Register Desig.</th>
<th>Description</th>
<th>Write</th>
<th>Read</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0 0 0 0</td>
<td>ORB/IRB</td>
<td>Output Register “B”</td>
<td>Input Register “B”</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0 0 0 1</td>
<td>ORA/IRA</td>
<td>Output Register “A”</td>
<td>Input Register “A”</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0 0 1 0</td>
<td>DDRB</td>
<td>Data Direction Register “B”</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>0 0 1 1</td>
<td>DDRA</td>
<td>Data Direction Register “A”</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>0 1 0 0</td>
<td>T1C-L</td>
<td>T1 Low-Order Latches</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>0 1 0 1</td>
<td>T1C-H</td>
<td>T1 High-Order Counter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>0 1 1 0</td>
<td>T1L-L</td>
<td>T1 Low-Order Latches</td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>0 1 1 1</td>
<td>T1L-H</td>
<td>T1 High-Order Latches</td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>1 0 0 0</td>
<td>T2C-L</td>
<td>T2 Low-Order Latches</td>
<td></td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>1 0 0 1</td>
<td>T2C-H</td>
<td>T2 High-Order Counter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>1 0 1 0</td>
<td>SR</td>
<td>Shift Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>1 0 1 1</td>
<td>ACR</td>
<td>Auxiliary Control Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>1 1 0 0</td>
<td>PCR</td>
<td>Peripheral Control Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>1 1 0 1</td>
<td>IFR</td>
<td>Interrupt Flag Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>14</td>
<td>1 1 1 0</td>
<td>IER</td>
<td>Interrupt Enable Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>1 1 1 1</td>
<td>ORA/IRA</td>
<td>Same as Reg 1 Except No “Handshake”</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
512 6502 ASSEMBLY LANGUAGE SUBROUTINES

Figure B-3. Output Register B and Input Register B (Register 0)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Data Direction Selection</th>
<th>WRITE</th>
<th>READ</th>
</tr>
</thead>
<tbody>
<tr>
<td>DDRB = &quot;1&quot; (OUTPUT)</td>
<td>MPU writes Output Level (ORB)</td>
<td>MPU reads output register bit in ORB. Pin level has no affect.</td>
<td></td>
</tr>
<tr>
<td>DDRB = &quot;0&quot; (INPUT)</td>
<td>MPU writes into ORB, but no effect on pin level, until DDRB changed.</td>
<td>MPU reads input level on PB pin.</td>
<td></td>
</tr>
<tr>
<td>DDRB = &quot;0&quot; (INPUT)</td>
<td>MPU reads ORB bit, which is the level of the PB pin at the time of the last CB1 active transition.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Figure B-4. Output Register A and Input Register A (Register 1)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Data Direction Selection</th>
<th>WRITE</th>
<th>READ</th>
</tr>
</thead>
<tbody>
<tr>
<td>DDRA = &quot;1&quot; (OUTPUT)</td>
<td>MPU writes Output Level (ORA)</td>
<td>MPU reads level on PA pin.</td>
<td></td>
</tr>
<tr>
<td>DDRA = &quot;0&quot; (OUTPUT)</td>
<td>MPU writes into ORA, but no effect on pin level, until DDRA changed.</td>
<td>MPU reads level on PA pin.</td>
<td></td>
</tr>
<tr>
<td>DDRA = &quot;0&quot; (INPUT)</td>
<td>MPU reads IRA bit which is the level of the PA pin at the time of the last CA1 active transition.</td>
<td>MPU reads level on PA pin.</td>
<td></td>
</tr>
<tr>
<td>DDRA = &quot;0&quot; (INPUT)</td>
<td>MPU reads IRA bit which is the level of the PA pin at the time of the last CA1 active transition.</td>
<td>MPU reads level on PA pin.</td>
<td></td>
</tr>
</tbody>
</table>
"0" ASSOCIATED PB/PA PIN IS AN INPUT (HIGH-IMPEDANCE)
"1" ASSOCIATED PB/PA PIN IS AN OUTPUT, WHOSE LEVEL IS DETERMINED BY ORB/OR REGISTER BIT.

WRITE – 8 BITS LOADED INTO T1 HIGH-ORDER LATCHES. ALSO, AT THIS TIME BOTH HIGH AND LOW-ORDER LATCHES TRANSFERRED INTO T1 COUNTER, T1 INTERRUPT FLAG ALSO IS RESET.
READ – 8 BITS FROM T1 HIGH-ORDER COUNTER TRANSFERRED TO MPU.

WRITE – 8 BITS LOADED INTO T1 LOW-ORDER LATCHES. LATCH CONTENTS ARE TRANSFERRED INTO LOW-ORDER COUNTER AT THE TIME THE HIGH-ORDER COUNTER IS LOADED (REG 5).
READ – 8 BITS FROM T1 LOW-ORDER COUNTER TRANSFERRED TO MPU. IN ADDITION, T1 INTERRUPT FLAG IS RESET (BIT 6 IN INTERRUPT FLAG REGISTER).

WRITE – 8 BITS LOADED INTO T1 LOW-ORDER LATCHES. THIS OPERATION IS THE SAME AS WRITING INTO REGISTER 4.
READ – 8 BITS FROM T1 LOW-ORDER LATCHES TRANSFERRED TO MPU. UNLIKE REG 4 OPERATION, THIS DOES NOT CAUSE RESET OF T1 INTERRUPT FLAG.

Figure B-5. Data Direction Registers B (Register 2) and A (Register 3)
Figure B-6. Timer 1 Low-Order Counter (Register 4)
Figure B-7. Timer 1 High-Order Counter (Register 5)
Figure B-8. Timer 1 Low-Order Latches (Register 6)
WRITE – 8 BITS LOADED INTO T1 HIGH-ORDER LATCHES. UNLIKE REG 4 OPERATION NO LATCH-TO-COUNTER TRANSFERS TAKE PLACE.
READ – 8 BITS FROM T1 HIGH-ORDER LATCHES TRANSFERRED TO MPU.

Figure B-9. Timer 1 High-Order Latches (Register 7)

WRITE – 8 BITS LOADED INTO T2 HIGH-ORDER COUNTER. ALSO, LOW-ORDER LATCHES TRANSFERRED TO LOW-ORDER COUNTER. IN ADDITION, T2 INTERRUPT FLAG IS RESET.
READ – 8 BITS FROM T2 HIGH-ORDER COUNTER TRANSFERRED TO MPU.

Figure B-11. Timer 2 High-Order Counter (Register 9)

WRITE – 8 BITS LOADED INTO T2 LOW-ORDER LATCHES.
READ – 8 BITS FROM T2 LOW-ORDER COUNTER TRANSFERRED TO MPU. T2 INTERRUPT FLAG IS RESET.

Figure B-10. Timer 2 Low-Order Counter (Register 8)

NOTES:
1. WHEN SHIFTING OUT, BIT 7 IS THE FIRST BIT OUT AND SIMULTANEOUSLY IS ROTATED BACK INTO BIT 0.
2. WHEN SHIFTING IN, BITS INITIALLY ENTER BIT 0 AND ARE SHIFTED TOWARDS BIT 7.

Figure B-12. Shift Register (Register 10)
Figure B-13. Auxiliary Control Register (Register 11)

Figure B-14. Peripheral Control Register (Register 12)
Figure B-15. Interrupt Flag Register (Register 13)

Figure B-16. Interrupt Enable Register (Register 14)
Appendix C ASCII Character Set

<table>
<thead>
<tr>
<th>MSD</th>
<th>000</th>
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<th>010</th>
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<th>111</th>
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<tbody>
<tr>
<td>LSD</td>
<td>NUL</td>
<td>DLE</td>
<td>SP</td>
<td>@</td>
<td>P</td>
<td>a</td>
<td>q</td>
<td>p</td>
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<tr>
<td>0</td>
<td>SOH</td>
<td>DC1</td>
<td>!</td>
<td>A</td>
<td>Q</td>
<td>b</td>
<td>r</td>
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<td>1</td>
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<td>’</td>
<td>B</td>
<td>R</td>
<td>s</td>
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<td></td>
</tr>
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<td>C</td>
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<td></td>
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<td></td>
</tr>
</tbody>
</table>
A

Absolute address. An address that identifies a storage location or a device without the use of a base, offset, or other factor. See also Effective address, Relative offset.

Absolute addressing. An addressing mode in which the instruction contains the actual address required for its execution. In 6502 terminology, absolute addressing refers to a type of direct addressing in which the instruction contains a full 16-bit address as opposed to zero page addressing in which the instruction contains only an 8-bit address on page 0.

Absolute indexed addressing. A form of indexed addressing in which the instruction contains a full 16-bit base address.

Accumulator. A register that is the implied source of one operand and the destination of the result for most arithmetic and logic operations.

ACIA (Asynchronous Communications Interface Adapter). A serial interface device. Common ACIAs in 6502-based computers are the 6551 and 6850 devices. See also UART.

Active transition (in a PIA or VIA). The edge on the control line that sets an Interrupt flag. The alternatives are a negative edge (1 to 0 transition) or a positive edge (0 to 1 transition).

Address. The identification code that distinguishes one memory location or input/output port from another and that can be used to select a specific one.

Addressing modes. The methods for specifying the addresses to be used in executing an instruction. Common addressing modes are direct, immediate, indexed, indirect, and relative.
Address register. A register that contains a memory address.

Address space. The total range of addresses to which a particular computer may refer.

ALU. See Arithmetic-logic unit.

Arithmetic-logic unit (ALU). A device that can perform any of a variety of arithmetic or logical functions; function inputs select which function is performed during a particular cycle.

Arithmetic shift. A shift operation that preserves the value of the sign bit (most significant bit). In a right shift, this results in the sign bit being copied into the succeeding bit positions (called sign extension).

Arm. See Enable, but most often applied to interrupts.

Array. A collection of related data items, usually stored in consecutive memory addresses.


Assembler. A computer program that converts assembly language programs into a form (machine language) that the computer can execute directly. The assembler translates mnemonic operation codes and names into their numerical equivalents and assigns locations in memory to data and instructions.

Assembly language. A computer language in which the programmer can use mnemonic operation codes, labels, and names to refer to their numerical equivalents.

Asynchronous. Operating without reference to an overall timing source, that is, at irregular intervals.

Autodecrementing. The automatic decrementing of an address register as part of the execution of an instruction that uses it.

Autoincrementing. The automatic incrementing of an address register as part of the execution of an instruction that uses it.

Automatic mode (of a peripheral chip). An operating mode in which the peripheral chip produces control signals automatically without specific program intervention.

Base address. The address in memory at which an array or table starts. Also called starting address or base.
Baud. A measure of the rate at which serial data is transmitted, bits per second, but including both data bits and bits used for synchronization, error checking, and other purposes. Common baud rates are 110, 300, 1200, 2400, 4800, and 9600.

Baud rate generator. A device that generates the proper time intervals between bits for serial data transmission.

BCD (Binary-Coded Decimal). A representation of decimal numbers in which each decimal digit is coded separately into a binary number.

Bidirectional. Capable of transporting signals in either direction.

Binary-coded decimal. See BCD.

Binary search. A search in which the set of items to be searched is divided into two equal (or nearly equal) parts during each iteration. The part containing the item being sought is then determined and used as the set in the next iteration. A binary search thus halves the size of the set being searched with each iteration. This method obviously assumes the set of items is ordered.

Bit test. An operation that determines whether a bit is 0 or 1. Usually refers to a logical AND operation with an appropriate mask.

Block. An entire group or section, such as a set of registers or a section of memory.

Block comparison (or block compare). A search that extends through a block of memory until either the item being sought is found or the entire block is examined.

Block move. Moving an entire set of data from one area of memory to another.

Boolean variable. A variable that has only two possible values, which may be represented as true and false or as 1 and 0. See also Flag.

Borrow. A bit which is set to 1 if a subtraction produces a negative result and to 0 if it produces a positive or zero result. The borrow is used commonly to subtract numbers that are too long to be handled in a single operation.

Bounce. To move back and forth between states before reaching a final state.

Branch instruction. See Jump instruction.

Break instruction. See Trap.

Breakpoint. A condition specified by the user under which program execution is to end temporarily. Breakpoints are used as an aid in debugging. The specification of the conditions under which execution will end is referred to as setting
breakpoints and the deactivation of those conditions is referred to as clearing breakpoints.

**BSC** (Binary Synchronous Communications or BISYNC). An older line protocol often used by IBM computers and terminals.

**Bubble sort.** A sorting technique which goes through an array exchanging each pair of elements that are out of order.

**Buffer.** Temporary storage area generally used to hold data before it is transferred to its final destination.

**Buffer empty.** A signal that is active when any data entered into a buffer or register has been transferred to its final destination.

**Buffer full.** A signal that is active when a buffer or register is completely occupied with data that has not been transferred to its final destination.

**Buffer index.** The index of the next available address in a buffer.

**Buffer pointer.** A storage location that contains the next available address in a buffer.

**Bug.** An error or flaw.

**Byte.** A unit of eight bits. May be described as consisting of a high nibble or digit (the four most significant bits) and a low nibble or digit (the four least significant bits).

**Byte-length.** A length of eight bits per item.

**C**

**Call** (a subroutine). Transfers control to the subroutine while retaining the information required to resume the current program. A call differs from a jump or branch in that a call retains information concerning its origin, whereas a jump or branch does not.

**Carry.** A bit that is 1 if an addition overflows into the succeeding digit position.

**Carry flag.** A flag that is 1 if the last operation generated a carry from the most significant bit and 0 if it did not.

**CASE statement.** A statement in a high-level computer language that directs the computer to perform one of several subprograms, depending on the value of a variable. That is, the computer performs the first subprogram if the variable has the first value specified, etc. The computed GO TO statement serves a similar function in FORTRAN.
Central processing unit (CPU). The control section of the computer which controls its operations, fetches and executes instructions, and performs arithmetic and logical functions.

Checksum. A logical sum that is included in a block of data to guard against recording or transmission errors. Also referred to as longitudinal parity or longitudinal redundancy check (LRC).

Circular shift. See Rotate.

Cleaning the stack. Removing unwanted items from the stack, usually by adjusting the stack pointer.

Clear. Set to zero.

Clock. A regular timing signal that governs transitions in a system.

Close (a file). To make a file inactive. The final contents of the file are the last information the user stored in it. The user must generally close a file after working with it.

Coding. Writing instructions in a computer language.

Combo chip. See Multifunction device.

Command register. See Control register.

Comment. A section of a program that has no function other than documentation. Comments are neither translated nor executed, but are simply copied into the program listing.

Complement. Invert; see also one's complement, two’s complement.

Concatenation. Linking together, chaining, or uniting in a series. In string operations, placing of one string after another.

Condition code. See Flag.

Control (command) register. A register whose contents determine the state of a transfer or the operating mode of a device.

Control signal. A signal that directs an I/O transfer or changes the operating mode of a peripheral.

Cyclic redundancy check (CRC). An error-detecting code generated from a polynomial that can be added to a block of data or a storage area.
D

Data accepted. A signal that is active when the most recent data has been transferred successfully.

Data direction register. A register that determines whether bidirectional I/O lines are being used as inputs or outputs. Abbreviated as DDR in some diagrams.

Data-link control. A set of conventions governing the format and timing of data exchange between communicating systems. Also called a protocol.

Data ready. A signal that is active when new data is available to the receiver. Same as valid data.

Data register. In a PIA or VIA, the actual input/output port. Also called an output register or a peripheral register.

DDCMP (Digital Data Communications Message Protocol). A widely used protocol that supports any method of physical data transfer (synchronous or asynchronous, serial or parallel).

Debounce. Convert the output from a contact with bounce into a single, clean transition between states. Debouncing is most commonly applied to outputs from mechanical keys or switches which bounce back and forth before settling into their final positions.

Debounce time. The amount of time required to debounce a change of state.

Debugger. A program that helps in locating and correcting errors in a user program. Some versions are referred to as dynamic debugging tools or DDT after the famous insecticide.

Debugging. The process of locating and correcting errors in a program.

Device address. The address of a port associated with an input or output device.

Diagnostic. A program that checks the operation of a device and reports its findings.

Digit shift. A shift of one BCD digit position or four bit positions.

Direct addressing. An addressing mode in which the instruction contains the address required for its execution. The 6502 microprocessor has two types of direct addressing: zero page addressing (requiring only an 8-bit address on page 0) and absolute addressing (requiring a full 16-bit address in two bytes of memory).

Disarm. See Disable, but most often applied to interrupts.
Disable (or disarm). Prohibit an activity from proceeding or a signal (such as an interrupt) from being recognized.

Double word. A unit of 32 bits.

Driver. See I/O driver.

Dump. A facility that displays the contents of an entire section of memory or group of registers on an output device.

Dynamic allocation (of memory). The allocation of memory for a subprogram from whatever is available when the subprogram is called. This is as opposed to the static allocation of a fixed area of storage to each subprogram. Dynamic allocation often reduces memory usage because subprograms can share areas; it does, however, generally require additional execution time and overhead spent in memory management.

E

EBCDIC (Expanded Binary-Coded Decimal Interchange Code). An 8-bit character code often used in large computers.

Echo. Reflects transmitted information back to the transmitter; sends back to a terminal the information received from it.

Editor. A program that manipulates text material and allows the user to make corrections, additions, deletions, and other changes.

Effective address. The actual address used by an instruction to fetch or store data.


Enable (or arm). Allows an activity to proceed or a signal (such as an interrupt) to be recognized.

Endless loop or jump-to-self instruction. An instruction that transfers control to itself, thus executing indefinitely (or until a hardware signal interrupts it).

Error-correcting code. A code that the receiver can use to correct errors in messages; the code itself does not contain any additional message.

Error-detecting code. A code that the receiver can use to detect errors in messages; the code itself does not contain any additional message.

Even parity. A 1-bit error-detecting code that makes the total number of 1 bits in a unit of data (including the parity bit) even.
**EXCLUSIVE OR function.** A logical function that is true if either of its inputs is true but not both. It is thus true if its inputs are not equal (that is, if one of them is a logic 1 and the other is a logic 0).

**External reference.** The use in a program of a name that is defined in another program.

**F**

*F* (flag) register. See Processor status register.

**File.** A collection of related information that is treated as a unit for purposes of storage or retrieval.

**Fill.** Placing values in storage areas not previously in use, initializing memory or storage.

**Flag (or condition code or status bit).** A single bit that indicates a condition within the computer, often used to choose between alternative instruction sequences.

**Flag (software).** An indicator that is either on (1) or off (0) and can be used to select between two alternative courses of action. *Boolean variable* and *semaphore* are other terms with the same meaning.

**Flag register.** See Processor status register.

**Free-running mode.** An operating mode for a timer in which it indicates the end of a time interval and then starts another of the same length. Also referred to as a continuous mode.

**Function key.** A key that causes a system to perform a function (such as clearing the screen of a video terminal) or execute a procedure.

**G**

**Globai.** This is a universal variable. Defined in more than one section of a computer program, rather than used only locally.

**H**

**Handshake.** An asynchronous transfer in which sender and receiver exchange predetermined signals to establish synchronization and to indicate the status of the data transfer. Typically, the sender indicates that new data is available and the receiver reads the data and indicates that it is ready for more.
Hardware stack. A stack that the computer automatically manages when executing instructions that use it.

Head (of a queue). The location of the item most recently entered into the queue.

Header, queue. See Queue header.

Hexadecimal (or hex). Number system with base 16. The digits are the decimal numbers 0 through 9, followed by the letters A through F.

Hex code. See Object code.

High-level language. A programming language that is aimed toward the solution of problems, rather than being designed for convenient conversion into computer instructions. A compiler or interpreter translates a program written in a high-level language into a form that the computer can execute. Common high-level languages include BASIC, COBOL, FORTRAN, and Pascal.

Immediate addressing. An addressing mode in which the data required by an instruction is part of the instruction. The data immediately follows the operation code in memory.

Independent mode (of a parallel interface). An operating mode in which the status and control signals associated with a parallel I/O port can be used independently of data transfers through the port.

Index. A data item used to identify a particular element of an array or table.

Indexed addressing. An addressing mode in which the address is modified by the contents of an index register to determine the effective address (the actual address used).

Indexed indirect addressing. An addressing mode in which the effective address is determined by indexing from the base address and then using the indexed address indirectly. This is also known as preindexing, since the indexing is performed before the indirection. Of course, the array starting at the given base address must consist of addresses that can be used indirectly.

Index register. A register that can be used to modify memory addresses.

Indirect addressing. An addressing mode in which the effective address is the contents of the address included in the instruction, rather than the address itself.

Indirect indexed addressing. An addressing mode in which the effective address is determined by first obtaining the base address indirectly and then indexing from that base address. Also known as postindexing, since the indexing is performed after the indirection.
Indirect jump. A jump instruction that transfers control to the address stored in a register or memory location, rather than to a fixed address.

Input/output control block (IOCB). A group of storage locations that contain the information required to control the operation of an I/O device. Typically included in the information are the addresses of routines that perform operations such as transferring a single unit of data or determining device status.

Input/output control system (IOCS). A set of computer routines that control the performance of I/O operations.

Instruction. A group of bits that defines a computer operation and is part of the instruction set.

Instruction cycle. The process of fetching, decoding, and executing an instruction.

Instruction execution time. The time required to fetch, decode, and execute an instruction.

Instruction fetch. The process of addressing memory and reading an instruction into the CPU for decoding and execution.

Instruction length. The amount of memory needed to store a complete instruction.

Instruction set. The set of general-purpose instructions available on a given computer. The set of inputs to which the CPU will produce a known response when they are fetched, decoded, and executed.

Interpolation. Estimating values of a function at points between those at which the values are already known.

Interrupt. A signal that temporarily suspends the computer’s normal sequence of operations and transfers control to a special routine.

Interrupt-driven. Dependent on interrupts for its operation, may idle until it receives an interrupt.

Interrupt flag. A bit in the input/output section that is set when an event occurs that requires servicing by the CPU. Typical events include an active transition on a control line and the exhaustion of a count by a timer.

Interrupt mask (or interrupt enable). A bit that determines whether interrupts will be recognized. A mask or disable bit must be cleared to allow interrupts, whereas an enable bit must be set.

Interrupt request. A signal that is active when a peripheral is requesting service, often used to cause a CPU interrupt. See also Interrupt flag.

Interrupt service routine. A program that performs the actions required to respond to an interrupt.
**Inverted borrow.** A bit which is set to 0 if a subtraction produces a negative result and to 1 if it produces a positive or 0 result. An inverted borrow can be used like a true borrow, except that the complement of its value (i.e., 1 minus its value) must be used in the extension to longer numbers.

**IOCB.** See Input/output control block.

**IOCS.** See Input/output control system.

**I/O device table.** A table that establishes the correspondence between the logical devices to which programs refer and the physical devices that are actually used in data transfers. An I/O device table must be placed in memory in order to run a program that refers to logical devices on a computer with a particular set of actual (physical) devices. The I/O device table may, for example, contain the starting addresses of the I/O drivers that handle the various devices.

**I/O driver.** A computer program that transfers data to or from an I/O device, also called a *driver* or *I/O utility*. The driver must perform initialization functions and handle status and control, as well as physically transfer the actual data.

**J**

**Jump instruction** (or Branch instruction). An instruction that places a new value in the program counter, thus departing from the normal one-step incrementing. Jump instructions may be conditional; that is, the new value may be placed in the program counter only if a condition holds.

**Jump table.** A table consisting of the starting addresses of executable routines, used to transfer control to one of them.

**L**

**Label.** A name attached to an instruction or statement in a program that identifies the location in memory of the machine language code or assignment produced from that instruction or statement.

**Latch.** A device that retains its contents until new data is specifically entered into it.

**Leading edge** (of a binary pulse). The edge that marks the beginning of a pulse.

**Least significant bit.** The rightmost bit in a group of bits, that is, bit 0 of a byte or a 16-bit word.

**Library program.** A program that is part of a collection of programs and is written and documented according to a standard format.
LIFO (last-in, first-out) memory. A memory that is organized according to the order in which elements are entered and from which elements can be retrieved only in the order opposite from that in which they were entered. See also Stack.

Linearization. The mathematical approximation of a function by a straight line between two points at which its values are known.

Linked list. A list in which each item contains a pointer (or link) to the next item. Also called a chain or chained list.

List. An ordered set of items.

Logical device. The input or output device to which a program refers. The actual or physical device is determined by looking up the logical device in an I/O device table — a table containing actual I/O addresses (or starting addresses for I/O drivers) corresponding to the logical device numbers.

Logical shift. A shift operation that moves zeros in at the end as the original data is shifted.

Longitudinal parity. See Checksum.

Logical sum. A binary sum with no carries between bit positions. See also Checksum, EXCLUSIVE OR function.

Longitudinal redundancy check (LRC). See Checksum.

Lookup table. An array of data organized so that the answer to a problem may be determined merely by selecting the correct entry (without any calculations).

Low-level language. A computer language in which each statement is translated directly into a single machine language instruction.

Machine language. The programming language that the computer can execute directly with no translation other than numeric conversions.

Maintenance (of programs). Updating and correcting computer programs that are in use.

Majority logic. A combinational logic function that is true when more than half the inputs are true.

Manual mode (of a peripheral chip). An operating mode in which the chip produces control signals only when specifically directed to do so by a program.

Mark. The 1 state on a serial data communications line.

Mask. A bit pattern that isolates one or more bits from a group of bits.
Maskable interrupt. An interrupt that the system can disable.

Memory capacity. The total number of different memory addresses (usually specified in terms of bytes) that can be attached to a particular computer.

Microcomputer. A computer that has a microprocessor as its central processing unit.

Microprocessor. A complete central processing unit for a computer constructed from one or a few integrated circuits.

Mnemonic. A memory jogger, a name that suggests the actual meaning or purpose of the object to which it refers.

Modem (Modulator/demodulator). A device that adds or removes a carrier frequency, thereby allowing data to be transmitted on a high-frequency channel or received from such a channel.

Modular programming. A programming method whereby the overall program is divided into logically separate sections or modules.

Module. A part or section of a program.

Monitor. A program that allows the computer user to enter programs and data, run programs, examine the contents of the computer’s memory and registers, and utilize the computer’s peripherals. See also Operating system.

Most significant bit. The leftmost bit in a group of bits, that is, bit 7 of a byte or bit 15 of a 16-bit word.

Multifunction device. A device that performs more than one function in a computer system; the term commonly refers to devices containing memory, input/output ports, timers, etc., such as the 6530, 6531, and 6532 devices.

Multitasking. Used to execute many tasks during a single period of time, usually by working on each one for a specified part of the period and suspending tasks that must wait for input, output, the completion of other tasks, or external events.

Murphy’s Law. The famous maxim that “whatever can go wrong, will.”

N

Negate. Finds the two’s complement (negative) of a number.

Negative edge (of a binary pulse). A 1-to-0 transition.

Negative flag. See Sign flag.
Negative logic. Circuitry in which a logic zero is the active or ON state.

Nesting. Constructing programs in a hierarchical manner with one level contained within another, and so forth. The nesting level is the number of transfers of control required to reach a particular part of a program without ever returning to a higher level.

Nibble (or nybble). A unit of four bits. A byte (eight bits) may be described as consisting of a high nibble (four most significant bits) and a low nibble (four least significant bits).

Nine's complement. The result of subtracting a decimal number from a number having nines in each digit position.

Nonmaskable interrupt. An interrupt that cannot be disabled within the CPU.

Nonvolatile memory. A memory that retains its contents when power is removed.

No-op (or no operation). An instruction that does nothing other than increment the program counter.

Normalization (of numbers). Adjusting a number into a regular or standard format. A typical example is the scaling of a binary fraction so that its most significant bit is 1.

O

Object code (or object program). The program that is the output of a translator program, such as an assembler. Usually it is a machine language program ready for execution.

Odd parity. A 1-bit error-detecting code that makes the total number of 1 bits in a unit of data (including the parity bit) odd.

Offset. Distance from a starting point or base address.

One's complement. A bit-by-bit logical complement of a number, obtained by replacing each 0 bit with a 1 and each 1 bit with a 0.

One-shot. A device that produces a pulse output of known duration in response to a pulse input. A timer operates in a one-shot mode when it indicates the end of a single interval of known duration.

Open (a file). Make a file ready for use. The user generally must open a file before working with it.

Operating system (OS). A computer program that controls the overall operations of a computer and performs such functions as assigning places in memory to
programs and data, scheduling the execution of programs, processing interrupts, and controlling the overall input/output system. Also known as a monitor, executive, or master-control program, although the term monitor is usually reserved for a simple operating system with limited functions.

Operation code (op code). The part of an instruction that specifies the operation to be performed.

OS. See Operating system.

Output register. In a PIA or VIA, the actual input/output port. Also called a data register or a peripheral register.

Overflow (of a stack). Exceeding the amount of memory allocated to a stack.

Overflow, two's complement. See Two's complement overflow.

P

P register. See Processor status register, Program counter. Most 6502 reference material abbreviates program counter as PC and processor status register as P, but some refer to the program counter as P and the processor status (flag) register as F.

Packed decimal. A binary-coded decimal format in which each 8-bit byte contains two decimal digits.

Page. A subdivision of the memory. In 6502 terminology, a page is a 256-byte section of memory in which all addresses have the same eight most significant bits (or page number). For example, page C6 consists of memory addresses C600 through C6FF.

Paged address. The identifier that characterizes a particular memory address on a known page. In 6502 terminology, this is the eight least significant bits of a memory address.

Page number. The identifier that characterizes a particular page of memory. In 6502 terminology, this is the eight most significant bits of a memory address.

Page 0. In 6502 terminology, the lowest 256 addresses in memory (addresses 0000 through 00FF).

Parallel interface. An interface between a CPU and input or output devices that handle data in parallel (more than one bit at a time).

Parameter. An item that must be provided to a subroutine or program in order for it to be executed.
Parity. A 1-bit error-detecting code that makes the total number of 1 bits in a unit of data, including the parity bit, odd (odd parity) or even (even parity). Also called vertical parity or vertical redundancy check (VRC).

Passing parameters. Making the required parameters available to a subroutine.

Peripheral Interface. One of the 6500 family versions of a parallel interface; examples are the 6520, 6522, 6530, and 6532 devices.

Peripheral ready. A signal that is active when a peripheral can accept more data.

Peripheral register. In a PIA or VIA, the actual input or output port. Also called a data register or an output register.

Physical device. An actual input or output device, as opposed to a logical device.

PIA. (Peripheral Interface Adapter). The common name for the 6520 or 6820 device which consists of two bidirectional 8-bit I/O ports, two status lines, and two bidirectional status or control lines. The 6821 is a similar device.

Pointer. A storage place that contains the address of a data item rather than the item itself. A pointer tells where the item is located.

Polling. Determining which I/O devices are ready by examining the status of one device at a time.

Polling interrupt system. An interrupt system in which a program determines the source of a particular interrupt by examining the status of potential sources one at a time.

Pop. Removes an operand from a stack.

Port. The basic addressable unit of the computer’s input/output section.

Positive edge (of a binary pulse). A 0-to-1 transition.

Postdecrementing. Decrementing an address register after using it.

Postincrementing. Incrementing an address register after using it.

Postindexing. See Indirect indexed addressing.

Power fail interrupt. An interrupt that informs the CPU of an impending loss of power.

Predecrementing. Decrementing an address register before using it.

Preincrementing. Incrementing an address register before using it.

Preindexing. See Indexed indirect addressing.
Priority interrupt system. An interrupt system in which some interrupts have precedence over others, that is, they will be serviced first or can interrupt the others' service routines.

Processor status (P or F) register. A register that defines the current state of a computer, often containing various bits indicating internal conditions. Other names for this register include condition code register, flag (F) register, status register, and status word.

Program counter (PC or P register). A register that contains the address of the next instruction to be fetched from memory.

Programmable I/O device. An I/O device that can have its mode of operation determined by loading registers under program control.

Programmable peripheral chip. A chip that can operate in a variety of modes; its current operating mode is determined by loading control registers under program control.

Programmable timer. A device that can handle a variety of timing tasks, including the generation of delays, under program control.

Program relative addressing. A form of relative addressing in which the base address is the program counter. Use of this form of addressing makes it easy to move programs from one place in memory to another.

Programmed input/output. Input or output performed under program control without using interrupts or other special hardware techniques.

Protocol. See Data-link control.

Pseudo-operation (or pseudo-op or pseudo-instruction). An assembly language operation code that directs the assembler to perform some action but does not result in the generation of a machine language instruction.

Pull. Removes an operand from a stack, same as pop.

Push. Stores an operand in a stack.

Queue. A set of tasks, storage addresses, or other items that are used in a first-in, first-out manner; that is, the first item entered in the queue is the first to be removed.

Queue header. A set of storage locations describing the current location and status of a queue.
R

RAM. See Random-access memory.

Random-access memory (RAM). A memory that can be both read and altered (written) in normal operation.

Read-only memory (ROM). A memory that can be read but not altered in normal operation.

Ready for data. A signal that is active when the receiver can accept more data.

Real-time. In synchronization with the actual occurrence of events.

Real-time clock. A device that interrupts a CPU at regular time intervals.

Real-time operating system. An operating system that can act as a supervisor for programs that have real-time requirements. May also be referred to as a real-time executive or real-time monitor.

Reentrant. A program or routine that can be executed concurrently while the same routine is being interrupted or otherwise held in abeyance.

Register. A storage location inside the CPU.

Relative addressing. An addressing mode in which the address specified in the instruction is the offset from a base address.

Relative offset. The difference between the actual address to be used in an instruction and the current value of the program counter.

Relocatable. Can be placed anywhere in memory without changes; that is, a program that can occupy any set of consecutive memory addresses.

Return (from a subroutine). Transfers control back to the program that originally called the subroutine and resumes its execution.

RIOT. (ROM/I/O/timer or RAM/I/O/timer). A device containing memory (ROM or RAM), I/O ports, and timers.

ROM. See Read-only memory.

Rotate. A shift operation that treats the data as if it were arranged in a circle, that is, as if the most significant and least significant bits were connected either directly or through a Carry bit.

Row major order. Storing elements of a multidimensional array in a linear memory by changing the indexes starting with the rightmost first. That is, if the elements are \( A(i,j,k) \) and begin with \( A(0,0,0) \), the order is \( A(0,0,0), A(0,0,1), \ldots, A(0,1,0), A(0,1,1), \ldots \). The opposite technique (change leftmost index first) is called column major order.
**RRIOT.** ROM/RAM/I/O/timer, a device containing read-only memory, read/write memory, I/O ports, and timers.

**RS-232** (or EIA RS-232). A standard interface for the transmission of serial digital data, sponsored by the Electronic Industries Association of Washington, D.C. It has been partially superseded by RS-449.

**S**

**Scheduler.** A program that determines when other programs should be started and terminated.

**Scratchpad.** An area of memory that is especially easy and quick to use for storing variable data or intermediate results. Page 0 is generally used as a scratchpad in 6502-based computers.

**SDLC (Synchronous Data Link Control).** The successor protocol to BSC for IBM computers and terminals.

**Semaphore.** See Flag.

**Serial.** One bit at a time.

**Serial interface.** An interface between a CPU and input or output devices that handle data serially. Serial interfaces commonly used in 6502-based computers are the 6551 and 6850 devices. See also UART.

**Shift instruction.** An instruction that moves all the bits of the data by a certain number of bit positions, just as in a shift register.

**Signed number.** A number in which one or more bits represent whether the number is positive or negative. A common format is for the most significant bit to represent the sign (0 = positive, 1 = negative).

**Sign extension.** The process of copying the sign (most significant) bit to the right as in an arithmetic shift. Sign extension preserves the sign when two’s complement numbers are being divided or normalized.

**Sign flag.** A flag that contains the most significant bit of the result of the previous operation. It is sometimes called a negative flag, since a value of 1 indicates a negative signed number.

**Sign function.** A function that is 0 if its parameter is positive and 1 if its parameter is negative.

**Software delay.** A program that has no function other than to waste time.

**Software interrupt.** See Trap.
Software stack. A stack that is managed by means of specific instructions, as opposed to a hardware stack which the computer manages automatically.

Source code (or source program). A computer program written in assembly language or in a high-level language.

Space. The zero state on a serial data communications line.

Stack. A section of memory that can be accessed only in a last-in, first-out manner. That is, data can be added to or removed from the stack only through its top; new data is placed above the old data and the removal of a data item makes the item below it the new top.

Stack pointer. A register that contains the address of the top of a stack. The 6502’s stack pointer contains the address on page 1 of the next available (empty) stack location.

Standard (or 8,4,2,1) BCD. A BCD representation in which the bit positions have the same weights as in ordinary binary numbers.

Standard teletypewriter. A teletypewriter that operates asynchronously at a rate of ten characters per second.

Start bit. A 1-bit signal that indicates the start of data transmission by an asynchronous device.

Static allocation (of memory). Assignment of fixed storage areas for data and programs, as opposed to dynamic allocation in which storage areas are assigned at the time when they are needed.

Status register. A register whose contents indicate the current state or operating mode of a device. See also Processor status register.

Status signal. A signal that describes the current state of a transfer or the operating mode of a device.

Stop bit. A 1-bit signal that indicates the end of data transmission by an asynchronous device.

String. An array (set of data) consisting of characters.

String functions. Procedures that allow the programmer to operate on data consisting of characters rather than numbers. Typical functions are insertion, deletion, concatenation, search, and replacement.

Strobe. A signal that identifies or describes another set of signals and that can be used to control a buffer, latch, or register.
**Subroutine.** A subprogram that can be executed (called) from more than one place in a main program.

**Subroutine call.** The process whereby a computer transfers control from its current program to a subroutine while retaining the information required to resume the current program.

**Subroutine linkage.** The mechanism whereby a computer retains the information required to resume its current program after it completes the execution of a subroutine.

**Suspend (a task).** Halts execution and preserves the status of the task until some future time.

**Synchronization (or sync) character.** A character that is used only to synchronize the transmitter and the receiver.

**Synchronous.** Operating according to an overall timing source or clock, that is, at regular intervals.

**Systems software.** Programs that perform administrative functions or aid in the development of other programs but do not actually perform any of the computer’s ultimate workload.

**T**

**Tail (of a queue).** The location of the oldest item in the queue, that is, the earliest entry.

**Task.** A self-contained program that can serve as part of an overall system under the control of a supervisor.

**Task status.** The set of parameters that specify the current state of a task. A task can be suspended and resumed as long as its status is saved and restored.

**Teletypewriter.** A device containing a keyboard and a serial printer that is often used in communications and with computers. Also referred to as a Teletype (a registered trademark of Teletype Corporation of Skokie, Illinois) or TTY.

**Ten's complement.** The result of subtracting a decimal number from zero (ignoring the negative sign), the nine’s complement plus one.

**Terminator.** A data item that has no function other than to signify the end of an array.

**Threaded code.** A program consisting of subroutines, each of which automatically transfers control to the next one upon its completion.
Timeout. A period during which no activity is allowed to proceed, an inactive period.

Top of the stack. The address containing the item most recently entered into the stack.

Trace. A debugging aid that provides information about a program while the program is being executed. The trace usually prints all or some of the intermediate results.

Trailing edge (of a binary pulse). The edge that masks the end of a pulse.

Translate instruction. An instruction that converts its operand into the corresponding entry in a table.

Transparent routine. A routine that operates without interfering with the operations of other routines.

Trap (or software interrupt). An instruction that forces a jump to a specific (CPU-dependent) address, often used to produce breakpoints or to indicate hardware or software errors.

True borrow. See Borrow.

Two's complement. A binary number that, when added to the original number in a binary adder, produces a zero result. The two’s complement of a number may be obtained by subtracting the number from zero or by adding 1 to the one’s complement.

Two’s complement overflow. A situation in which a signed arithmetic operation produces a result that cannot be represented correctly — that is, the magnitude overflows into the sign bit.

UART (Universal Asynchronous Receiver/Transmitter). An LSI device that acts as an interface between systems that handle data in parallel and devices that handle data in asynchronous serial form.

Underflow (of a stack). Attempting to remove more data from a stack than has been entered into it.

Unsigned number. A number in which all the bits are used to represent magnitude.

Utility. A general-purpose program, usually supplied by the computer manufacturer or part of an operating system, that executes a standard or common operation such as sorting, converting data from one format to another, or copying a file.
V

Valid data. A signal that is active when new data is available to the receiver.

Vectored interrupt. An interrupt that produces an identification code (or vector) that the CPU can use to transfer control to the appropriate service routine. The process whereby control is transferred to the service routine is called vectoring.

Versatile Interface Adapter (VIA). The name commonly given to the 6522 parallel interface device; it consists of two 8-bit bidirectional I/O ports, four status and control lines, two 16-bit timers, and a shift register.

VIA. See Versatile Interface Adapter.

Volatile memory. A memory that loses its contents when power is removed.

W

Walking bit test. A procedure whereby a single 1 bit is moved through each bit position in an area of memory and a check is made as to whether it can be read back correctly.

Word. The basic grouping of bits that a computer can process at one time. In dealing with microprocessors, the term often refers to a 16-bit unit of data.

Word boundary. A boundary between 16-bit storage units containing two bytes of information. If information is being stored in word-length units, only pairs of bytes conforming to (aligned with) word boundaries contain valid information. Misaligned pairs of bytes contain one byte from one word and one byte from another.

Word-length. A length of 16 bits per item.

Wraparound. Organization in a circular manner as if the ends were connected. A storage area exhibits wraparound if operations on it act as if the boundary locations were contiguous.

Write-only register. A register that the CPU can change but cannot read. If a program must determine the contents of such a register, it must save a copy of the data placed there.

Z

Zero flag. A flag that is 1 if the last operation produced a result of zero and 0 if it did not.
Zero page. In 6502 terminology, the lowest 256 memory addresses (addresses 0000 through 00FF).

Zero page addressing. In 6502 terminology, a form of direct addressing in which the instruction contains only an 8-bit address on page 0. That is, zero is implied as the more significant byte of the direct address and need not be included specifically in the instruction.

Zero-page indexed addressing. A form of indexed addressing in which the instruction contains a base address on page 0. That is, zero is implied as the more significant byte of the base address and need not be included explicitly in the instruction.

Zoned decimal. A binary-coded decimal format in which each 8-bit byte contains only one decimal digit.
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